

# HighPROTEC | PROTECTION TECHNOLOGY

MRMV4 | MOTOR PROTECTION DEVICE

# **NEW FEATURES - Release 3.6**

- · VDE-AR-N 4110
- · Wattmetric Ground Fault Protection
- · IEC 60870-5-104
- · SCADApter for Retrofit
- · Usability improvements
- · IT Security
- · Improved Frequency and ROCOF precision\*

#### **FUNCTIONS**

The MRMV4 is a protection relay which uses the latest Dual-Core-Processor Technology to provide precise and reliable protective functions. Also it is very easy to operate.

The MRMV4 provides all necessary functions to protect low and medium voltage motors at all power levels. The protection functions are based on current and voltage measurement and supervise all thermal conditions, motor start sequence, stall and locked rotor, undercurrent and incomplete sequence. Overcurrent functions and earth fault functions are also available as power protection, frequency and voltage elements. The motor operation can be monitored by statistic and trend recorders

# **APPLICABLE FOR:**

→ Low and high voltage asynchronous motors. Protection based on current and voltage measurement.

#### **MOTOR PROTECTION**

- → Thermal overload protection 49M
- → Locked rotor Protection 51LRS
- → JAM or Stall protection 51LR
- → Underload protection 37
- → Motor start 48
- → Starts per Hour 66
- → Negative phase sequence (current unbalance) 46
- → Overcurrent/short circuit prot. 50P/51P
- → Earth overcurrent- and short circuit protection 50N/51N
- → Reclosing lockout 86
- → RTD supervision via optional external temperature box (Type MRMV4-B) 26
- → Wattmetric Ground Fault Protection

# ADDITIONAL PROTECTION

- → 6 Overcurrent elements (nondir)
- → 4 Earth Overcurrent elements (nondir)
- → 2 Elements Residual Voltage
- → 4 Over-/Undervoltage elements
- → 6 Frequency elements
- → 6 Power protection elements
- → 2 Power Factor elements
- → Demand Management
- → THD Protection

#### **PC TOOLS**

- → Setting and analyzing software Smart view for free
- → Including page editor to design own pages

# SUPERVISION FUNCTIONS

- → Breaker Failure, Trip Circuit Superv.
- → Loss of Potential, Switch onto Fault

#### MOTOR START RECORDER

- → Max. RMS values of phase currents
- → Negative phase sequence currents
- → Start duration, successful starts
- → Used thermal capacity
- → Temperature profile (optional)

# STATISTIC RECORDER

- → Number of successful starts
- → Average I2T values
- → Average max. start current

# **ADDITIONAL RECORDERS**

- → Disturbance recorder: 120 s non volatile
- → Fault recorder: 20 faults
- → Event recorder: 300 events
- → Trend recorder: 4000 non volatile entries

#### **COUNTERS**

- → History (e.g. Motor starts values, Alarms, Trips...
- → Total Counters (e.g. Run Time...)

# **COMMUNICATION OPTIONS**

- → IEC 61850, IEC 60870-5-103, IEC 60870-5-104, Profibus DP
- → Modbus RTU and/or Modbus TCP
- → DNP 3.0 (RTU, TCP, UDP)
- → SCADApter for Retrofit

#### **IT SECURITY**

- → Menu for the activation of BDEW-Whitepaper-compliant security settings (e.g. hardening of interfaces)
- IT Security Logger
- → Syslog (to centralized server)
- → Encrypted connection with Smart view



# **COMMISSIONING SUPPORT**

- → USB connection
- Customizable Display (Single-Line, ...)
- → Customizable Inserts
- → Copy and compare parameter sets
- Configuration files are convertible
- → Forcing and disarming of output relays
- → Fault simulator: current and voltage
- → Graphical display of tripping characteristics
- → 8 languages selectable within the relay

# **ADDITIONAL HIGHLIGHTS**

- → 4 Analog Outputs (Type MRMV4-B)
- → Long starting time for reduced voltage starts
- → Emergency Start
- → Incomplete sequence
- → Anti-backspin time delay
- → Permitted number of cold starts
- → Supervision of starts per hour
- → Mechanical load shedding
- → Zero speed indication via input
- → Motor stop inputs
- → External alarm and trip inputs
- → 4 setting groups

#### **CONTROL AND SUPERVISION**

→ of one breaker

#### LOGIC

→ Up to 80 logic equations for protection, control and monitoring

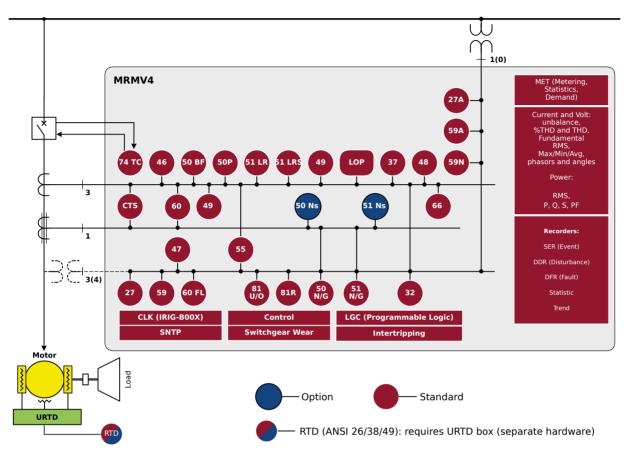
#### TIME SYNCHRONISATION

→ SNTP, IRIG-B00X, Modbus, DNP 3.0, IEC 60870-5-103/-104

# **FUNCTIONAL OVERVIEW**

	Elements	ANSI
Protective Functions		
B, thermal overload protection		49M
, time overcurrent and short circuit protection (non direction) instantaneous, definite time, characteristicsaccording to IEC60255, ANSI		50P, 51P
Voltage controlled overcurrent protection by means of adaptive parameters. Voltage dependent overcurrent protection Negative phase sequence overcurrent protection	6	51C 51V 51Q
2, unbalanced load protection with evaluation of the negative phase sequence current	2	46
G, earth time overcurrent and short circuit protection (non direction) instantaneous, definite time, characteristics according to IEC60255, ANSI	4	50N/G, 51N/G
< underload protection	2	37
Reclosing lockout		49R
ncomplete sequence		
IAM protection	2	51LR
ocked rotor Protection		51LRS
Motor start		48
Starts per Hour		66
Start control input		
Reversing mode		
Emergency start		
/<, V>, V(t)<, under- and overvoltage protection, time dependent undervoltage protection	6	27, 59
Voltage asymmetry supervision (V012) V1, under and overvoltage in positive phase sequence system V2, overvoltage in negative phase sequence system	6	47
Each of the six frequency protection elements can be used as:	6	
<ul> <li>f &lt; or f &gt; (over- or under frequency supervision)</li> <li>df/dt rate of change of frequency (ROCOF)</li> <li>(f &lt; and df/dt) or (f &gt; and df/dt) combination of over-, under- and ROCOF)</li> <li>(f &lt; and DF/DT) or (f &gt; and DF/DT) combination of over-, under- and increase of frequency</li> <li>Delta Phi (Vector surge)</li> </ul>		81U/O 81R 78
/X, residual voltage protection	2	59N
PQS, Power protection	6	32, 37
PF. Power factor	2	55
The factor		33
Control and Logic		
Control: Position indication, supervision time management and interlockings a breaker		
Logic: Up to 80 logic equations, with 4 inputs, selectable logical gates, timers and memory function		
Supervision Functions		
CBF, circuit breaker failure protection	1	50BF/62BF
CS, trip circuit supervision	1	74TC
OP, loss of potential	1	60FL
CTS, current transformer supervision	1	60L
SOTF, switch onto fault	1	
Demand management and peak value supervision (current and power)		
THD supervision		
Breaker wear with programmable wear curves		
Recorders: Disturbance, fault, event, trend, start and statistic recorders		

#### **FUNCTIONAL OVERVIEW IN ANSI FORM**



# **APPROVALS**





certified regarding UL508 (Industrial Controls)



certified regarding CSA-C22.2 No. 14 (Industrial Controls)

Type tested according to IEC60255-1

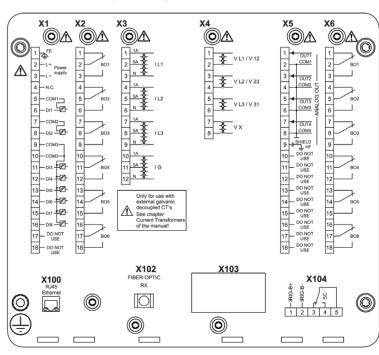


certified by EAC (Eurasian Conformity)



Complies with IEEE 1547-2003 Amended by IEEE 1547a-2014 Complies with ANSI C37.90-2005

# **CONNECTIONS** (EXAMPLE)



Complies with "Engineering Recommendation G59 Issue 3 Amendment 4 - July 2018"

#### **ORDER FORM MRMV4**

Motor Protection MRMV4										
Version 2 v	with USB, enhance	ed communication	and user opt	ions						
Digital Inputs	Binary output relays	Analog Inputs/ Outputs	Housing	Large display						
8	7	0/4	B2	-			Α			
8	13	0/4	B2	-			C			
Hardware	variant 2									
Phase Curr	rent 5 A/1 A, Grou	ind Current 5 A/1 A	4					0		
		tive Ground Curren	it 5 A/1 A					1		
	and mounting									
Door mour	•								4	
	nting 19" (flush m	ounting)							3	
	ication protocol									
Without pr									Α	
		)3, DNP 3.0 RTU   <i>RS</i>							B*	
		DP, IEC 60870-5-104	Ethernet 10	0 MB/RJ45					C,	
	P   optic fiber/ST-co	onnector							D,	
	P   RS485/D-SUB								E*	
		)3, DNP 3.0 RTU   <i>op</i>		nnector					F*	
		3, DNP 3.0 RTU   <i>RS</i>		F.1	0./0.1.15				G,	
		3.0 TCP/UDP, IEC 60			B/RJ45				H³	,
		TU, DNP 3.0 RTU   <i>R</i> S DP, IEC 60870-5-10-							*	
		3.0 TCP/UDP, IEC 60			et 100MR/I	- dun	lev co	nnecti	or K*	×-
		DP, IEC 60870-5-104						micen	)/ IX  *	
		U, DNP 3.0 RTU   <i>R</i> S	1 '		с аирісх соі	IIICCI	.01		_	
		3.0 TCP/UDP, IEC 6			1B/RJ45				T*	ŀ
	vironment Optio		- 1			-				
	•									
None										

<sup>\*</sup> Within every communication option only one communication protocol is usable. Smart view can be used in parallel via the Ethernet interface (RJ45).

The parameterizing- and disturbance analyzing software Smart view is included in the delivery of HighPROTEC devices.

Current inputs4 (1 A and 5 A) with automatic CT DisconnectVoltage inputs4 (0-800 V)Digital InputsSwitching thresholds adjustable via softwarePower supplyWide range power supply $24 V_{DC} - 270 V_{DC} / 48 V_{AC} - 230 V_{AC} (-20/+10\%)$ 

Terminals All terminals plug type

Type of enclosure IP54

 $(W \times H \times D)$ 

**Dimensions of housing** 19" flush mounting: 212.7 mm × 173 mm × 208 mm

8.374 in. × 6.811 in. × 8.189 in.

Door mounting 212.7 mm  $\times$  183 mm  $\times$  208 mm

8.374 in. × 7.205 in. × 8.189 in.

Weight (max. components) approx. 4.2 kg / 9.259 lb

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