

MANUAL

Professional Line | PROTECTION TECHNOLOGY MADE SIMPLE XI1S, XI1SR | EARTH FAULT RELAY FOR SOLIDLY-EARTHED OR RESISTANCE-EARTHED SYSTEMS



EARTH FAULT RELAY FOR SOLIDLY-EARTHED OR RESISTANCE-EARTHED SYSTEMS

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1. Applications and features

The X11-S of the PROFESSIONAL LINE is an all-purpose protection against earth faults, used for electrical machines, lines and networks with solidly earthed or resistance-earthed neutral; it is mainly used in radial networks. Very often the X11-S can be found as backup protection at the central earthing point of the system. It detects all earth-faults occuring in the system. In this case the trip delay selected must exceed the longest time delay setting of any other earthing protection used in the system.

Type *XI1-S-R* with directional current sensing is a selective earth-fault protection and is normally used in ring systems, networks with parallel feeders and in complex meshed systems.

It is possible to select from the following tripping characteristics:

- Definite time overcurrent protection (DMT)
- Inverse time overcurrent protection (IDMT) with selectable tripping characteristics Normal Inverse Very Inverse

Extremely Inverse

When compared to the conventional protection equipment all relays of the *PROFESSIONAL LINE* reflect the superiority of digital protection techniques with the following features:

- High measuring accuracy by digital data processing
- Fault indication via LEDs
- Extremely wide operating ranges of the supply voltage by universal wide-range power supply
- Very fine graded wide setting ranges
- Data exchange with process management system by serial interface adapter XRS1 which can be retrofitted
- RMS measurement
- Extremely short response time
- Compact design by SMD-technology

Note:

The relay type *XI1-E* can be used if a very sensitive earth current relay is needed for earth current measuring without directional feature.

2. Design

Analog inputs

The analog input signals are connected to the protection device via terminals IE1 and IE2.

Additional for relay type *XI1-S-R* the residual voltage U_E required for determining earth fault direction can be connected from the e-n winding to the terminals Ue and Un.

Auxiliary voltage supply

Unit *XI1-S/-S-R* needs a separate auxiliary voltage supply. Therefore a DC or AC voltage must be used. Unit *XI1-S/-S-R* has an integrated wide range power supply. Voltages in the range from 19 - 390 V DC or 36 - 275 V AC can be applied at connection terminals A1 and A2.

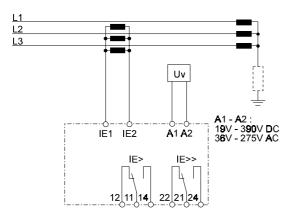


Fig. 2.1: Connections XI1-S

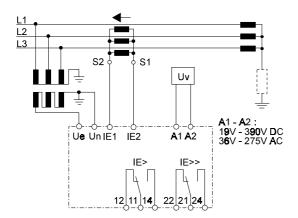


Fig. 2.2: Connections XI1-S-R

Contact positions

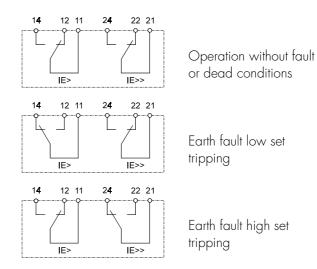


Fig. 2.3: Contact positions of the output relays

Note:

In case of both the tripping contacts of IE> and IE>> should cause the tripping coil of the C.B. to trip, they have to be interconnected.

A core balance C.T. can be connected to terminals IE1 and IE2 instead of holmgreen circuit.

3. Working principle

The incoming currents from the main current transformers on the protected object are converted to voltage signals in proportion to the currents via the input transformers and burden. The noise signals caused by inductive and capacitive coupling are supressed by an analog R-C filter circuit.

The analog voltage signals are fed to the A/Dconverter of the microprocessor and transformed to digital signals through Sample- and Hold-circuits. The analog signals are sampled at 50 Hz (60 Hz) with a sampling frequency of 800 Hz (960 Hz), namely, a sampling rate of 1.25 ms (1.04 ms) for every measuring quantity.

A pickup of a supervision circuit is indicated by flashing of the corresponding LED. At tripping the flashing light changes to steady light.

3.1 Determining earth fault direction

The measuring principle for determining the direction is based on phase angle measurement and therefore also on the coincidence-time measurement between earth current and zero sequence voltage.

The residual voltage $U_{\rm E}$ required for determining earth fault direction can be measured at the e-n winding (Connection at terminals Ue and Un).

Most faults in a characteristic angle are predominantly inductive in character. The characteristic angle between current and voltage at which the greatest measuring sensitivity is achieved has therefore been selected to precede zero sequence voltage U_0 by 110°.

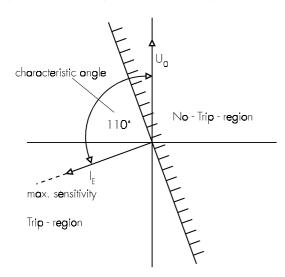
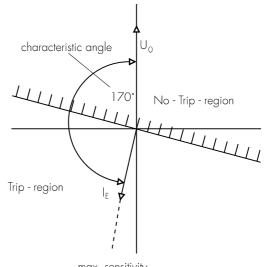


Fig. 3.1: Earth fault in solidly earthed systems

Most faults in a resistance-earthed system are predominantly ohmic in character, with a small inductive component. The characteristic angle for these types of system has therefore been set at $+170^{\circ}$ in relation to the zero sequence voltage U_o (see Fig. 3.2).



max. sensitivity

Fig. 3.2: Earth fault in resistance earthed systems

3.2 Demand imposed on the main current transformers

The current transformers have to be rated in such a way, that a saturation should not occur within the following operating current ranges:

Independent time overcurrent function: K1 = 2Inverse time overcurrent function: K1 = 20High-set function: K1 = 1.2 - 1.5K1 = Current factor related to set value

Moreover, the current transformers have to be rated according to the maximum expected short circuit current in the network or in the protected objects. The low power consumption in the current circuit of *XI1-S/-S-R*, namely <0.1 VA, has a positive effect on the selection of current transformers. It implies that, if an electromechanical relay is replaced by *XI1-S/-S-R*, a high accuracy limit factor is automatically obtained by using the same current transformer.

4. Operation and settings

All operating elements needed for setting parameters are located on the front plate of the *XI1-S/-S-R* as well as all display elements.

Because of this all adjustments of the unit can be made or changed without disconnecting the unit off the DINrail.

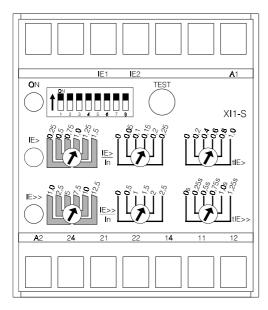


Fig. 4.1: Front plate XI1-S

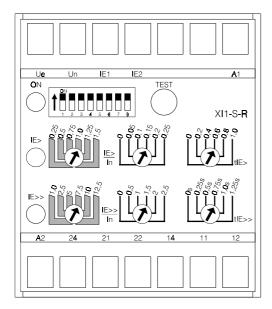


Fig. 4.2: Front plate XI1-S-R

For adjustment of the unit the transparent cover has to be opened as illustrated. Do not use force! The transparent cover has two inserts for labels.

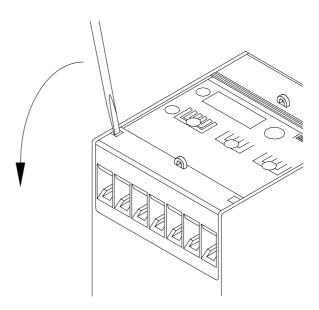


Fig. 4.3: How to open the transparent cover

LEDs

LED "ON" is used for display of the readiness for service (at applied auxiliary voltage Uv). LED IE> and IE>> indicate pickup (flashing) or tripping (steady light) of the corresponding function.

Test push button

This push button is used for test tripping of the unit and when pressed for 5 s a check-up of the hardware takes place. Both output relays are tripped and all tripping LEDs light up.

4.1 Setting of DIP-switches

The DIP-switch block on the front plate of the *XI1-S/-S-R* is used for adjustment of the nominal values and setting of function parameters:

DIP-switch	OFF	ON	Function
] *	DEFT	NINV	
2*	DEFT	VINV	Adjustment of the tripping characteristic
3*	DEFT	EINV	
4	solidly earthed 110°	resistance earthed 170°	Relay characteristic angle (<i>XI1-S-R</i> only)
5	not blocked	blocked	Blocking of the IE>> element
6	50 Hz	60 Hz	Adjustment of the rated frequency
7*	x]s(x])	x10 s (x2)	Time multiplier DEFT for tIE> (the multipliers for in- verse time characteristic are indicated in brackets)
8*	xls	x100 s	Time multiplier DEFT for tIE>

Table 4.1: Functions of DIP-switches

*Only one of the DIP-switches 1 - 3 or 7 - 8 shall be in "ON"-position at the same time.

Tripping characteristic

The required tripping characteristic for the time overcurrent protection can be adjusted with the aid of DIP-switches 1 - 3. It must be ensured that only one of the three DIP-switches is switched on. Wrong adjustment (e.g. 2 DIP-switches "ON") leads to instant tripping.

For the adjustment of the tripping characteristics, the following DIP-switch configurations are allowed:

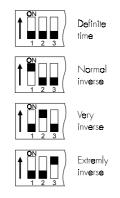


Fig. 4.4: Setting the tripping characteristics

Switching over from solidly earthed neutral to resistance-earthed neutral.

Dependent on the earthing method used, there is a certain characteristic angle between current and voltage when an earth-fault occurs. By using DIP-switch 4 it can be chosen between solidly earthed neutral (characteristic angle = 110°) and resistance-earthed neutral (characteristic angle = 170°).

Blocking of the earth fault high set element (IE>>)

When the DIP-switch 5 is in position "ON", the earth fault high set element of the relay is blocked.

Rated frequency

With the aid of DIP-switch 6 the rated frequency can be set to 50 or 60 Hz, depending upon the given mains characteristics.

Change over of the time multiplier

By using DIP-switch 7, the trip delay tIE> of the definite time element (DEFT) is multiplied by factor 10 and the inverse time element (NINV, VINV or EINV) by factor 2.

By using DIP switch 8, the trip delay of the definite time element can be multiplied by factor 100.

4.2 Setting of the tripping values

The *PROFESSIONAL LINE* units have the unique possibility of high accuracy fine adjustments. For this, two potentiometers are used. The coarse setting potentiometer can be set in discrete steps of 0.25 x ln. A second fine adjustment potentiometer is then used for continuously variable setting of the final 0.25. Adding of the two values results in the precise tripping value.

Earth fault low set element IE>

The tripping value can be set in the range from $0.25 - 1.75 \times In$ with the aid of the potentiometer illustrated on the following diagram.

Example:

A tripping value of $1.15 \times In$ is to be set. The set value of the right potentiometer is just added to the value of the coarse setting potentiometer. (The arrow of the coarse setting potentiometer must be inside of the marked bar, otherwise no defined setting value).

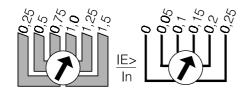


Fig. 4.5: Adjustment example

Trip delay for the earth fault low set element

The time delay for the low set element (DEFT) can be adjusted in the range from 0 - 100 s. For inverse time characteristics (NINV, VINV oder EINV) the time multiplier is adjustable in the range from 0,1 - 2.

Earth fault high set element

The high set element IE>> can be adjusted in the range from 1 - $15 \times In$. This adjustment is done similar to the low set element adjustment. Note:

The earth fault high set element of the *X11-S-R* has no direction decision. In case of a fault the relay must trip in shortest time.

Trip delay for earth fault high set element

The time delay for the high set element is adjustable in the range from 0 - 1.25 s.

4.3 Communication via serial interface adapter XRS1

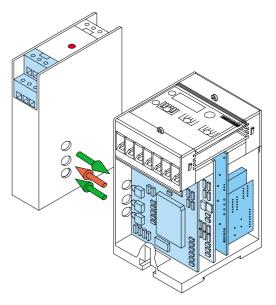


Fig.: 4.6: Communication principle

For communication of the units among each other and with a superior management system, the interface adapter **XRS1** is available for data transmission, including operating software for our relays. This adapter can easily be retrofitted at the side of relay. Screw terminals simplify its installation. Optical transmission of this adapter makes galvanic isolation of the relay possible. Aided by the software, actual measured values can be processed, relay parameters set and protection functions programmed at the output relays. Information about unit **XRS1** in detail can be taken from the description of this unit.

5. Relay case and technical data

5.1 Relay case

Relay X11-S/-S-R is designed to be fastened onto a DIN-rail acc. to DIN EN 50022, the same as all units of the *PROFESSIONAL LINE*.

The front plate of the relay is protected with a sealable transparent cover (IP40).

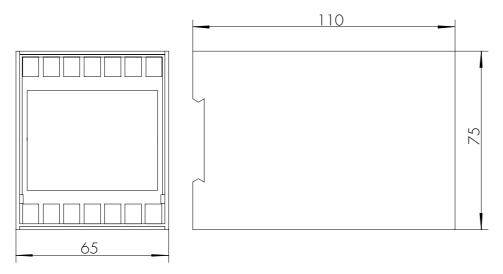


Fig. 5.1: Dimensional drawing

Connection terminals

The connection of up to a maximum $2 \times 2.5 \text{ mm}^2$ cross-section conductors is possible. For this the transparent cover of the unit has to be removed (see para. 4).

5.2 Technical data

Measuring input circuits

Rated frequency fn:	50/60 Hz		
Thermal capacity of the voltage circuit: Thermal withstand capability	continuously 120	V AC	
in current circuits:	dynamic current v for 1 s for 10 s continuously	vithstand (half wave)	250 x ln 100 x ln 30 x ln 4 x ln
Power consumption in current circuit Power consumption	at $\ln = 1 A$ at $\ln = 5 A$	0.1 VA 0.1 VA	
in voltage circuit:	at Un = 100 V	0.1 VA	
Auxiliary voltage			
Auxiliary voltage range /	10 - 300 V DC a	or 36 - 275 V AC (f = 40	- 70 H-1 /
Power consumption:	4 W (terminals A		- / 0 1 12/ /
Common data			
Dropout to pickup ratio: Resetting time from pickup: Returning time from trip: Minimum initialization time after supply voltage has applied: Minimum response time when supply voltage is available:	> 97 % <50 ms 200 ms 100 ms 50 ms		
Output relay			
Number of relays: Contacts: Maximum breaking capacity: Max. rated voltage:	ohmic 1250 VA inductive 500VA 250 V AC 220 V DC ohm indu	ntact for each trip relay / AC resp. 120 W / DC / AC resp. 75 W / DC nic load Imax. = 0,2 A uctive load Imax. = 0,1 A uctive load Imax. = 5 A	
Minimum load: Maximum rated current: Making current (16ms): Contact life span: Contact material:	1 W / 1 VA at L 5 A 20 A		

System data

Design standard:	VDE 0435, VDE 0843	Parts 1-4, VDE 0871, EN 50178:1998		
Temperature range at storage and operation: Constant climate class F acc. DIN 40040 and	- 25°C to + 70°C			
DIN IEC 68, part 2-3: High voltage test	more than 56 days at 40°	more than 56 days at 40°C and 95 % relative humidity		
acc. to VDE 0435, part 303 Voltage test: Surge voltage test: High frequency test:	2.5 kV (eff.) / 50 Hz; 1 min 5 kV; 1.2/50 μs, 0.5 J 2.5 kV / 1 MHz			
Electrostatic discharge (ESD) acc. to IEC 0801, part 2:	8 kV			
Radiated electromagnetic field test acc. to IEC 0801, part 3:	10 V/m			
Electrical fast transient (burst) acc. to IEC 0801, part 4:	4 kV / 2.5kHz, 15 ms			
Radio interference suppression test as per DIN 57871 and VDE 0871:	limit value class A			
Repeat accuracy:	1 %			
Basic time delay accuracy:	0.5 % or ±25 ms			
Basic accuracy of current:	±3 % of the setting value of	or ±2 % of IE.		
Accuracy of time delay in the range of 2 - 20 x I _s : Accuracy of the earth	2 % DEFT/5 % NINV and	VINV/7,5 % EINV/ or 25 ms		
detection (XI1-S-R):	Accuracy of angle measuring:	+1°/-13° at IE \geq 0,5 x $I_{\rm N}$ and Ue \geq 0,5 V +1°/-3° at IE \geq 1 x $I_{\rm N}$ and Ue \geq 5 V		
Transient overreach at instaneous operation: Temperature effect: Frequency effect:	≤ 5 % 0.08 % per K 1 % per K deviation from ± 10 % of fn (50 or 60 H	rated value in the range from z)		
Mechanical test: Shock: Vibration:	class 1 acc. to DIN IEC 2 class 1 acc. to DIN IEC 2			
Degree of protection Front plate: Weight: Mounting position: Relay case material:	IP40 at closed front cover approx. 0.7 kg any self-extinguishing			

5.3 Definite time earth current protection

Parameter	Setting range	Graduation
IE>	0.25 - 1.75 x ln	Continuously variable
IE>>	1 - 15 x ln	Continuously variable
tIE>	0 - 1s/0 - 10s/0 - 100s	Continuously variable
tIE>>	0 - 1.25 s	Continuously variable

Table 5.1: Setting ranges and graduation

5.4 Inverse time earth current protection

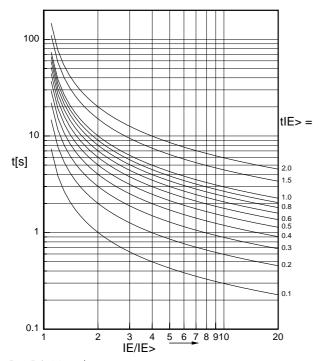
Tripping characteristics according to IEC 255-4 or BS 142

Normal Inverse	$t = \frac{0.14}{\left(\frac{ E }{ E }\right)^{0.02}}$	— tIE > [s] — 1
Very Inverse	$t = \frac{13.5}{\left(\frac{ E }{ E }\right) - 1}t$	IE > [s]
Extremely Inverse	$t = \frac{80}{\left(\frac{ E }{ E }\right)^2 - 1}$	t E > [s]
Where:	t = tIE> = IE = IE> =	trip delay time multiplier fault current setting value of the current

Parameter	Setting range	Graduation
IE>	0.25 - 1.75 x ln	Continuously variable
IE>>	1 - 15 x ln	Continuously variable
tIE>	0.1 - 2	Continuously variable
tIE>>	0 - 1.25 s	Continuously variable

Table 5.2: Setting ranges and graduation

5.5 Tripping characteristics



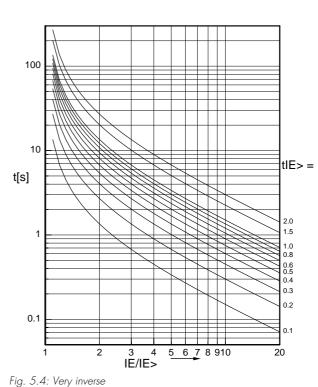
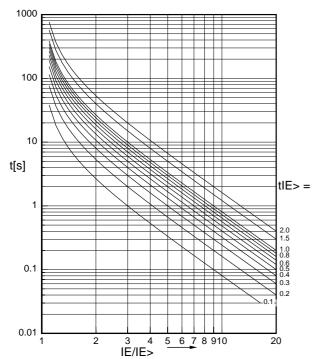


Fig. 5.2: Normal inverse



 $t[s] = \begin{bmatrix} 1 & 100 \\ 1 & 100 \\ 0 & 1 & 100 \\ 0.1 & 0 & 1 & 100 \\ 0.01 & 0 & 1 & 0 & 100 \\ 0.01 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0$

IE> ►1.75

Fig. 5.3: Extremely inverse

Fig.: 5.5:Definite time

100

10

0.25+

6. Order form

Time overcurrent relay	XI1-	S		
for solidly earthed or resistance earth	ned systems			
with earth fault directional feature			R	
Nominal current:	1 A			1
	5 A			5

Technical data subject to change without notice!

8. Setting-list X11-S/-S-R

Project:Wo		podward jobno <u>.:</u>
Function group: <u>=</u>	Location: <u>+</u>	Relay code:
Relay functions:		Date:

Setting of parameters

Function		Unit	Default settings	Actual settings
IE>	Earth fault low set element	x In	0.25	
IE>>	Earth fault high set element	x In]	
tIE>	Trip delay for earth fault low set element (DEFT)	S	0	
tIE>	Time multiplier for inverse time tripping characteristic			
tIE>>	Trip delay for earth fault high set element	S	0	

DIP-switch	Function	Default settings	Actual settings
]*		DEFT	
2*	Adjustment of the tripping characteristic	DEFT	
3*		DEFT	
4	Relay characteristic angle (<i>XI1-S-R</i> only)	solidly earthed 110°	
5	Blocking of the IE>> element	not blocked	
6	Adjustment of the rated frequency	50 Hz	
7*	Time multiplier DEFT for tIE> (the multipliers for inverse time characteristic are indicated in brackets)	x ls(xl)	
8*	Time multiplier DEFT for tIE>	x ls	

*Only one of the DIP-switches 1 - 3 or 7 - 8 shall be in "ON"-position at the same time.



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