

## **PROTECTION MADE SIMPLE.**

# High **PRO**TEG

# MRMV4 MOTOR PROTECTION DEVICE FOR ASYNCHRONOUS MOTORS

The MRMV4 is a protection relay which uses the latest Dual-Core-Processor Technology to provide precise and reliable protective functions. Also it is very easy to operate.

The MRMV4 provides all necessary functions to protect low and medium voltage motors at all power levels. The protection functions are based on current and voltage measurement and supervise all

thermal conditions, motor start sequence, stall and locked rotor, undercurrent and incomplete sequence. Overcurrent functions and earth fault functions are also available as power protection, frequency and voltage elements. The motor operation can be monitored by statistic and trend recorders.

The protection functions of the MRM4 have been adapted to comply with the requirements of the VDE-AR-N-4110:2018.

## Application

 Low and high voltage asynchronous motors. Protection based on current and voltage measurement

#### **Motor Protection**

- Thermal overload protection 49M
- Locked rotor protection 51LRS
- ► JAM or Stall protection 51LR
- Underload protection 37
- ▶ Motor start 48
- Starts per Hour 66
- Negative phase sequence (current unbalance) 46
- Overcurrent/short circuit prot. 50P/51P
- Earth overcurrent and short circuit protection 50N/51N
- Reclosing lockout 86
- RTD supervision via external temperature box 26 (type MRMV4-2B
- Wattmetric Ground Fault Protection

#### **Additional Protection**

- 6 Overcurrent elements (nondir)
- 4 Earth Overcurrent elements (nondir)
- 2 Elements Residual Voltage
- 4 Over-/Undervoltage elements
- ▶ 6 Frequency elements
- 6 Power protection elements
- ▶ 2 Power Factor elements
- Demand Management
- THD Protection

#### **Additional Highlights**

- 4 Analog Outputs (Type MRMV4-B)
- Long starting time for reduced voltage starts
- Emergency Start
- Incomplete sequence
- Anti-backspin time delay

- Permitted number of cold starts
- Supervision of starts per hour
- Mechanical load shedding
- Zero speed indication via input
- Motor stop inputs
- External alarm and trip inputs

#### **Motor Start Recorder**

- Max. RMS values of phase currents
- Negative phase sequence currents
- Start duration, Successful starts
- Used thermal capacity
- Temperature profile (optional)

#### **Statistic Recorder**

- Number of successful starts
- Average I2T values
- Average max. start current

#### **Supervision Functions**

- Breaker Failure, Trip Circuit Superv.
- Loss of Potential, Switch onto Fault

#### Recorders

- Disturbance recorder: 120 s non volatile
- Fault recorder: 20 faults
- Event recorder: 300 events
- Trend recorder: 4000 non volatile entries

#### **PC Tools**

- Setting and analyzing software Smart view for free
- Including page editor to design own Control pages
- SCADApter to re-assign datapoints for Retrofit projects: Modbus, Profibus, IEC 60870-5-103/ -104



#### New Features - Release 3.7

- Improved frequency and ROCOF precision
- Improved design of the PC tools
- Configurable SCADA protocols: Modbus, Profibus, IEC 60870-5-103/-104, DNP3

All HighPROTEC devices have been type tested and fully certified by KEMA Laboratories (IEC 60255-1:2009).

#### Control

1 breaker, Breaker wear

#### **Commissioning Support**

- Customizable Display (Single-Line)
- Customizable Inserts
- Copy and compare parameter sets
- Configuration files are convertible
- Forcing and disarming of output relays
  - Integrated fault simulator
  - Graphical display of tripping characteristics
  - 8 languages selectable within the relay

#### **Communication Options**

- ▶ IEC 61850
- Profibus DP
- Modbus RTU and/or Modbus TCP
- ► IEC 60870-5-103
- ► IEC 60870-5-104
- ► DNP 3.0 (RTU, TCP, UDP)
- SCADApter

#### **Cyber Security**

- Menu for the activation of security settings (e.g. hardening of interfaces)
- Security Logger
- Centralized Security Logs (Syslog)
- Encrypted Connection Smart view Device
- Device specific certificates (No man in the middle attacks)

#### Logic

 Up to 80 logic equations for protection, control and monitoring

**Time Synchronisation** 

IEC 60870-5-103/-104

SNTP, IRIG-BOOX, Modbus, DNP 3.0,

# High **Pro**tec

# MRMV4 MOTOR PROTECTION DEVICE FOR ASYNCHRONOUS MOTORS

# **Functional Overview**

Protective Functions		ANSI	IEC 61850
IB, thermal overload protection		49M	PTTR
I, time overcurrent and short circuit protection (non direction)	6	50P, 51P	PTOC
(instantaneous, definite time, characteristicsaccording to IEC60255, ANSI			
Voltage controlled overcurrent protection by means of adaptive parameters.		51C	
Voltage dependent overcurrent protection		51V	
Negative phase sequence overcurrent protection		51Q	
I2, unbalanced load protection with evaluation of the negative phase sequence current	2	46	PTOC
IG, earth time overcurrent and short circuit protection (non direction)	4	50N/G, 51N/G	PTOC
(instantaneous, definite time, characteristics according to IEC60255, ANSI			
I< underload protection	2	37	PTUC
Reclosing lockout		49R	PTTR
Incomplete sequence			
JAM protection	2	51LR	PIOC
Locked rotor Protection		51LRS	
Motor start		48	PMRI, PMSS
Starts per Hour		66	
Start control input			
Reversing mode			
Emergency start			
V<, V>, V(t)<, under- and overvoltage protection,	6	27 59	PTOV PTUV
time dependent undervoltage protection	0	27, 55	1100,1100
Voltage asymmetry supervision (V012)			
V1, under and overvoltage in positive phase sequence system	6	47	PTOV, PTUV
V2, overvoltage in negative phase sequence system			
Each of the six frequency protection elements can be used as:	6		PTOF, PTUF,
f< or f> (over- or under frequency supervision)		81U/O	PFRC, PPAM
df/dt rate of change of frequency (ROCOF)		81R	
(f< and df/dt) or (f> and df/dt) combination of over-, under- and ROCOF			
▶ (f< and DF/DT) or (f> and DF/DT) combination of over-, under- and increase of frequency			
Delta Phi (Vector surge)		78	
VX, residual voltage protection	2	59N	PTOV, PTUV
PQS, Power protection	6	32, 37	PDOP, PDUP
PF, Power factor	2	55	PUPF
Control and Logic			
Control: Position indication, supervision time management and interlockings a breaker			CILO, CSWI,
			XCBR, XSWI
Logic: Up to 80 logic equations, with 4 inputs, selectable logical gates,			
timers and memory function			
Supervision Functions			
CBF, circuit breaker failure protection	1	50BF/62BF	RBRF
TCS, trip circuit supervision	1	74TC	SCBR
LOP, loss of potential	1	60FL	
CTS, current transformer supervision	1	60L	
SOTF, switch onto fault	1		PSOF
Demand management and peak value supervision (current and power)			
THD supervision			
Breaker wear with programmable wear curves			
Recorders: Disturbance, fault, event, trend, start and statistic recorders			RDRE

## Functional Overview in ANSI / IEEE C37.2 Form





19 " Variants Available!

### **Terminals Available Separately!**



Order codes HPTTERMKIT-1 ... -5 For MRMV4: HPTTERMKIT-3 The terminal kits allow for making all required wirings in advance, thus speeding up the installation and commissioning work.

# **Connections (Example)**

X2 X6 Х3 X4 Χ5 X1 (O)(O) $(\bigcirc)$ <u>1</u>⊉<sup>™</sup> 1 1 1 OUT V L1 V 12 2 - L+ 2 2 2 COM1 2 B01 воз L+ Power Δ I 3 3 3 3 3 3 OUT2 V L2 V 23 COM2 4 N.C. 4 4 4 4 4 50 \_\_\_\_\_\_ 5A 5 ◄ 5 -5 5 5 5 OUT3 OUT3 BO2 BO2 OUT3 V L3 V 31 \_\_\_\_\_ 6 6 6 6 Т 6 7 \_ сом2\_ 7 7 7 7 • OUT4 vх 8 <u>COM4</u> \_ DI2 \_ \_ 5A 8 8 8 BO3 8 BO3 9 SHIELD 9 SHIELD HF 10 USE 11 DO NOT 11 USE сомз\_ 9 Ν 9 Т 9 9 10 \_сомз\_ 10 14 10 10 11 . BO4 11 11 BO4 I G 12 USE 12 USE 13 USE 14 USE 12 N \_ DI4 - 🖉 -12-1 12 12 - DI5 - 🔁-13-13 13 Only for use with external galvanic decoupled CT's. See chapter Current Transform of the manual! 14 DIG 🖅 14 14 BOS BO5 15 DO NOT 15-017-15 15 \_ DI8 <u>L</u>@-16 DO NOT 16 16 16 17 DO NOT USE 18 DO NOT USE DO NOT 17 17 BO6 17 BO6 Т 18-DO NOT 18 18 X102 X103 FIBER-OPTIC X104 X100 RX RIGB Ethernel R IGB SC  $(\bigcirc)$  $( \bigcirc )$ 1  $\bigcirc$  $( \bigcirc )$ Г 

# Approvals / Standards



**KEMA** Labs

CE

certified regarding UL508 (Industrial Controls)

certified regarding CSA-C22.2 No. 14 (Industrial Controls)

certified by EAC (Eurasian Conformity)

Type tested and certified by KEMA Laboratories in accordance with the complete type test requirements of IEC 60255-1:2009.

Fulfills the requirements of the German grid code standard VDE-AR-N 4110 (2018-11)

Complies with IEEE 1547-2003.

Amended by IEEE 1547a-2014.

Complies with ANSI C37.90-2005.

## **PROTECTION MADE SIMPLE.**

## Order Form MRMV4

Motor	Protection				MRMV4	-2				
Version 2	2 with USB, enhar	nced communicat	ion and use	r options						
Digital Inputs	Binary output relays	Analog Inputs/ Outputs	Housing	Large display						
8	7	0/4	B2	_			A			
8	13	0/4	B2	_			С			
Hardware	e variant 2									
Phase Cu	rrent 5 A/1 A, Gr	ound Current 5 A,	/1 A				0			
Phase Cu	rrent 5 A/1 A, Se	nsitive Ground Cu	urrent 5 A/1	A			1			
Housing	and mounting									
Housing	suitable for door	mounting						А		
Housing	suitable for 19" ra	ack mounting						В		
Communi	cation protocol									
Without	protocol								A*	
Modbus RTU, IEC 60870-5-103, DNP 3.0 RTU   RS485/terminals						В*				
Modbus TCP, DNP 3.0 TCP/UDP, IEC 60870-5-104   Ethernet 100 MB/RJ45						C*				
Profibus-DP   Optical fiber/ST-connector						D*				
Profibus-DP   RS485/D-SUB						E*				
Modbus RTU, IEC 60870-5-103, DNP 3.0 RTU   Optical fiber/ST-connector					F*					
Modbus RTU, IEC 60870-5-103, DNP 3.0 RTU   RS485/D-SUB						G*				
IEC 61850, Modbus ICP, DNP 3.0 TCP/UDP, IEC 60870-5-104   Ethernet 100MB/RJ45						H≛				
Modbus TCP, DNP 3.0 TCP/UDP, IEC 60870-5-104   Ethernet 100 MB/RI45					*					
IEC 61850	). Modbus TCP. DI	NP 3.0 TCP/UDP. IE	EC 60870-5-	104   Opt.	Eth. 100MB/	LC dı	uplex c	onn.	K*	
Modbus	CP, DNP 3.0 TCP/	UDP, IEC 60870-5	-104   Opt. E	Ethernet 10	0MB/LC dup	olex d	connec	tor	L*	
IEC 60870-5-103, Modbus RTU, DNP 3.0 RTU   RS485/terminals			Τ*							
IEC 61850	), Modbus TCP, D	NP 3.0 TCP/UDP, I	EC 60870-5	-104   Ethe	rnet 100 MB	/RJ45	5		1	J
Harsh En	vironment Option	1								
None										Α
Conform	al Coating									E
Available	menu languages	(in every device)								

English / German / Spanish / Russian / Polish / Portuguese / French / Romanian

\* Within every communication option only one communication protocol is usable.

Smart view can be used in parallel via the Ethernet interface (RJ45).

The parameterizing- and disturbance analyzing software Smart view can be used without extra costs.

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#### **Technical Documents:**

https://docs.SEGelectronics.de/mrmv4-2







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Subject to alterations, errors excepted.

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JOK-FLY-MRMV4-2E\_Rev.

Current inputs	
Voltage inputs	
Digital Inputs	
Analog outputs (Type C)	
Power supply	

Terminals Type of enclosure Dimensions of housing (W x H x D) 4 (1 A and 5 A) with automatic CT Disconnect 4 (0 ... 800 V)\* Switching thresholds adjustable via software 0 ... 20mA / 4 ... 20mA / 0 ... 10V Wide range power supply 24  $V_{DC}$  - 270  $V_{DC}$  / 48  $V_{AC}$  - 230  $V_{AC}$  (-20/+10%) All terminals plug type IP54 19" flush mounting: 212.7 mm × 173 mm × 208 mm 8.374 in. × 6.811 in. × 8.189 in. Door mounting: 212.7 mm × 183 mm × 208 mm 8.374 in. × 7.205 in. × 8.189 in. approx. 4.2 kg / 9.26 lb

\* under UL: max. 600 V

Weight (max. components)



**SEG**