WOODWARD

HighPROTEC

Manual | Motor Protection

MRM4

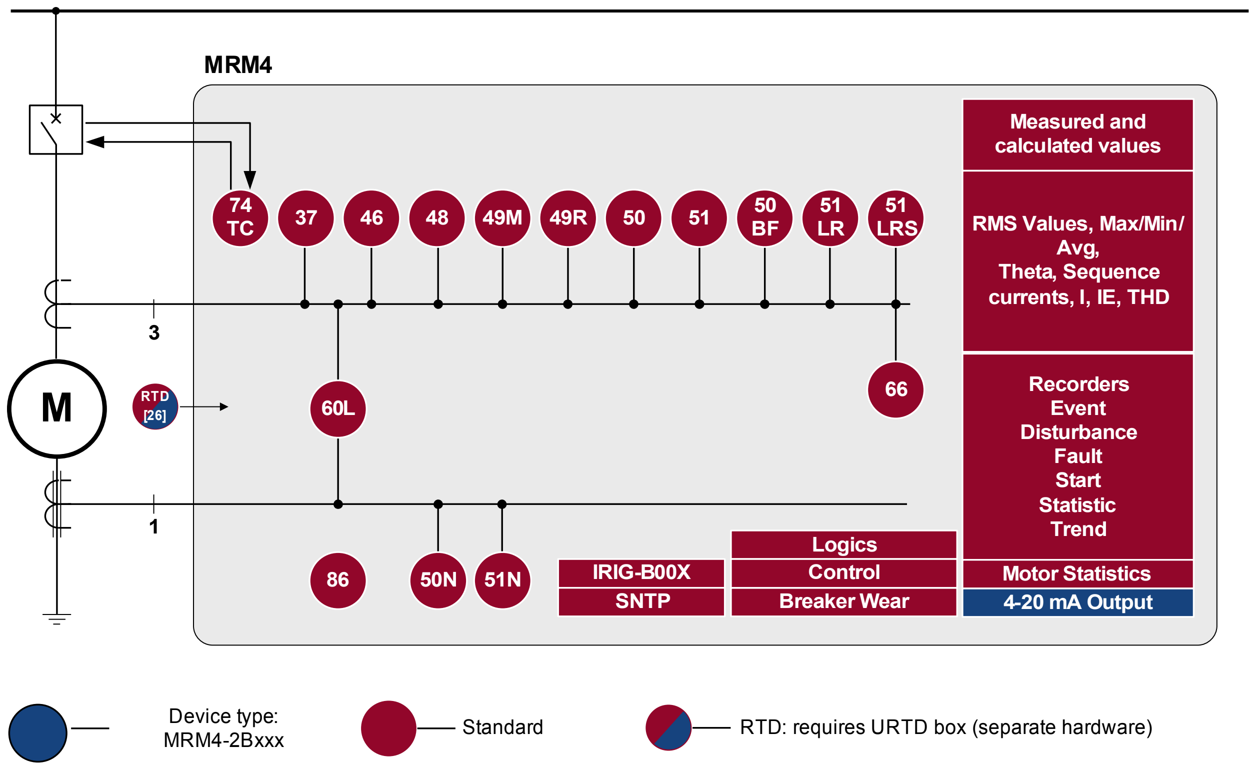
Software-Version: 3.4.a

DOK-HB-MRM4-2E

Revision: C

English

MRM4 Functional Overview



Order Code

Motor Protection (Version 2 with USB, enhanced communication options and new front plate)	MRM4	-2					
Digital Inputs / Binary output relays / Analog Inputs/Outputs / RTD box / Housing / Large display							
8 / 6 / 0/0 / - / B1 / -			A				
4 / 4 / 0/1 / ✔ / B1 / -			B				
Hardware variant 2							
Phase Current 5A/1A, Ground Current 5 A/1 A				0			
Phase Current 5A/1A, Sensitive Ground Current 5 A/1 A				1			
Housing and mounting							
Door mounting					A		
Door mounting 19” (flush mounting)					B		
Communication protocol							
Without protocol						A	
Modbus RTU, DNP3.0, IEC60870-5-103, RS485/terminals						B*	
Modbus TCP, DNP3.0, Ethernet 100 MB/RJ45						C*	
Profibus-DP, optic fibre						D*	
Profibus-DP, RS485/D-SUB						E*	
Modbus RTU, IEC60870-5-103, optic fiber						F*	
Modbus RTU, IEC60870-5-103, RS485/D-SUB						G*	
IEC61850, DNP3.0, Ethernet 100MB/ RJ45						H*	
IEC60870-5-103, Modbus RTU, DNP3.0 RTU | *RS485/terminals* Modbus TCP, DNP3.0 TCP/UDP | *Ethernet 100 MB/RJ45*						I*	
IEC61850, Modbus TCP, DNP3.0 TCP/UDP | *Optical Ethernet 100MB/LC duplex connector*						K*	
Modbus TCP, DNP3.0 TCP/UDP | *Optical Ethernet 100MB/LC duplex connector*						L*	
IEC60870-5-103, Modbus RTU, DNP3.0 RTU | RS485/terminals *IEC61850, Modbus TCP, DNP3.0 TCP/UDP | Ethernet 100 MB/RJ45*						T*	
Harsh Environment Option							
None							A
Conformal Coating							B
Available menu languages							
Standard English/German/Spanish/Russian/Polish/Portuguese/French/Romanian							

* Within every communication option only one communication protocol is usable.
Smart view can be used in parallel via the Ethernet interface (RJ45).

The parameterizing- and disturbance analyzing software Smart view is included in the delivery of HighPROTEC devices.

All devices are equipped with an IRIG-B interface for Time Synchronization.

With control function for 1 switchgear and logic up to 80 equations.

Table of Contents

This manual applies to devices (version):

Version 3.4.a

Build: 35599

Comments on the Manual

This manual explains in general the tasks of device planning, parameter setting, installation, commissioning, operation and maintenance of the HighPROTEC devices.

The manual serves as working basis for:

- Engineers in the protection field,
- commissioning engineers,
- people dealing with setting, testing and maintenance of protection and control devices,
- as well as trained personnel for electrical installations and power stations.

All functions concerning the type code will be defined. Should there be a description of any functions, parameters or inputs/outputs which do not apply to the device in use, please ignore that information.

All details and references are explained to the best of our knowledge and are based on our experience and observations.

This manual describes the (optionally) full featured versions of the devices.

All technical information and data included in this manual reflect their state at the time this document was issued. We reserve the right to carry out technical modifications in line with further development without changing this manual and without previous notice. Hence no claim can be brought based on the information and descriptions this manual includes.

Text, graphic and formulae do not always apply to the actual delivery scope. The drawings and graphics are not true to scale. We do not accept any liability for damage and operational failures caused by operating errors or disregarding the directions of this manual.

No part of this manual is allowed to be reproduced or passed on to others in any form, unless *Woodward Kempen GmbH* have approved in writing.

This user manual is part of the delivery scope when purchasing the device. In case the device is passed on (sold) to a third party, the manual has to be handed over as well.

Any repair work carried out on the device requires skilled and competent personnel who need to be well aware especially of the local safety regulations and have the necessary experience for working on electronic protection devices and power installations (provided by evidence).

Information Concerning Liability and Warranty

Woodward does not accept any liability for damage resulting from conversions or changes carried out on the device or planning (projecting) work, parameter setting or adjustment changes done by the customer.

The warranty expires after a device has been opened by others than *Woodward* specialists.

Warranty and liability conditions stated in *Woodward* General Terms and Conditions are not supplemented by the above mentioned explanations.

IMPORTANT DEFINITIONS

The signal definitions shown below serve the safety of life and limb as well as for the appropriate operating life of the device.

⚠ DANGER	DANGER indicates a hazardous situation which, if not avoided, will result in death or serious injury.
⚠ WARNING	WARNING indicates a hazardous situation which, if not avoided, could result in death or serious injury.
⚠ CAUTION	CAUTION, used with the safety alert symbol, indicates a hazardous situation which, if not avoided, could result in minor or moderate injury.
NOTICE	NOTICE is used to address practices not related to personal injury.
CAUTION	CAUTION, without the safety alert symbol, is used to address practices not related to personal injury.

WARNING

FOLLOW INSTRUCTIONS

Read this entire manual and all other publications pertaining to the work to be performed before installing, operating, or servicing this equipment. Practice all plant and safety instructions and precautions. Failure to follow instructions can cause personal injury and/or property damage.

WARNING

PROPER USE

Any unauthorized modifications to or use of this equipment outside its specified mechanical, electrical, or other operating limits may cause personal injury and/or property damage, including damage to the equipment. Any such unauthorized modifications: (1) constitute "misuse" and/or "negligence" within the meaning of the product warranty thereby excluding warranty coverage for any resulting damage, and (2) invalidate product certifications or listings.

The programmable devices subject to this manual are designed for protection and also control of power installations and operational devices that are fed by voltage sources with a fixed frequency, i.e. fixed at 50 or 60 Hertz. They are not intended for use with Variable Frequency Drives. The devices are further designed for installation in low-voltage (LV) compartments of medium voltage (MV) switchgear panels or in de-centralized protection panels. The programming and parameterization has to meet all requirements of the protection concept (of the equipment that is to be protected). You must ensure that the device will properly recognize and manage (e.g. switch off the circuit breaker) on the basis of your programming and parameterization all operational conditions (failures). The proper use requires a backup protection by an additional protective device. Before starting any operation and after any modification of the programming (parameterization) test make a documentary proof that your programming and parameterization meets the requirements of your protection concept.

The Self-Supervision Contact (Life-Contact) has to be wired with the substation automation system in order to supervise and monitor the state of health of the programmable protective device. It is very important that an alarm annunciation is driven from the programmable protective device self-supervision contact (Life-Contact) that requires immediate attention when tripped. The alarm indicates that the protective device is no longer protecting the circuit and the system should be serviced.

Typical applications for this product family/device line are for instance:

- **Feeder protection**
- **Mains protection**
- **Machine protection**
- **Transformer Differential Protection**

Any usage beyond these applications the devices are not designed for. This applies also to the use as a partly completed machinery. The manufacturer cannot be held liable for any resulting damage, the user alone bears the risk for this. As to the appropriate use of the device: The technical data and tolerances specified by *Woodward* have to be met.

WARNING

OUT-OF-DATE PUBLICATION

This publication may have been revised or updated since this copy was produced. To verify that you have the latest revision, please visit the download section of our website:

www.woodward.com

If your publication is not there, please contact your customer service representative to get the latest copy.

Important Information

WARNING

In line with the customer's requirement the devices are combined in a modular way (in compliance with the order code). The terminal assignment of the device can be found on the top of the device (wiring diagram).

CAUTION

Electrostatic Discharge Awareness

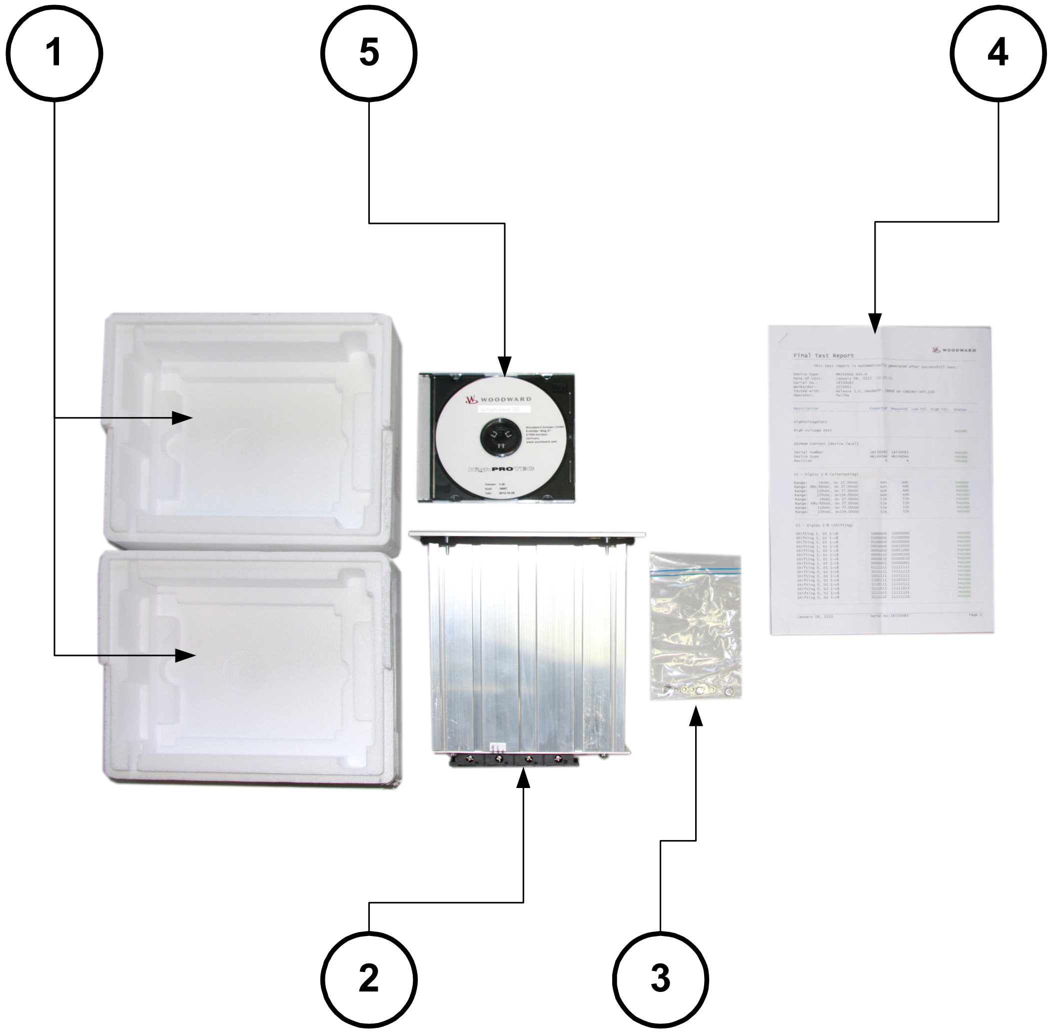
All electronic equipment is electro static-sensitive, some components more than others. To protect these components from electro static damage, you must take special precautions to minimize or eliminate electrostatic discharges.Follow these precautions when working with or near the control.

1. **Before doing maintenance on the electronic control, discharge the static electricity on your body to ground by touching and holding a grounded metal object (pipes, cabinets, equipment, etc.).**
2. **Avoid the build-up of static electricity on your body by not wearing clothing made of synthetic materials. Wear cotton or cotton-blend materials as much as possible because these do not store static electric charges as much as synthetics.**
3. **Keep plastic, vinyl, and Styrofoam materials (such as plastic or Styrofoam cups, cup holders, cigarette packages, cellophane wrappers, vinyl books or folders, plastic bottles, and plastic ash trays) away from the control, the modules, and the work area as much as possible.**
4. **Do not remove any printed circuit board (PCB) from the control cabinet unless absolutely necessary. If you must remove the PCB from the control cabinet, follow these precautions:**
   - **Verify the safe isolation from supply. All connectors have to be unplugged.**
   - **Do not touch any part of the PCB except the edges.**
   - **Do not touch the electrical conductors, the connectors, or the components with conductive devices or with your hands.**
   - **When replacing a PCB, keep the new PCB in the plastic antistatic protective bag it comes in until you are ready to install it. Immediately after removing the old PCB from the control cabinet, place it in the antistatic protective bag.**

To prevent damage to electronic components caused by improper handling, read and observe the precautions in Woodward manual 82715, Guide for Handling and Protection of Electronic Controls, Printed Circuit Boards, and Modules.

Woodward reserves the right to update any portion of this publication at any time. Information provided by Woodward is believed to be correct and reliable. However, no responsibility is assumed by Woodward unless otherwise expressly undertaken.

Scope of Delivery



The delivery scope includes:

1	The transportation box
2	The protective device
3	The mounting nuts
4	The test report
5	The product DVD that includes the manuals and related documentation as well as the parameter setting and evaluation software.

Please check the consignment for completeness on arrival (delivery note).

Please ascertain whether the type plate, connection diagram, type code and description of the device tally.

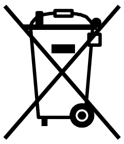
If you have any doubts please contact our Service Department (contact address to be found on the reverse of the manual).

Storage

The devices must not be stored outdoors. The storing facilities have to be sufficiently ventilated and must be dry (see Technical Data).

Waste Disposal

This protective device contains a battery, and therefore it is labeled with the following symbol according to the EU Directive 2006/66/EC:



⚠ WARNING

Batteries can be harmful to the environment. Damaged or unusable batteries must be disposed of in a container that is specially reserved for this purpose.

In general, appropriate local guidelines and regulations must be followed when disposing of electrical devices and batteries.

Purpose of the Battery

The purpose of the battery is to buffer the real time clock in case of an outage of the power supply of the protective device.

Removal of the Battery

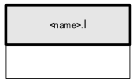
The battery has to be soldered out or alternatively the contacts have to be pinched off.
Please see the product safety data sheet of the battery manufacturer for further information.

Manufacturer and Type of the Battery

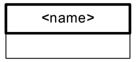
Panasonic, Type BR2032 (http://panasonic.net/ec/) or equivalent.

Symbols

Setting value:

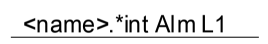


Device planning:

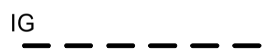


Signal:

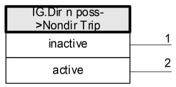
internal message



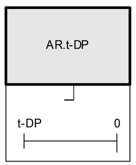
Measured Values:



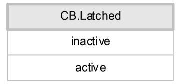
Functional description: If the setting value "IE Dir n poss-> Nondir Trip" is set to "inactive" the output 1 is active and output 2 is inactive. If the setting value "IE Dir n poss-> Nondir Trip" is set to "active" the output 2 is active and the output 1 is inactive.



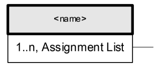
"⅃"=Elements with complex functions "gray-box".



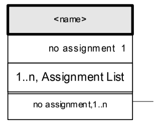
Option/features to be realised in the future



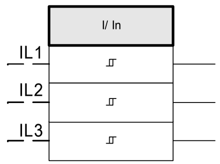
Parameter of a Module-Input with a SelectionList/DropDown. An (1..n) signal/output from the list or a pre-defined value can be selected.



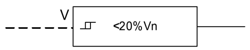
Parameter of a Module-Input (with special values): An (1..n) output from the list will be assigned to the input "<name>.identifier". If the parameter is set to "ItemNull", an "inactive"-signal will be given out.

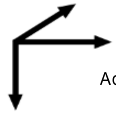


Limit value monitoring with three analogue input values. Compares 3 analogue values with the set limit; output values are three different binary values as a result of the comparision. If the analogue signal exceeds the limit I/In the corresponding output signal becomes "1".



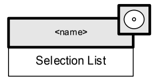
Limit value monitoring (Compared to a fixed value). Compares a value with the fixed set limit; output value is binary as a result of the comparision. If the signal exceeds the limit the corresponding output signal becomes "1".



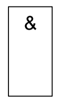


Adaptive Parameter

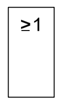
Direct Command



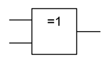
And



Or



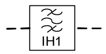
Exclusive-OR



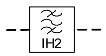
Negated input

Negated output

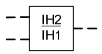
Band-pass (filter)
IH1



Band-pass (filter)
IH2



Quotient of analogue values

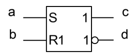


Analog values

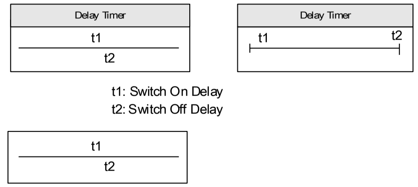
Analogue values comparator

RS flip-flop

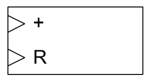
a b	c d
0 0	Unchanged
0 1	0 1
1 0	1 0
1 1	0 1



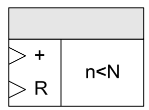
Time stage: A "1" at the input starts the stage. If the time <name>.t is expired the output becomes "1" too. The time stage will be reset by "0" at the input. Thus the output will be set to "0" at the same time.



Edge triggered counter
+ increment
R Reset

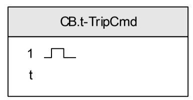


Counter increments with every rising edge. Output will be set as long as n<N.



+ increment
R Reset

Time stage minimum pulse width: The pulse width <name>.t will be started if a "1" is feed to the input. By starting <name>.t the output becomes "1". If the time is expired, the output becomes "0" independent from the input signal.



General Conventions

»Parameters are indicated by right and left double arrow heads and written in italic .«

»SIGNALS are indicated by right and left double arrow heads and small caps .«

[Paths are indicated by brackets.]

Software and Device names are written in italic.

<u>*Module and Instance (Element) names are displayed italic and underlined.*</u>

»Pushbuttons, Modes and Menu entries are indicated by right and left double arrow heads .«

1	**2**	**3**	Image References (Squares)

Output Signal ——— 2

2 ——— Input Signal

Output Signal	*Description / Diagram*	——— 2 (Symbol)
Prot.available	*Please Refer To Diagram: Prot*	——— (1)
Prot.available (as a signal sent via ProtCom to the remote protective device)	*Please Refer To Diagram: Prot* *only for line differential protection*	——— (1R)
name . active	*Please Refer To Diagram: Blockings*	——— (2)
name . Blo TripCmd	*Please Refer To Diagram: Trip blockings*	——— (3)
name . active	*Please Refer To Diagram: Blockings* *(Phase Overcurrent Stages I[1] … [n])*	——— (4)
name . active	*Please Refer To Diagram: Blockings* *(Earth Overcurrent Stages IG[1] … [n])*	——— (4G)
name . active (as local signal)	*Please Refer To Diagram: Blockings* *only for line differential protection*	——— (4L)
name . active (as a signal sent via ProtCom to the remote protective device)	*Please Refer To Diagram: Blockings* *only for line differential protection*	——— (4R)
IH2 . Blo L1	*Please Refer To Diagram: IH2*	——— (5)
IH2 . Blo L2	*Please Refer To Diagram: IH2*	——— (6)
IH2 . Blo L3	*Please Refer To Diagram: IH2*	——— (7)
IH2 . Blo IG	*Please Refer To Diagram: IH2*	——— (8)
name . Fault in projected direction	*Please Refer To Diagram: direction decision phase overcurrent*	——— (9)
name . Fault in projected direction	*Please Refer To Diagram: direction decision Earth fault*	——— (10)
CB . Trip CB	*Please Refer To Diagram: CB*	——— (11)
VTS . Alarm	*Please Refer To Diagram: VTS*	——— (12a)
VTS . Ex FF VT-I	*Please Refer To Diagram: VTS*	——— (12b)
VTS . Ex FF EVT-I	*Please Refer To Diagram: VTS*	——— (12c)
name . Alarm	*Each alarm of a module (except from supervision modules but including CBF) will lead to a general alarm (collective alarm).*	——— (14)
name . Trip	*Each trip of an active, trip authorized protection module will lead to a general trip.*	——— (15)
name . TripCmd		——— (15a)

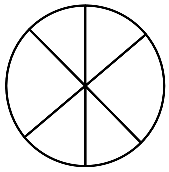
Output Signal	*Description / Diagram*	② (Symbol)
name . Trip L1	*Each trip of an active, trip authorized protection module will lead to a general trip.*	(16) (16a) (16b)
name . Trip L2	*Each trip of an active, trip authorized protection module will lead to a general trip.*	(17) (17a) (17b)
name . Trip L3	*Each trip of an active, trip authorized protection module will lead to a general trip.*	(18) (18a) (18b)
name . TripCmd	*Each trip of an active, trip authorized protection module will lead to a general trip.*	(19) (19a) (19b) (19c)
name . TripCmd	*Each trip of an active, trip authorized protection module will lead to a general trip.*	(19d)
name . Trip L1	*Each trip of an active, trip authorized protection module will lead to a general trip.*	(20)
name . Trip L2	*Each trip of an active, trip authorized protection module will lead to a general trip.*	(21)
name . Trip L3	*Each trip of an active, trip authorized protection module will lead to a general trip.*	(22)
name . Trip	*Each trip of an active, trip authorized protection module will lead to a general trip.*	(23)
name . Alarm L1	*Each phase selective alarm of a module (I, IG, V, VX depending on the device type) will lead to a phase selective general alarm (collective alarm).*	(24) (24a) (24b)
name . Alarm L2	*Each phase selective alarm of a module (I, IG, V, VX depending on the device type) will lead to a phase selective general alarm (collective alarm).*	(25) (25a) (25b)
name . Alarm L3	*Each phase selective alarm of a module (I, IG, V, VX depending on the device type) will lead to a phase selective general alarm (collective alarm).*	(26) (26a) (26b)

Output Signal	*Description / Diagram*	——② (Symbol)
name . Alarm	*Each phase selective alarm of a module (I, IG, V, VX depending on the device type) will lead to a phase selective general alarm (collective alarm).*	——(27) ——(27a) ——(27b) ——(27c) ——(27d)
name . Alarm L1	*Each phase selective alarm of a module (I, IG, V, VX depending on the device type) will lead to a phase selective general alarm (collective alarm).*	——(28)
name . Alarm L2	*Each phase selective alarm of a module (I, IG, V, VX depending on the device type) will lead to a phase selective general alarm (collective alarm).*	——(29)
name . Alarm L3	*Each phase selective alarm of a module (I, IG, V, VX depending on the device type) will lead to a phase selective general alarm (collective alarm).*	——(30)
name . Alarm	*Each phase selective alarm of a module (I, IG, V, VX depending on the device type) will lead to a phase selective general alarm (collective alarm).*	——(31)
Prot . Blo TripCmd		——(32)
CB . Pos	*Please Refer To Diagram: CB.CB Manager*	——(33)
CB . Pos ON	*Please Refer To Diagram: CB.CB Manager*	——(34)
CB . Pos OFF	*Please Refer To Diagram: CB.CB Manager*	——(35)
CB . Pos Indeterm	*Please Refer To Diagram: CB.CB Manager*	——(36)
CB . Pos Disturb	*Please Refer To Diagram: CB.CB Manager*	——(37)
LOP . LOP Blo	*Please Refer To Diagram: LOP.LOP Blo*	——(38a)
LOP . Ex FF VT-I	*Please Refer To Diagram: LOP.Ex FF VT*	——(38b)
LOP . Ex FF EVT-I	*Please Refer To Diagram: LOP.Ex FF EVT*	——(38c)
Q->&V< . Decoupling Distributed Generator	*Please Refer To Diagram: Q->&V<: “QU_Y02”*	——(39)
CTS . Alarm	*Please Refer To Diagram: CTS.Alarm*	——(40)
SG.Prot ON	*Please Refer To Diagram: SG.Prot ON*	——(41)
SG . ON Cmd	*Please Refer To Diagram: SG.ON Cmd*	——(42)
AnIn[1] . Value	*Please Refer To Diagram: Analog values*	——(43)
AnIn[2] . Value	*Please Refer To Diagram: Analog values*	——(44)
AnIn[n] . Value	*Please Refer To Diagram: Analog values*	——(45)
Trip Incomplete (Motor) Start Sequence		——(46)
Q->&V< . active	*Please refer to diagram: Blocking (Q->&V<)*	——(47)

Access Level

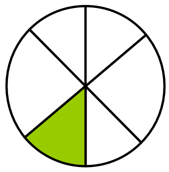
(Please refer to chapter [Parameter\Access Level])

Read Only-Lv0



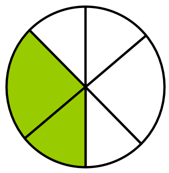
Parameters can only be read within this level.

Prot-Lv1



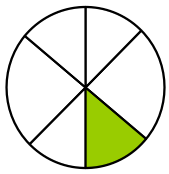
This level enables execution of Resets and Acknowledgements

Prot-Lv2



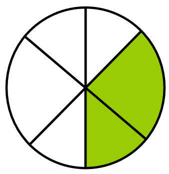
This level enables modification of protection settings

Control-Lv1



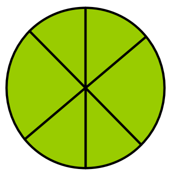
This level enables control functions

Control-Lv2



This level enables modification of switchgear settings

Supervisor-Lv3



This level provides full access (not limited) to all settings

Load Reference Arrow System

Within the HighPROTEC the “Load Reference Arrow System” is used in principal. Generator protection relays are working based on the “Generator Reference System”.

Device

MRM4

Device Planning

Planning of a device means to reduce the functional range to a degree that suits the protection task to be fulfilled, i.e. the device shows only those functions you really need. If you, for example, deactivate the voltage protection function, all parameter branches related to this function do not appear in the parameter tree any more. All corresponding events, signals etc. will be deactivated too. By this the parameter trees become very transparent. Planning also involves adjustment of all basic system data (frequency etc.).

WARNING

But it has to be taken into account that by deactivating, for instance, protective functions, you also change the functionality of the device. If you cancel the directional feature of the overcurrent protections then the device no longer trips in a directional way but merely in a non-directional way.

The manufacturer does not accept liability for any personal or material damage as a result of wrong planning.

A planning service is also offered by *Woodward Kempen GmbH*.

WARNING

Beware of inadvertent deactivating protective functions/modules

If you are deactivating modules within the device planning all parameters of those modules will be set on default.
If you are activating one of these modules again all parameters of those reactivated modules will be set on default.

Device Configuration Parameters of the Device

Parameter	*Description*	*Options*	*Default*	*Menu path*
Hardware Variant 1	Optional Hardware Extension	»A« 8 digital inputs | 6 binary output relays | IRIG-B, »B« 4 DI, 2 NO, 2 Changeover, 1 AnOut, IRIG, URTD	8 digital inputs | 6 binary output relays | IRIG-B	[MRM4]
Hardware Variant 2	Optional Hardware Extension	»0« Phase Current 5A/1A, Ground Current 5A/1A, »1« Phase Current 5A/1A, Sensitive Ground Current 5A/1A	Phase Current 5A/1A, Ground Current 5A/1A	[MRM4]
Housing	Mounting form	»A« Flush mounting, »B« 19 inch mounting (semi-flush), »H« Customized Version 1, »K« Customized Version 2	Flush mounting	[MRM4]

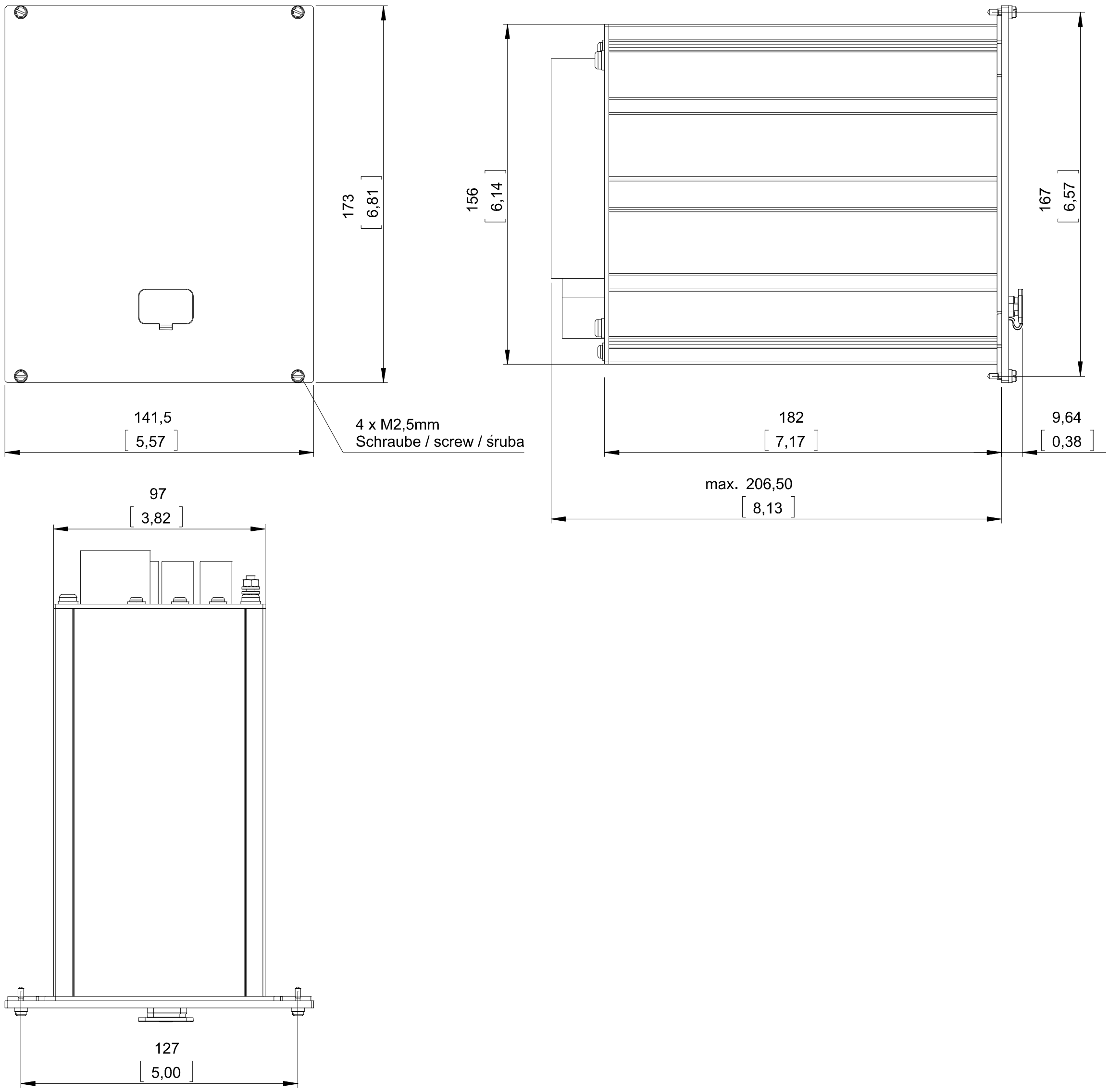
Parameter	*Description*	*Options*	*Default*	*Menu path*
Communication	Communication	»A« Without, »B« RS 485: Modbus RTU | IEC 60870-5-103 | DNP RTU, »C« Ethernet: Modbus TCP | DNP UDP, TCP, »D« Fiber Optics: Profibus-DP, »E« D-SUB: Profibus-DP, »F« Fiber Optics: Modbus RTU | IEC 60870-5-103 | DNP RTU, »G« RS 485/D-SUB: Modbus RTU | IEC 60870-5-103 | DNP RTU, »H« Ethernet: IEC61850 | Modbus TCP | DNP UDP, TCP, »I« RS 485, Ethernet: Modbus TCP, RTU | IEC 60870-5-103 | DNP UDP, TCP, RTU, »K« Ethernet/Fiber Optics: IEC61850 | Modbus TCP | DNP UDP, TCP, »L« Ethernet/Fiber Optics: Modbus TCP | DNP UDP, TCP, »T« RS 485, Ethernet: IEC61850 | Modbus TCP, RTU | IEC 60870-5-103 | DNP UDP, TCP, RTU	»A« Without	[MRM4]
Printed Circuit Board	Printed Circuit Board	»A« Standard, »B« conformal coating	»A« Standard	[MRM4]

Installation and Connection

Three-Side-View - 19”

NOTICE **Dependent on the connection method of the SCADA system used the needed space (depth) differs. If, for instance, a D-Sub-Plug is used, it has to be added to the depth dimension.**

NOTICE **The three-side-view shown in this section is exclusively valid for 19” devices.**



3-Side-View B1 Housing (19” Devices). (All dimensions in mm, except dimensions in brackets [inch].)

WARNING

The housing must be carefully grounded. Connect a ground cable (protective earth, 4 to 6 mm^2 [AWG 11–9], tightening torque 1.7 Nm [15 lb·in]) to the housing, using the screw that is marked with the ground symbol (at the rear side of the device).

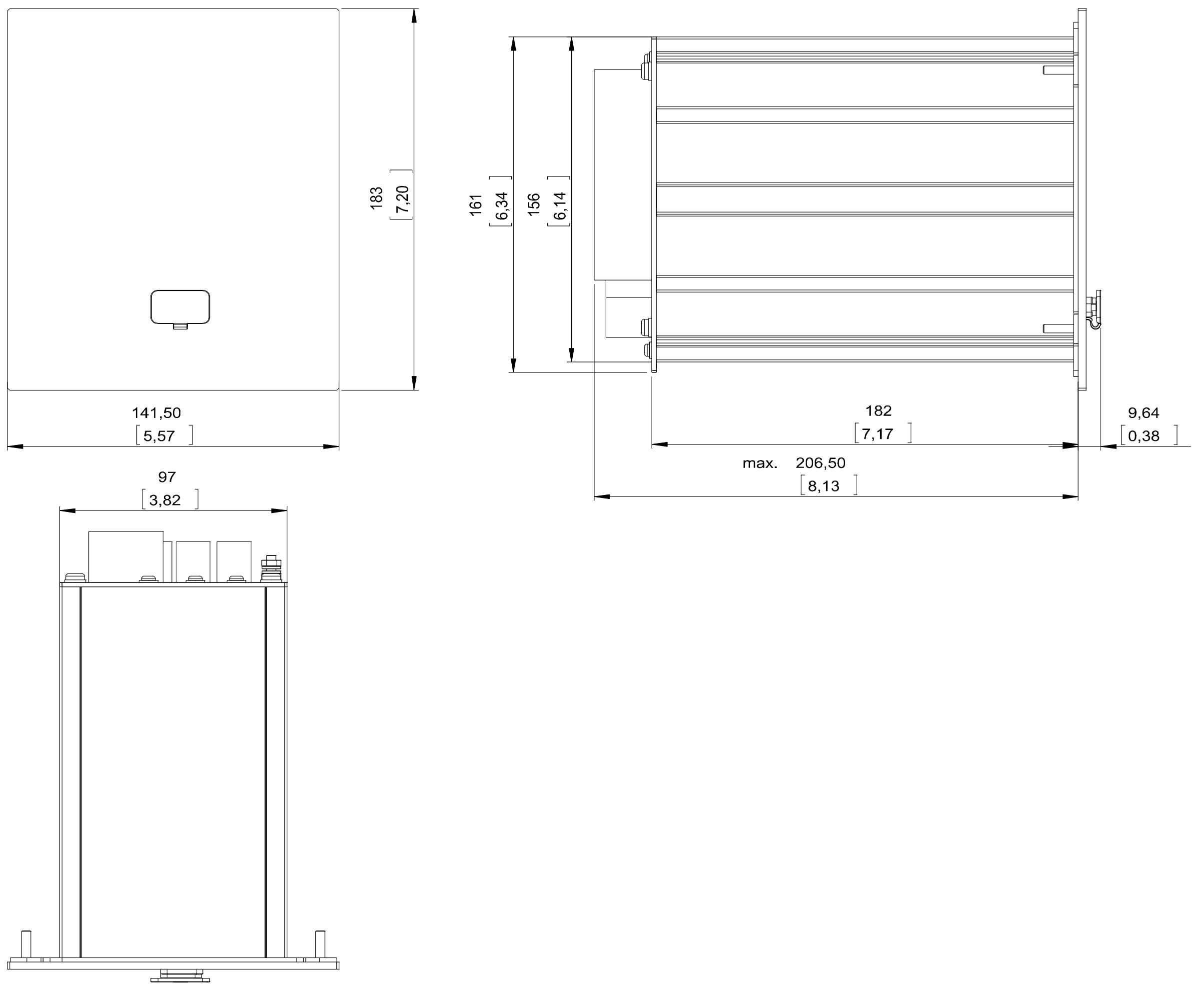
Moreover, the power supply card needs a separate ground connection (functional earth, min. 2.5 mm^2 [≤ AWG 13], tightening torque 0,56 – 0,79 Nm [5–7 lb·in]). See the “Terminal Marking” diagram in Section “DI-4 X – Power Supply and Digital Inputs” to check for the correct terminal.

All grounding connections (i. e. protective and functional earth) must be low-inductance, i. e. as short as possible, and national standards – if applicable – must be followed.

Three-Side-View - 8-Pushbutton Version

NOTICE Dependent on the connection method of the SCADA system used the needed space (depth) differs. If, for instance, a D-Sub-Plug is used, it has to be added to the depth dimension.

NOTICE The installation diagram shown in this section is exclusively valid for devices with 8 pushbuttons at the front side of the HMI.
(INFO-, C-, OK-, CTRL-Pushbutton and 4 Softkeys (Pushbuttons)).



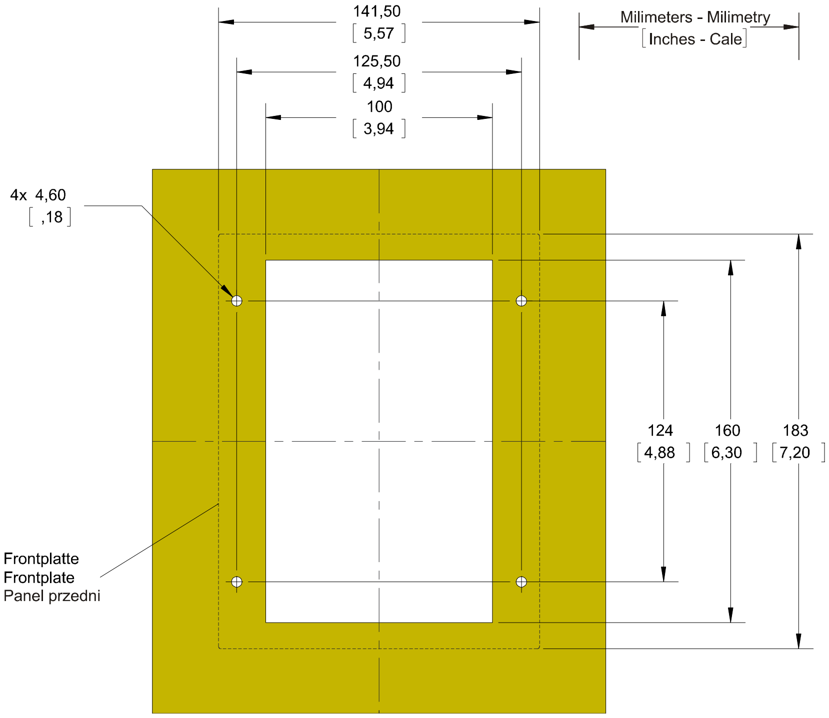
3-Side-View B1 Housing (Devices with 8 Softkeys). (All dimensions in mm, except dimensions in brackets [inch].)

WARNING The housing must be carefully grounded. Connect a ground cable (protective earth, 4 to 6 mm^2 [AWG 11–9], tightening torque 1.7 Nm [15 lb·in]) to the housing, using the screw that is marked with the ground symbol (at the rear side of the device). Moreover, the power supply card needs a separate ground connection (functional earth, min. 2.5 mm^2 [≤ AWG 13], tightening torque 0,56 – 0,79 Nm [5–7 lb·in]). See the “Terminal Marking” diagram in Section “DI-4 X” to check for the correct terminal.
All grounding connections (i. e. protective and functional earth) must be low-inductance, i. e. as short as possible, and national standards – if applicable – must be followed.

Installation Diagram 8-Pushbutton Version

WARNING Even when the auxiliary voltage is switched-off, unsafe voltages might remain at the device connections.

NOTICE The installation diagram shown in this section is exclusively valid for devices with 8 pushbuttons at the front side of the HMI.
(INFO-, C-, OK-, CTRL-Pushbutton and 4 Softkeys (Pushbuttons)).



B1 Housing Door Cut-out (8-Pushbutton Version). (All dimensions in mm, except dimensions in brackets [inch].)

WARNING **The housing must be carefully grounded. Connect a ground cable (protective earth, 4 to 6 mm^2 [AWG 11–9], tightening torque 1.7 Nm [15 lb·in]) to the housing, using the screw that is marked with the ground symbol (at the rear side of the device).**

Moreover, the power supply card needs a separate ground connection (functional earth, min. 2.5 mm^2 [≤ AWG 13], tightening torque 0,56 – 0,79 Nm [5–7 lb·in]). See the "Terminal Marking" diagram in Section "DI-4 X – Power Supply and Digital Inputs" to check for the correct terminal.

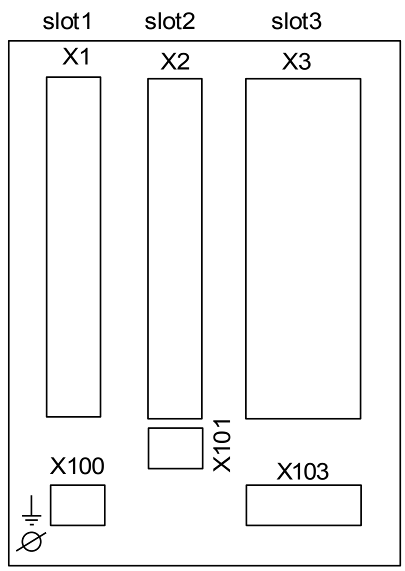
All grounding connections (i. e. protective and functional earth) must be low-inductance, i. e. as short as possible, and national standards – if applicable – must be followed.

CAUTION Be careful. Do not overtighten the mountings nuts of the relay (M4 metric 4 mm). Check the torque by means of a torque wrench (1,7 Nm [15 lb•in]). Overtightening the mounting nuts could due to personal injury or damage the relay.

Assembly Groups

WARNING **In line with the customer's requirement the devices are combined in a modular way (in compliance with the order code). In each of the slots an assembly-group may be integrated. In the following the terminal assignment of the individual assembly-groups are shown. The exact installation place of the individual modules can be learned from the connection diagram fixed at the top of your device.**

Housing B1



B1 housing – schematic diagram

Grounding

WARNING **The housing must be carefully grounded. Connect a ground cable (protective earth, 4 to 6 mm^2 [AWG 11–9], tightening torque 1.7 Nm [15 lb·in]) to the housing, using the screw that is marked with the ground symbol (at the rear side of the device).**

Moreover, the power supply card needs a separate ground connection (functional earth, min. 2.5 mm^2 [≤ AWG 13], tightening torque 0,56 – 0,79 Nm [5–7 lb·in]). See the "Terminal Marking" diagram in Section "DI-4 X – Power Supply and Digital Inputs" to check for the correct terminal.

All grounding connections (i. e. protective and functional earth) must be low-inductance, i. e. as short as possible, and national standards – if applicable – must be followed.

CAUTION The devices are very sensitive to electro-static discharges.

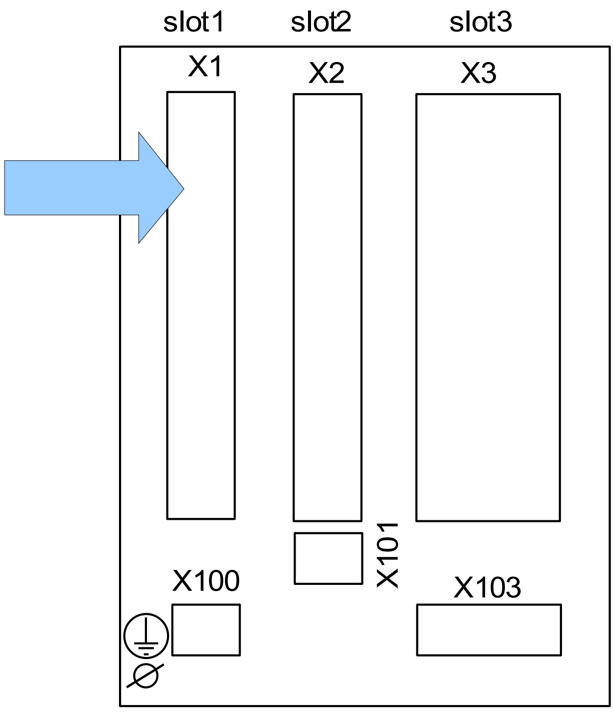
Legend for Wiring Diagrams

In this legend designations of various device types are listed, e. g. transformer protection, motor protection, generator protection, etc. Therefor it can occur that you will not find each designation on the wiring diagram of your device.

Designation	Meaning
FE	Connection of functional earth
Power Supply	Connection for auxiliary power supply
I L1	Phase current input L1
I L2	Phase current input L2
I L3	Phase current input L3
IG	Earth current input IG
I L1 W1	Phase current input L1, winding side 1
I L2 W1	Phase current input L2, winding side 1
I L3 W1	Phase current input L3, winding side 1
I G W1	Earth current input IG, winding side 1
I L1 W2	Phase current input L1, winding side 2
I L2 W2	Phase current input L2, winding side 2
I L3 W2	Phase current input L3, winding side 2
I G W2	Earth current input IG, winding side 2
V L1	Phase voltage L1
V L2	Phase voltage L2
V L3	Phase voltage L3
V 12	Phase to phase voltage V 12
V 23	Phase to phase voltage V 23
V 31	Phase to phase voltage V 31
V X	Forth voltage measuring input for measuring residual voltage or for Synchro-check
BO	Contact output, change over contact
NO	Contact output, normally open
DI	Digital input
COM	Common connection of digital inputs
Out+	Analog output + (0/4...20 mA or 0...10 V)
IN-	Analog input + (0/4...20 mA or 0...10 V)
N.C.	Not connected
DO NOT USE	Do not use
SC	Self supervision contact
GND	Ground

Designation	Meaning
HF SHIELD	Connection cable shield
Fibre Connection	Fibre optic connection
Only for use with external galvanic decoupled CTs. See chapter Current Transformers of the manual.	Only for use with external galvanic decoupled CTs. See chapter Current Transformers of the manual.
Caution Sensitive Current Inputs	Caution Sensitive Current Inputs
Connection Diagram see specification	Connection Diagram see specification

Slot X1: Power Supply Card with Digital Inputs



Rear side of the device (Slots)

The type of power supply card and the number of digital inputs on it used in this slot is dependent on the ordered device type. The different variants have a different scope of functions.

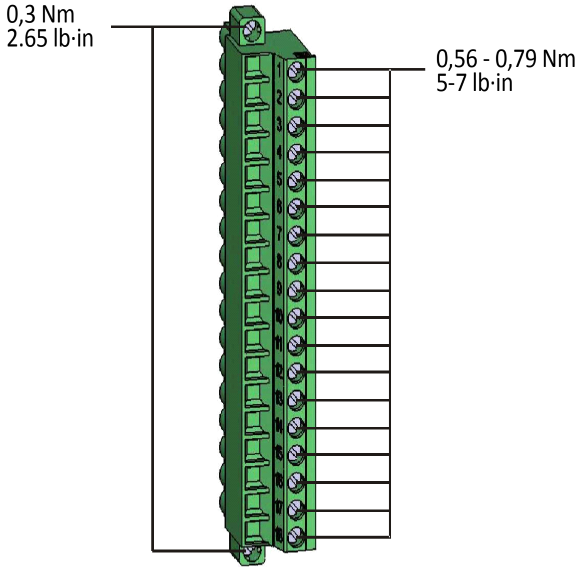
Available assembly groups in this slot:

- **(DI8-X1):** This assembly group comprises a wide-range power supply unit; and two non-grouped digital inputs and six (6) digital inputs (grouped).

NOTICE **The available combinations can be gathered from the ordering code.**

DI8-X Power Supply and Digital Inputs

WARNING **Ensure the correct tightening torques.**



This assembly group comprises:

- a wide-range power supply unit
- 6 digital inputs, grouped
- 2 digital inputs, non-grouped
- Connector for the functional earth

Functional Earth

WARNING **In addition to the grounding of the housing (protective earth, see Chapter "Installation and Wiring") there must be an additional ground cable connected to the power supply card (functional earth, min. 2.5 mm^2 [≤ AWG 13], tightening torque 0,56 – 0,79 Nm [5–7 lb·in]).**
Connect this ground cable to terminal No. 1, see the "Terminals" diagram below.
All grounding connections (i. e. protective and functional earth) must be low-inductance, i. e. as short as possible, and national standards – if applicable – must be followed.

Auxiliary voltage supply

- The aux. voltage inputs (wide-range power supply unit) are non-polarized. The device could be provided with AC or DC voltage.

Digital inputs

CAUTION **For each digital input group the related voltage input range has to be parameterized. Wrong switching thresholds can result in malfunctions/wrong signal transfer times.**

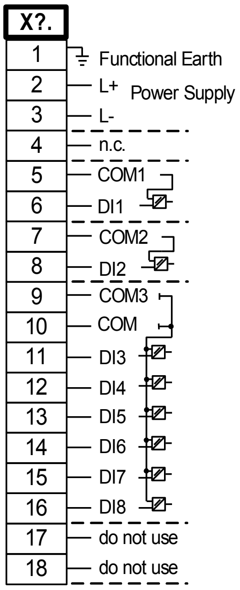
The digital inputs are provided with different switching thresholds (can be parameterized) (two AC and five DC input ranges). For the six grouped (connected to common potential) inputs and the two non-grouped inputs the following switching levels can be defined:

- 24V DC
- 48V DC / 60V DC
- 110 V AC/DC
- 230 V AC/DC

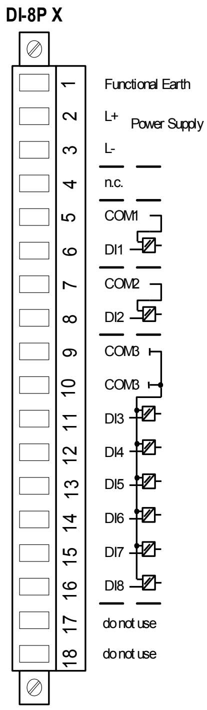
If a voltage >80% of the set switching threshold is applied at the digital input, the state change is recognized (physically "1"). If the voltage is below 40% of the set switching threshold, the device detects physically "0".

CAUTION **When using DC supply, the negative potential has to be connected to the common terminal (COM1, COM2, COM3 - please see the terminal marking).**

Terminals

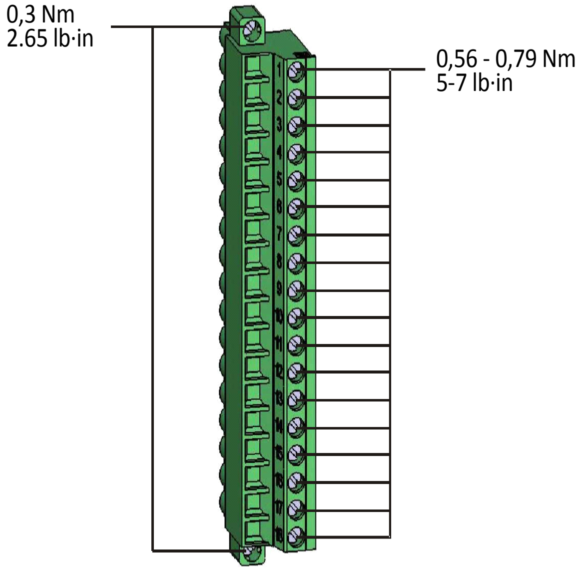


Electro-mechanical assignment



DI-4 X - Power Supply and Digital Inputs

WARNING **Ensure the correct tightening torques.**



This assembly group comprises:

- a wide-range power supply unit
- 4 digital inputs, grouped
- Connector for the functional earth

Functional Earth

WARNING **In addition to the grounding of the housing (protective earth, see Chapter "Installation and Wiring") there must be an additional ground cable connected to the power supply card (functional earth, min. 2.5 mm^2 [≤ AWG 13], tightening torque 0,56 – 0,79 Nm [5–7 lb·in]).**
Connect this ground cable to terminal No. 1, see the "Terminals" diagram below.
All grounding connections (i. e. protective and functional earth) must be low-inductance, i. e. as short as possible, and national standards – if applicable – must be followed.

Auxiliary voltage supply

- The aux. voltage inputs (wide-range power supply unit) are non-polarized. The device could be provided with AC or DC voltage.

Digital inputs

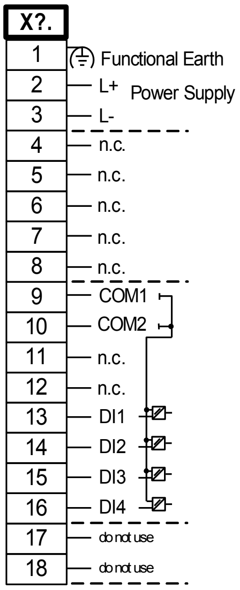
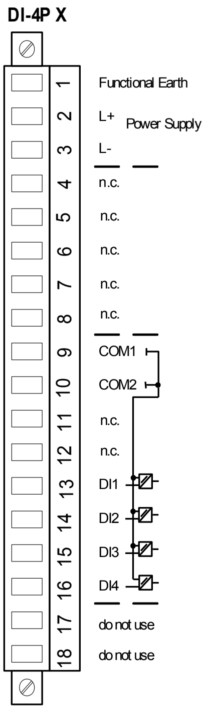
CAUTION **For each digital input group the related voltage input range has to be parameterized. Wrong switching thresholds can result in malfunctions/wrong signal transfer times.**

The digital inputs are provided with different switching thresholds (can be parameterized) (two AC and five DC input ranges). For the six grouped (connected to common potential) inputs and the two non-grouped inputs the following switching levels can be defined:

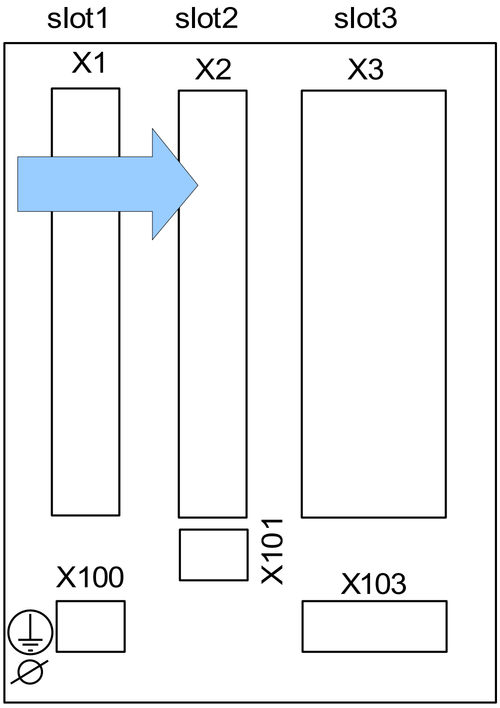
- 24V DC
- 48V DC / 60V DC
- 110 V AC/DC
- 230 V AC/DC

If a voltage >80% of the set switching threshold is applied at the digital input, the state change is recognized (physically "1"). If the voltage is below 40% of the set switching threshold, the device detects physically "0".

CAUTION **When using DC supply, the negative potential has to be connected to the common terminal (COM1, COM2, COM3 - please see the terminal marking).**

Terminals

Electro-mechanical assignment


Slot X2: Relay Output Card



Rear side of the device (Slots)

The type of card in this slot is dependent on the ordered device type. The different variants have a different scope of functions.

Available assembly groups in this slot:

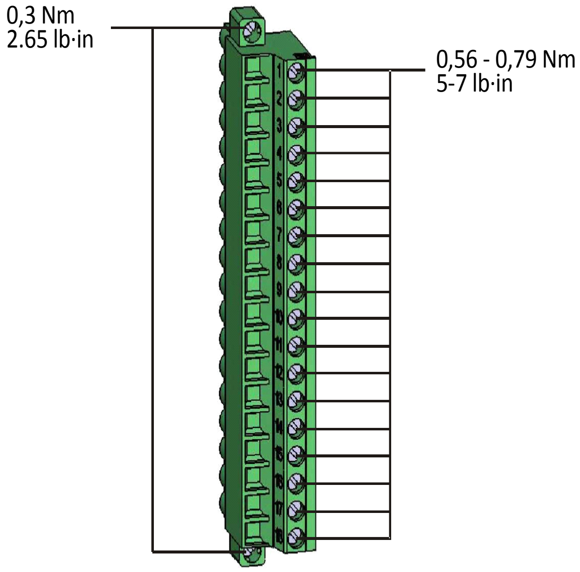
- **(OR-5 X2):** Assembly Group with 5 Changeover (CO), Supervision Contact (SC)
- **(OR-3AI X2):** Assembly Group with 2 Normally Open (Form A), 1 Changeover (Form C), SC , Analog Output IRIG-B

NOTICE **The available combinations can be gathered from the ordering code.**

Binary Output Relays and System Contact

The number of the binary output relay contacts is related to the type of the device or type code. The binary output relays are potential-free change-over contacts. In chapter [Assignment/binary outputs] the assignment of the binary output relays is specified. The changeable signals are listed in the »assignment list« which can be found in the appendix.

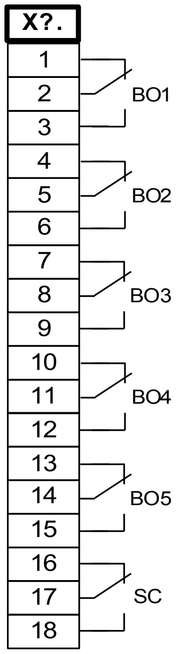
WARNING **Ensure the correct tightening torques.**



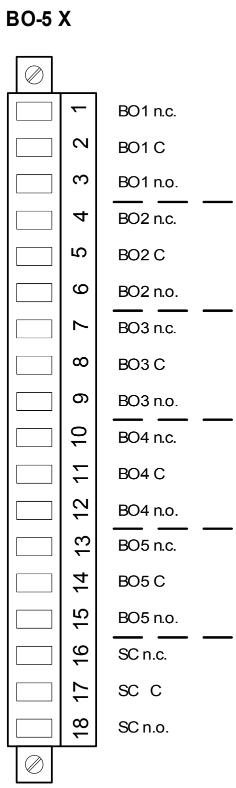
CAUTION **Please duly consider the current carrying capacity of the binary output relays. Please refer to the Technical Data.**

The *System-OK contact (SC relay)* cannot be configured. The system contact is a changeover contact that picks up when the device is free from internal faults. While the device is booting up, the *System OK relay (SC)* remains dropped-off (unenergized). As soon as the system is properly started (and protection is active), the System Contact picks up and the assigned LED is activated accordingly (please refer to the Self Supervision chapter).

Terminals



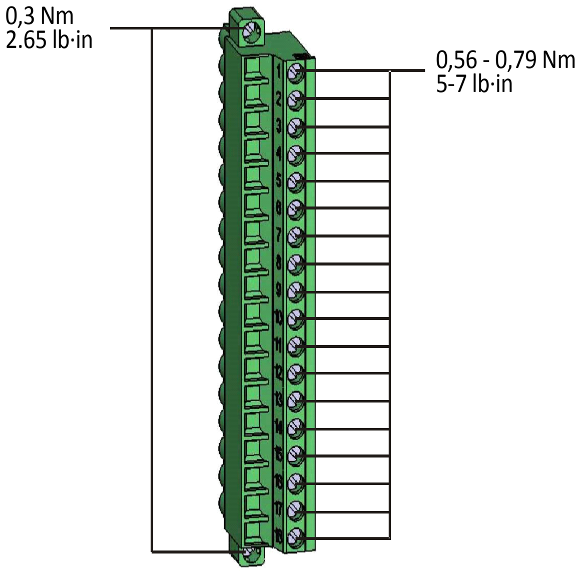
Electro-mechanical assignment



OR - 3AI X - Output Relays and System Contact

The number of the binary output relay contacts is related to the type of the device or type code. The binary output relays are potential-free contacts. In chapter [Assignment/binary outputs] the assignment of the binary output relays is specified. The changeable signals are listed in the »assignment list« which can be found in the appendix.

WARNING **Ensure the correct tightening torques.**

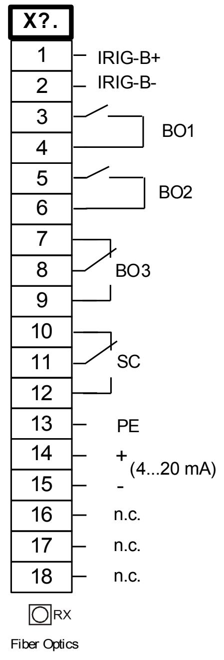


CAUTION **Please duly consider the current carrying capacity of the binary output relays. Please refer to the Technical Data.**

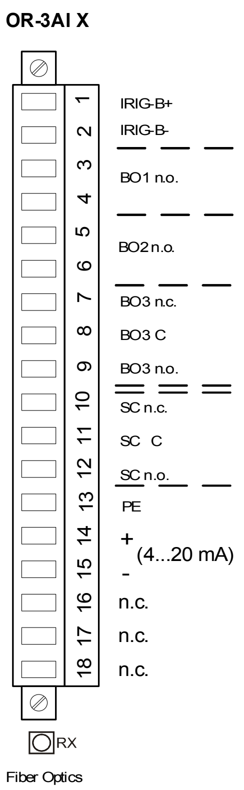
The *System-OK contact (SC relay)* cannot be configured. The system contact is a changeover contact that picks up when the device is free from internal faults. While the device is booting up, the *System OK relay (SC)* remains dropped-off (unenergized). As soon as the system is properly started (and protection is active), the System Contact picks up and the assigned LED is activated accordingly (please refer to the Self Supervision chapter).

For details on the Analoge Output please refer to the Technical Data.

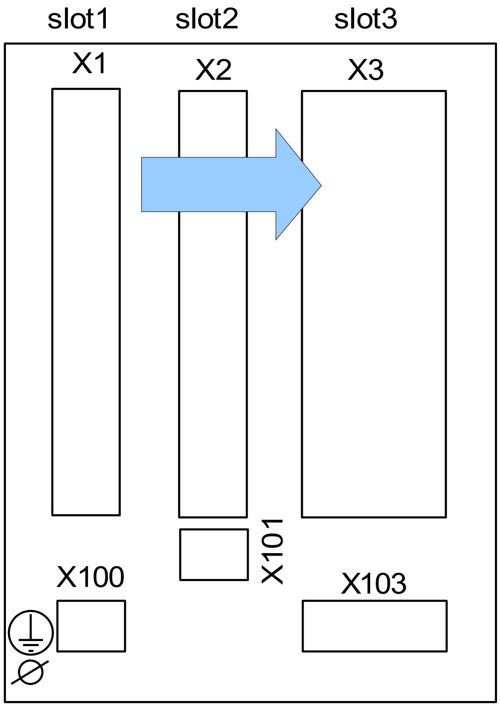
Terminals



Electro-mechanical assignment



Slot X3: Current Transformer Measuring Inputs



Rear side of the device (Slots)

This slot contains the current transformer measuring inputs.

TI X- Standard Phase and Ground Current Measuring Input Card

This measuring card is provided with 4 current measuring inputs: three for measuring the phase currents and one for measuring of the earth current. Each of the current measuring inputs has a measuring input for 1 A and 5 A.

The input for earth current measuring either can be connected to a cable-type current transformer or alternatively it is possible to connect the summation current path of the phase current transformer to this input (Holmgreen connection).

DANGER **Current transformers have to be earthed on their secondary side.**

DANGER **Interrupting the secondary circuits of current transformers causes hazardous voltages.**

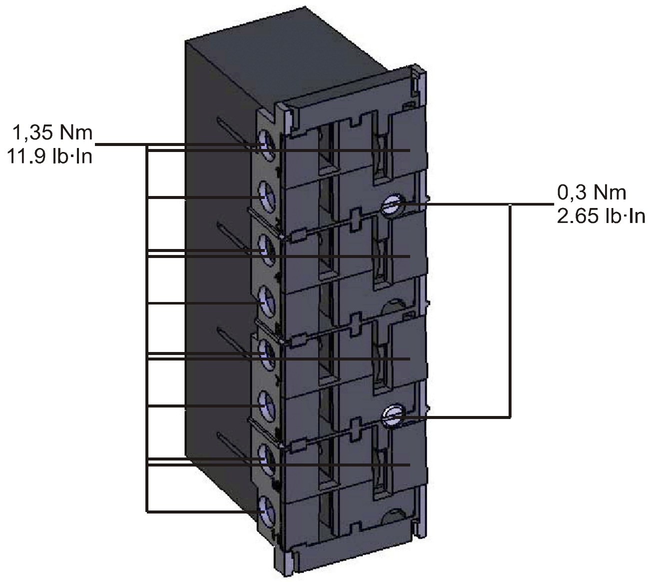
The secondary side of the current transformers have to be short circuited before the current circuit to the device is opened.

DANGER **The current measuring inputs may exclusively be connected to current measuring transformers (with galvanic separation).**

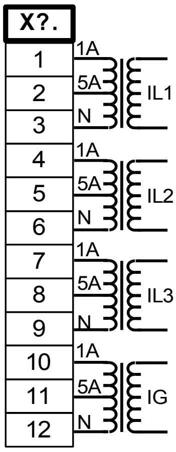
WARNING

- **Do not interchange the inputs (1 A/5 A)**
- **Make sure the transformation ratios and the power of the CTs are correctly rated. If the rating of the CTs is not right (overrated), then the normal operational conditions may not be recognized. The pickup value of the measuring unit amounts approx. 3% of the rated current of the device. Also the CTs need a current greater than approx 3% of the rated current to ensure sufficient accuracy. Example: For a 600 A CT (primary current) any currents below 18 A cannot be detected any more.**
- **Overloading can result in destruction of the measuring inputs or faulty signals. Overloading means that in case of a short-circuit the current-carrying capacity of the measuring inputs could be exceeded.**

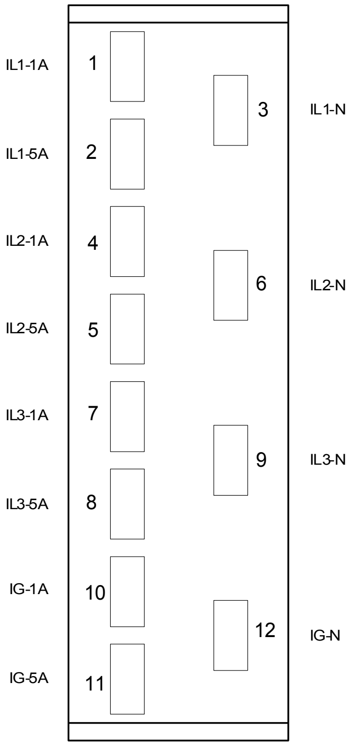
WARNING **Ensure the correct tightening torques.**


1,35 Nm
11.9 lb·In
0,3 Nm
2.65 lb·In

Terminals



Electro-mechanical assignment



TIS X – Phase and Sensitive Ground Current Measuring Card

The measuring card is provided with 4 current measuring inputs: three for measuring the phase currents and one for measuring of the earth current. The sensitive Ground current Input has different technical data. Please refer to chapter Technical Data.

The input for earth current measuring either can be connected to a cable-type current transformer or alternatively it is possible to connect the summation current path of the phase current transformer to this input (Holmgreen connection).

DANGER **Current transformers have to be earthed on their secondary side.**

DANGER **Interrupting the secondary circuits of current transformers causes hazardous voltages.**

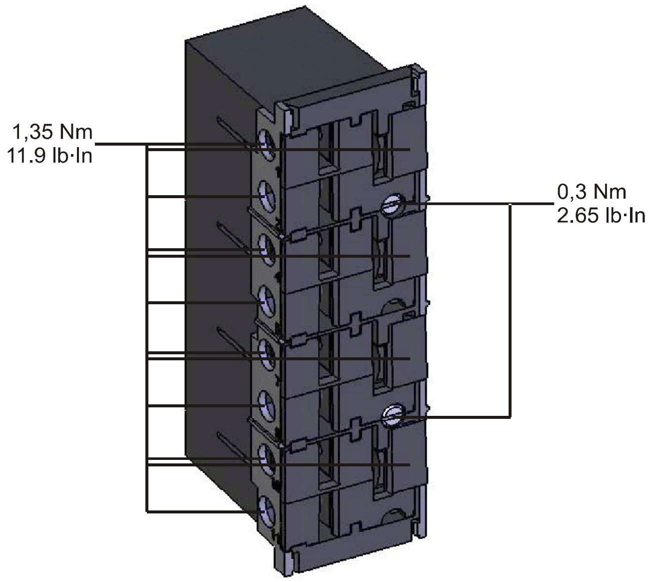
The secondary side of the current transformers have to be short circuited before the current circuit to the device is opened.

DANGER **The current measuring inputs may exclusively be connected to current measuring transformers (with galvanic separation).**

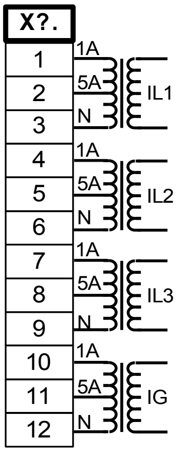
WARNING

- **Do not interchange the inputs (1 A/5 A)**
- **Make sure the transformation ratios and the power of the CTs are correctly rated. If the rating of the CTs is not right (overrated), then the normal operational conditions may not be recognized. The pickup value of the measuring unit amounts approx. 3% of the rated current of the device. Also the CTs need a current greater than approx 3% of the rated current to ensure sufficient accuracy. Example: For a 600 A CT (primary current) any currents below 18 A cannot be detected any more.**
- **Overloading can result in destruction of the measuring inputs or faulty signals. Overloading means that in case of a short-circuit the current-carrying capacity of the measuring inputs could be exceeded.**

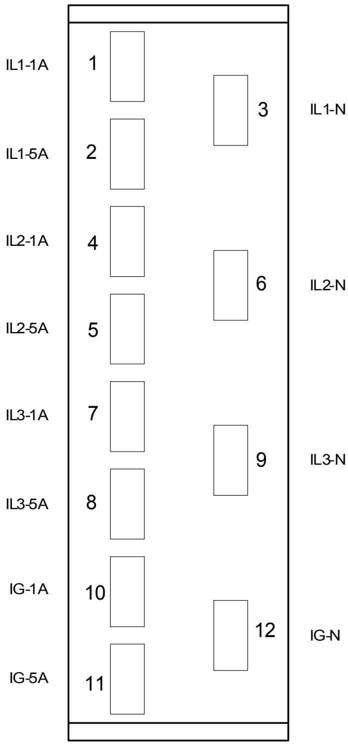
WARNING **Ensure the correct tightening torques.**



Terminals



Electro-mechanical assignment



Current Transformers (CT)

Check the installation direction.

DANGER **It is imperative that the secondary sides of measuring transformers be grounded.**

DANGER **The current measuring inputs may exclusively be connected to current measuring transformers (with galvanic separation).**

WARNING **CT secondary circuits must always to be low burdened or short-circuited during operation.**

NOTICE **For current and voltage sensing function external wired and appropriate current and voltage transformer shall be used, based on the required input measurement ratings. Those devices provide the necessary insulation functionality.**

All current measuring inputs can be provided with 1 A or 5 A nominal. Make sure that the wiring is correct.

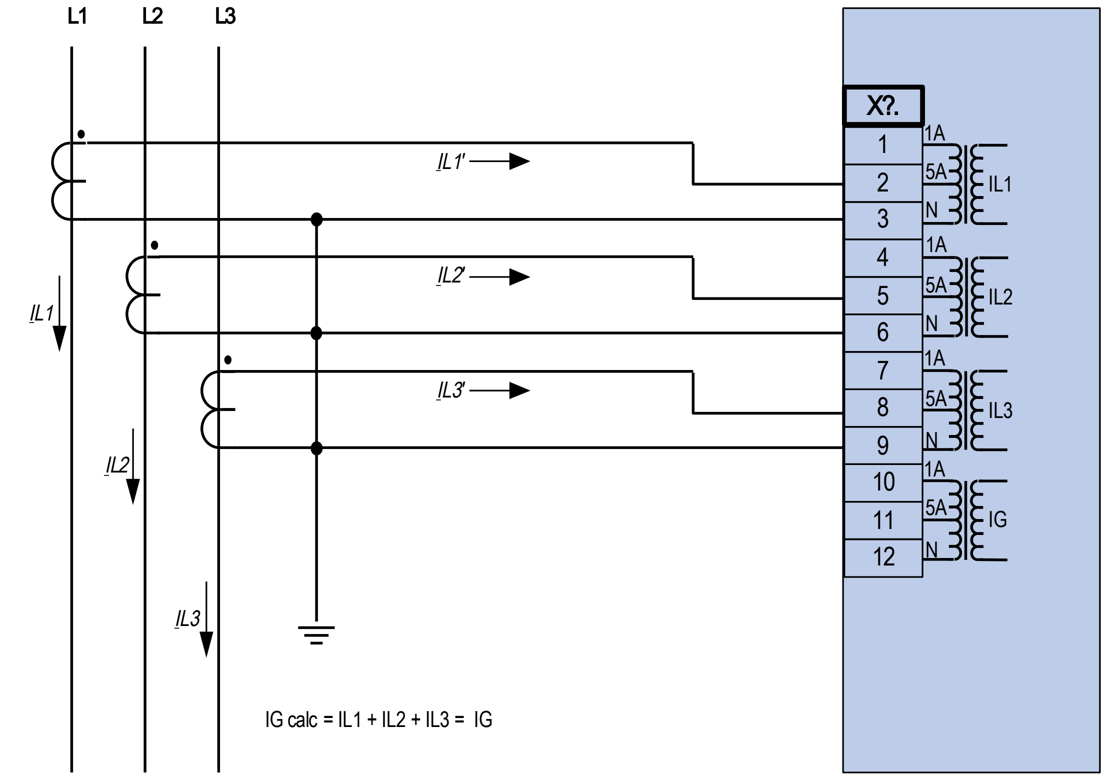
Sensitive Ground Current Measurement

The proper use of sensitive current measuring inputs is the measurement of small currents like they could occur in isolated and high resistance grounded networks.

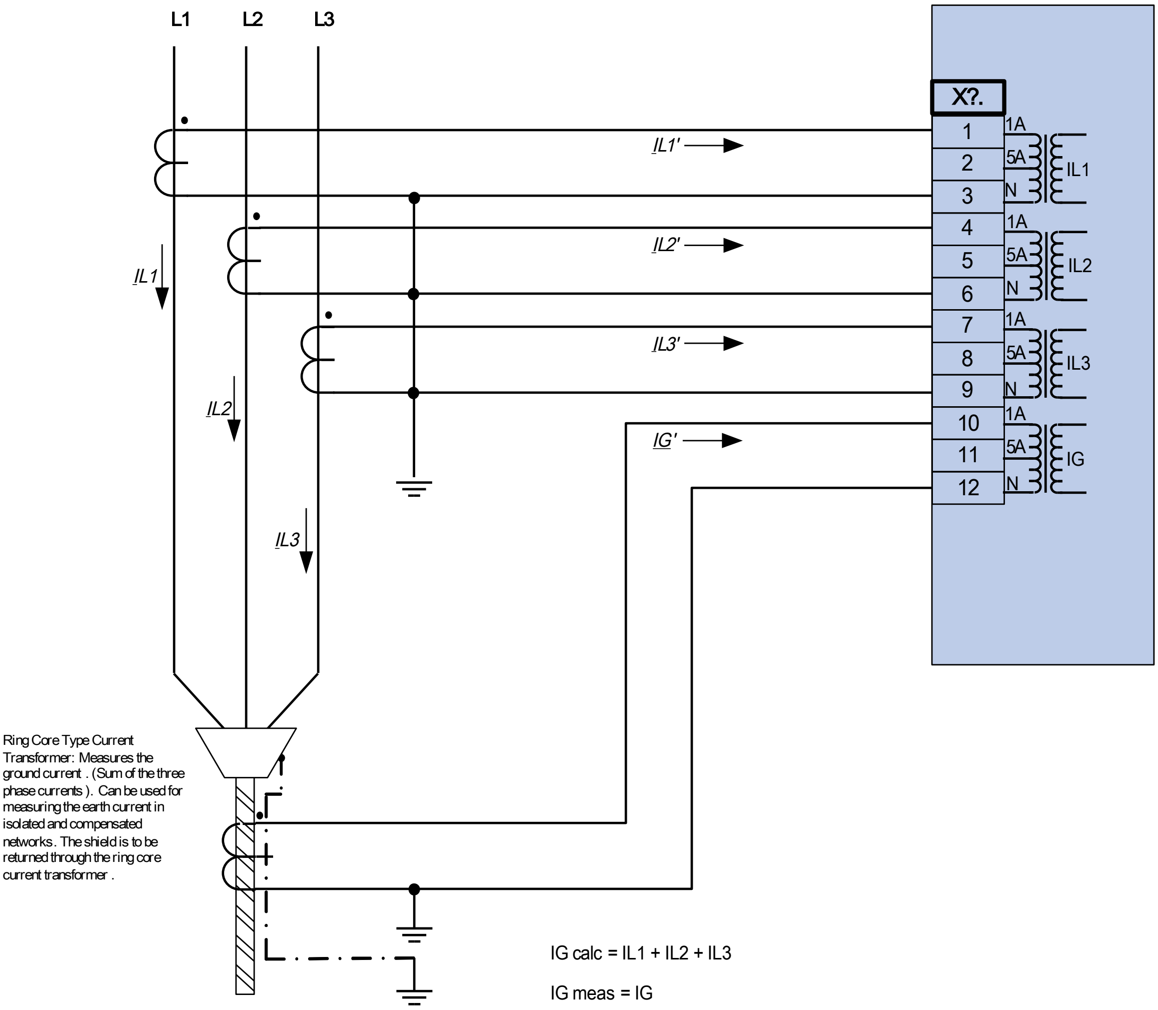
Due to the sensitiveness of these measuring inputs don´t use them for the measurement of ground short circuit currents like they occur in solidly earthed networks.

If a sensitive measuring input should be used for the measurement of ground short circuit currents, it has to be ensured, that the measuring currents are transformed by a matching transformer according to the technical data of the protective device.

Current Transformer Connection Examples

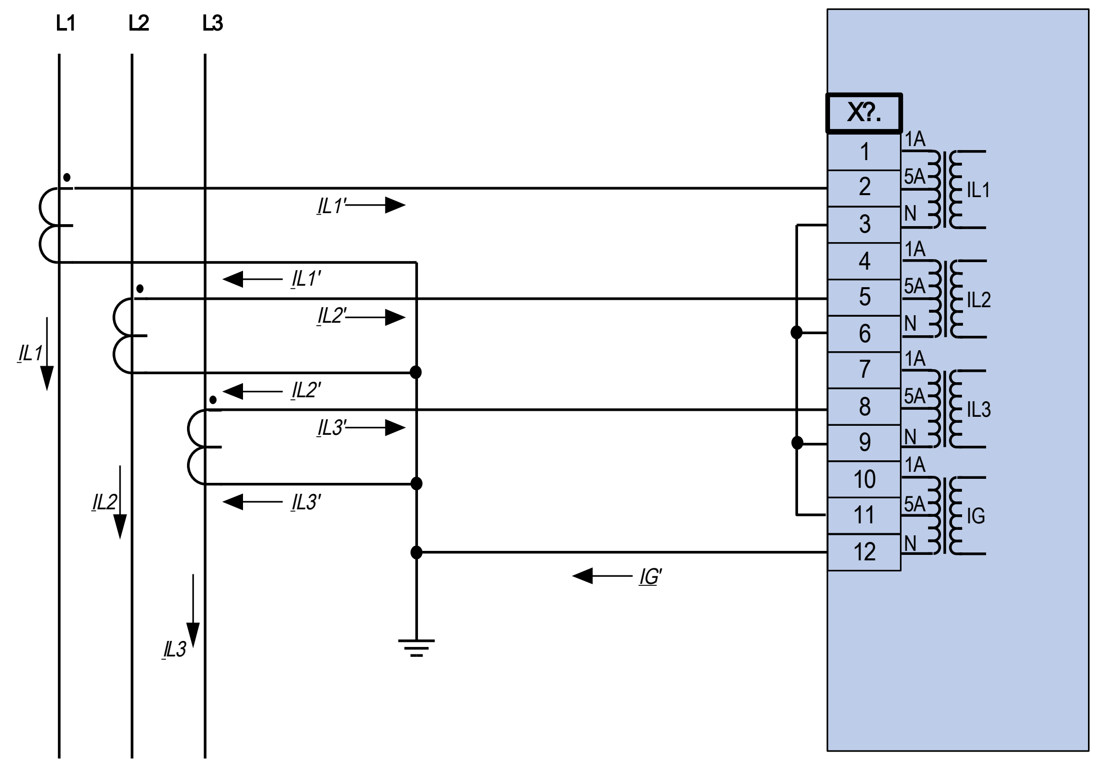


Three phase current measurement; In secondary = 5 A.

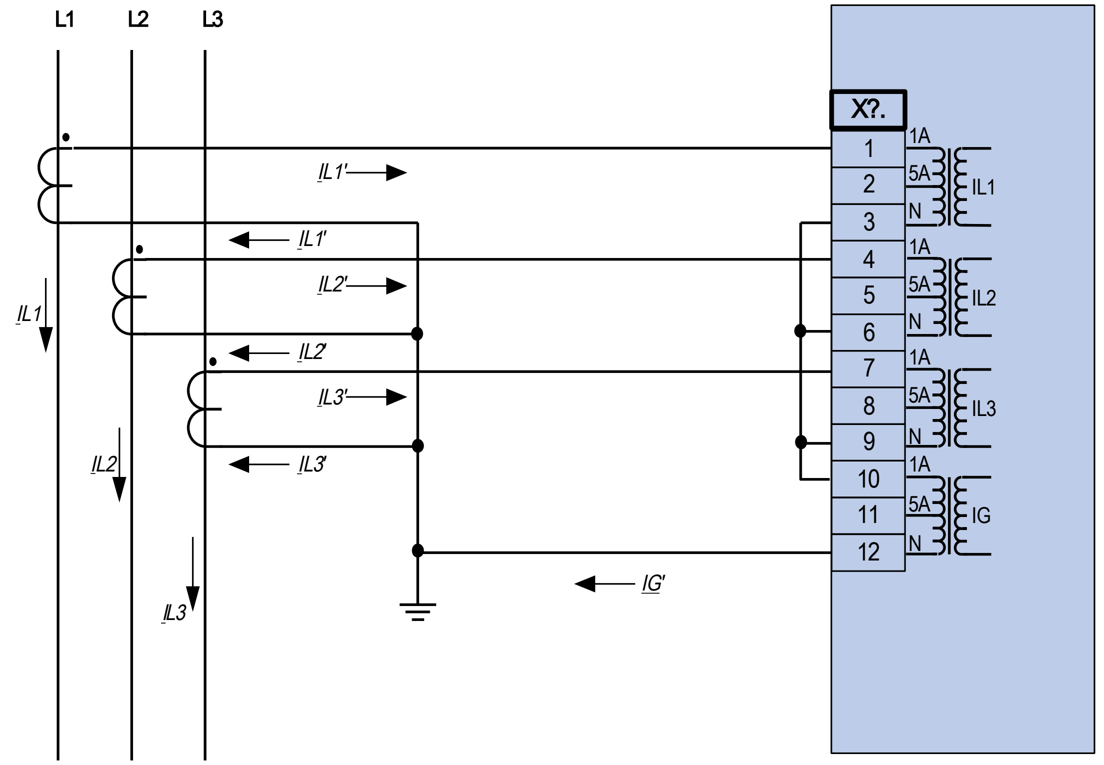


Three phase current measurement; In secondary = 1 A.
Earth-current measuring via cable-type current transformer ; IGnom secondary = 1 A.

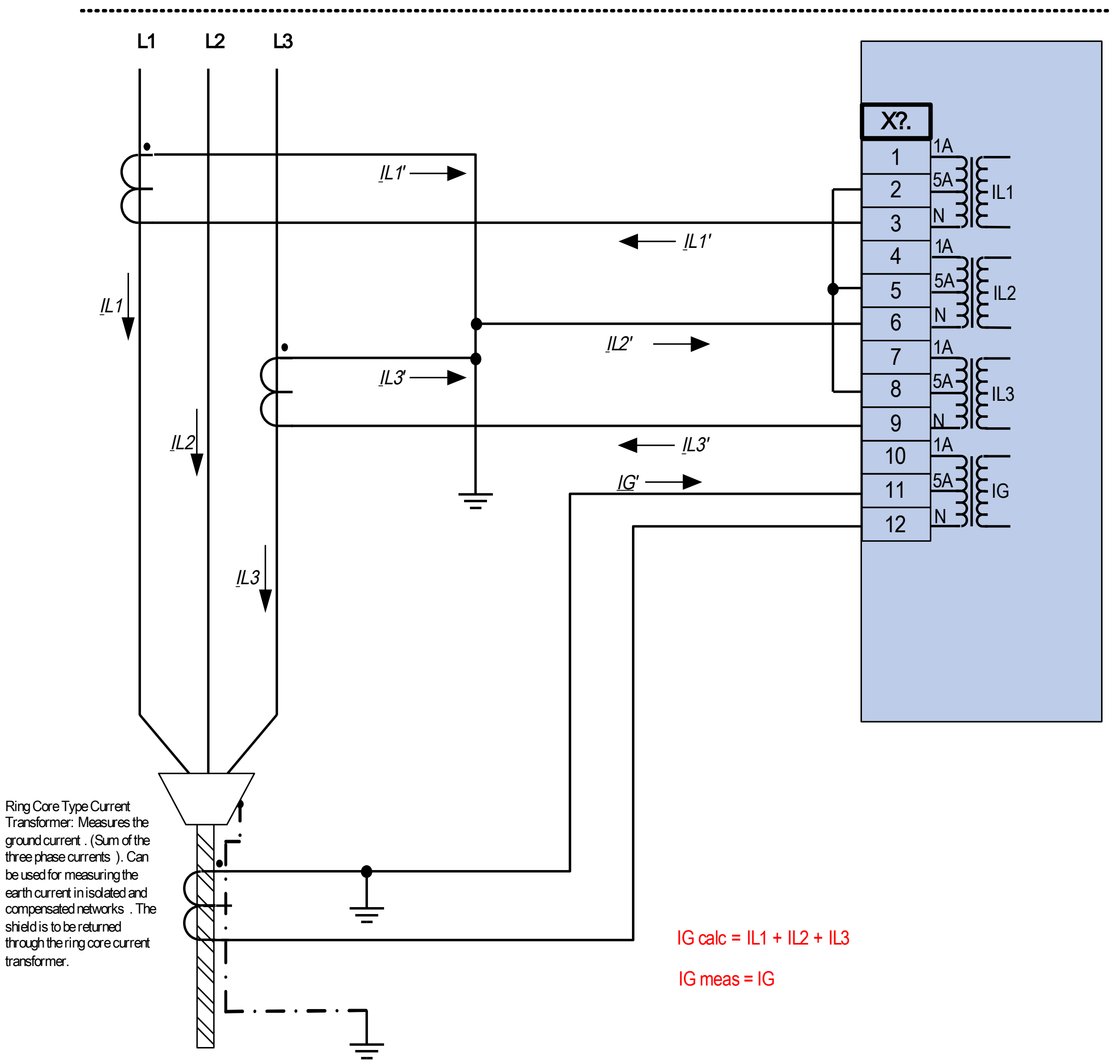
Warning!
The shielding at the dismantled end of the line has to be put through the cable -type current transformer and has to be grounded at the cable side .



Three phase current measurement; In secondary = 5 A.
Earth-current measuring via Holmgreen-connection; IGnom secondary = 5 A.

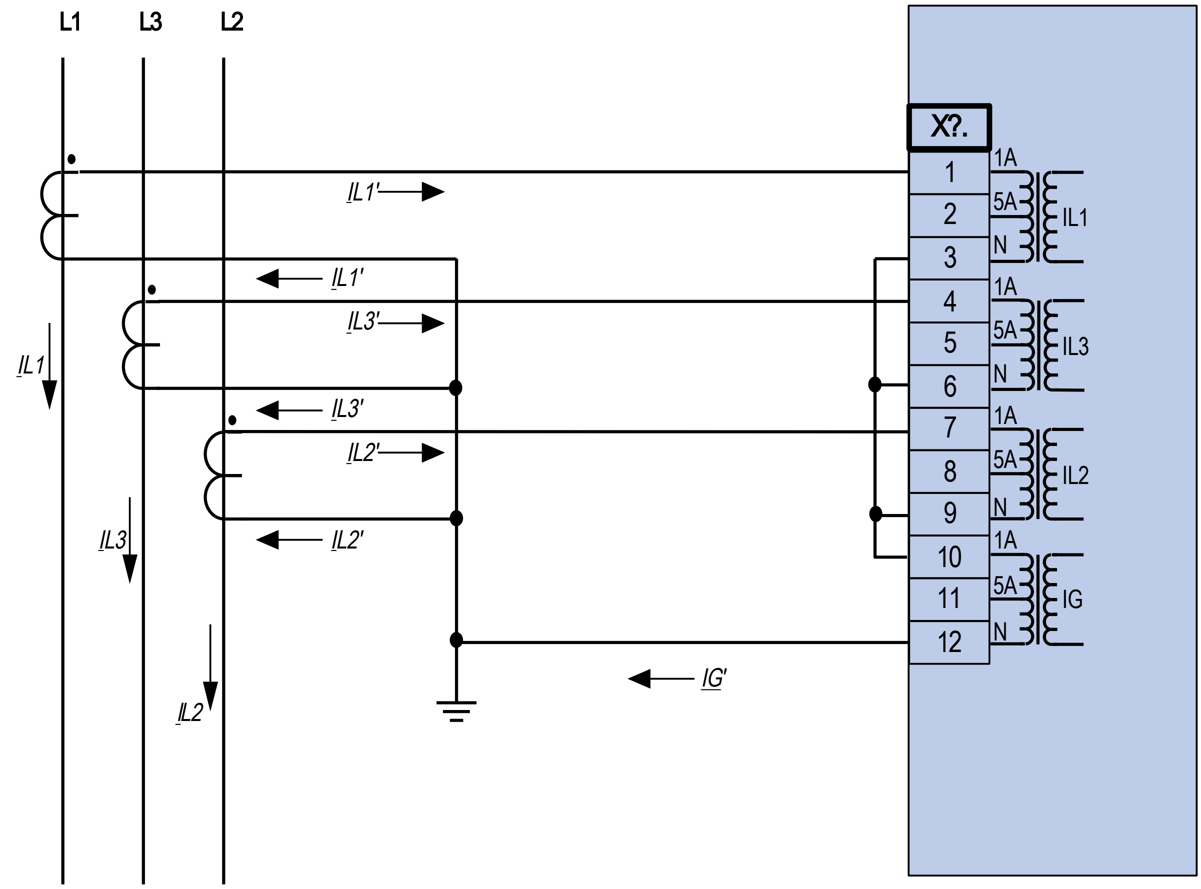


Three phase current measurement; In secondary = 1 A.
Earth-current measuring via Holmgreen-connection; IGnom secondary = 1 A.



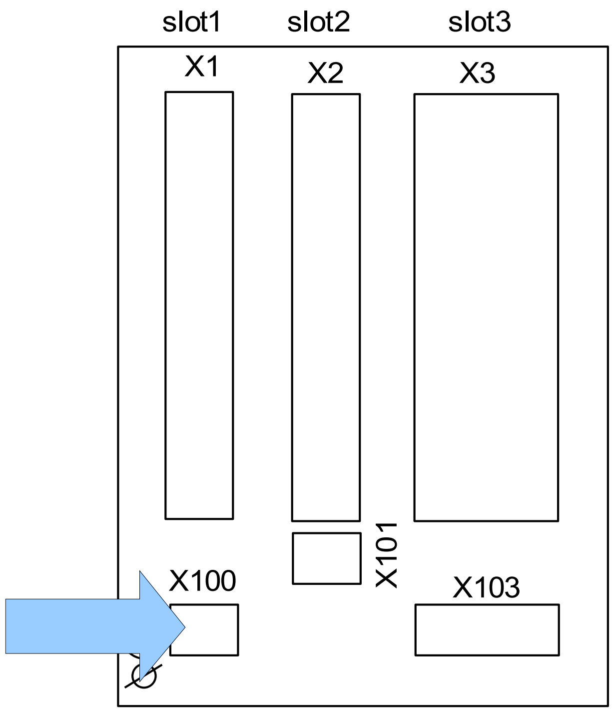
Two phase current measurement (Open Delta); In secondary = 5 A.
Earth-current measuring via cable-type current transformer ; IGnom secondary = 5 A.

Warning!
The shielding at the dismantled end of the line has to be put through the cable -type current transformer and has to be grounded at the cable side .



Three phase current measurement; In secondary = 1 A.
Earth-current measuring via Holmgreen-connection; IGnom secondary = 1 A.

Slot X100: Ethernet Interface

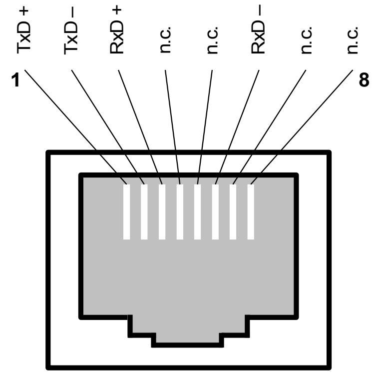


Rear side of the device (Slots)

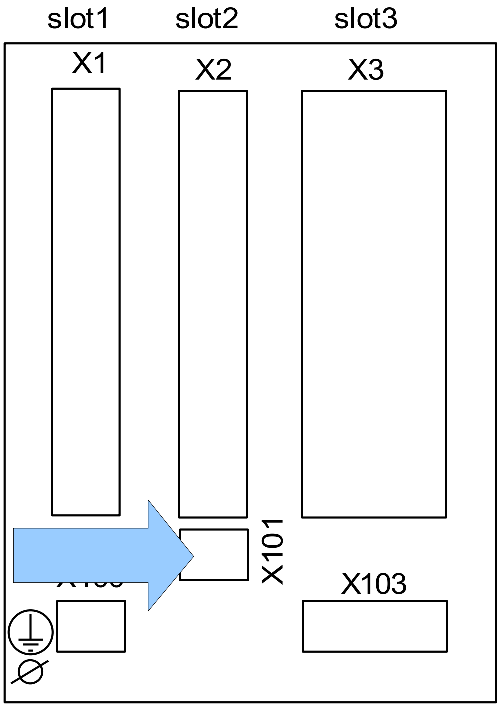
An Ethernet interface may be available depending on the device type ordered.

NOTICE **The available combinations can be gathered from the ordering code.**

Ethernet - RJ45

Terminals


Slot X101: IRIG-B00X



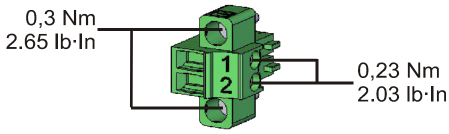
Rear side of the device (Slots)

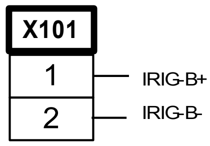
If the device is equipped with an IRIG-B00X interface is dependent on the ordered device type.

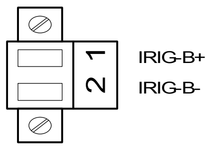
NOTICE **The available combinations can be gathered from the ordering code.**

IRIG-B00X

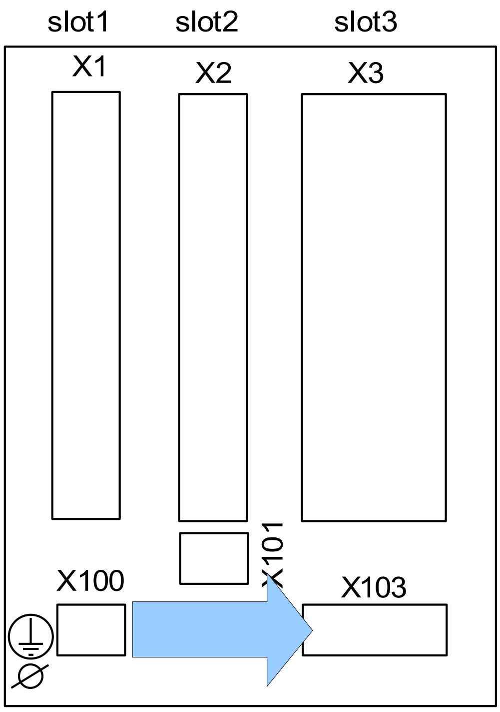
WARNING **Ensure the correct tightening torques.**



Terminal Markings


Electromechanical Assignment


Slot X103: Data Communication



Rear side of the device (Slots)

The data communication interface in the **X103** slot is dependent on the ordered device type. The scope of functions is dependent on the type of data communication interface.

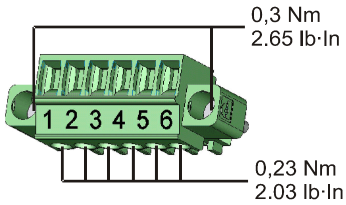
Available assembly groups in this slot:

- RS485 Terminals for Modbus and IEC
- LWL Interface for Modbus, IEC and Profibus
- D-SUB Interface for Modbus and IEC
- D-SUB Interface for Profibus
- Fiber Optics Interface for Ethernet*
  *=ask for availability

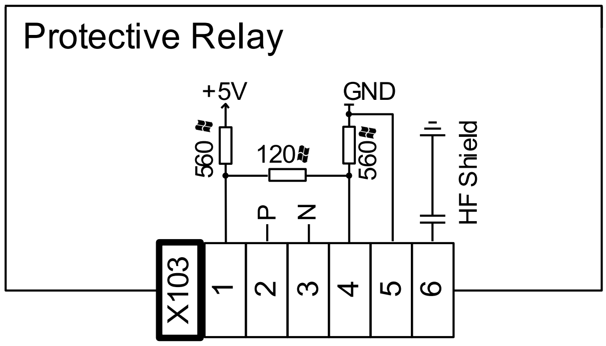
NOTICE **The available combinations can be gathered from the ordering code.**

Modbus® RTU / IEC 60870-5-103 via RS485

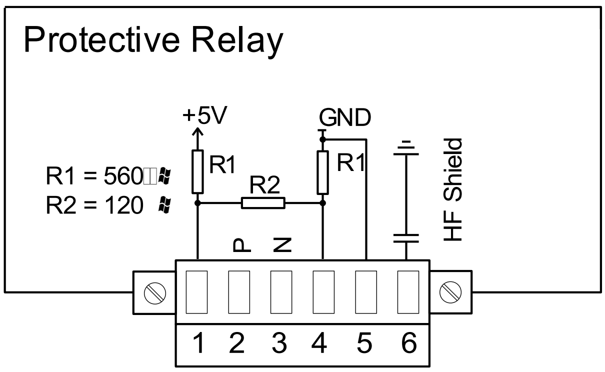
WARNING **Ensure the correct tightening torques.**



RS485



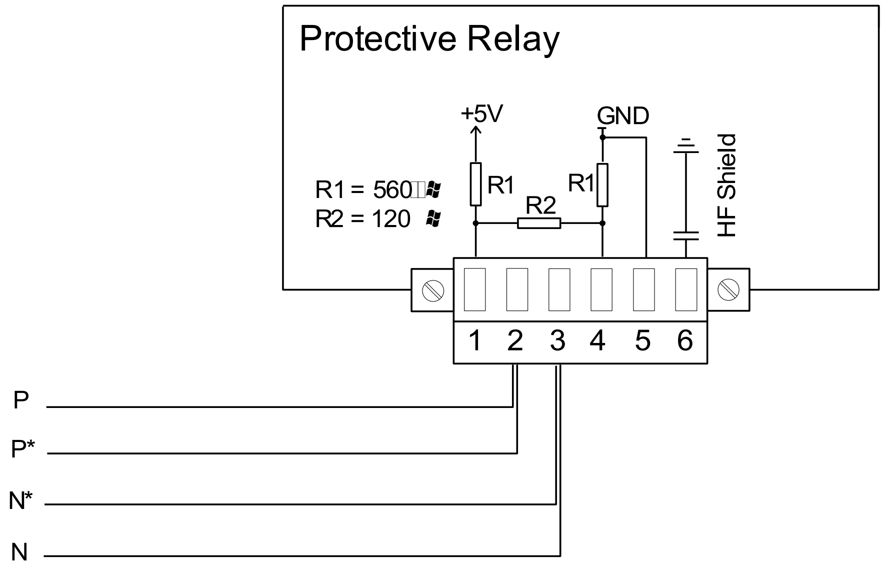
RS485 – Electro-mechanical assignment



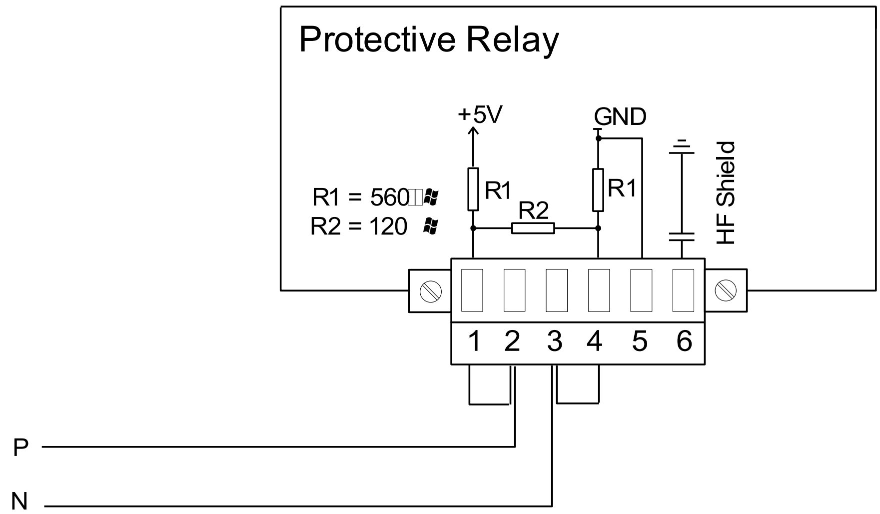
NOTICE **The Modbus® / IEC 60870-5-103 connection cable must be shielded. The shielding has to be fixed at the screw beneath the interface at the rear side of the device.**

The communication is halfduplex.

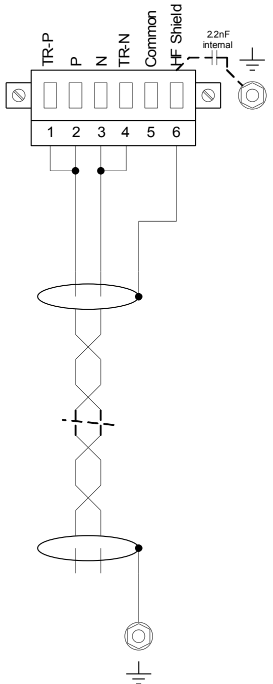
*Wiring example, Device **in the middle** of the bus*



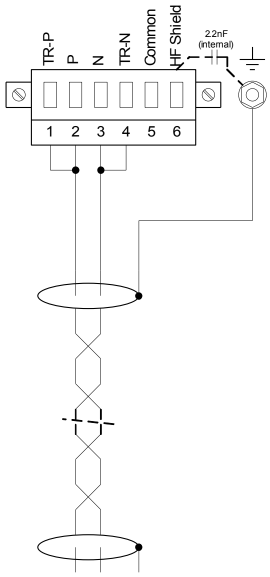
*Wiring example, Device **at the end** of the bus*
(setting wire jumpers to activate the integrated Terminal Resistor)



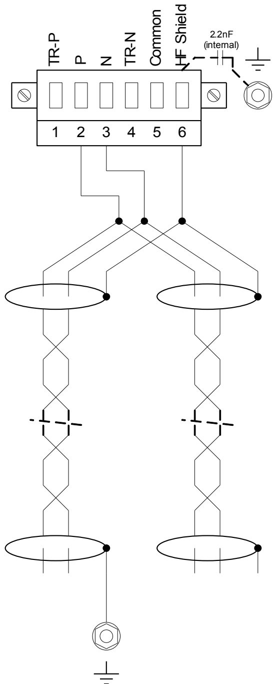
Shielding Options (2-wire + Shield)



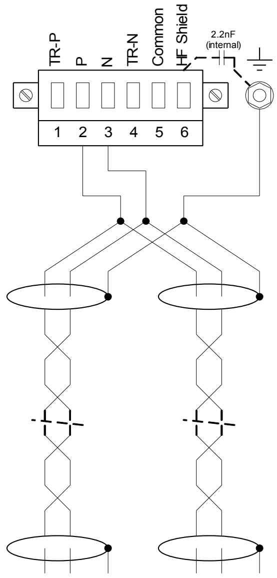
Shield at bus master side
connected to earth termination
resistors used



Shield at bus device side
connected to earth termination
resistors used

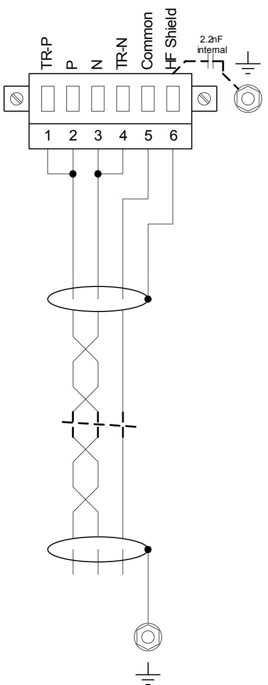


Shield at bus master side
connected to earth termination
resistors not used

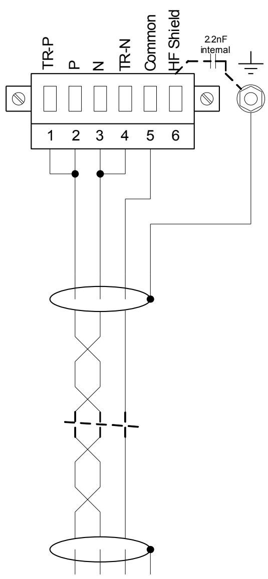


Shield at bus device side
connected to earth termination
resistors not used

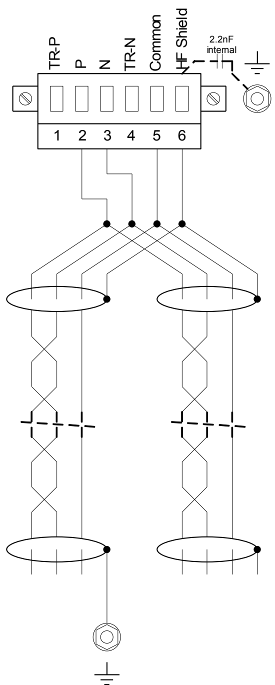
Shielding Options (3-wire + Shield)



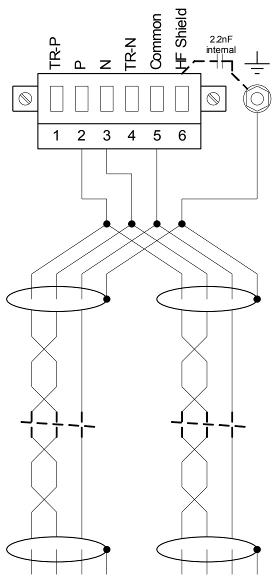
Shield at bus master side
connected to earth termination
resistors used



Shield at bus device side
connected to earth termination
resistors used

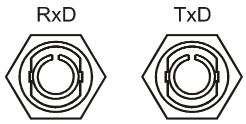


Shield at bus master side
connected to earth termination
resistors not used



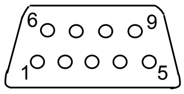
Shield at bus device side
connected to earth termination
resistors not used

Profibus DP/ Modbus® RTU / IEC 60870-5-103 via fibre optic

Fibre Optic


Modbus® RTU / IEC 60870-5-103 via D-SUB

D-SUB

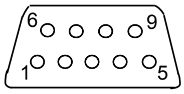


Electro-mechanical assignment
D-SUB assignment - bushing 1 Earthing/shielding 3 RxD TxD - P: High-Level 4 RTS-signal 5 DGND: Ground, neg. Potential of aux voltage supply 6 VP: pos. Potential of the aux voltage supply 8 RxD TxD - N: Low-Level

NOTICE **The connection cable must be shielded.**

Profibus DP via D-SUB

D-SUB

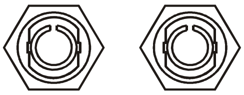


Electro-mechanical assignment

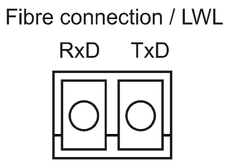
D-SUB assignment - bushing
1 Earthing/shielding
3 RxD TxD - P: High-Level
4 RTS-signal
5 DGND: Ground, neg. Potential of aux voltage supply
6 VP: pos. Potential of the aux voltage supply
8 RxD TxD - N: Low-Level

NOTICE **The connection cable must be shielded. The shielding has to be fixed at the screw which is marked with the ground symbol at the back side of the device.**

Profibus DP/ Modbus® RTU / IEC 60870-5-103 via fibre optic

Fibre Optic


Ethernet / TCP/IP via Fiber Optics

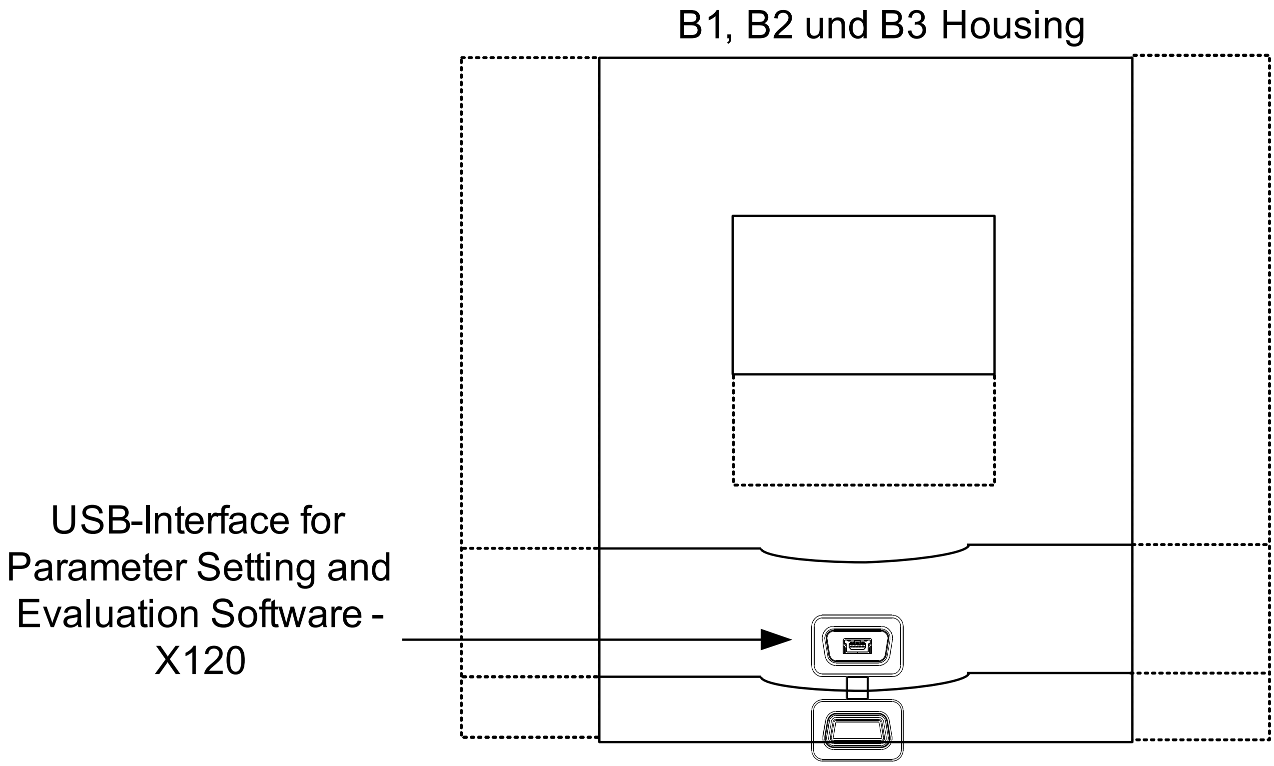
Fiber Optics - FO


CAUTION **After plugging in the LC connector, fasten the metal protecting cap.**

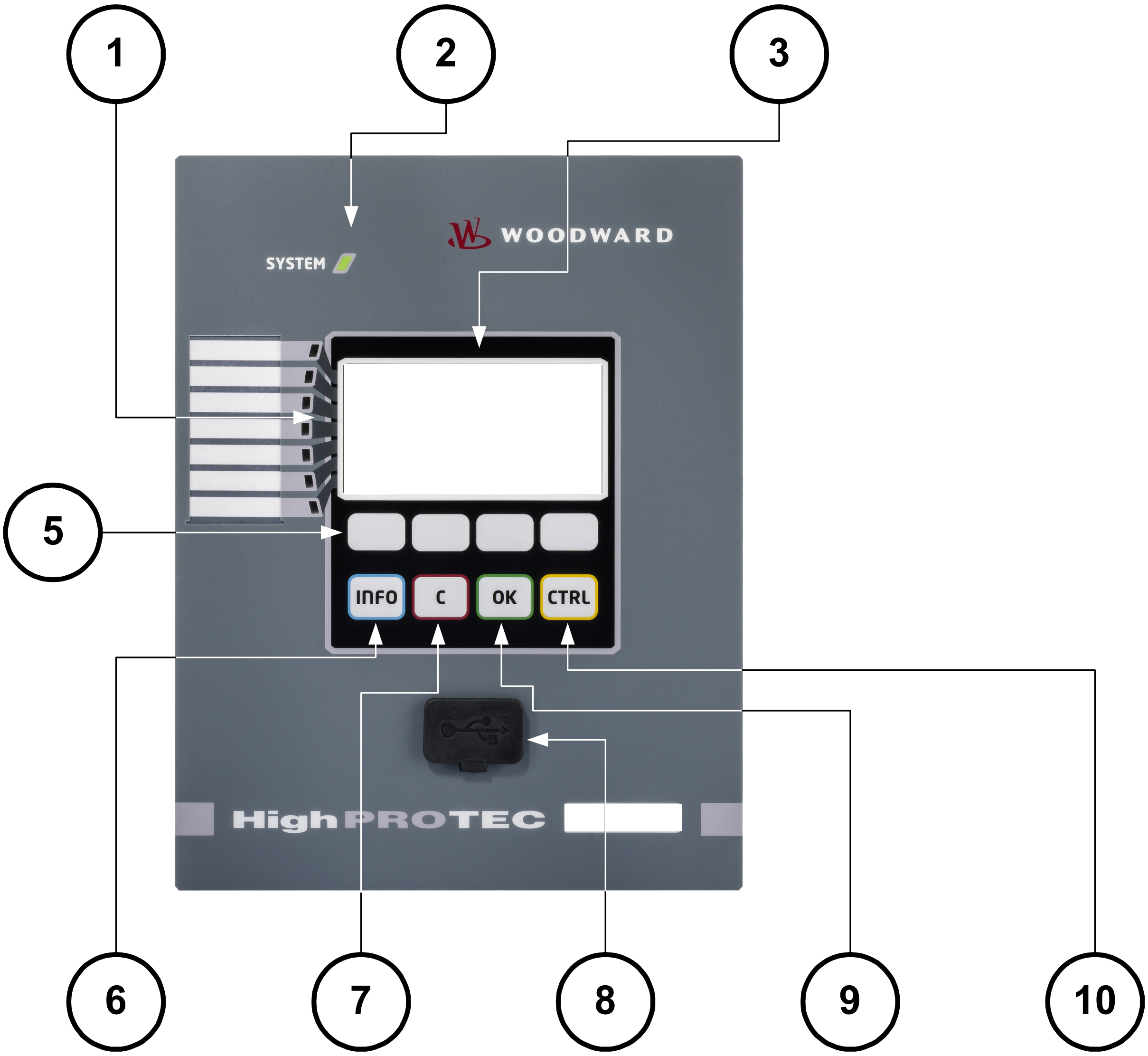
The tightening torque for the screw is 0.3 Nm [2.65 lb·in]).

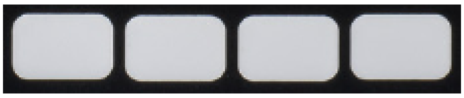
PC Interface - X120

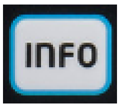
- USB (Mini-B)



Navigation - Operation



1		LEDs	Messages inform you about operational conditions, system data or other device particulars. They additionally provide you with information regarding failures and functioning of the device as well as other states of the device and the equipment. Alarm signals can be freely allocated to LEDs out of the »ASSIGNMENT LIST«. An overview about all alarm signals available in the device can be obtained from the »ASSIGNMENT LIST« which can be found in the appendix.
		LED »System OK«	Should LED »System OK« flash red during operation, contact the Service Dept. immediately.
3		Display	Via the display you can read-out operational data and edit parameters.
5		Softkeys	The function of the »SOFTKEYS« are contextual. On the bottom line of the display the present function is displayed/symbolized. Possible functions are: ■ Navigation ■ Parameter decrement/increment. ■ Scrolling up/down a menu page ■ Moving to a digit ■ Change into the parameter setting mode »wrench symbol«.

6		INFO Key (Signals/Messages)	Looking through the present LED assignment. The direct select key can be actuated at any time. If the INFO key is actuated again you will leave the LED menu. Here only the first assignments of the LEDs will be shown. Every three seconds the »SOFTKEYs« will be shown (flashing). *Displaying the multiple Assignments* If the INFO-Button is pressed only the first assignments of any LED is shown. Every three seconds the »SOFTKEYs« will be shown (flashing). If there is more than one signal assigned to a LED (indicated by three dots) you can check the state of the multiple assignments if you proceed as follows. In order to show all (multiple) assignments select a LED by means of the »SOFTKEYs« »up« and »down« Via the »Softkey« »right« call up a Submenu of this LED that gives you detailed information on the state of all signals assigned to this LED. An arrow symbol points to the LED whose assignments are currently displayed. Via the »SOFTKEYs« »up« and »down« you can call up the next / previous LED. In order to leave the LED menu press the »SOFTKEY« »left« multiple times.
7		»C Key«	To abort changes and to acknowledge messages. In order to reset please press the Softkey »wrench« and enter the password.

			The reset menu can be left by pressing the Softkey »Arrow-left«
8		USB Interface (*Smart view* Connection)	Connection to software *Smart view* is done via the USB interface.
9		»OK Key«	When using the »OK« key parameter changes are temporarily stored. If the »OK« key is pressed again, those changes are stored definitely.
10		»CTRL Key«*	Direct Access to the Control Menu.

*=Not for all devices available.

Basic Menu Control

The graphic user interface is equivalent to a hierarchical structured menu tree. For access to the individual submenus the »SOFTKEYS«/Navigation Keys are used. The function of the »SOFTKEYS« can be found as symbol in the footer of the display.

Softkey	*Description*
	■ Via »SOFTKEY« »up« you will come to the prior menu point/one parameter up by scrolling upwards.
	■ Via »SOFTKEY« »left« you will go one step back.
	■ Via »SOFTKEY« »down« you will change to the next menu point/one parameter down by scrolling downwards.
	■ Via »SOFTKEY« »right« you will come to a submenu.
	■ Via »SOFTKEY« »Top of list« you will jump directly to the top of a list.
	■ Via »SOFTKEY« »Bottom of list« you will jump directly to the end of a list.
	■ Via »SOFTKEY« »+« the related digit will be incremented. (Continuous pressure -> fast).
	■ Via »SOFTKEY« »-« the related digit will be decremented. (Continuous pressure -> fast)
	■ Via »SOFTKEY« »left« you will go one digit to the left.
	■ Via »SOFTKEY« »right« you will go one digit to the right.
	■ Via »SOFTKEY« »Parameter setting« you will call up the parameter setting mode.
	■ Via »SOFTKEY« »Parameter setting« you will call up the parameter setting mode. Password authorization required.
	■ Via »SOFTKEY« »delete« data will be deleted.
	■ Fast forward scrolling is possible via »SOFTKEY« »Fast forward«
	■ Fast backward scrolling is possible via »SOFTKEY« »Fast backward«

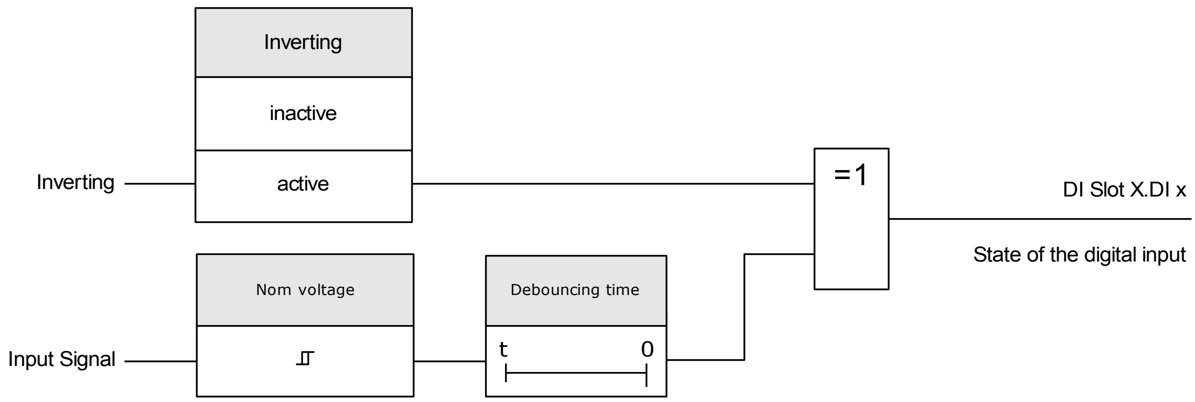
In order to return to the main menu, just keep pressing the Softkey »Arrow-Left« until you arrive at the »main menu».

Input, Output and LED Settings

Configuration of the Digital Inputs

Set the following parameters for each of the digital inputs:

- *»Nominal voltage«*
- *»Debouncing time«*: A state change will only be adopted by the digital input after the debouncing time has expired.
- *»Inverting«* (where necessary)

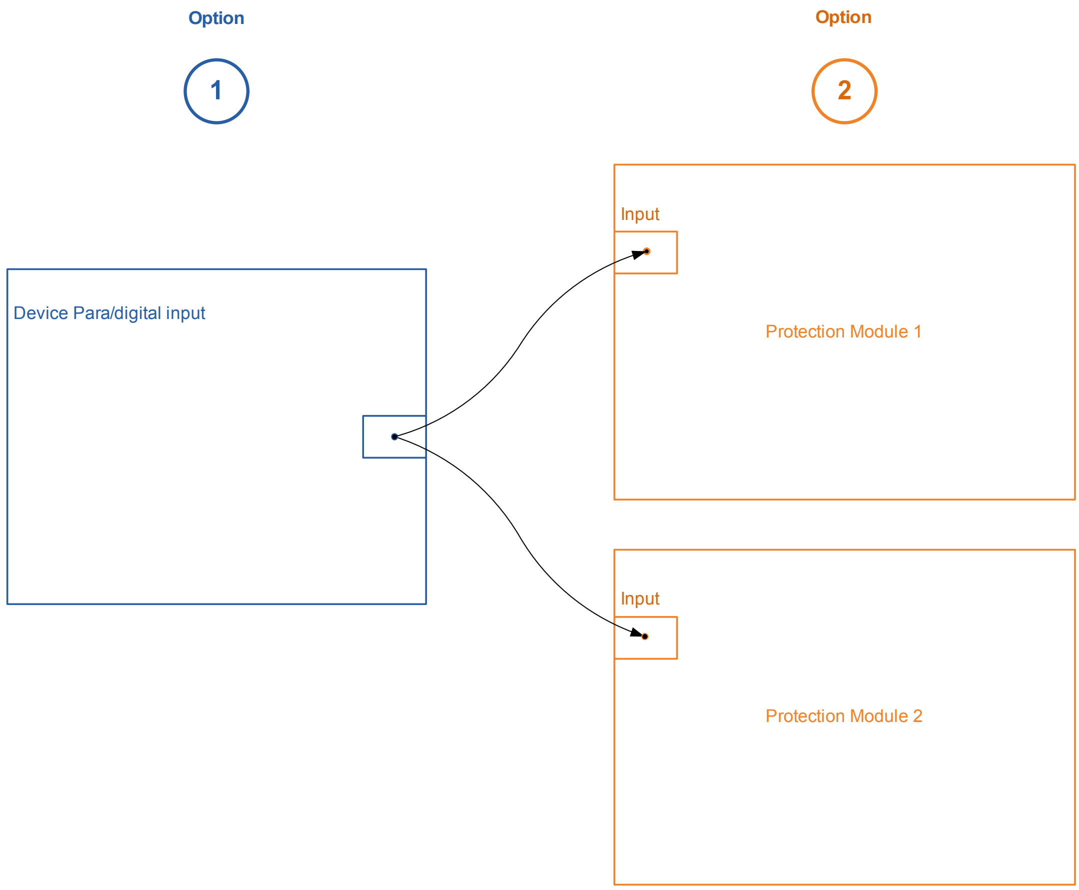


CAUTION **The debouncing time will be started each time the state of the input signal alternates.**

CAUTION **In addition to the debouncing time that can be set via software, there is always a hardware debouncing time (approx 12 ms) that cannot be turned of.**

Assignment of Digital Inputs

There are two options available in order to determine where a Digital Input should be assigned to.



Option 1 – Assigning a Digital Input onto one or mutliple modules.

Adding an assignment:
Within menu [Device Parameter\Digital Inputs] Digital Inputs can be assigned onto one or multiple targets.

Call up the Digital Input (Arrow right on the DI). Click on the Softkey *»Parameter Setting/Wrench«* . Click on *»Add«* and assign a target. Assign where required additional targets.

Deleting an assignment:
Select as described above a Digital Input that should be edited at the HMI.

Call up the assignments of the Digital Input (Arrow-right on the DI) and select the assignment that should be removed/deleted (Please note, this has to marked with the cursor). The assignment can now be deleted at the HMI by means of the Softkey »*Parameter setting«* and selection of »*remove«*. Confirm the parameter setting update.

Option 2 – Connecting a Module Input with a Digital Input

Call a module. Within this module assign a Digital Input onto a module input. Example: A protection module should be blocked depending on the state of a Digital Input.. For this assign onto the blocking input within the Global Parameters the Digital Input (e.g. Ex Blo 1).

Checking the Assignments of a Digital Input

In order to check the targets that a Digital Input is assigned to please proceed as follows:

Call up menu [Device Parameter\Digital Inputs].

Navigate to the Digital Input that should be checked.

At the HMI:
A multiple assignment, that means if a Digital Input is used more than once (if it is assigned to multiple targets), this will be indicated by an "..." behind a Digital Input. Call up this Digital Input by Softkey »Arrow right« in order to see the list of targets of this Digital Input.

DI-8P X

DI Slot X1

Device Parameters of the Digital Inputs on DI-8P X

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Nom voltage	Nominal voltage of the digital inputs	24 V DC, 48 V DC, 60 V DC, 110 V DC, 230 V DC, 110 V AC, 230 V AC	24 V DC	[Device Para /Digital Inputs /DI Slot X1 /Group 1]
Inverting 1	Inverting the input signals.	inactive, active	inactive	[Device Para /Digital Inputs /DI Slot X1 /Group 1]
Debouncing time 1	A change of the state of a digital input will only be recognized after the debouncing time has expired (become effective). Thus, transient signals will not be misinterpreted.	no debouncing time, 20 ms, 50 ms, 100 ms	no debouncing time	[Device Para /Digital Inputs /DI Slot X1 /Group 1]
Nom voltage	Nominal voltage of the digital inputs	24 V DC, 48 V DC, 60 V DC, 110 V DC, 230 V DC, 110 V AC, 230 V AC	24 V DC	[Device Para /Digital Inputs /DI Slot X1 /Group 2]
Inverting 2	Inverting the input signals.	inactive, active	inactive	[Device Para /Digital Inputs /DI Slot X1 /Group 2]
Debouncing time 2	A change of the state of a digital input will only be recognized after the debouncing time has expired (become effective). Thus, transient signals will not be misinterpreted.	no debouncing time, 20 ms, 50 ms, 100 ms	no debouncing time	[Device Para /Digital Inputs /DI Slot X1 /Group 2]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Nom voltage	Nominal voltage of the digital inputs	24 V DC, 48 V DC, 60 V DC, 110 V DC, 230 V DC, 110 V AC, 230 V AC	24 V DC	[Device Para /Digital Inputs /DI Slot X1 /Group 3]
Inverting 3	Inverting the input signals.	inactive, active	inactive	[Device Para /Digital Inputs /DI Slot X1 /Group 3]
Debouncing time 3	A change of the state of a digital input will only be recognized after the debouncing time has expired (become effective). Thus, transient signals will not be misinterpreted.	no debouncing time, 20 ms, 50 ms, 100 ms	no debouncing time	[Device Para /Digital Inputs /DI Slot X1 /Group 3]
Inverting 4	Inverting the input signals.	inactive, active	inactive	[Device Para /Digital Inputs /DI Slot X1 /Group 3]
Debouncing time 4	A change of the state of a digital input will only be recognized after the debouncing time has expired (become effective). Thus, transient signals will not be misinterpreted.	no debouncing time, 20 ms, 50 ms, 100 ms	no debouncing time	[Device Para /Digital Inputs /DI Slot X1 /Group 3]
Inverting 5	Inverting the input signals.	inactive, active	inactive	[Device Para /Digital Inputs /DI Slot X1 /Group 3]
Debouncing time 5	A change of the state of a digital input will only be recognized after the debouncing time has expired (become effective). Thus, transient signals will not be misinterpreted.	no debouncing time, 20 ms, 50 ms, 100 ms	no debouncing time	[Device Para /Digital Inputs /DI Slot X1 /Group 3]
Inverting 6	Inverting the input signals.	inactive, active	inactive	[Device Para /Digital Inputs /DI Slot X1 /Group 3]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Debouncing time 6	A change of the state of a digital input will only be recognized after the debouncing time has expired (become effective). Thus, transient signals will not be misinterpreted.	no debouncing time, 20 ms, 50 ms, 100 ms	no debouncing time	[Device Para /Digital Inputs /DI Slot X1 /Group 3]
Inverting 7	Inverting the input signals.	inactive, active	inactive	[Device Para /Digital Inputs /DI Slot X1 /Group 3]
Debouncing time 7	A change of the state of a digital input will only be recognized after the debouncing time has expired (become effective). Thus, transient signals will not be misinterpreted.	no debouncing time, 20 ms, 50 ms, 100 ms	no debouncing time	[Device Para /Digital Inputs /DI Slot X1 /Group 3]
Inverting 8	Inverting the input signals.	inactive, active	inactive	[Device Para /Digital Inputs /DI Slot X1 /Group 3]
Debouncing time 8	A change of the state of a digital input will only be recognized after the debouncing time has expired (become effective). Thus, transient signals will not be misinterpreted. 8	no debouncing time, 20 ms, 50 ms, 100 ms	no debouncing time	[Device Para /Digital Inputs /DI Slot X1 /Group 3]

Signals of the Digital Inputs on DI-8P X

Signal	*Description*
DI 1	Signal: Digital Input
DI 2	Signal: Digital Input
DI 3	Signal: Digital Input
DI 4	Signal: Digital Input
DI 5	Signal: Digital Input
DI 6	Signal: Digital Input
DI 7	Signal: Digital Input
DI 8	Signal: Digital Input

DI-4P X

DI Slot X1

Device Parameters of the Digital Inputs on DI-4P X

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Nom voltage	Nominal voltage of the digital inputs	24 V DC, 48 V DC, 60 V DC, 110 V DC, 230 V DC, 110 V AC, 230 V AC	24 V DC	[Device Para /Digital Inputs /DI Slot X1]
Inverting 1	Inverting the input signals.	inactive, active	inactive	[Device Para /Digital Inputs /DI Slot X1]
Debouncing time 1	A change of the state of a digital input will only be recognized after the debouncing time has expired (become effective). Thus, transient signals will not be misinterpreted.	no debouncing time, 20 ms, 50 ms, 100 ms	no debouncing time	[Device Para /Digital Inputs /DI Slot X1]
Inverting 2	Inverting the input signals.	inactive, active	inactive	[Device Para /Digital Inputs /DI Slot X1]
Debouncing time 2	A change of the state of a digital input will only be recognized after the debouncing time has expired (become effective). Thus, transient signals will not be misinterpreted.	no debouncing time, 20 ms, 50 ms, 100 ms	no debouncing time	[Device Para /Digital Inputs /DI Slot X1]
Inverting 3	Inverting the input signals.	inactive, active	inactive	[Device Para /Digital Inputs /DI Slot X1]
Debouncing time 3	A change of the state of a digital input will only be recognized after the debouncing time has expired (become effective). Thus, transient signals will not be misinterpreted.	no debouncing time, 20 ms, 50 ms, 100 ms	no debouncing time	[Device Para /Digital Inputs /DI Slot X1]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Inverting 4	Inverting the input signals.	inactive, active	inactive	[Device Para /Digital Inputs /DI Slot X1]
Debouncing time 4	A change of the state of a digital input will only be recognized after the debouncing time has expired (become effective). Thus, transient signals will not be misinterpreted.	no debouncing time, 20 ms, 50 ms, 100 ms	no debouncing time	[Device Para /Digital Inputs /DI Slot X1]

Signals of the Digital Inputs on DI-4P X

Signal	*Description*
DI 1	Signal: Digital Input
DI 2	Signal: Digital Input
DI 3	Signal: Digital Input
DI 4	Signal: Digital Input

Output Relays Settings

The conditions of module outputs and signals/protective functions (such as reverse interlocking) can be passed by means of alarm relays. The alarm relays are potential-free contacts (which can be used as opening or closing contact). Each alarm relay can be assigned up to 7 functions out of the »assignment list«.

Set the following parameters for each of the binary output relays:

- Up to 7 signals from the »assignment list« (OR-connected)
- Each of the assigned signals can be inverted.
- The (collective) state of the binary output relay can be inverted (open or closed circuit current principle)
- By the Operating Mode it can be determined whether the relay output works in working current or closed-circuit principle.
- *»Latched«* active or inactive
    - *»Latched = inactive«*:
      If the latching function is *»inactive«*, the alarm relay respectively the alarm contact will adopt the state of those alarms that were assigned.
    - *»Latched = active«*
      If the »latching function« is *»active«*, the state of the alarm relay respectively alarm contact that was set by the alarms will be stored.

      The alarm relay can only be acknowledged after reset of those signals that had initiated setting of the relay and after expiry of the minimum retention time.
- *»Hold time«*: At signal changes, the minimal latching time ensures that the relay will be maintained picked-up or released for at least this period.

CAUTION

If binary outputs are parameterized »Latched=*active«*, they will keep (return into) their position even if there is a break within the power supply.

If binary output relays are parameterized »Latched=*active«*, The binary output will also retain, if the binary output is reprogrammed in another way. This applies also if »Latched is set to ina*ctive«*. Resetting a binary output that has latched a signal will always require an acknowledgement.

NOTICE

The *»System OK Relay«* (watchdog) cannot be configured.

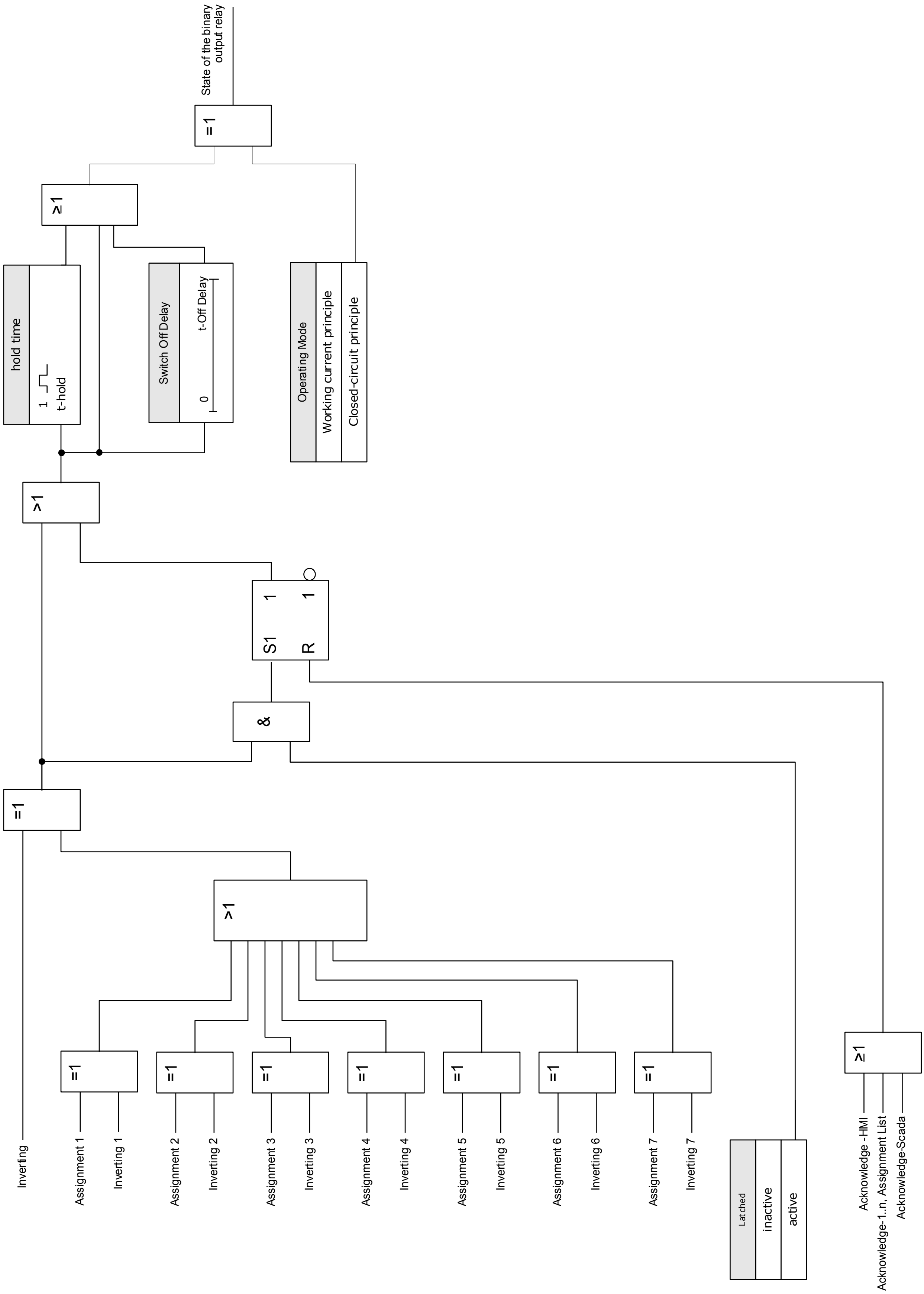
Acknowledgment options

Binary output relays can be acknowledged:

- Via the push-button »C« at the operating panel.
- Each binary output relay can be acknowledged by a signal of the »assignment list« (If »*Latched is active«*).
- Via the module »Ex Acknowledge« all binary output relays can be acknowledged at once, if the signal for external acknowledgement that was selected from the »assignment list« becomes true. (e.g the state of a digital input).
- Via SCADA, all output relays can be acknowledged at once.

WARNING

Relay output contacts can be set by force or disarmed (for commisioning support, please refer to the „Service/Disarming the Output Relay Contacts“ and „Service/Forcing the Output Relay Contacts“ sections).


State of the binary output relay
=1
≥1
hold time
1
t-hold
Switch Off Delay
t-Off Delay
0
Operating Mode
Working current principle
Closed-circuit principle
>1
S1
1
R
1
&
=1
>1
=1
=1
=1
=1
=1
=1
=1
Inverting
Assignment 1
Inverting 1
Assignment 2
Inverting 2
Assignment 3
Inverting 3
Assignment 4
Inverting 4
Assignment 5
Inverting 5
Assignment 6
Inverting 6
Assignment 7
Inverting 7
Latched
inactive
active
≥1
Acknowledge -HMI
Acknowledge-1..n, Assignment List
Acknowledge-Scada

System Contact

The *System OK alarm relay (SC)* is the devices »LIFE CONTACT«. Its installation location depends on the housing type. Please refer to the wiring diagram of the device (WDC-contact).

The *System-OK relay (SC)* cannot be parameterized. The system contact is an operating current contact that picks-up, when the device is free from internal faults. While the device is booting up, the *System OK relay (SC)* remains dropped-off. As soon as the system was duly started up, the relay picks up and the assigned LED is activated accordingly (please refer to chapter Self Supervision).

OR-5 X

BO Slot X2

Direct Commands of OR-5 X

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
DISARMED	This is the second step, after the "DISARMED Ctrl" has been activated, that is required to DISARM the relay outputs. This will DISARM those output relays that are currently not latched and that are not on “hold” by a pending minimum hold time. CAUTION! RELAYS DISARMED in order to safely perform maintenance while eliminating the risk of taking an entire process off-line. (Note: Zone Interlocking and Supervision Contact cannot be disarmed). YOU MUST ENSURE that the relays are ARMED AGAIN after maintenance. Only available if: DISARMED Ctrl = active	inactive, active	inactive	[Service /Test (Prot inhibit) /DISARMED /BO Slot X2]
Force all Outs	By means of this function the normal Output Relay State can be overwritten (forced). The relay can be set from normal operation (relay works according to the assigned signals) to "force energized" or "force de-energized" state. Forcing all outputs relays of an entire assembly group is superior to forcing a single output relay.	Normal, De-Energized, Energized	Normal	[Service /Test (Prot inhibit) /Force OR /BO Slot X2]
Force OR1	By means of this function the normal Output Relay State can be overwritten (forced). The relay can be set from normal operation (relay works according to the assigned signals) to "force energized" or "force de-energized" state.	Normal, De-Energized, Energized	Normal	[Service /Test (Prot inhibit) /Force OR /BO Slot X2]
Force OR2	By means of this function the normal Output Relay State can be overwritten (forced). The relay can be set from normal operation (relay works according to the assigned signals) to "force energized" or "force de-energized" state.	Normal, De-Energized, Energized	Normal	[Service /Test (Prot inhibit) /Force OR /BO Slot X2]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Force OR3	By means of this function the normal Output Relay State can be overwritten (forced). The relay can be set from normal operation (relay works according to the assigned signals) to "force energized" or "force de-energized" state.	Normal, De-Energized, Energized	Normal	[Service /Test (Prot inhibit) /Force OR /BO Slot X2]
Force OR4	By means of this function the normal Output Relay State can be overwritten (forced). The relay can be set from normal operation (relay works according to the assigned signals) to "force energized" or "force de-energized" state.	Normal, De-Energized, Energized	Normal	[Service /Test (Prot inhibit) /Force OR /BO Slot X2]
Force OR5	By means of this function the normal Output Relay State can be overwritten (forced). The relay can be set from normal operation (relay works according to the assigned signals) to "force energized" or "force de-energized" state.	Normal, De-Energized, Energized	Normal	[Service /Test (Prot inhibit) /Force OR /BO Slot X2]

Device Parameters of the Binary Output Relays on OR-5 X

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Operating Mode	Operating Mode	Working current principle, Closed-circuit principle	Working current principle	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
t-hold	To clearly identify the state transition of a binary output relay, the "new state" is being hold, at least for the duration of the hold time.	0.00 - 300.00s	0.00s	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
t-Off Delay	Switch Off Delay	0.00 - 300.00s	0.00s	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Latched	Defines whether the Relay Output will be latched when it picks up.	inactive, active	active	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Acknowledgement	Acknowledgement Signal - An acknowledgement signal (that acknowledges the corresponding binary output relay) can be assigned to each output relay. The acknowledgement-signal is only effective if the parameter "Latched" is set to active. Only available if: Latched = active	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Inverting	Inverting of the collective signal (OR-gate/disjunction). In combination with inverted input signals an AND-gate can be programmed (Conjunction).	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Assignment 1	Assignment	1..n, Assignment List	SG[1].TripCmd	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Inverting 1	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 1]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Assignment 2	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Inverting 2	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Assignment 3	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Inverting 3	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Assignment 4	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Inverting 4	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Assignment 5	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Inverting 5	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Assignment 6	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 1]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Inverting 6	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Assignment 7	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Inverting 7	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Operating Mode	Operating Mode	Working current principle, Closed-circuit principle	Working current principle	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
t-hold	To clearly identify the state transition of a binary output relay, the "new state" is being hold, at least for the duration of the hold time.	0.00 - 300.00s	0.00s	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
t-Off Delay	Switch Off Delay	0.00 - 300.00s	0.00s	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Latched	Defines whether the Relay Output will be latched when it picks up.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Acknowledgement	Acknowledgement Signal - An acknowledgement signal (that acknowledges the corresponding binary output relay) can be assigned to each output relay. The acknowledgement-signal is only effective if the parameter "Latched" is set to active. Only available if: Latched = active	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Inverting	Inverting of the collective signal (OR-gate/disjunction). In combination with inverted input signals an AND-gate can be programmed (Conjunction).	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Assignment 1	Assignment	1..n, Assignment List	Prot.Alarm	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Inverting 1	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Assignment 2	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Inverting 2	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Assignment 3	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Inverting 3	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Assignment 4	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Inverting 4	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Assignment 5	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 2]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Inverting 5	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Assignment 6	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Inverting 6	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Assignment 7	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Inverting 7	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Operating Mode	Operating Mode	Working current principle, Closed-circuit principle	Working current principle	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
t-hold	To clearly identify the state transition of a binary output relay, the "new state" is being hold, at least for the duration of the hold time.	0.00 - 300.00s	0.00s	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
t-Off Delay	Switch Off Delay	0.00 - 300.00s	0.00s	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Latched	Defines whether the Relay Output will be latched when it picks up.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]

Parameter	Description	Setting range	Default	Menu path
Acknowledgement	Acknowledgement Signal - An acknowledgement signal (that acknowledges the corresponding binary output relay) can be assigned to each output relay. The acknowledgement-signal is only effective if the parameter "Latched" is set to active. Only available if: Latched = active	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Inverting	Inverting of the collective signal (OR-gate/disjunction). In combination with inverted input signals an AND-gate can be programmed (Conjunction).	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Assignment 1	Assignment	1..n, Assignment List	SG[1].ON Cmd	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Inverting 1	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Assignment 2	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Inverting 2	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Assignment 3	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Inverting 3	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Assignment 4	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 3]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Inverting 4	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Assignment 5	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Inverting 5	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Assignment 6	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Inverting 6	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Assignment 7	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Inverting 7	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Operating Mode	Operating Mode	Working current principle, Closed-circuit principle	Working current principle	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
t-hold	To clearly identify the state transition of a binary output relay, the "new state" is being hold, at least for the duration of the hold time.	0.00 - 300.00s	0.00s	[Device Para /Binary Outputs /BO Slot X2 /BO 4]

Parameter	Description	Setting range	Default	Menu path
t-Off Delay	Switch Off Delay	0.00 - 300.00s	0.00s	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
Latched	Defines whether the Relay Output will be latched when it picks up.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
Acknowledgement	Acknowledgement Signal - An acknowledgement signal (that acknowledges the corresponding binary output relay) can be assigned to each output relay. The acknowledgement-signal is only effective if the parameter "Latched" is set to active. Only available if: Latched = active	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
Inverting	Inverting of the collective signal (OR-gate/disjunction). In combination with inverted input signals an AND-gate can be programmed (Conjunction).	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
Assignment 1	Assignment	1..n, Assignment List	SG[1].OFF Cmd	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
Inverting 1	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
Assignment 2	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
Inverting 2	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
Assignment 3	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 4]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Inverting 3	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
Assignment 4	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
Inverting 4	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
Assignment 5	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
Inverting 5	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
Assignment 6	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
Inverting 6	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
Assignment 7	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
Inverting 7	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 4]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Operating Mode	Operating Mode	Working current principle, Closed-circuit principle	Working current principle	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
t-hold	To clearly identify the state transition of a binary output relay, the "new state" is being hold, at least for the duration of the hold time.	0.00 - 300.00s	0.00s	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
t-Off Delay	Switch Off Delay	0.00 - 300.00s	0.00s	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
Latched	Defines whether the Relay Output will be latched when it picks up.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
Acknowledgement	Acknowledgement Signal - An acknowledgement signal (that acknowledges the corresponding binary output relay) can be assigned to each output relay. The acknowledgement-signal is only effective if the parameter "Latched" is set to active. Only available if: Latched = active	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
Inverting	Inverting of the collective signal (OR-gate/disjunction). In combination with inverted input signals an AND-gate can be programmed (Conjunction).	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
Assignment 1	Assignment	1..n, Assignment List	MStart.Blo	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
Inverting 1	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
Assignment 2	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 5]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Inverting 2	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
Assignment 3	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
Inverting 3	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
Assignment 4	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
Inverting 4	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
Assignment 5	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
Inverting 5	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
Assignment 6	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
Inverting 6	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 5]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Assignment 7	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
Inverting 7	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
DISARMED Ctrl	Enables and disables the disarming of the relay outputs. This is the first step of a two step process, to inhibit the operation or the relay outputs. Please refer to "DISARMED" for the second step.	inactive, active	inactive	[Service /Test (Prot inhibit) /DISARMED /BO Slot X2]
Disarm Mode	CAUTION! RELAYS DISARMED in order to safely perform maintenance while eliminating the risk of taking an entire process off-line. (Note: The Supervision Contact cannot be disarmed). YOU MUST ENSURE that the relays are ARMED AGAIN after maintenance.	permanent, timeout	permanent	[Service /Test (Prot inhibit) /DISARMED /BO Slot X2]
t-Timeout DISARM	The relays will be armed again after expiring of this time. Only available if: Mode = Timeout DISARM	0.00 - 300.00s	0.03s	[Service /Test (Prot inhibit) /DISARMED /BO Slot X2]
Force Mode	By means of this function the normal Output Relay States can be overwritten (forced) in case that the Relay is not in a disarmed state. The relays can be set from normal operation (relay works according to the assigned signals) to "force energized" or "force de-energized" state.	permanent, timeout	permanent	[Service /Test (Prot inhibit) /Force OR /BO Slot X2]
t-Timeout Force	The Output State will be set by force for the duration of this time. That means for the duration of this time the Output Relay does not show the state of the signals that are assigned on it. Only available if: Mode = Timeout DISARM	0.00 - 300.00s	0.03s	[Service /Test (Prot inhibit) /Force OR /BO Slot X2]

Input States of the Binary Output Relays on OR-5 X

Name	*Description*	*Assignment via*
BO1.1	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
BO1.2	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
BO1.3	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
BO1.4	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
BO1.5	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
BO1.6	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
BO1.7	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Ack signal BO 1	Module input state: Acknowledgement signal for the binary output relay. If latching is set to active, the binary output relay can only be acknowledged if those signals that initiated the setting are fallen back and the hold time is expired.	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
BO2.1	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 2]

Name	*Description*	*Assignment via*
BO2.2	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
BO2.3	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
BO2.4	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
BO2.5	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
BO2.6	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
BO2.7	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Ack signal BO 2	Module input state: Acknowledgement signal for the binary output relay. If latching is set to active, the binary output relay can only be acknowledged if those signals that initiated the setting are fallen back and the hold time is expired.	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
BO3.1	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
BO3.2	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 3]

Name	*Description*	*Assignment via*
BO3.3	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
BO3.4	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
BO3.5	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
BO3.6	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
BO3.7	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Ack signal BO 3	Module input state: Acknowledgement signal for the binary output relay. If latching is set to active, the binary output relay can only be acknowledged if those signals that initiated the setting are fallen back and the hold time is expired.	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
BO4.1	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
BO4.2	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
BO4.3	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 4]

Name	*Description*	*Assignment via*
BO4.4	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
BO4.5	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
BO4.6	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
BO4.7	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
Ack signal BO 4	Module input state: Acknowledgement signal for the binary output relay. If latching is set to active, the binary output relay can only be acknowledged if those signals that initiated the setting are fallen back and the hold time is expired.	[Device Para /Binary Outputs /BO Slot X2 /BO 4]
BO5.1	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
BO5.2	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
BO5.3	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
BO5.4	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 5]

Name	*Description*	*Assignment via*
BO5.5	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
BO5.6	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
BO5.7	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 5]
Ack signal BO 5	Module input state: Acknowledgement signal for the binary output relay. If latching is set to active, the binary output relay can only be acknowledged if those signals that initiated the setting are fallen back and the hold time is expired.	[Device Para /Binary Outputs /BO Slot X2 /BO 5]

Signals of the Binary Output Relays on OR-5 X

Signal	*Description*
BO 1	Signal: Binary Output Relay
BO 2	Signal: Binary Output Relay
BO 3	Signal: Binary Output Relay
BO 4	Signal: Binary Output Relay
BO 5	Signal: Binary Output Relay
DISARMED!	Signal: CAUTION! RELAYS DISARMED in order to safely perform maintenance while eliminating the risk of taking an entire process off-line. (Note: The Self Supervision Contact cannot be disarmed). YOU MUST ENSURE that the relays are ARMED AGAIN after maintenance
Outs forced	Signal: The State of at least one Relay Output has been set by force. That means that the state of at least one Relay is forced and hence does not show the state of the assigned signals.

OR-3AI X

BO Slot X2

Direct Commands of OR- 3AI X

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
DISARMED	This is the second step, after the "DISARMED Ctrl" has been activated, that is required to DISARM the relay outputs. This will DISARM those output relays that are currently not latched and that are not on “hold” by a pending minimum hold time. CAUTION! RELAYS DISARMED in order to safely perform maintenance while eliminating the risk of taking an entire process off-line. (Note: Zone Interlocking and Supervision Contact cannot be disarmed). YOU MUST ENSURE that the relays are ARMED AGAIN after maintenance. Only available if: DISARMED Ctrl = active	inactive, active	inactive	[Service /Test (Prot inhibit) /DISARMED /BO Slot X2]
Force all Outs	By means of this function the normal Output Relay State can be overwritten (forced). The relay can be set from normal operation (relay works according to the assigned signals) to "force energized" or "force de-energized" state. Forcing all outputs relays of an entire assembly group is superior to forcing a single output relay.	Normal, De-Energized, Energized	Normal	[Service /Test (Prot inhibit) /Force OR /BO Slot X2]
Force OR1	By means of this function the normal Output Relay State can be overwritten (forced). The relay can be set from normal operation (relay works according to the assigned signals) to "force energized" or "force de-energized" state.	Normal, De-Energized, Energized	Normal	[Service /Test (Prot inhibit) /Force OR /BO Slot X2]
Force OR2	By means of this function the normal Output Relay State can be overwritten (forced). The relay can be set from normal operation (relay works according to the assigned signals) to "force energized" or "force de-energized" state.	Normal, De-Energized, Energized	Normal	[Service /Test (Prot inhibit) /Force OR /BO Slot X2]

Parameter	Description	Setting range	Default	Menu path
Force OR3	By means of this function the normal Output Relay State can be overwritten (forced). The relay can be set from normal operation (relay works according to the assigned signals) to "force energized" or "force de-energized" state.	Normal, De-Energized, Energized	Normal	[Service /Test (Prot inhibit) /Force OR /BO Slot X2]

Device Parameters of the Binary Output Relays on OR- 3AI X

Parameter	Description	Setting range	Default	Menu path
Operating Mode	Operating Mode	Working current principle, Closed-circuit principle	Working current principle	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
t-hold	To clearly identify the state transition of a binary output relay, the "new state" is being hold, at least for the duration of the hold time.	0.00 - 300.00s	0.00s	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
t-Off Delay	Switch Off Delay	0.00 - 300.00s	0.00s	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Latched	Defines whether the Relay Output will be latched when it picks up.	inactive, active	active	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Acknowledgement	Acknowledgement Signal - An acknowledgement signal (that acknowledges the corresponding binary output relay) can be assigned to each output relay. The acknowledgement-signal is only effective if the parameter "Latched" is set to active. Only available if: Latched = active	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Inverting	Inverting of the collective signal (OR-gate/disjunction). In combination with inverted input signals an AND-gate can be programmed (Conjunction).	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 1]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Assignment 1	Assignment	1..n, Assignment List	SG[1].TripCmd	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Inverting 1	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Assignment 2	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Inverting 2	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Assignment 3	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Inverting 3	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Assignment 4	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Inverting 4	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Assignment 5	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 1]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Inverting 5	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Assignment 6	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Inverting 6	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Assignment 7	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Inverting 7	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Operating Mode	Operating Mode	Working current principle, Closed-circuit principle	Working current principle	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
t-hold	To clearly identify the state transition of a binary output relay, the "new state" is being hold, at least for the duration of the hold time.	0.00 - 300.00s	0.00s	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
t-Off Delay	Switch Off Delay	0.00 - 300.00s	0.00s	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Latched	Defines whether the Relay Output will be latched when it picks up.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Acknowledgement	Acknowledgement Signal - An acknowledgement signal (that acknowledges the corresponding binary output relay) can be assigned to each output relay. The acknowledgement-signal is only effective if the parameter "Latched" is set to active. Only available if: Latched = active	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Inverting	Inverting of the collective signal (OR-gate/disjunction). In combination with inverted input signals an AND-gate can be programmed (Conjunction).	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Assignment 1	Assignment	1..n, Assignment List	SG[1].ON Cmd	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Inverting 1	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Assignment 2	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Inverting 2	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Assignment 3	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Inverting 3	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Assignment 4	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 2]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Inverting 4	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Assignment 5	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Inverting 5	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Assignment 6	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Inverting 6	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Assignment 7	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Inverting 7	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Operating Mode	Operating Mode	Working current principle, Closed-circuit principle	Working current principle	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
t-hold	To clearly identify the state transition of a binary output relay, the "new state" is being hold, at least for the duration of the hold time.	0.00 - 300.00s	0.00s	[Device Para /Binary Outputs /BO Slot X2 /BO 3]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
t-Off Delay	Switch Off Delay	0.00 - 300.00s	0.00s	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Latched	Defines whether the Relay Output will be latched when it picks up.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Acknowledgement	Acknowledgement Signal - An acknowledgement signal (that acknowledges the corresponding binary output relay) can be assigned to each output relay. The acknowledgement-signal is only effective if the parameter "Latched" is set to active. Only available if: Latched = active	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Inverting	Inverting of the collective signal (OR-gate/disjunction). In combination with inverted input signals an AND-gate can be programmed (Conjunction).	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Assignment 1	Assignment	1..n, Assignment List	SG[1].OFF Cmd	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Inverting 1	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Assignment 2	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Inverting 2	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Assignment 3	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 3]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Inverting 3	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Assignment 4	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Inverting 4	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Assignment 5	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Inverting 5	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Assignment 6	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Inverting 6	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Assignment 7	Assignment	1..n, Assignment List	-.-	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Inverting 7	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /Binary Outputs /BO Slot X2 /BO 3]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
DISARMED Ctrl	Enables and disables the disarming of the relay outputs. This is the first step of a two step process, to inhibit the operation or the relay outputs. Please refer to "DISARMED" for the second step.	inactive, active	inactive	[Service /Test (Prot inhibit) /DISARMED /BO Slot X2]
Disarm Mode	CAUTION! RELAYS DISARMED in order to safely perform maintenance while eliminating the risk of taking an entire process off-line. (Note: The Supervision Contact cannot be disarmed). YOU MUST ENSURE that the relays are ARMED AGAIN after maintenance.	permanent, timeout	permanent	[Service /Test (Prot inhibit) /DISARMED /BO Slot X2]
t-Timeout DISARM	The relays will be armed again after expiring of this time. Only available if: Mode = Timeout DISARM	0.00 - 300.00s	0.03s	[Service /Test (Prot inhibit) /DISARMED /BO Slot X2]
Force Mode	By means of this function the normal Output Relay States can be overwritten (forced) in case that the Relay is not in a disarmed state. The relays can be set from normal operation (relay works according to the assigned signals) to "force energized" or "force de-energized" state.	permanent, timeout	permanent	[Service /Test (Prot inhibit) /Force OR /BO Slot X2]
t-Timeout Force	The Output State will be set by force for the duration of this time. That means for the duration of this time the Output Relay does not show the state of the signals that are assigned on it. Only available if: Mode = Timeout DISARM	0.00 - 300.00s	0.03s	[Service /Test (Prot inhibit) /Force OR /BO Slot X2]

Input States of the Binary Output Relays on OR- 3AI X

Name	*Description*	*Assignment via*
BO1.1	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
BO1.2	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
BO1.3	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
BO1.4	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
BO1.5	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
BO1.6	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
BO1.7	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
Ack signal BO 1	Module input state: Acknowledgement signal for the binary output relay. If latching is set to active, the binary output relay can only be acknowledged if those signals that initiated the setting are fallen back and the hold time is expired.	[Device Para /Binary Outputs /BO Slot X2 /BO 1]
BO2.1	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 2]

Name	*Description*	*Assignment via*
BO2.2	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
BO2.3	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
BO2.4	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
BO2.5	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
BO2.6	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
BO2.7	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
Ack signal BO 2	Module input state: Acknowledgement signal for the binary output relay. If latching is set to active, the binary output relay can only be acknowledged if those signals that initiated the setting are fallen back and the hold time is expired.	[Device Para /Binary Outputs /BO Slot X2 /BO 2]
BO3.1	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
BO3.2	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 3]

Name	*Description*	*Assignment via*
BO3.3	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
BO3.4	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
BO3.5	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
BO3.6	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
BO3.7	Module input state: Assignment	[Device Para /Binary Outputs /BO Slot X2 /BO 3]
Ack signal BO 3	Module input state: Acknowledgement signal for the binary output relay. If latching is set to active, the binary output relay can only be acknowledged if those signals that initiated the setting are fallen back and the hold time is expired.	[Device Para /Binary Outputs /BO Slot X2 /BO 3]

Signals of the Binary Output Relays on OR- 3AI X

Signal	*Description*
BO 1	Signal: Binary Output Relay
BO 2	Signal: Binary Output Relay
BO 3	Signal: Binary Output Relay
DISARMED!	Signal: CAUTION! RELAYS DISARMED in order to safely perform maintenance while eliminating the risk of taking an entire process off-line. (Note: The Self Supervision Contact cannot be disarmed). YOU MUST ENSURE that the relays are ARMED AGAIN after maintenance
Outs forced	Signal: The State of at least one Relay Output has been set by force. That means that the state of at least one Relay is forced and hence does not show the state of the assigned signals.

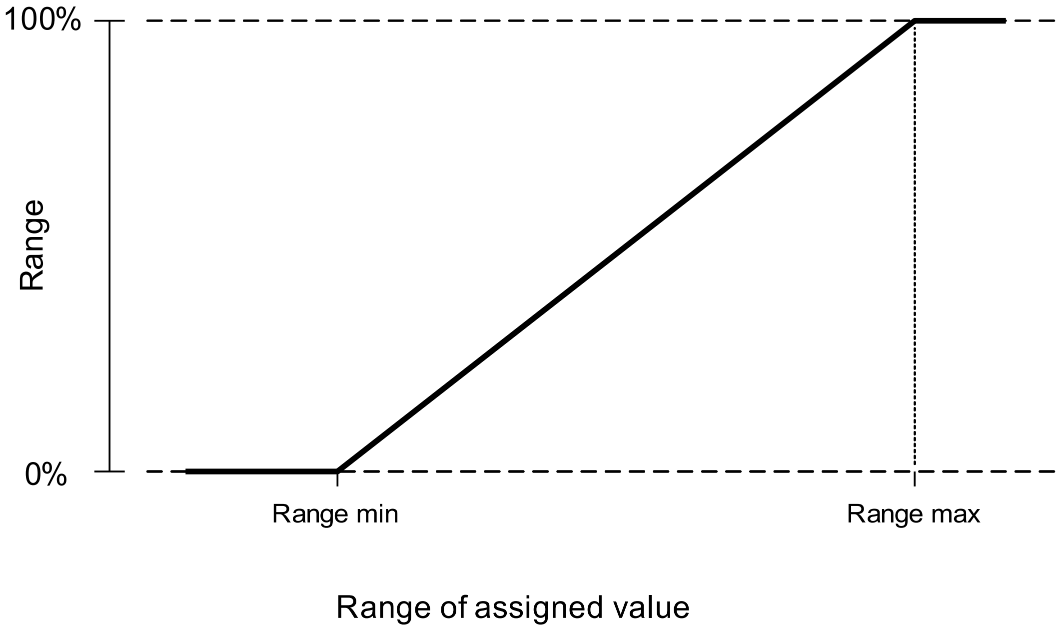
Configuration of the Analog Outputs

Available Elements:
AnOut[1]

The Analog Outputs can be programmed to output for three different ranges of either »*0- 20mA«*, »*4- 20 mA«*, or »*0-10 Volts«*.

These outputs can be configured by the User to represent the status of User programmed parameters that are available from the relay. The User will find the configuration menu for this feature under the [Device Para/ Analog Outputs] menu option. Here the User can define to which parameter the output will correlate.

Once the assignment has been made, the User can select the expected range of the parameter that will correlate to the analog output. The User will be required to enter a »*Range min«*, and »*Range max«*. The »*Range min«* will determine the value at which value the transmission will start. Likewise, the »*Range max«* value will determine the value that will result in the end value of the transmission.



Setting Example: Analog Output with Active Power P*

*=only available in Devices that offer Power Protection

All settings/thresholds within the power module are to be set as per unit thresholds. Per definition S_n is to be used as scale basis.

$S_n=\sqrt{3} * VoltageTransformer_{Line\text{-}to\text{-}Line\_Rated\_Voltage} * CurrentTransformer_{Rated\_Current}$

If thresholds should base on primary side values:

$S_n=\sqrt{3} * VoltageTransformer_{Pri\_Line\text{-}to\text{-}Line\_Rated\_Voltage} * CurrentTransformer_{Pri\_Rated\_Current}$

If thresholds should base on secondary side values

$S_n=\sqrt{3} * VoltageTransformer_{Sec\_Line\text{-}to\text{-}Line\_Rated\_Voltage} * CurrentTransformer_{Sec\_Rated\_Current}$

Example – Field Data

- CurrentTransformer CT pri =200 A; CT sec = 5 A
- VoltageTransformer VT pri = 10 kV; VT sec =100 V
- Active power range 1 MW to 4 MW is mapped to an Analog Outputs 0% to 100%.

Calculating setting for Range min and Range max based on primary side values

Active power range is 1 MW to 4 MW.

First S_n is to be calculated:

$S_n = \sqrt{3} * VoltageTransformer_{Pri\_Line-to-Line\_Rated\_Voltage} * CurrentTransformer_{Pri\_Rated\_Current}$

S_n= 1.73 * 10000 V * 200 A = 3.464 MVA

Calculating the range settings based to S_n :

Range min (0%) = 1 MW/ 3.464 MVA = 0.29 S_n
Range max (100%) = 4 MW/ 3.464 MVA = 1.15 S_n

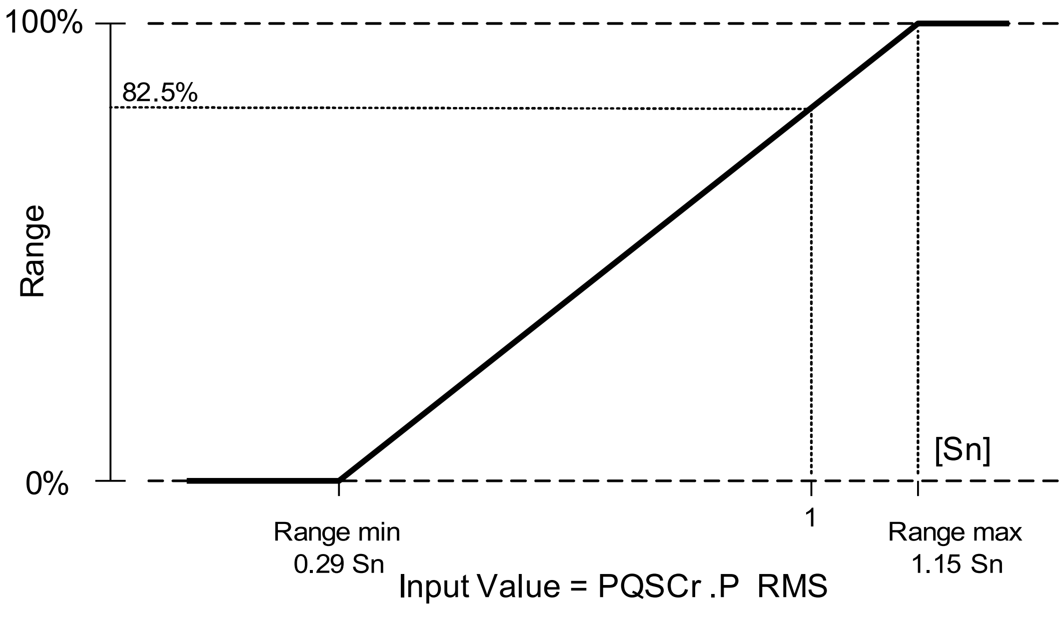
Calculate the Analog Output percentage for specific value:

AnalogOutput (InputValue) = 100% / (Range max – Range min) * (InputValue – Range min)

For e.g. Input value 1 S_n :

AnalogOutput(1 Sn) = 100% / 0.86 S_n * (1 S_n – 0.29 S_n) = 82.5%

The Output current for e.g. 4...20mA type is then 17.7 mA = 4mA + 82.5% * (20mA – 4mA)



Setting Example: Analog Output with Power Factor PF*

*=only available in Devices that offer Power Protection

Since the sign of Power Factor PF follows the sign of Active Power P, there is no distinguish between capacitive and inductive Reactive Power. Hence, for Analog Output assignment the setting for PF output range uses a Power Factor with a “Sign Convention”:

a positive sign (+) PF, if Active and Reactive Power has same sign
a negative sign (-) PF, if Active and Reactive Power has different sign

For e.g. if Active Power is flowing into the load and Current lags the voltage for a inductive load, PF with sign convention uses a positive sign. This is important to set the right range settings for Analog Ouput.

Use case for analog instrument with 4...20mA with linear scale, where scale is in range from 0.8 capacitive to 0.3 inductive, following setting should be uses:

Range min (0%) = -0.8
Range max (100%) = +0.3

Calculate the Analog Output percentage for specific value for e.g. unitiy: |PF|=1 at phi = 0°:

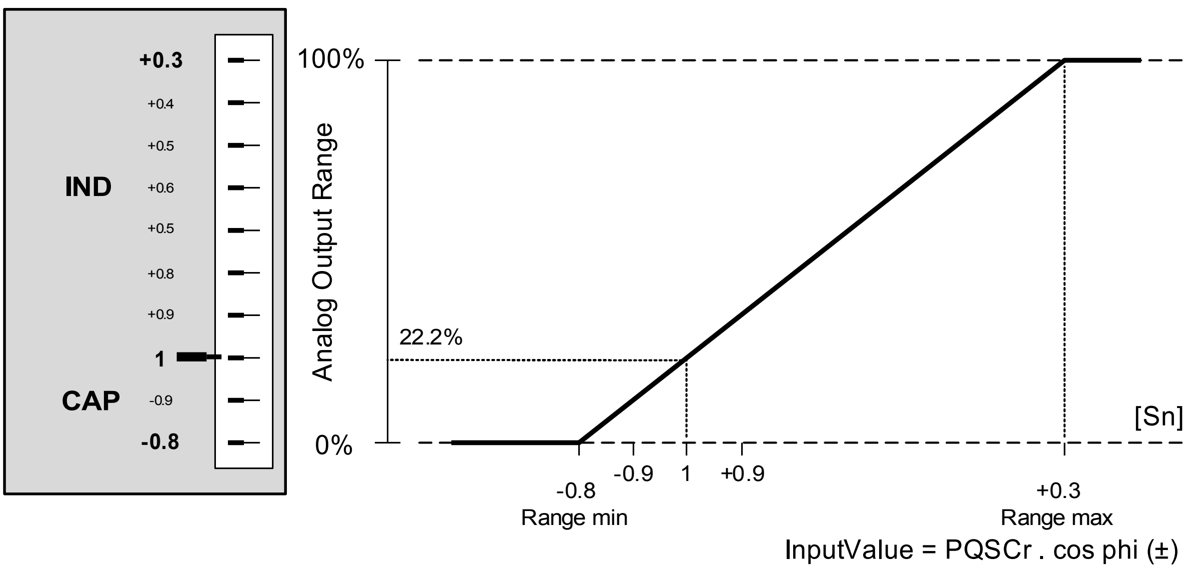
First the signed PF needs to be converted into a linear range:

Range min' (0%) = -1 – (-0.8) = -0.2
Range max' (100%) = +1 – (+0.3) = +0.7
InputValue' = +1 – (+1) = 0.0

AnalogOutput (InputValue') = 100% / (Range max' – Range min') * (InputValue' – Range min')

AnalogOutput(0) = 100% / 0.9 * 0.2 = 22.2%

The Output current for e.g. 4...20mA type is then 7.5 mA = 4mA + 22.2% * (20mA – 4mA)



Global Protection Parameters of the Analog Outputs

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Assignment	Assignment	1..n, AnalogOutputList	-.-	[Device Para /Analog Outputs /AnOut[1]]
Range	Adjustable range	0...20mA, 4...20mA	0...20mA	[Device Para /Analog Outputs /AnOut[1]]
Range max	Adjustable range maximum.	-999999.00 - 999999.00°C	1.00°C	[Device Para /Analog Outputs /AnOut[1]]
Range min	Adjustable range minimum.	-999999.00 - 999999.00°C	0.00°C	[Device Para /Analog Outputs /AnOut[1]]
Force Mode	For commissioning purposes or for maintenance, Analog Outputs can be set by force. By means of this function the normal Analog Outputs can be overwritten (forced).	permanent, timeout	permanent	[Service /Test (Prot inhibit) /Analog Outputs /AnOut[1]]
t-Timeout Force	The Analog Output Value will be set by force for the duration of this time. That means for the duration of this time the Analog Output does not show the value of the signals that are assigned on it. Only available if: Force Mode = active	0.00 - 300.00s	0.03s	[Service /Test (Prot inhibit) /Analog Outputs /AnOut[1]]

Direct Commands of the Analog Outputs

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[Service /Test (Prot inhibit) /Analog Outputs /AnOut[1]]
Force Value	By means of this function the Analog Output Value can be overwritten (forced).	0.00 - 100.00%	0%	[Service /Test (Prot inhibit) /Analog Outputs /AnOut[1]]

Signals of the Analog Outputs

Signal	*Description*
Force Mode	For commissioning purposes or for maintenance, Analog Outputs can be set by force. By means of this function the normal Analog Outputs can be overwritten (forced).

List of the Analog Outputs

Name	*Description*
-.-	No assignment
CT.IL1 RMS	Measured value: Phase current (RMS)
CT.IL2 RMS	Measured value: Phase current (RMS)
CT.IL3 RMS	Measured value: Phase current (RMS)
CT.IG meas RMS	Measured value (measured): IG (RMS)
CT.IG calc RMS	Measured value (calculated): IG (RMS)
CT.I1	Measured value (calculated): Positive phase sequence current (fundamental)
CT.I2	Measured value (calculated): Unbalanced load current (fundamental)
CT.%IL1 THD	Measured value (calculated): IL1 Total Harmonic Distortion
CT.%IL2 THD	Measured value (calculated): IL2 Total Harmonic Distortion
CT.%IL3 THD	Measured value (calculated): IL3 Total Harmonic Distortion
CT.IL1 THD	Measured value (calculated): IL1 Total Harmonic Current
CT.IL2 THD	Measured value (calculated): IL2 Total Harmonic Current
CT.IL3 THD	Measured value (calculated): IL3 Total Harmonic Current
MStart.IL1 Ib	Measured value: Phase current as multiple of Ib
MStart.IL2 Ib	Measured value: Phase current as multiple of Ib
MStart.IL3 Ib	Measured value: Phase current as multiple of Ib
MStart.I3 P (%Ib) avg	Average RMS current of all 3 phases as percentages of Ib
MStart.I3P Fla Demand	RMS current of all 3 phases calculated in a fixed demand window as percentages of Ib
ThR.I2T Used	Thermal capacity used.
ThR.I2T Remained	Thermal capacity remained.
URTD.Windg1	Winding 1
URTD.Windg2	Winding 2
URTD.Windg3	Winding 3
URTD.Windg4	Winding 4
URTD.Windg5	Winding 5
URTD.Windg6	Winding 6
URTD.MotBear1	Motor Bearing 1
URTD.MotBear2	Motor Bearing 2
URTD.LoadBear1	Load Bearing 1
URTD.LoadBear2	Load Bearing 2
URTD.Aux1	Auxiliary1
URTD.Aux2	Auxiliary2
URTD.RTD Max	Maximum temperature of all channels.
RTD.HottestWindingTemp	Hottest motor winding temperature in degrees C.
RTD.Hottest MotBearTemp	Hottest motor bearing temperature in degrees C.

Global Protection Parameters of the LED Module

LEDs group A

Parameter	Description	Setting range	Default	Menu path
Latched	Defines whether the LED will be latched when it picks up.	inactive, active, active, ack. by alarm	active	[Device Para /LEDs /LED 1]
Ack signal	Acknowledgement signal for the LED. If latching is set to active the LED can only be acknowledged if those signals that initiated the setting are no longer present. Dependency Only available if: Latched = active	1..n, Assignment List	-.-	[Device Para /LEDs /LED 1]
LED active color	The LED lights up in this color if the state of the OR-assignment of the signals is true.	green, red, red flash, green flash, -	red	[Device Para /LEDs /LED 1]
LED inactive color	The LED lights up in this color if the state of the OR-assignment of the signals is untrue.	green, red, red flash, green flash, -	-	[Device Para /LEDs /LED 1]
Assignment 1	Assignment	1..n, Assignment List	SG[1].TripCmd	[Device Para /LEDs /LED 1]
Inverting 1	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 1]
Assignment 2	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 1]
Inverting 2	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 1]
Assignment 3	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 1]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Inverting 3	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 1]
Assignment 4	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 1]
Inverting 4	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 1]
Assignment 5	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 1]
Inverting 5	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 1]
Latched	Defines whether the LED will be latched when it picks up.	inactive, active, active, ack. by alarm	active	[Device Para /LEDs /LED 2]
Ack signal	Acknowledgement signal for the LED. If latching is set to active the LED can only be acknowledged if those signals that initiated the setting are no longer present. Only available if: Latched = active	1..n, Assignment List	-.-	[Device Para /LEDs /LED 2]
LED active color	The LED lights up in this color if the state of the OR-assignment of the signals is true.	green, red, red flash, green flash, -	red	[Device Para /LEDs /LED 2]
LED inactive color	The LED lights up in this color if the state of the OR-assignment of the signals is untrue.	green, red, red flash, green flash, -	-	[Device Para /LEDs /LED 2]
Assignment 1	Assignment	1..n, Assignment List	Prot.Alarm	[Device Para /LEDs /LED 2]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Inverting 1	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 2]
Assignment 2	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 2]
Inverting 2	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 2]
Assignment 3	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 2]
Inverting 3	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 2]
Assignment 4	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 2]
Inverting 4	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 2]
Assignment 5	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 2]
Inverting 5	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 2]
Latched	Defines whether the LED will be latched when it picks up.	inactive, active, active, ack. by alarm	active	[Device Para /LEDs /LED 3]
Ack signal	Acknowledgement signal for the LED. If latching is set to active the LED can only be acknowledged if those signals that initiated the setting are no longer present. Only available if: Latched = active	1..n, Assignment List	-.-	[Device Para /LEDs /LED 3]

Parameter	Description	Setting range	Default	Menu path
LED active color	The LED lights up in this color if the state of the OR-assignment of the signals is true.	green, red, red flash, green flash, -	red	[Device Para /LEDs /LED 3]
LED inactive color	The LED lights up in this color if the state of the OR-assignment of the signals is untrue.	green, red, red flash, green flash, -	-	[Device Para /LEDs /LED 3]
Assignment 1	Assignment	1..n, Assignment List	ThR.Alarm	[Device Para /LEDs /LED 3]
Inverting 1	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 3]
Assignment 2	Assignment	1..n, Assignment List	I[1].Alarm	[Device Para /LEDs /LED 3]
Inverting 2	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 3]
Assignment 3	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 3]
Inverting 3	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 3]
Assignment 4	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 3]
Inverting 4	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 3]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Assignment 5	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 3]
Inverting 5	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 3]
Latched	Defines whether the LED will be latched when it picks up.	inactive, active, active, ack. by alarm	active	[Device Para /LEDs /LED 4]
Ack signal	Acknowledgement signal for the LED. If latching is set to active the LED can only be acknowledged if those signals that initiated the setting are no longer present. Only available if: Latched = active	1..n, Assignment List	-.-	[Device Para /LEDs /LED 4]
LED active color	The LED lights up in this color if the state of the OR-assignment of the signals is true.	green, red, red flash, green flash, -	red	[Device Para /LEDs /LED 4]
LED inactive color	The LED lights up in this color if the state of the OR-assignment of the signals is untrue.	green, red, red flash, green flash, -	-	[Device Para /LEDs /LED 4]
Assignment 1	Assignment	1..n, Assignment List	MStart.Blo	[Device Para /LEDs /LED 4]
Inverting 1	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 4]
Assignment 2	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 4]
Inverting 2	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 4]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Assignment 3	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 4]
Inverting 3	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 4]
Assignment 4	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 4]
Inverting 4	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 4]
Assignment 5	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 4]
Inverting 5	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 4]
Latched	Defines whether the LED will be latched when it picks up.	inactive, active, active, ack. by alarm	inactive	[Device Para /LEDs /LED 5]
Ack signal	Acknowledgement signal for the LED. If latching is set to active the LED can only be acknowledged if those signals that initiated the setting are no longer present. Only available if: Latched = active	1..n, Assignment List	-.-	[Device Para /LEDs /LED 5]
LED active color	The LED lights up in this color if the state of the OR-assignment of the signals is true.	green, red, red flash, green flash, -	red flash	[Device Para /LEDs /LED 5]
LED inactive color	The LED lights up in this color if the state of the OR-assignment of the signals is untrue.	green, red, red flash, green flash, -	-	[Device Para /LEDs /LED 5]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Assignment 1	Assignment	1..n, Assignment List	MStart.Start	[Device Para /LEDs /LED 5]
Inverting 1	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 5]
Assignment 2	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 5]
Inverting 2	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 5]
Assignment 3	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 5]
Inverting 3	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 5]
Assignment 4	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 5]
Inverting 4	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 5]
Assignment 5	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 5]
Inverting 5	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 5]
Latched	Defines whether the LED will be latched when it picks up.	inactive, active, active, ack. by alarm	inactive	[Device Para /LEDs /LED 6]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Ack signal	Acknowledgement signal for the LED. If latching is set to active the LED can only be acknowledged if those signals that initiated the setting are no longer present. Only available if: Latched = active	1..n, Assignment List	-.-	[Device Para /LEDs /LED 6]
LED active color	The LED lights up in this color if the state of the OR-assignment of the signals is true.	green, red, red flash, green flash, -	red	[Device Para /LEDs /LED 6]
LED inactive color	The LED lights up in this color if the state of the OR-assignment of the signals is untrue.	green, red, red flash, green flash, -	-	[Device Para /LEDs /LED 6]
Assignment 1	Assignment	1..n, Assignment List	MStart.Run	[Device Para /LEDs /LED 6]
Inverting 1	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 6]
Assignment 2	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 6]
Inverting 2	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 6]
Assignment 3	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 6]
Inverting 3	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 6]
Assignment 4	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 6]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Inverting 4	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 6]
Assignment 5	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 6]
Inverting 5	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 6]
Latched	Defines whether the LED will be latched when it picks up.	inactive, active, active, ack. by alarm	inactive	[Device Para /LEDs /LED 7]
Ack signal	Acknowledgement signal for the LED. If latching is set to active the LED can only be acknowledged if those signals that initiated the setting are no longer present. Only available if: Latched = active	1..n, Assignment List	-.-	[Device Para /LEDs /LED 7]
LED active color	The LED lights up in this color if the state of the OR-assignment of the signals is true.	green, red, red flash, green flash, -	green	[Device Para /LEDs /LED 7]
LED inactive color	The LED lights up in this color if the state of the OR-assignment of the signals is untrue.	green, red, red flash, green flash, -	-	[Device Para /LEDs /LED 7]
Assignment 1	Assignment	1..n, Assignment List	MStart.Stop	[Device Para /LEDs /LED 7]
Inverting 1	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 7]
Assignment 2	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 7]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Inverting 2	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 7]
Assignment 3	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 7]
Inverting 3	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 7]
Assignment 4	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 7]
Inverting 4	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 7]
Assignment 5	Assignment	1..n, Assignment List	-.-	[Device Para /LEDs /LED 7]
Inverting 5	Inverting of the state of the assigned signal.	inactive, active	inactive	[Device Para /LEDs /LED 7]

LED Module Input States

Name	*Description*	*Assignment via*
LED1.1	Module input state: LED	[Device Para /LEDs /LED 1]
LED1.2	Module input state: LED	[Device Para /LEDs /LED 1]
LED1.3	Module input state: LED	[Device Para /LEDs /LED 1]
LED1.4	Module input state: LED	[Device Para /LEDs /LED 1]
LED1.5	Module input state: LED	[Device Para /LEDs /LED 1]
Acknow Sig 1	Module input state: Acknowledgement Signal (only for automatic acknowledgement)	[Device Para /LEDs /LED 1]
LED2.1	Module input state: LED	[Device Para /LEDs /LED 2]
LED2.2	Module input state: LED	[Device Para /LEDs /LED 2]
LED2.3	Module input state: LED	[Device Para /LEDs /LED 2]
LED2.4	Module input state: LED	[Device Para /LEDs /LED 2]
LED2.5	Module input state: LED	[Device Para /LEDs /LED 2]
Acknow Sig 2	Module input state: Acknowledgement Signal (only for automatic acknowledgement)	[Device Para /LEDs /LED 2]

Name	*Description*	*Assignment via*
LED3.1	Module input state: LED	[Device Para /LEDs /LED 3]
LED3.2	Module input state: LED	[Device Para /LEDs /LED 3]
LED3.3	Module input state: LED	[Device Para /LEDs /LED 3]
LED3.4	Module input state: LED	[Device Para /LEDs /LED 3]
LED3.5	Module input state: LED	[Device Para /LEDs /LED 3]
Acknow Sig 3	Module input state: Acknowledgement Signal (only for automatic acknowledgement)	[Device Para /LEDs /LED 3]
LED4.1	Module input state: LED	[Device Para /LEDs /LED 4]
LED4.2	Module input state: LED	[Device Para /LEDs /LED 4]
LED4.3	Module input state: LED	[Device Para /LEDs /LED 4]
LED4.4	Module input state: LED	[Device Para /LEDs /LED 4]
LED4.5	Module input state: LED	[Device Para /LEDs /LED 4]
Acknow Sig 4	Module input state: Acknowledgement Signal (only for automatic acknowledgement)	[Device Para /LEDs /LED 4]
LED5.1	Module input state: LED	[Device Para /LEDs /LED 5]

Name	*Description*	*Assignment via*
LED5.2	Module input state: LED	[Device Para /LEDs /LED 5]
LED5.3	Module input state: LED	[Device Para /LEDs /LED 5]
LED5.4	Module input state: LED	[Device Para /LEDs /LED 5]
LED5.5	Module input state: LED	[Device Para /LEDs /LED 5]
Acknow Sig 5	Module input state: Acknowledgement Signal (only for automatic acknowledgement)	[Device Para /LEDs /LED 5]
LED6.1	Module input state: LED	[Device Para /LEDs /LED 6]
LED6.2	Module input state: LED	[Device Para /LEDs /LED 6]
LED6.3	Module input state: LED	[Device Para /LEDs /LED 6]
LED6.4	Module input state: LED	[Device Para /LEDs /LED 6]
LED6.5	Module input state: LED	[Device Para /LEDs /LED 6]
Acknow Sig 6	Module input state: Acknowledgement Signal (only for automatic acknowledgement)	[Device Para /LEDs /LED 6]
LED7.1	Module input state: LED	[Device Para /LEDs /LED 7]
LED7.2	Module input state: LED	[Device Para /LEDs /LED 7]

Name	*Description*	*Assignment via*
LED7.3	Module input state: LED	[Device Para /LEDs /LED 7]
LED7.4	Module input state: LED	[Device Para /LEDs /LED 7]
LED7.5	Module input state: LED	[Device Para /LEDs /LED 7]
Acknow Sig 7	Module input state: Acknowledgement Signal (only for automatic acknowledgement)	[Device Para /LEDs /LED 7]

LED configuration

The LEDs can be configured within menu:

[Device Para/LEDs/Group X]

CAUTION **Attention must be paid that there are no overlapping functions due to double or multiple LED assignment of colors and flashing codes.**

CAUTION **If LEDs are parameterized »Latched=*active*«, they will keep (return into) their blink code/color even if there is a break within the power supply.**

If LEDs are parameterized »Latched=*active*«, The LED blink code will also retain, if the LED is reprogrammed in another way. This applies also if »Latched is set to ina*ctive*«. Resetting a LED that has latched a signal will always require an acknowledgement.

NOTICE **This chapter contains information on the LEDs that are placed on the left hand of the display (group A).**

If your device is also equipped with LEDs on the right hand of the display (group B), the information in this chapter is valid analog. The only difference is "group A" and "group B" within the menu paths.

Via push button »INFO« it is always possible to display the current alarms/alarm texts that are assigned to an LED. Please refer to chapter *Navigation* (description of the »INFO-key«).

Set the following parameters for each LED:

- *»Latching/self holding function«*: If *»Latching«* is set to *»active«*, the state that is set by the alarms will be stored. If latching *»Latching« is set to »inactive«*, the LED always adopts the state of those alarms that were assigned.
- *»Acknowledgment«* (signal from the »assignment list«)
- *»LED active color«*, LED lights up in this color in case that at least one of the allocated functions is valid (red, red flashing, green, green flashing, off).
- *»LED inactive color«*, LED lights up in this color in case that none of the allocated functions is valid (red, red flashing, green, green flashing, off).
- Apart from the *LED for System OK*, each LED can be assigned up to five functions/alarms out of the »assignment list«.
- *»Inverting«* (of the signals), if necessary.

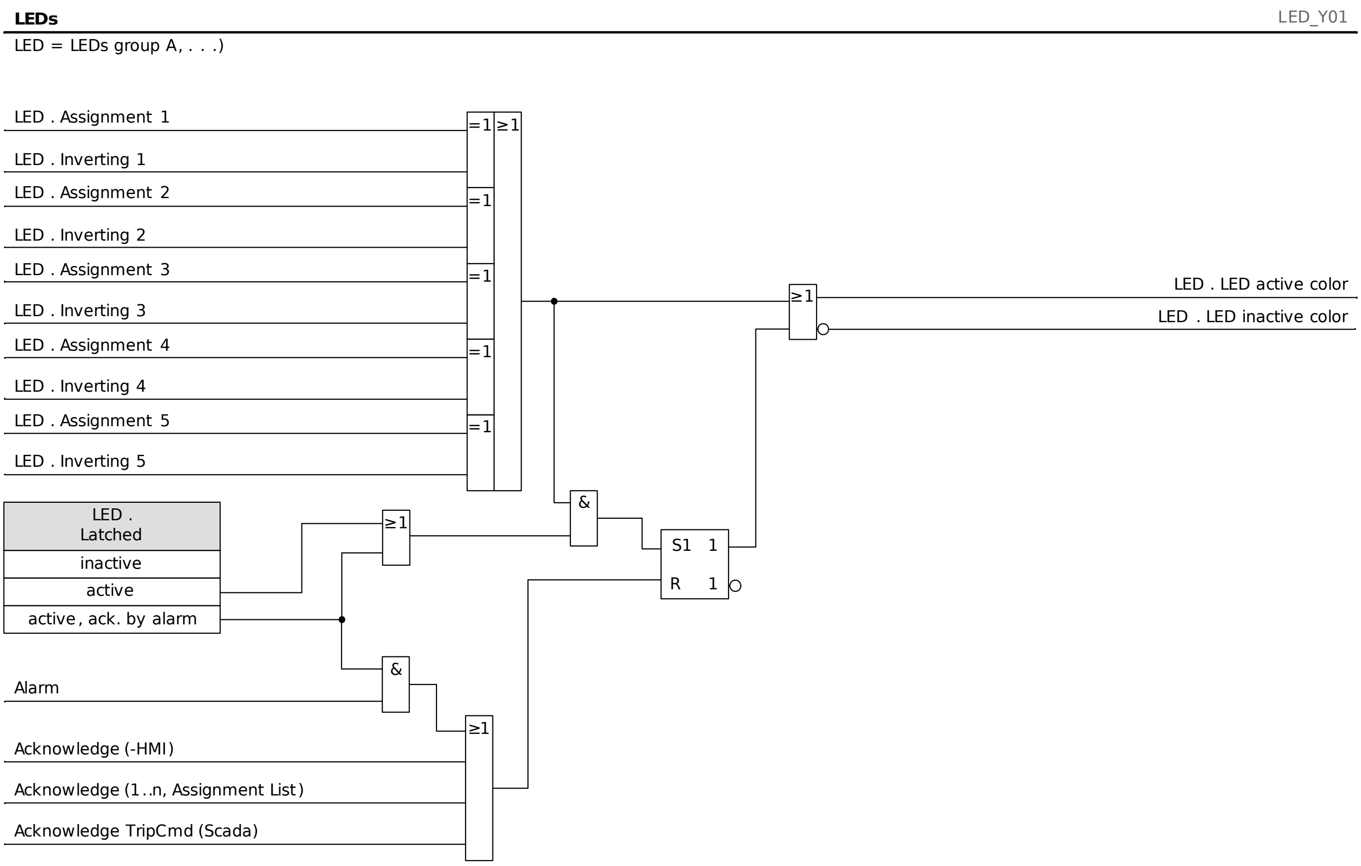
Acknowledgment options

LEDs can be acknowledged by:

- Via the push-button »C« at the operating panel.
- Each LED can be acknowledged by a signal of the »assignment list« (If »*Latched = active*«).
- Via the module »Ex Acknowledge« all LEDs can be acknowledged at once, if the signal for external acknowledgment that was selected from the »assignment list« becomes true (e.g. the state of a digital input).
- Via SCADA, all LEDs can be acknowledged at once.
- Automatically in case of an alarm from a protection function.
  The automatic acknowledgment must be activated by setting:
  [Device Para / LEDs / LEDs group A / LED 1...n] *»Latched«* = "active, ack. by pickup"

See also Chapter "Acknowledgments" for more information.

NOTICE **The Product-CD that is delivered with the device contains a PDF-Template in order to create and print out self adhesive films for LED assignment texts (front foil) by means of a laser printer. Recommendation: (AVERY Zweckform Art.Nr.3482)**



The »System OK« LED

This LED flashes green while the device is booting. After completed booting, the LED for *System OK* lights up in green thus signalizing that the *protection* (function) is »*activated*«. Please refer to chapter ”Self-Supervision” and to the external document ”*Troubleshooting Guide"* to find out further information on blink codes of the *System OK LED*

LED System OK cannot be parameterized.

Security

CAUTION

All security settings have to be made by the user of the device!
It is strictly recommended that you adapt the security settings according to the local regulations and requirements at the end of the commissioning procedure.

The device is delivered with maximum “open” settings, i. e. all access restrictions are deactivated. This way the commissioning is not complicated unnecessarily. But afterwards, when the device is running, it is probably required to restrict the access to some extent. There are in particular the following two aspects to consider:

CAUTION

It is strictly recommended to define passwords different from the default ones. (The default password “1234” does not provide any security against unauthorized access.)

It is recommended to define (as part of the overall security concept) the rules and restrictions for accessing the device via the operating software *Smart view*.

It is recommended to define different, level-specific passwords for the different access areas / levels. This way it is possible to make sure that different user groups get their individual access permissions.

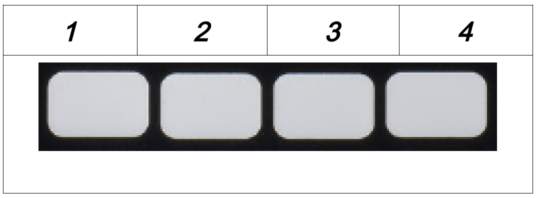
By default, all kinds of *Smart view* access to the device are permitted. Note, however, that it can be required for security reasons to block (or at least restrict) the access after commissioning (e. g. block the TCP/IP access over the network).

Access Authorizations (access areas)

Password Handling

Password Entry at the Panel

Passwords can be entered by way of the Softkeys.



Example: For password (3244) press successively:

- Softkey 3
- Softkey 2
- Softkey 4
- Softkey 4

Changing Passwords

Passwords can be changed at the device in menu [Device Para/Passwords] or by means of the *Smart view* software.

NOTICE **A password must be a user-defined combination of the numerics 1, 2, 3 and 4. All other characters and keys won't be accepted.**

When you want to change a password, the existing one has to be entered firstly. The new password (up to 8 digits) is then to be confirmed twice. Please proceed as follows:

- In order to change the password please enter your old password by means of the Softkeys followed by pressing the »OK«-key.
- Enter the new password by means of the Softkeys and press the »OK«-key.
- Afterwards enter the new password once again by means of the Softkeys and press the »OK«-key.

Acknowledge without Entering a Password

If there is the need to be able to acknowledge without entering any password set an empty password for the level »Prot-Lv1«. For general information about acknowledgments see Chapter “Acknowledgments“. Information about access areas / levels can be found below („Passwords – Areas”).

Deactivating Passwords during Commissioning

It is possible optionally to deactivate passwords during commissioning. It is not allowed to use this feature for other purposes than commissioning. In order to deactivate the password protection replace the existing password with an empty one for the corresponding access areas. All access authorizations (access areas) that are protected by an empty password are unlocked permanently. That means, that all parameters and settings within those areas can be modified without any further access authorization. It is no longer possible to change into the »*Read Only-Lv0*« level (the protective device will also not fall back into this mode if the maximum edit time is expired (t-max-Edit).

CAUTION

You have to ensure that all passwords are activated again after the commissioning. That means, that all access areas have to be protected by a password that consists of 4 digits as minimum.

Woodward will not take over any liability for any personal injuries or damages that are caused by deactivated password protection.

Password Forgotten

It is possible to reset all passwords via a general Reset dialog. See “Reset to Factory Defaults, Reset All Passwords” for details.

General Considerations

You have to ensure that the access authorizations are protected by secure passwords. These passwords have to be kept as a secret and to be known only by the authorized persons. The default password “1234” does not provide any security against unauthorized access.

A lock symbol indicates in the upper right corner of the display if there are any access authorizations active at the moment . That means, within the mode "Read Only Lv0" a closed (locked) lock symbol will be shown in the upper right corner of the display. As soon as there are any access authorizations active (above the "Read Only-Lv0" level), the upper right corner of the display will show an unlocked (open) lock symbol.

During setting parameters the C-Button can be used for canceling the parameter changes. Because of that it is not possible to acknowledge (LEDs, Output Relays...) as long as there are non-saved (cached only) parameters.

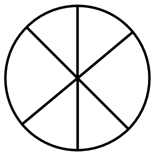
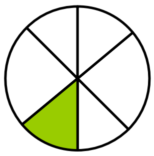
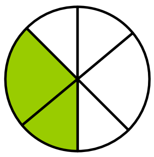
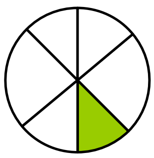
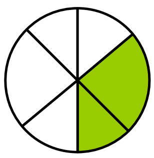
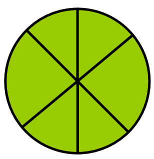
The acknowledgment menu cannot be accessed as long as the parameter modifications are not overtaken by the device (indicated by a star symbol in the upper left corner).

The passwords are part of the device (fixed assignments). That means, passwords will not be overwritten, if a parameter file is transmitted into a device.

Existing passwords are persistent (assigned to a device). If an offline created parameter file is transmitted into a device, or if a parameter file is transmitted from one device to another, this will have no impact on existing passwords within the device.

Passwords – Areas

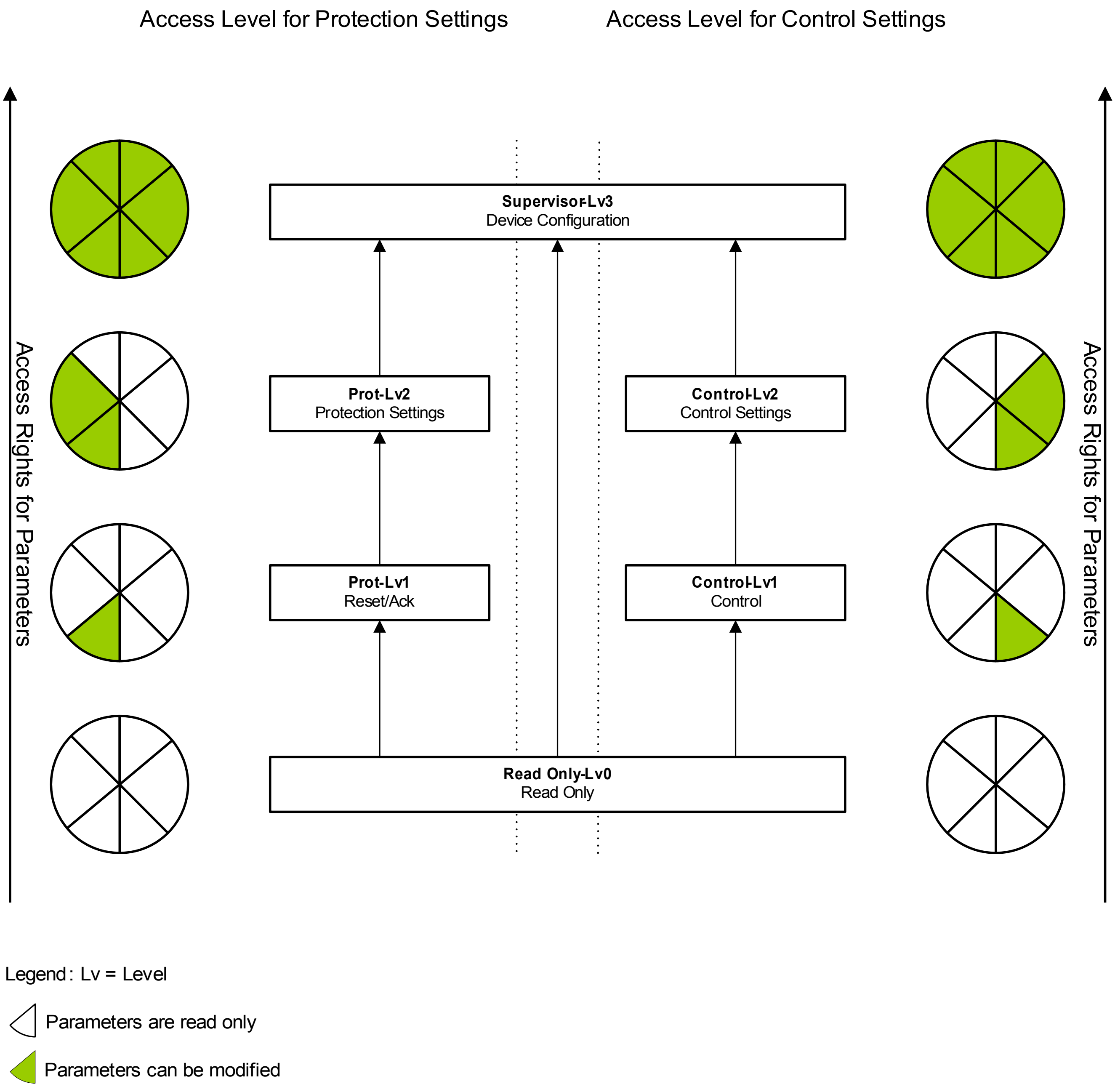
The following table shows the access areas and the authorization passwords that they require in order to access them.

Area Symbol		*Authorization Password*	*Access to:*
		**Read Only-Lv0**	Level 0 provides Read Only access to all settings and parameters of the device. The device will fall back into this level automatically after a longer period or inactivity
		**Prot-Lv1**	This password provides access to the reset- and acknowledge options. In addition to that, it permits the execution of manual trigger signals.
		**Prot-Lv2**	This password provides access to the reset and acknowledge options. In addition to that it permits changing of protection settings and the configuration of the trip manager.
		**Control-Lv1**	This password grants permission for switching operations (switching switchgears)
		**Control-Lv2**	This password grants permission for switching operations (switching switchgears). In addition to that it gives access to the switchgear settings (switching authority, interlockings, general settings of switchgears, Breaker wear...).
		**Supervisor-Lv3**	This password grants non-restricted access to all parameters and settings of the device (device configuration). This includes also the devices planning, device parameters (e.g. Date and Time), Field Parameters, Service Parameters and Logic Parameters.

Available Levels/Access Authorizations

The access authorizations are designed in form of two hierarchic strings.

The supervisor (administrator) password provides access to all parameters and settings.



If the device was not active within the parameter setting mode for a longer time (can be set between 20 – 3600 seconds) it changes into »Read Only-Lv0« mode automatically. This parameter (t-max-Edit) can be modified within menu [Device Para / HMI].

How to Unlock an Access Area or Check which Ones are Unlocked?

Check for unlocked access areas:

The menu [Device Para / Access Level] provides the information, which access areas (authorizations) are currently unlocked. Within this menu it is also possible to enter (unlock) a particular area.

However, the common way during every-day-use of the device is not to use this [Access Level] menu, but to simply enter the menu path of a parameter to be changed, then start editing the parameter; at the end, immediately before the change is accepted, the user is asked for the appropriate password, which then unlocks the respective access area.

As soon as there is an unlocked access area (authorization) above *»Read Only-Lv0«*, this will be indicated by an unlocked lock symbol within the upper right corner of the device display.

If you want to explicitly set back (i. e. lock) the access area at the end (instead waiting for the *»t-max Edit/Access«* timeout) you have to enter the *»Read Only-Lv0«* mode.

Unlock an access area at the panel:

Within the menu [Device Para / Access level] it is possible to unlock or lock access areas (authorizations). After an access area has been unlocked all parameter changes or activities that are assigned to this (or a lower) level can be made without entering a password once again. However, the access permission is valid only for the panel; any access via *Smart view* has to be unlocked separately.

When no key is pressed for a time that can be specified via the [Device para / HMI / Security] *»t-max Edit/Access«* setting, the access area is reset automatically to *»Read Only-Lv0«*, and all unsaved parameter changes get canceled.

CAUTION

Do not leave the device unsupervised as long as there are still access areas (levels) unlocked (unlocked lock symbol on the display). If the access is no longer needed it is advisable to reset the permissions back to *»Read Only-Lv0«.*

Unlock an access area via Smart view:

After an access area (authorizations) has been unlocked by entering the password all parameter changes or activities that are assigned to this (or a lower) level can be made without entering a password once again. However, the access permission is valid only for this instance of *Smart view*; any access via panel or other *Smart view* instances has to be unlocked separately.

When no key is pressed for some (*Smart view*-internal) time the access area is automatically reset.

CAUTION

Do not leave the device unsupervised as long as Smart view still keeps some access area unlocked. Lock your PC during your absence, or at least reset the access permissions. This can be done by a double-click on the lock symbol in the status line on the bottom margin of the Smart view window (or, alternatively, via the menu *[Device / Reset to Parameter "Read Only" Status]*.

Network Access

Access via Smart view:

One of the fundamental requirements of *»IT Security«* is to prevent unauthorized persons from accessing the own systems, including the protective device. The device offers access via its front panel, and via the operating software *Smart view*.

Since the access via front panel is possible only for someone who is located directly in front of the device the risk should normally be rather low, compared to the risk of unauthorized access via *Smart view*, especially if the device is part of an Ethernet / TCP/IP network.

NOTICE

After commissioning of the device, it is recommended to deactivate the *Smart view* access via Ethernet; this can be done with the setting parameter [Device Para / HMI / Security] *»Smart view via Eth«*.

Independent of this, there is also the option to deactivate the *Smart view* access via the USB interface; this can be done with the setting parameter [Device Para / HMI / Security] *»Smart view via USB«*.

For Line Differential devices there is the additional option to deactivate the access to the remote device via Protection Communication; this can be done with the setting parameter [Device Para / HMI / Security] *»Sm. view via ProtCom«*.

Note: If *Smart view* is used to deactivate the Smart view access, then the current session gets automatically terminated.

SCADA Communication:

It is to be noted that there are always certain security risks related to the use of SCADA protocols. Detailed information can be found in the technical literature.

Intranet Security:

If the Ethernet interface of the device is connected to a network, it is the responsibility of the user to maintain all necessary means required for the security of the company network. In particular, it must be guaranteed that external access (i. e. out of the internet) to the device has been made impossible. Please keep yourself informed about up-to-date technology (firewalls, VPN etc.)!

Reset to Factory Defaults, Reset All Passwords

There is a dedicated Reset dialog that allows for selecting any of the following options:

- **Reset to the factory defaults**, or
- **reset all passwords**.

This Reset dialog is available at the HMI only (i. e. **not** via *Smart view*).

Press the »C« key during a cold start until the Reset dialog appears.

NOTICE **For technical reasons, this Reset dialog is available only in English language (independent of the regional language being used later, after the device has started).**

Note furthermore that the dialog might not appear at all because it has been intentionally disabled (see below), or the option to reset all passwords has been disabled.

Reset to Factory Defaults

WARNING **All records will be deleted and the measured values and counters will be reset. Exception: The operation hours counter is preserved.**

- From the Reset dialog, select »Reset to factory default«.
  ⇨ There is a confirmation dialog, asking »Reset device to factory defaults and reboot?«
- Confirm with »Yes«.
  ⇨ The reset to factory defaults is executed, and the device restarts.

Reset All Passwords

It is possible to remove this option from the Reset dialog for security reasons (see below).

- From the Reset dialog, select »Reset all passwords «.
  ⇨ There is a confirmation dialog, asking »Reset all passwords?«
- Confirm with »Yes«.
  ⇨ The device starts using the standard password » **1234**« .

WARNING **For security reasons, it is strictly recommended to change the default passwords immediately to some individual passwords. (See chapter "Changing Passwords".**

Security Settings

The Reset dialog can be restricted for security reasons.
The setting parameter [Device para / HMI / Security] *»Options Reset Dialog«* allows for specifying which resetting options shall be available from the Reset dialog:

- *"Fact.def.", "PW rst":* Both options –»Reset to factory default« and »Reset all passwords« – shall be available.
- *Only "Fact.defaults":* Only the »Reset to factory default« option shall be available.
- *Dialog deact.:* The Reset dialog shall be disabled.

CAUTION

If the password should be lost and the *»Reset all passwords«* option has been made unavailable then the only chance to recover control is to reset the device to factory default. If this option has been deactivated, too, then the device has to be sent to Woodward as a service request.

Smart View

Smart view is a parameter setting and evaluation software. Please see separate manual (DOK-HB-SMARTVE).

- Menu-controlled parameter setting incl. validity checks
- Offline configuration of all relay types
- Reading and evaluating of statistical data and measuring values
- Setting into operation assistance
- Display of the device status
- Fault analysis via event- and fault recorder

Data visualizer

Data visualizer is an disturbance record and event viewing software. It is installed automatically with *Smart view*. It can also be used as a standard COMTRADE file viewer.

- Open and review downloaded disturbance records.
- Customize disturbance record channel layout and views including channel overlapping and zooming
- Analyze sample by sample data points and line up the displayed analog waveform channels along with the recorded internal relay logic
- Save window setups (snapshots) and print for reporting
- Open industry standard COMTRADE files from other intelligent electronic devices
- Convert downloaded waveform files to COMTRADE file format using "Export" feature

Measuring Values

Read out Measured Values

In menu »Operation/Measured Values« both measured and calculated values can be viewed. The measured values are ordered by »Standard values« and »special values« (depending on the type of device).

Measurement Display

Menu [Device Para\Measurem Display] offers options to change the display of measured values.

Scaling of Measured values

By means of the parameter »Scaling« the user can determine how measured values are to be displayed within the HMI and *Smart view*:

- Primary quantities
- Secondary quantities
- Per Unit quantities

Power Units (applies only for devices with power measurement)

By means of the parameter »*Power Units«* the User can determine how measured values are to be displayed within the HMI and *Smart view*:

- Power Auto Scaling
- kW, kVAr or kVA
- MW, MVAr or MVA
- GW, GVAr or GVA

Energy Units (applies only for devices with energy measurement)

By means of the parameter »*Energy Units«* the User can determine how measured values are to be displayed within the HMI and *Smart view*:

- Energy Auto Scaling
- kWh, kVArh or kVAh
- MWh, MVArh or MVAh
- GWh, GVArh or GVAh

In case of an overflow of the counter, the counter will start counting again at zero. A corresponding signal will indicate the counter overflow.

	Counter overflow at:
Energy Auto Scaling	Depends on the settings for the current and voltage transformers
kWh, kVArh or kVAh	999,999.99
MWh, MVArh or MVAh	999,999.99
GWh, GVArh or GVAh	999,999.99

Temperature Unit (applies only for devices with temperature measurement)

By means of the parameter »*Temperatur Unit«* the User can determine how measured values are to be displayed within the HMI and *Smart view*:

- ° Celsius
- ° Fahrenheit

Cutoff level

In order to suppress noise within measured values that are close to zero the user has the option to set cutoff levels. By means of the cutoff levels, measuring quantities that are close to zero will be displayed as zero. These parameters have no impact on recorded values.

Current - Measured Values

CT

If the device is not equipped with an voltage measuring card the first measuring input on the first current measuring card (slot with the lowest number) will be used as the reference angle (»*IL1«).*

Current Transformer Signals (Output States)

Signal	*Description*
Phase seq. wrong	Signal that the device has detected a phase sequence (L1-L2-L3 / L1-L3-L2) that is different from the one that had been set at [Field settings / General Settings] »Phase Sequence«.

Current Transformer Values

Value	*Description*	*Menu path*
IL1	Measured value: Phase current (fundamental)	[Operation /Measured Values /Current]
IL2	Measured value: Phase current (fundamental)	[Operation /Measured Values /Current]
IL3	Measured value: Phase current (fundamental)	[Operation /Measured Values /Current]
IG meas	Measured value (measured): IG (fundamental)	[Operation /Measured Values /Current]
IG calc	Measured value (calculated): IG (fundamental)	[Operation /Measured Values /Current]
I0	Measured value (calculated): Zero current (fundamental)	[Operation /Measured Values /Current]
I1	Measured value (calculated): Positive phase sequence current (fundamental)	[Operation /Measured Values /Current]
I2	Measured value (calculated): Unbalanced load current (fundamental)	[Operation /Measured Values /Current]

Value	*Description*	*Menu path*
phi IL1	Measured value (calculated): Angle of Phasor IL1 Reference phasor is required to calculate the angle.	[Operation /Measured Values /Current]
phi IL2	Measured value (calculated): Angle of Phasor IL2 Reference phasor is required to calculate the angle.	[Operation /Measured Values /Current]
phi IL3	Measured value (calculated): Angle of Phasor IL3 Reference phasor is required to calculate the angle.	[Operation /Measured Values /Current]
phi IG meas	Measured value (calculated): Angle of Phasor IG meas Reference phasor is required to calculate the angle.	[Operation /Measured Values /Current]
phi IG calc	Measured value (calculated): Angle of Phasor IG calc Reference phasor is required to calculate the angle.	[Operation /Measured Values /Current]
phi I0	Measured value (calculated): Angle Zero Sequence System Reference phasor is required to calculate the angle.	[Operation /Measured Values /Current]
phi I1	Measured value (calculated): Angle of Positive Sequence System Reference phasor is required to calculate the angle.	[Operation /Measured Values /Current]
phi I2	Measured Value (calculated): Angle of Negative Sequence System Reference phasor is required to calculate the angle.	[Operation /Measured Values /Current]
phi I2-phi I1	Measured Value (calculated): Angle of Negative Sequence System - Measured value (calculated): Angle of Positive Sequence System	[Operation /Measured Values /Current]
IL1 RMS	Measured value: Phase current (RMS)	[Operation /Measured Values /Current RMS]

Value	*Description*	*Menu path*
IL2 RMS	Measured value: Phase current (RMS)	[Operation /Measured Values /Current RMS]
IL3 RMS	Measured value: Phase current (RMS)	[Operation /Measured Values /Current RMS]
IG meas RMS	Measured value (measured): IG (RMS)	[Operation /Measured Values /Current RMS]
IG calc RMS	Measured value (calculated): IG (RMS)	[Operation /Measured Values /Current RMS]
%IL1 THD	Measured value (calculated): IL1 Total Harmonic Distortion	[Operation /Measured Values /Current RMS]
%IL2 THD	Measured value (calculated): IL2 Total Harmonic Distortion	[Operation /Measured Values /Current RMS]
%IL3 THD	Measured value (calculated): IL3 Total Harmonic Distortion	[Operation /Measured Values /Current RMS]
IL1 THD	Measured value (calculated): IL1 Total Harmonic Current	[Operation /Measured Values /Current RMS]
IL2 THD	Measured value (calculated): IL2 Total Harmonic Current	[Operation /Measured Values /Current RMS]
IL3 THD	Measured value (calculated): IL3 Total Harmonic Current	[Operation /Measured Values /Current RMS]
%(I2/I1)	Measured value (calculated): I2/I1, phase sequence will be taken into account automatically.	[Operation /Measured Values /Current]

Statistics

Statistics

In menu *»Operation/Statistics«* the min., max. and mean values of the measured and calculated measured quantities can be found.

Configuration of the Minimum and Maximum Values

The calculation of the minimum and maximum values will be started:

- When a Reset signal becomes active (Min/Max)
- When the device is restarted
- After configuration

	Minimum and Maximum Values (Peak Values/Pointers)	
	Time interval for the calculation of the minimum and maximum values	**Reset**
Configuration Options Where to configure? Within menu [Device Para\ Statistics\ Min/Max]	The minimum and maximum values will be reset with the rising edge of the corresponding reset signal.	Res Min Res Max (e.g. via digital Inputs). These signals will reset the minimum and maximum pointers.
Display of Minimum Values	Where? Within menu [Operation\Statistics\Min]	
Display of Maximum Values	Where? Within menu [Operation\Statistics\Max]	

Configuration of the Average Value Calculation

Configuration of the Current Based Average Value Calculation*

*=Availability depends on the ordered device code.

	Current based Average Values and Peak Values		
	Time period for the calculation of the average and peak values	**Start options**	**Reset of the average and peak values**
Configuration Options Where to configure? In [Device Para\ Statistics\ Demand\ Current Demand]	sliding: (sliding: average calculation based on sliding period) fixed: (fixed: Average calculation is reset by the end of the period, that means with the next starting period)	duration: (fixed or sliding period) Start Fct: (The average values are calculated based on the time period between two rising edges ot this signal)	Res Fc (e.g. via Digital Input in order to reset the average values in advance (before the next rising edge of the start signal). This applies to option „Start FC“ only.
Trip (command) option to limit the average current demand: Yes	Please refert to chapter „System Alarms“		
View average values and peak values	Where? Within menu [Operation\Statistics\Demand]		

Configuration of the Voltage Based Average Value Calculation*

*=Availability depends on the ordered device code.

	Voltage based Average Values		
	Time period for the calculation of the average values	**Start options**	**Reset of the average and peak values**
Configuration Options Where to configure? In [Device Para\ Statistics\ Umit]	sliding: (sliding: average calculation based on sliding period) fixed: (fixed: Average calculation is reset by the end of the period, that means with the next starting period)	duration: (fixed or sliding period) Start Fct: (The average values are calculated based on the time period between two rising edges ot this signal)	Res Fc (e.g. via Digital Input in order to reset the average values in advance (before the next rising edge of the start signal). This applies to option „Start FC“ only.
View average values	Where? Within menu [Operation\Statistics\Vavg]		

Configuration of the Power Based Average Value Calculation*

*=Availability depends on the ordered device code.

	Power based Average Values (Demand) and Peak Values		
	Time period for the calculation of the average and peak values	**Start options**	**Reset of the average and peak values**
Configuration Options Where to configure? In [Device Para\ Statistics\ Bezugsmanagm\ Power Demand]	sliding: (sliding: average calculation based on sliding period) fixed: (fixed: Average calculation is reset by the end of the period, that means with the next starting period)	duration: (fixed or sliding period) Start Fct: (The average values are calculated based on the time period between two rising edges ot this signal)	Res Fc (e.g. via Digital Input in order to reset the average values in advance (before the next rising edge of the start signal). This applies to option „Start FC“ only.
Trip (command) option to limit the average power demand: Yes	Please refert to chapter „System Alarms“		
View average values and peak values	Where? Within menu [Operation\Statistics\Demand]		

Direct Commands

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ResFc all	Resetting of all Statistic values (Current Demand, Power Demand, Min, Max)	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]
ResFc I Demand	Resetting of Statistics - Current Demand (avg, peak avg)	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]
ResFc Min	Resetting of all Minimum values	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]
ResFc Max	Resetting of all Maximum values	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]

Global Protection Parameters of the Statistics Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ResFc Max	Resetting of all Maximum values	1..n, Assignment List	-.-	[Device Para /Statistics /Min / Max]
ResFc Min	Resetting of all Minimum values	1..n, Assignment List	-.-	[Device Para /Statistics /Min / Max]
Start I Demand via:	Start Current demand by:	Duration, StartFct	Duration	[Device Para /Statistics /Demand /Current Demand]
Start I Demand Fc	Start of the calculation, if the assigned signal becomes true. Only available if: Start I Demand via: = StartFct	1..n, Assignment List	-.-	[Device Para /Statistics /Demand /Current Demand]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ResFc I Demand	Resetting of Statistics - Current Demand (avg, peak avg)	1..n, Assignment List	-.-	[Device Para /Statistics /Demand /Current Demand]
Duration I Demand	Recording time Only available if: Start I Demand via: = Duration	2 s, 5 s, 10 s, 15 s, 30 s, 1 min, 5 min, 10 min, 15 min, 30 min, 1 h, 2 h, 6 h, 12 h, 1 d, 2 d, 5 d, 7 d, 10 d, 30 d	15 s	[Device Para /Statistics /Demand /Current Demand]
Window I Demand	Window configuration	sliding, fixed	sliding	[Device Para /Statistics /Demand /Current Demand]

States of the Inputs of the Statistics Module

Name	*Description*	*Assignment via*
StartFc I Demand-I	State of the module input: Start of the Statistics of the Current Demand	[Device Para /Statistics /Demand /Current Demand]
ResFc Vavg-I	State of the module input: Resetting of the sliding average calculation.	[]
ResFc I Demand-I	State of the module input: Resetting of Statistics - Current Demand (avg, peak avg)	[Device Para /Statistics /Demand /Current Demand]
ResFc P Demand-I	State of the module input: Resetting of Statistics - Power Demand (avg, peak avg)	[]
ResFc Max-I	State of the module input: Resetting of all Maximum values	[Device Para /Statistics /Min / Max]
ResFc Min-I	State of the module input: Resetting of all Minimum values	[Device Para /Statistics /Min / Max]

Signals of the Statistics Module

Signal	*Description*
ResFc all	Signal: Resetting of all Statistic values (Current Demand, Power Demand, Min, Max)
ResFc I Demand	Signal: Resetting of Statistics - Current Demand (avg, peak avg)
ResFc Max	Signal: Resetting of all Maximum values
ResFc Min	Signal: Resetting of all Minimum values

Counters of the Module Statistics

Value	*Description*	*Menu path*
Res Cr I Demand	Number of resets since last booting. The timestamp shows date and time of the last reset.	[Operation /Statistics /Demand /Current Demand]
Res Cr Min values	Number of resets since last booting. The timestamp shows date and time of the last reset.	[Operation /Statistics /Min /Current]
Res Cr Max values	Number of resets since last booting. The timestamp shows date and time of the last reset.	[Operation /Statistics /Max /URTD]

Current - Statistic Values

Value	*Description*	*Menu path*
I1 max	Maximum value positive phase sequence current (fundamental)	[Operation /Statistics /Max /Current]
I1 min	Minimum value positive phase sequence current (fundamental)	[Operation /Statistics /Min /Current]
I2 max	Maximum value negative sequence current (fundamental)	[Operation /Statistics /Max /Current]
I2 min	Minimum value unbalanced load current (fundamental)	[Operation /Statistics /Min /Current]
IL1 max RMS	IL1 maximum value (RMS)	[Operation /Statistics /Max /Current]
IL1 avg RMS	IL1 average value (RMS)	[Operation /Statistics /Demand /Current Demand]
IL1 min RMS	IL1 minimum value (RMS)	[Operation /Statistics /Min /Current]
IL2 max RMS	IL2 maximum value (RMS)	[Operation /Statistics /Max /Current]
IL2 avg RMS	IL2 average value (RMS)	[Operation /Statistics /Demand /Current Demand]

Value	*Description*	*Menu path*
IL2 min RMS	IL2 minimum value (RMS)	[Operation /Statistics /Min /Current]
IL3 max RMS	IL3 maximum value (RMS)	[Operation /Statistics /Max /Current]
IL3 avg RMS	IL3 average value (RMS)	[Operation /Statistics /Demand /Current Demand]
IL3 min RMS	IL3 minimum value (RMS)	[Operation /Statistics /Min /Current]
IG meas max RMS	Measured value: IG maximum value (RMS)	[Operation /Statistics /Max /Current]
IG meas min RMS	Measured value: IG minimum value (RMS)	[Operation /Statistics /Min /Current]
IG calc max RMS	Measured value (calculated):IG maximum value (RMS)	[Operation /Statistics /Max /Current]
IG calc min RMS	Measured value (calculated):IG minimum value (RMS)	[Operation /Statistics /Min /Current]
%(I2/I1) max	Measured value (calculated): I2/I1 maximum value, phase sequence will be taken into account automatically	[Operation /Statistics /Max /Current]

Value	*Description*	*Menu path*
%(I2/I1) min	Measured value (calculated): I2/I1 minimum value, phase sequence will be taken into account automatically	[Operation /Statistics /Min /Current]
IL1 Peak demand	IL1 Peak value, RMS value	[Operation /Statistics /Demand /Current Demand]
IL2 Peak demand	IL2 Peak value, RMS value	[Operation /Statistics /Demand /Current Demand]
IL3 Peak demand	IL3 Peak value, RMS value	[Operation /Statistics /Demand /Current Demand]

System Alarms

Available Elements:
SysA

NOTICE **Please note that Power Protection and (Active/Reactive/Apparent) Power Demand is only available within Protective Devices that offer current and voltage measurement.**

Within the System Alarms menu [SysA] the User can configure:

- General Settings (activate/inactivate the Demand Management, optional assign a signal, that will block the Demand Management);
- Power Protection (Peak values);
- Demand Management (Power and Current); and
- THD Protection.

Please note, that all thresholds are to be set as primary values.

Demand Management

Demand is the average of system current or power over a time interval (window). Demand management supports the User to keep energy demand below target values bound by contract (with the energy supplier). If the contractual target values are exceeded, extra charges are to be paid to the energy supplier.

Therefore, demand management helps the User detect and avoid averaged peak loads that are taken into account for the billing. In order to reduce the demand charge respective to demand rate, peak loads, if possible, should be diversified. That means, if possible, avoiding large loads at the same time. In order to assist the User in analyzing the demand, demand management might inform the User by an alarm. The User might also use demand alarms and assign them on relays in order to perform load shedding (where applicable).

Demand management comprises:

- Power Demand
    - Watt Demand (Active Power);
    - VAr Demand (Reactive Power);
    - VA Demand (Apparent Power); and
- Current Demand.

Configuring the Demand

Configuring the demand is a two step procedure. Proceed as follows.

Step1: Configure the general settings within the [Device Para/Statistics/Demand] menu:

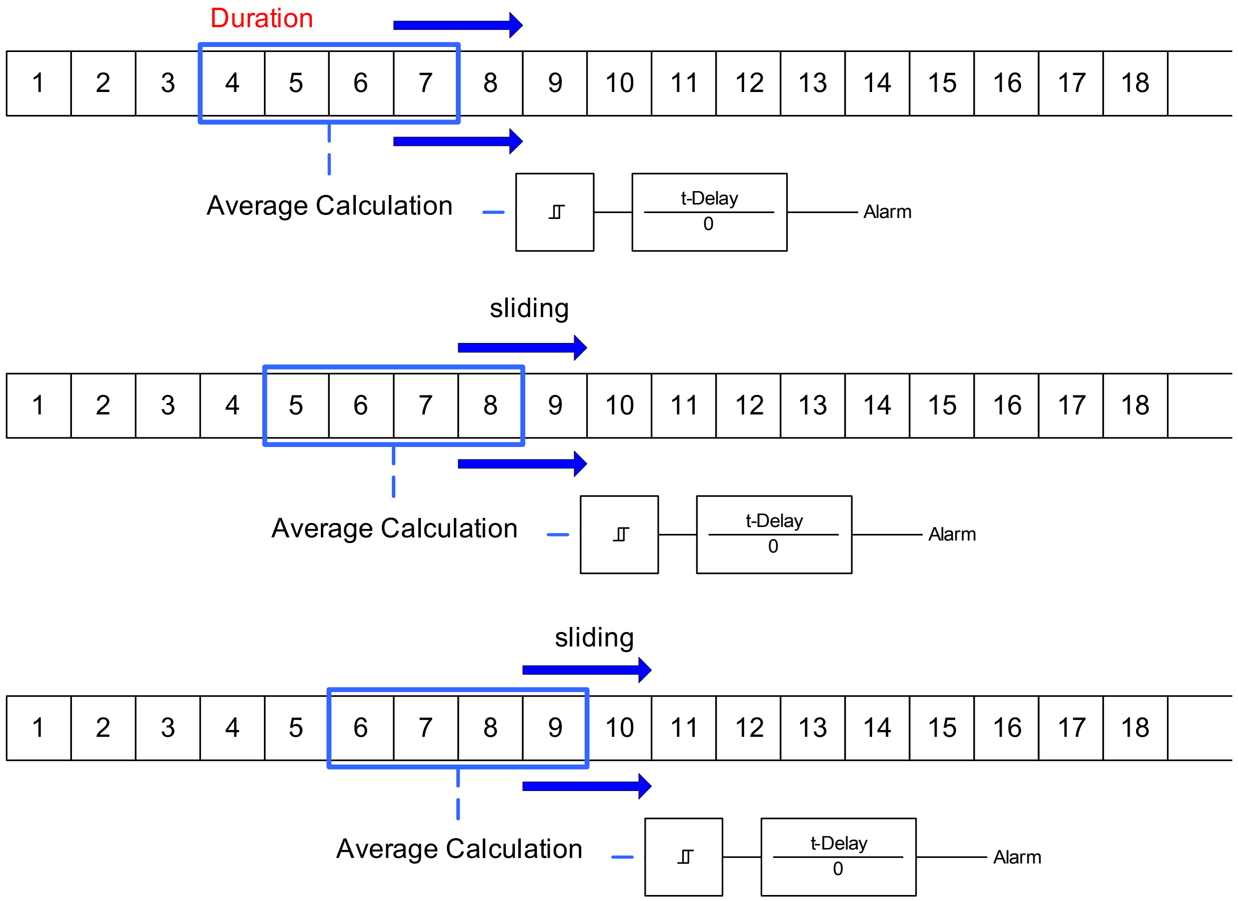
- Set the trigger source to »*Duration«*.
- Select a time base for the »*window«*.
- Determine if the window is »*fixed«* or »*sliding*«.
- If applicable assign a reset signal.

The interval time (window) can be set to fixed or sliding.

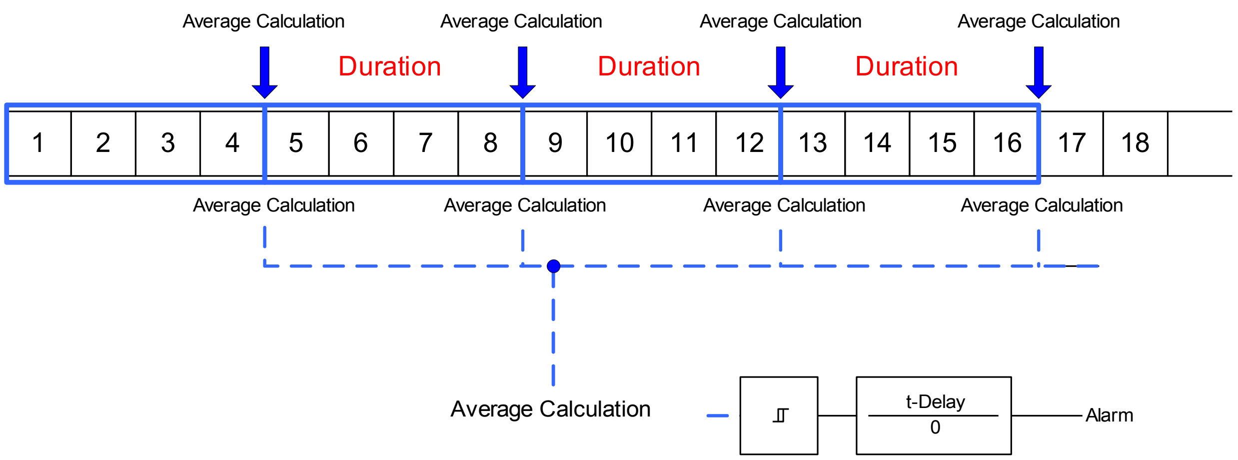
Example for a fixed window: If the range is set for 15 minutes, the protective device calculates the average current or power over the past 15 minutes and updates the value every 15 minutes.

Example for a sliding window: If the sliding window is selected and the interval is set to 15 minutes, the protective device calculates and updates the average current or power continuously, for the past 15 minutes (the newest measuring value replaces the oldest measuring value continuously).

Window configuration = sliding



Window configuration = fixed



Step 2:

- In addition, the Demand specific settings have to be configured in the [SysA/Demand] menu.
- Determine if the demand should generate an alarm or if it should run in the silent mode. (Alarm active/inactive).
- Set the threshold.
- Where applicable, set a delay time for the alarm.

Peak Values

The protective device also saves the peak demand values for current and power. The quantities represent the largest demand value since the demand values were last reset. Peak demands for current and system power are date and time stamped.

Within the [Operation/Statistics] menu, the current Demand and Peak demand values can be seen.

Configuring the Peak Value Supervision

The supervision for the peak values can be configurated within menu [SysA/Power] in order to monitor:

- Active Power (Watt),
- Reactive Power (VAr)
- Apparent Powr (VA)

The specific settings are to be set within menu [SysA/Power].

- Determine if the peak value supervision should generate an alarm or if it should run in the silent mode. (Alarm active/inactive).
- Set the threshold.
- Where applicable, set a delay time for the alarm.

Min. and Max. Values.

Within [Operation/Statistics] menu the minimum (min.) and maximum (max.) values can be seen.

Minimum values since last reset: The minimum values are continuously compared to the last minimum value for that measuring value. If the new value is less than the last minimum, the value is updated. Within the [Device Para/Statistics/"Min / Max"] menu, a reset signal can be assigned.

Maximum values since last reset: The maximum values are continuously compared to the last maximum value for that measuring value. If the new value is greater than the last maximum, the value is updated. Within the [Device Para/Statistics/"Min / Max"] menu, a reset signal can be assigned.

THD Protection

In order to supervise power quality, the protective device can monitor the voltage (phase-to-phase) and current THDs.

Within the [SysA/THD] menu:

- Determine if an alarm is to be issued or not (Alarm active/inactive);
- Set the threshold; and
- Where applicable, set a delay time for the alarm.

Device Planning Parameters of the Demand Management

Parameter	*Description*	*Options*	*Default*	*Menu path*
Mode	Mode	do not use, use	do not use	[Device planning]

Signals of the Demand Management (States of the Outputs)

Signal	*Description*
active	Signal: active
ExBlo	Signal: External Blocking
Alm Current Demd	Signal: Alarm averaged demand current
Alarm I THD	Signal: Alarm Total Harmonic Distortion Current
Trip Current Demand	Signal: Trip averaged demand current
Trip I THD	Signal: Trip Total Harmonic Distortion Current

Global Protection Parameter of the Demand Management

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[SysA /General Settings]
ExBlo Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo Fc=active".	1..n, Assignment List	-.-	[SysA /General Settings]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Alarm	Alarm	inactive, active	inactive	[SysA /Demand /Current Demand]
Threshold	Threshold (to be entered as primary value)	10 - 500000A	500A	[SysA /Demand /Current Demand]
t-Delay	Tripping Delay	0 - 60min	0min	[SysA /Demand /Current Demand]
Alarm	Alarm	inactive, active	inactive	[SysA /THD /I THD]
Threshold	Threshold (to be entered as primary value)	1 - 500000A	500A	[SysA /THD /I THD]
t-Delay	Tripping Delay	0 - 3600s	0s	[SysA /THD /I THD]

States of the Inputs of the Demand Management

Name	*Description*	*Assignment via*
ExBlo-I	Module input state: External blocking	[SysA /General Settings]

Acknowledgments

Collective Acknowledgments for latched signals:

Collective Acknowledgments					
	LEDs	*Binary Output Relays*	*SCADA*	*Pending Trip Command*	*LEDs+* *Binary Output Relays+* *SCADA+* *Pending Trip Command*
Via ***Smart view*** or at the ***panel all***... can be acknowledged. At the panel, the menu [Operation\ Acknowledge] can directly be accessed via the **»C« key**	All LEDs at once: Where? [Operation / Acknowledge]	All Binary Output Relays at once: Where? [Operation / Acknowledge]	All SCADA signals at once: Where? [Operation / Acknowledge]	All pending trip commands at once: Where? [Operation / Acknowledge]	All at once: Where? [Operation / Acknowledge]
External Acknowledg-ment*: Via a signal from the assignment list (e.g. a digital Input) ***all***... can be acknowledged.	All LEDs at once: Where? Within the menu [Device Para / Acknowledge]	All Binary Output Relays at once: Where? Within the menu [Device Para / Acknowledge]	All SCADA signals at once: Where? Within the menu [Device Para / Acknowledge]	All pending trip commands at once: Where? Within the menu [Device Para / Acknowledge]	
Automatic Acknowledg-ment: Via a new alarm from any protection function	All LEDs at once, automatically in case of a protection alarm.				

*The External Acknowledgment might be disabled if parameter »*Ex Ack «*is set to »*inactive«* within menu [Device Para / Acknowledge]. This blocks also the acknowledgment via Communication (e.g. Modbus).
** If the automatic acknowledgment is active all LEDs get acknowledged with a protection alarm.
The automatic acknowledgment must be activated by setting:
[Device Para / LEDs / LEDs group A / LED 1...n] *»Latched«* = “active, ack. by alarm”

Options for individual acknowledgments for latched signals:

Individual Acknowledgment			
	LEDs	*Binary Output Relays*	*Pending Trip Command*
Via a signal from the assignment list (e.g.:a digital Input) a ***single***... can be acknowledged.	Single LED: Where? Within the configuration menu of this single LED.	Binary Output Relay: Where? Within the configuration menu of this single Binary Output Relay.	Pending Trip Command. Where? Within the module *TripControl*

NOTICE

As long as you are within the parameter setting mode, you cannot acknowledge.

NOTICE

In case of a fault during parameter setting via the operating panel, you must first leave the parameter mode by pressing either push-button »C« or »OK« before you may access to menu »Acknowledgments« via push-button.

Manual Acknowledgment

It is possible to acknowledge LEDs, SCADA, binary output relays and / or a pending trip command by pressing the »C« key at the panel.

There are two principles available how the »C« key shall react when being pressed:

- **(1.)** *With intermediate selection step:* After the »C« key has been pressed, you select the items to be acknowledged (LEDs, SCADA, binary output relays, trip command, or all of these) via the Softkeys. After this, you press the Softkey with the »Wrench-Symbol«.
- **(2.)** *Immediate acknowledge:* After it has been configured which items shall be be assigned to the *»Ack via »C« key«*, these are acknowledged by simply pressing the »C« key (for ca. 1 second).

The setting parameter [Device Para / Acknowledge] *»Ack via »C« key«* decides about which principle described above shall be available when the »C« key is pressed:

- “Nothing” – Pressing the »C« key works as described with “principle (1.)“, i. e. you explicitly select the items to be acknowledged.
- “Ack LEDs” – Pressing the »C« key (for approx. 1 second) acknowledges all LEDs immediately (only the password will be asked for, see below).
- “Ack LEDs, relays” – Pressing the »C« key (for approx. 1 second) acknowledges all LEDs and all binary output relays immediately (only the password will be asked for, see below).
- “Ack Everything” – Pressing the »C« key (for approx. 1 second) acknowledges all (above) mentioned items immediately (only the password will be asked for, see below).

The three immediate types of acknowledgments according to “principle (2.)“ can be recognized from the fact that it always includes an LED test, i. e. all LEDs flash in red color for a second, then flash in green color for a second.

NOTICE

Independent of which acknowledgment type you have set, note that you are asked to enter the password.

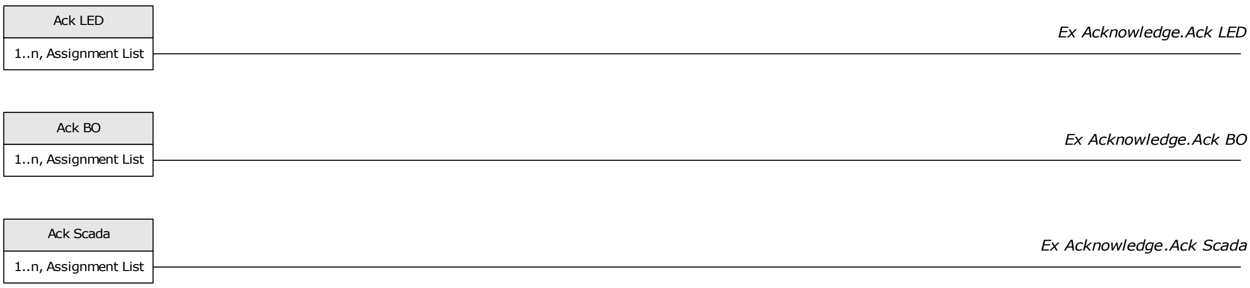
If there is the need to be able to acknowledge without entering any password set an empty password for the level *»Prot-Lv1«*.

For general information about passwords and security-related considerations, see the „Security“ chapter.

External Acknowledgments

Within the menu [Device Parameter\Ex Acknowledge] you can assign a signal (e.g. the state of a digital input) from the assignment list that:

- acknowledges all (acknowledgeable) LEDs at once;
- acknowledges all (acknowledgeable) binary outputs at once:
- acknowledges all (acknowledgeable) SCADA-signals at once.



Manual Resets

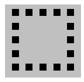
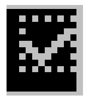
In menu *»Operation/Reset«* you can:

- reset counters,
- delete records (e.g. disturbance records) and
- reset special things (like statistics, thermal replica...).

NOTICE **The description of the reset commands can be found within the corresponding modules.**

Status Display

In the status display within the »Operation« menu, the present state of all signals can be viewed. This means the User is able to see if the individual signals are active or inactive at that moment. The User can see all signals sorted by protective elements/modules.

State of the module input/signal is...	*Is shown at the panel as...*
false / »0«	
true / »1«	

Operating Panel (HMI)

HMI

Special Parameters of the Panel

This menu »Device Parameter/HMI« is used to define the contrast of the display, the maximum admissible edit time and the menu language (after expiry of which, all unsaved parameter changes will be rejected).

Direct Commands of the Panel

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Contrast	Contrast	0 - 100%	50%	[Device Para /HMI]
Reset Options	If the »C« key is pressed while the device is performing a cold restart a general Reset Dialog appears on the screen. Select which options shall be available with this dialog.	Fact.def., "PW rst", Only "Fact.defaults", Reset deact.	Fact.def., "PW rst"	[Device Para /Security /Miscellaneous]
Smart view via USB	Activate (allow) or inactivate (disallow) the Smart view access via the USB interface.	inactive, active	active	[Device Para /Security /Communication]
Smart view via Eth	Activate (allow) or inactivate (disallow) the Smart view access via the Ethernet interface.	inactive, active	active	[Device Para /Security /Communication]

Global Protection Parameters of the Panel

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
t-max Edit/Access	If no other key(s) is pressed at the panel, after expiration of this time, all cached (changed) parameters are canceled. The device access will be locked by falling back into Read-only level Lv0.	20 - 3600s	180s	[Device Para /Security /Miscellaneous]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Display Off	The display back light will be turned off when this timer has expired.	20 - 3600s	180s	[Device Para /HMI]
Menu language	Selection of the language	English, German, Russian, Polish, French, Portuguese, Spanish, Romanian	English	[Device Para /HMI]
Display ANSI Device No.	Display ANSI Device Numbers	inactive, active	active	[Device Para /HMI]

Recorders

Disturbance Recorder

Available elements:
Disturb rec

- Disturbance records can be downloaded (read out) by means of the parameter setting and evaluation software *Smart view.*
- The disturbance records can be viewed and analyzed within *Data visualizer* (will be installed with *Smart view*).
- Disturbance reoords can be converted into the COMTRADE file format by means of *Data visualizers.*

The disturbance recorder works with 32 samples per cycle. The disturbance recorder can be started by any of eight start events (selection from the »assignment list« / OR-Logic).The disturbance record contains the measuring values inclusively pre-trigger-time. By means of *Smart view/Datavisualizer* (option) the oscillographic curves of the analogue (current, voltage) and digital channels/traces can be shown and evaluated in a graphical form. The disturbance recorder has a storage capacity of 120 s. The disturbance recorder is able to record up to 15 s (adjustable) per record. The amount of records depends on the size of each record.

The disturbance recorder can be configured in the menu *»Device Parameter/Recorder/Disturb rec«*.

Determine the max. recording time to register a disturbance event. This can be set via the parameter *»Max file size«, the maximum value is* 15 s (including pre-trigger and post-trigger time). The pre-trigger and post-trigger times of the disturbance recorder are set (via parameters *»Pre-trigger time«* and *»Post-trigger time«*) in percent of the *»Max file size«* value.

To trigger the disturbance recorder, up to 8 signals can be selected from the »assignment list«. The trigger events are OR-linked. If a disturbance record has been written, a new disturbance record cannot be triggered until all trigger signals that have triggered the previous disturbance record are gone.

NOTICE

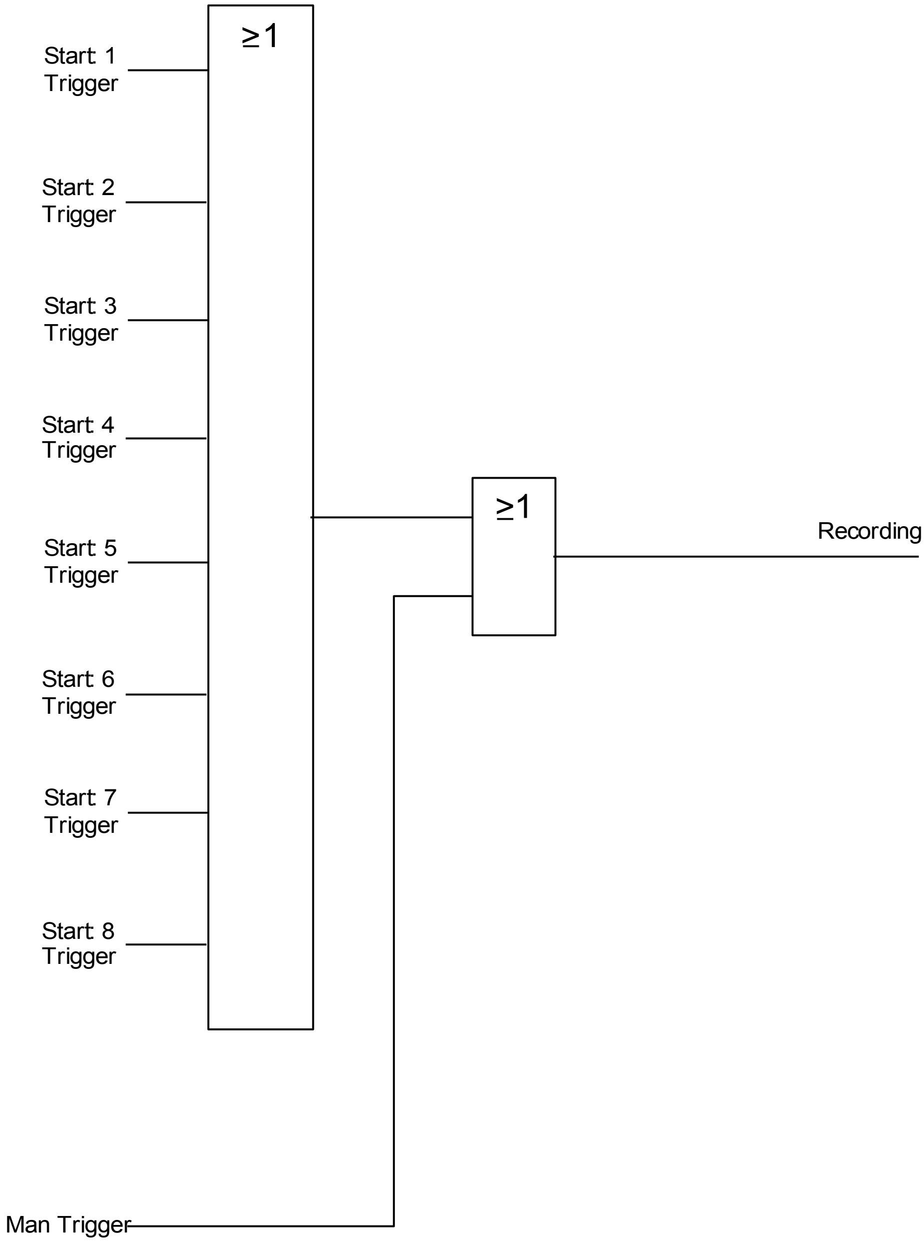
If t_T is the duration of the trigger signal and t_{Max}=*»Max file size«*, t_{Pre}=(*»Pre-trigger time«* · t_{Max}), t_{Post}=(*»Postt-trigger time«* · t_{Max}), then the resulting durations are as follows:

- **The actual pre-trigger timer always equals t_{Pre}**
- **The disturbance event is recorded for the time t_{Ev}, which is:**
  t_{Ev} = min(t_T , (t_{Max} −t_{Pre}))
- **The actual post-trigger timer t_{Rest} is:**
  t_{Rest} = min(t_{Post} , (t_{Max} −t_{Pre}−t_{Ev}))

It can obviously happen that – depending on the actual duration of the trigger signal and the setting t_{Pre} – that t_{Ev} < t_T, I. e. that the disturbance event does not get recorded completely. The only way to mitigate this risk (besides setting a smaller value for t_{Pre}) is to configure a larger value for t_{Max}. This, however, has the consequence that a smaller number of events can be held in memory.

In the same way it can happen that no more post-trigger time is left (i. e. t_{Rest} = 0). Note that the recording always gets stopped after the configured time t_{Max}=*»Max file size«* has elapsed.

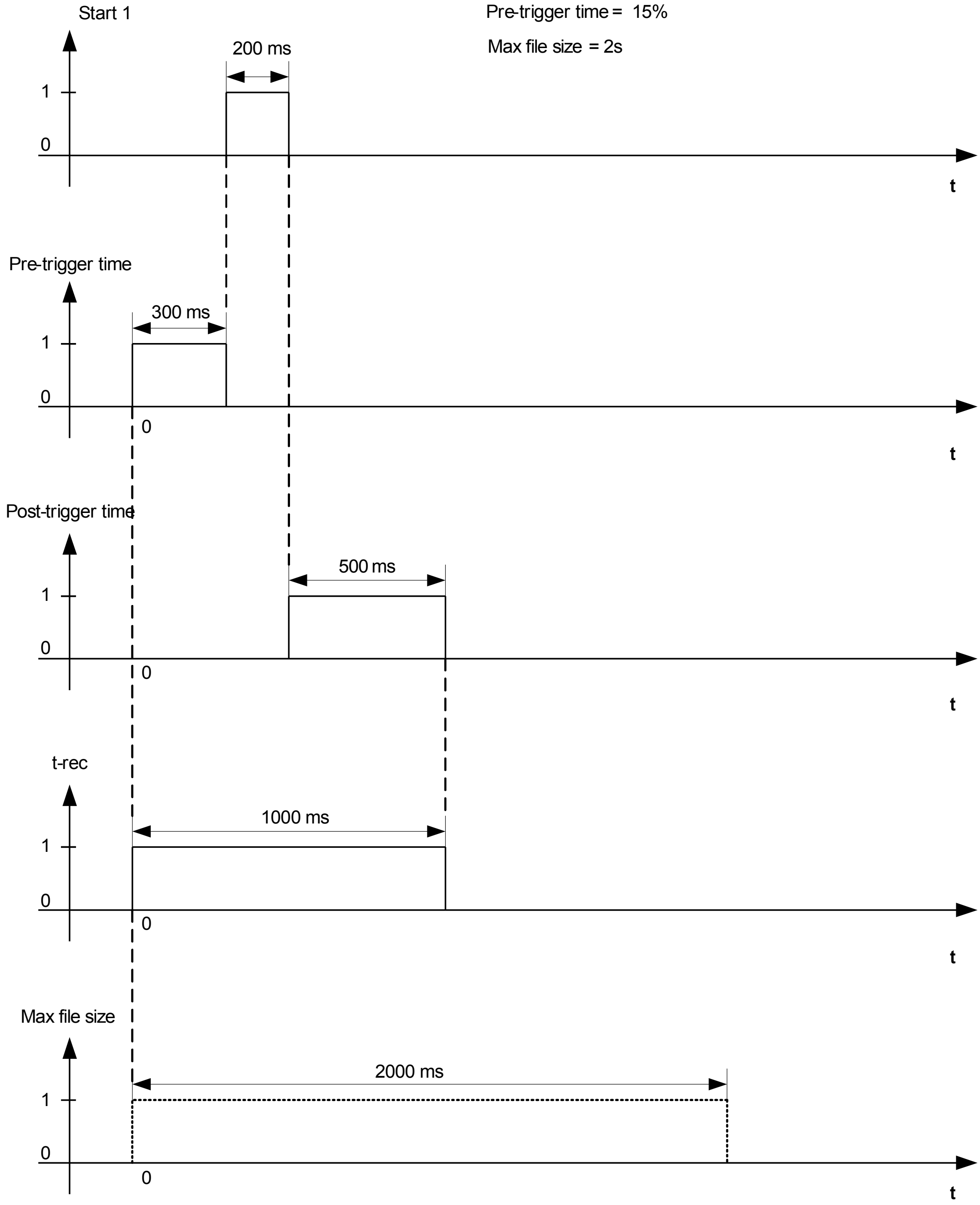
Moreover, decide about the behavior of the disturbance recorder in case the storage capacity has been used up: Do you want it to automatically overwrite the oldest recordings (*»Auto overwriting«*="active"), or do you want it to stop making any further recordings (*»Auto overwriting«*="inactive") until the memory has been cleared manually.


≥1
Start 1 Trigger
Start 2 Trigger
Start 3 Trigger
Start 4 Trigger
Start 5 Trigger
Start 6 Trigger
Start 7 Trigger
Start 8 Trigger
≥1
Recording
Man Trigger

Example Disturbance Recorder Timing Chart I

Start 1 = Prot.Trip
Start 2 = -.-
Start 3 = -.-
Start 4 = -.-
Start 5 = -.-
Start 6 = -.-
Start 7 = -.-
Start 8 = -.-
Auto overwriting = active
Post-trigger time = 25%
Pre-trigger time = 15%
Max file size = 2s

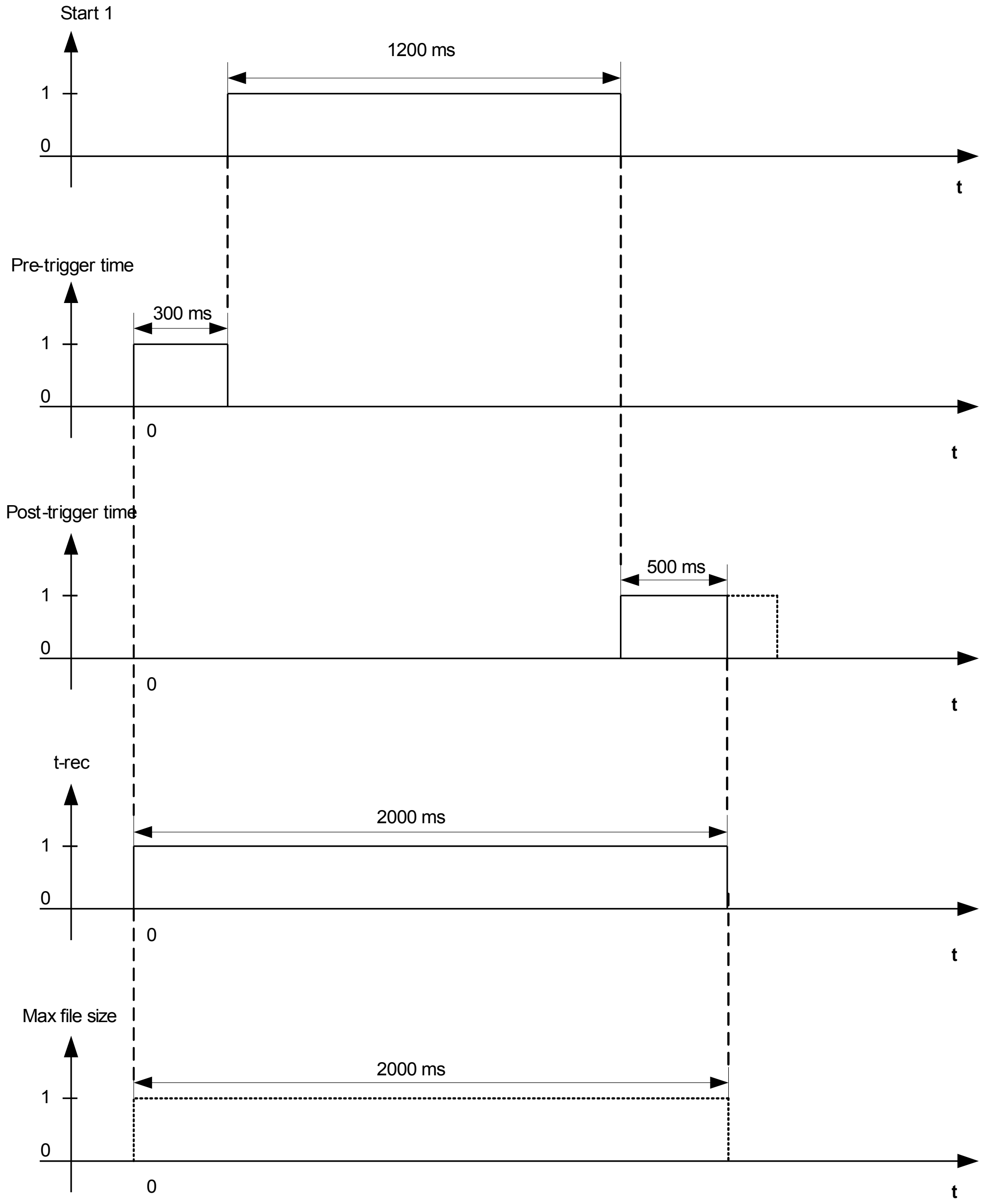
t-rec < Max file size



Example Disturbance Recorder Timing Chart II

Start 1 = Prot.Alarm
Start 2 = -.-
Start 3 = -.-
Start 4 = -.-
Start 5 = -.-
Start 6 = -.-
Start 7 = -.-
Start 8 = -.-
Auto overwriting = active
Post-trigger time = 25%
Pre-trigger time = 15%
Max file size = 2s

t-rec = Max file size



Read Out Disturbance Records

- Within the menu »Operation/Disturb rec« you can detect accumulated disturbance records.

NOTICE **Within the Menu »Operation/Recorders/Man Trigger« you can trigger the disturbance recorder manually.**

Deleting Disturbance Records

Within the menu »Operation/Disturb rec« you can:

- Delete disturbance records.
- Choose via »SOFTKEY« »up« and »SOFTKEY« »down« the disturbance record that is to be deleted.
- Call up the detailed view of the disturbance record via »SOFTKEY« »right«.
- Confirm by pressing »SOFTKEY« »delete«
- Enter your password followed by pressing the key »OK«
- Choose whether only the current of whether all disturbance records should be deleted.
- Confirm by pressing »SOFTKEY« »OK«

Direct Commands of the Disturbance Recorder

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Man Trigger	Manual Trigger	False, True	False	[Operation /Recorders /Man Trigger]
Res all rec	Reset all records	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]

Global Protection Parameters of the Disturbance Recorder

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Start: 1	Start recording if the assigned signal is true.	1..n, Assignment List	Prot.Trip	[Device Para /Recorders /Disturb rec]
Start: 2	Start recording if the assigned signal is true.	1..n, Assignment List	-.-	[Device Para /Recorders /Disturb rec]
Start: 3	Start recording if the assigned signal is true.	1..n, Assignment List	-.-	[Device Para /Recorders /Disturb rec]
Start: 4	Start recording if the assigned signal is true.	1..n, Assignment List	-.-	[Device Para /Recorders /Disturb rec]
Start: 5	Start recording if the assigned signal is true.	1..n, Assignment List	-.-	[Device Para /Recorders /Disturb rec]
Start: 6	Start recording if the assigned signal is true.	1..n, Assignment List	-.-	[Device Para /Recorders /Disturb rec]
Start: 7	Start recording if the assigned signal is true.	1..n, Assignment List	-.-	[Device Para /Recorders /Disturb rec]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Start: 8	Start recording if the assigned signal is true.	1..n, Assignment List	-.-	[Device Para /Recorders /Disturb rec]
Auto overwriting	If there is no more free memory capacity left, the oldest file will be overwritten.	inactive, active	active	[Device Para /Recorders /Disturb rec]
Pre-trigger time	The pre trigger time is set in percent of the »Max file size« value. It corresponds to the part of recording before the onset of the trigger event.	0 - 99%	20%	[Device Para /Recorders /Disturb rec]
Post-trigger time	The post trigger time is set in percent of the »Max file size« value. It is the remaining time of the »Max file size«, depending on the »Pre-trigger time« setting and the duration of the trigger event, but at maximum the »Post-trigger time« set here.	0 - 99%	20%	[Device Para /Recorders /Disturb rec]
Max file size	The maximum storage capacity per record, including pre-trigger and post-trigger time. The amount of records depends on the size of each record, on the max. file size (set here), and on the total storage capacity.	0.1 - 15.0s	2s	[Device Para /Recorders /Disturb rec]

Disturbance Recorder Input States

Name	*Description*	*Assignment via*
Start1-I	State of the module input:: Trigger event / start recording if:	[Device Para /Recorders /Disturb rec]
Start2-I	State of the module input:: Trigger event / start recording if:	[Device Para /Recorders /Disturb rec]
Start3-I	State of the module input:: Trigger event / start recording if:	[Device Para /Recorders /Disturb rec]
Start4-I	State of the module input:: Trigger event / start recording if:	[Device Para /Recorders /Disturb rec]

Name	*Description*	*Assignment via*
Start5-I	State of the module input:: Trigger event / start recording if:	[Device Para /Recorders /Disturb rec]
Start6-I	State of the module input:: Trigger event / start recording if:	[Device Para /Recorders /Disturb rec]
Start7-I	State of the module input:: Trigger event / start recording if:	[Device Para /Recorders /Disturb rec]
Start8-I	State of the module input:: Trigger event / start recording if:	[Device Para /Recorders /Disturb rec]

Disturbance Recorder Signals

Signal	*Description*
recording	Signal: Recording
memory full	Signal: Memory full
Clear fail	Signal: Clear failure in memory
Res all records	Signal: All records deleted
Res rec	Signal: Delete record
Man Trigger	Signal: Manual Trigger

Special Parameters of the Disturbance Recorder

Value	*Description*	*Default*	*Size*	*Menu path*
Rec state	Recording state	Ready	Ready, Recording, Writing file, Trigger Blo	[Operation /Status Display /Recorders /Disturb rec]
Error code	Error code	OK	OK, Write err, Clear fail, Calculation err, File not found, Auto overwriting off	[Operation /Status Display /Recorders /Disturb rec]

Fault Recorder

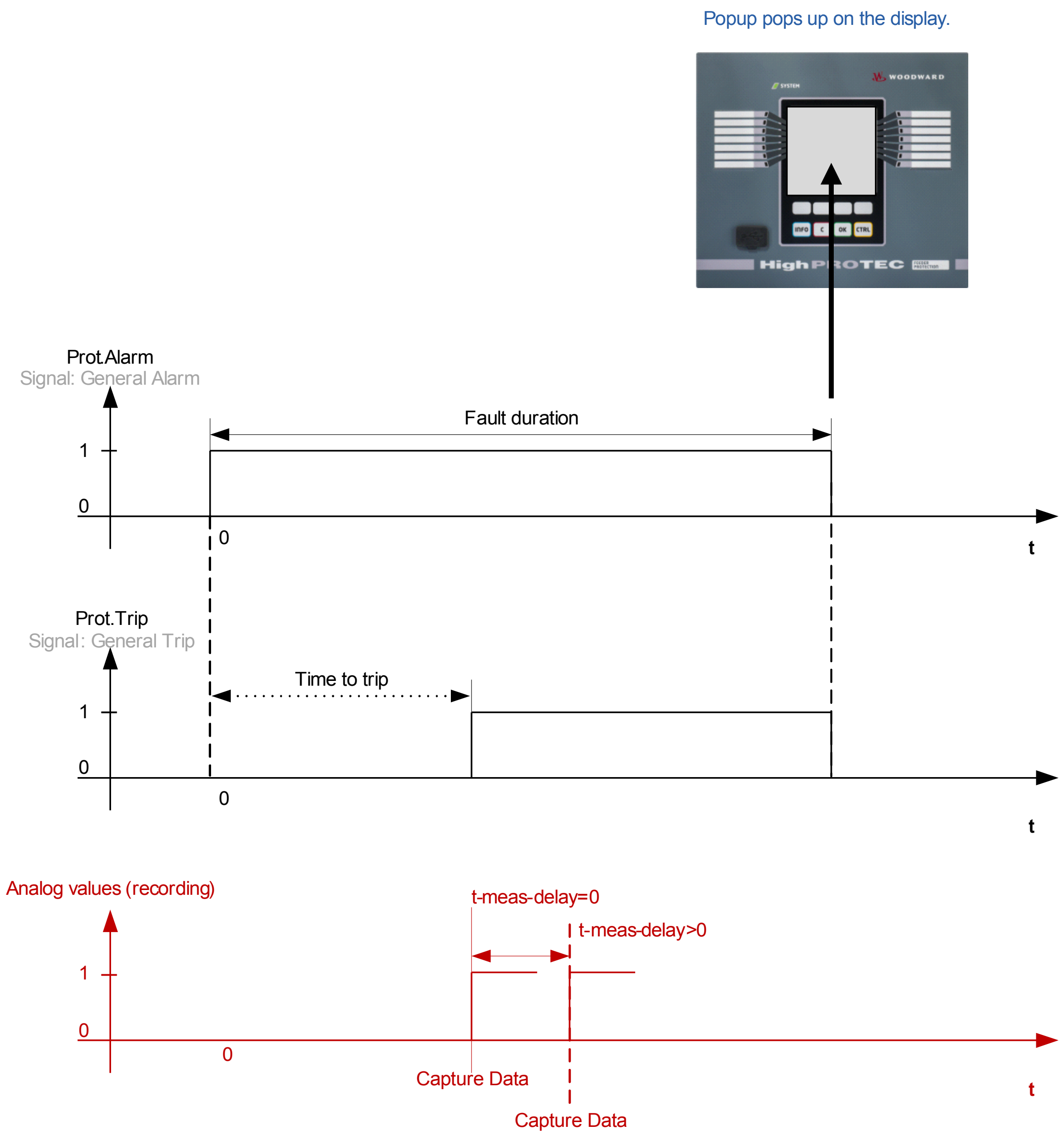
Fault rec

Purpose of the Fault recorder

The *Fault Recorder* provides compressed information about faults (e.g. Trip Causes). The compressed information can be read out also at the HMI. This might be helpful for fast fault analysis already at the HMI. After a fault, a popup window will be sent onto the display in order to draw the users attention to the fault. The *Fault Recorder* will provide information on the causes of the fault. A detailed fault analysis (in oscillographic form) can be done means of the Disturbance Recorder. The reference between the Fault Records and the corresponding Disturbance Records are the »*Fault Number«* and the »*Grid Fault Number«*.

Definitions

Time to Trip:	Time between *First Alarm* (Prot.Pickup) and *First Trip* (Prot.Trip) decision
Fault Duration:	Time period from the rising edge of the General Pickup (»PROT.PICKUP«) signal up to the falling edge of the General Pickup Signal. Please note that General Pickup is an or-connection (disjunction) of all Pickup signals. General Trip is an OR-connection of all Trips.



Behaviour of the Fault Recorder

Who triggers the Fault Recorder?
The *Fault Recorder* will be triggered by the rising edge of the »PROT.PICKUP« (General Pickup) signal. Please note that »PROT.PICKUP« (General Pickup) is an or-connection of all Pickup signals. The first Pickup will trigger the Fault recorder.

At which point of time will the fault measurements be captured?
The fault measurements will be captured (written) when the trip decision is taken. The point in time, when the measurements are captured (after a trip) can be delayed optionally by the parameter »*t-meas-delay«.* This might be reasonable in order to achieve more reliable measuring values (e.g. in order to avoid measuring disturbances caused by significant DC-components).

Modes
In case of a fault record should be written even if an general alarm has not lead to a trip, the parameter »*Record-Mode«* is to be set to »*Alarms and Trips«* .

Set parameter »*Record-Mode«* to »*Trips only«*, if an Alarm that is not followed by a trip decision should not lead to a trip.

When does the overlay (popup) appears on the display of the HMI?
A popup will appear on the HMI display, when the General Pickup (Prot.Pickup) disappears.

NOTICE

No time to trip will be shown if the pickup signal that triggers the fault recorder is issued by another protection module than the trip signal. This might happen if more than one protection module is involved into a fault.

NOTICE

Please note: The parameter settings (thresholds etc.) that are shown in a fault record are not part of the fault record itself. They are always read out from the current device setting. If parameters settings that are shown in a fault record could have been updated, they will be indicated with an asterisk symbol within the fault record.

To prevent this please proceed as follows:

Save any fault record that should be archived to your local network/hard disk before doing any parameter change. Delete all the fault records in your fault recorder afterwards.

Memory
The last stored fault record is saved (fail-safe) within the *Fault Recorder* (the others are saved within a memory that depends on the auxiliary power of the protective relay). If there is no more memory free, the oldest record will be overwritten (FIFO). Up to 20 records can be stored.

How to close the overlay/popup?
By using Softkey »OK«.

How to find out fast, if a fault has lead to a trip or not?
Faults that lead to a trip will be indicated by a flash icon (right side) within the overview menu of the fault recorder.

Which fault record pops up?
The newest fault.

Content of a Fault Record

A fault record comprises information about:

Date/Time	Date and Time of the Fault			
FaultNr	The number of the fault will be incremented with each fault (General Alarm or »PROT.PICKUP«)			
Grid Fault No.	This counter will be incremented by each General Pickup (Exception AR: this applies only to devices that offer auto reclosing).			
Active Set	The active parameter set			
Time to trip	The time between pickup and trip. Please note: No time to trip will be shown if the first pickup and the first trip are issued by different protection modules.			
Alarm	Name of the module that picked up first.			
Trip	Name of the module that tripped first. The information that will be displayed depends on which protection module has tripped. That means e.g. that the thresholds are shown. In case that the trip was initiated by the MotorStart (applies to motor protection relays) protection module, additional information will be displayed.			
Adaptive Set	In case that adaptive sets are used, the number of the active set will be displayed.			
Fault type	In case of overcurrent trips, the fault type will be evaluated based on the energized phases.			
	Alarm Phase A	Alarm Phase B	Alarm Phase C	Fault Type
	x			L1G
		x		L2G
			x	L3G
	x	x		L1B
		x	x	L2L3
	x		x	L1L3
	x	x	x	L1L2L3
Direction	In case that a direction has been detected, the evaluated direction will be displayed (this applies to directional phase and ground overcurrent relays only).			
Measured Values	Various measuring values at the time of tripping (or delayed depending on parameter setting) will be displayed.			

How to set up the Fault Recorder

The »*Record-Mode*« will determine if trips only cause a fault record or if also Alarms without a consecutively trip should cause a fault record. This parameter is to be set within menu [Device Para\Recorders\Fault rec]

How to navigate within the Fault Recorder

Navigation within the <u>Fault recorder</u>	Softkey
Back to overview.	
Next (upper) item within this fault record.	
Previous fault record.	
Next (lower) item within this fault record.	

How to read Out the Fault Recorder

In order to read out a fault record there are two options available:

- Option 1: A Fault has popped up on the HMI (because an trip or pickup has occurred).
- Option 2: Call up manually the Fault recorder menu.

Option 1 (in case a fault record pops up on the display (overlay):

- Analyze the fault record by using Softkeys Arrow Up and Arrow Down.
- Or close the Popup by using Softkey OK

Option 2 :

- Call up the main menu;
- Call up the sub-menu »Operation/Recorders/Fault rec.«;
- Select a fault record; and
- Analyze the fault record by using Softkeys Arrow Up and Arrow Down.

Direct Commands of the Fault Recorder

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Res all rec	Reset all records	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]

Global Protection Parameters of the Fault Recorder

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Record-Mode	Recorder Mode (Set the behaviour of the recorder)	Alarms and Trips, Trips only	Trips only	[Device Para /Recorders /Fault rec]
t-meas-delay	After the Trip, the measurement will be delayed for this time.	0 - 60ms	0ms	[Device Para /Recorders /Fault rec]

Fault Recorder Signals

Signal	*Description*
Res rec	Signal: Delete record

Event Recorder

<u>Event rec</u>

The event recorder can register up to 300 events and the last (minimum) 50 saved events are recorded fail-safe. The following information is provided for any of the events:

Events are logged as follows:

Record No.	*Fault No.*	*No of grid faults*	*Date of Record*	*Module.Name*	*State*
Sequential Number	Number of the ongoing fault This counter will be incremented by each General Alarm (Prot.Alarm)	A grid fault No. can have several Fault No. This counter will be incremented by each General Alarm (Exception AR: this applies only to devices that offer auto reclosing)	Time stamp	What has changed?	Changed Value

There are three different classes of events:

- ***Alternation of binary states are shown as:***
  - 0->1 if the signal changes physically from »0« to »1«.
  - 1->0 if the signal changes physically from »1« to »0«.
- ***Counters increment is shown as:***
  - Old Counter state -> New Counter state (e.g. 3->4)
- ***Alternation of multiple states are shown as:***
  - Old state -> New state (e.g. 0->2)

Read Out the Event Recorder

- Call up the »*main menu«.*
- Call up the submenu *»Operation/Recorders/Event rec«*.
- Select an event.

Direct Commands of the Event Recorder

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Res all rec	Reset all records	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]

Event Recorder Signals

Signal	*Description*
Res all records	Signal: All records deleted

Trend Recorder

Available Elements:
Trend rec

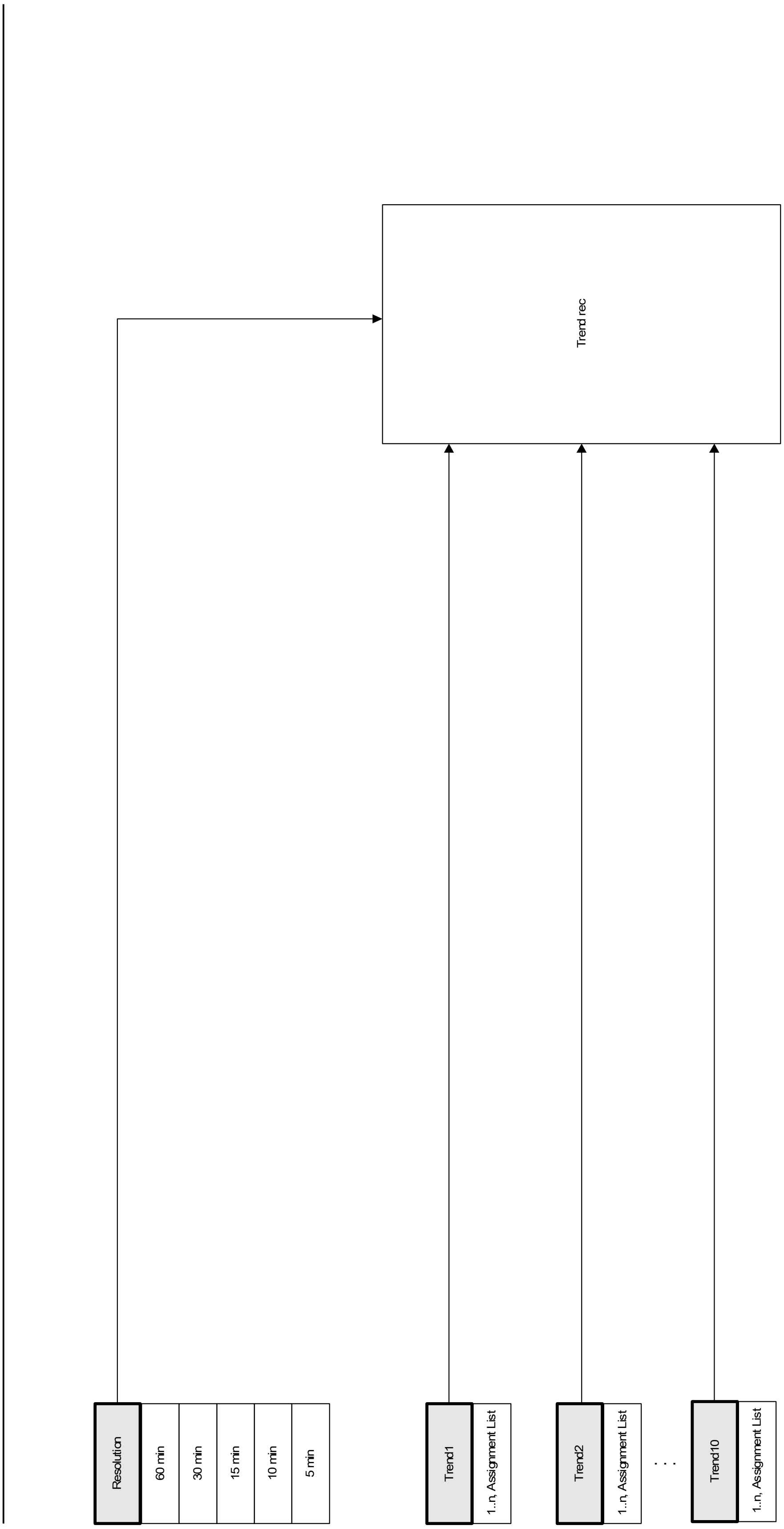
Configuring the Trend Recorder

The Trend Recorder is to be configured within [Device Para/Recorders/Trend Recorder] menu.

The User has to set the time interval. This defines the distance between two measuring points.

The User can select up to ten values that will be recorded.

Trend rec


Trend rec
Resolution
60 min
30 min
15 min
10 min
5 min
Trend1
1..n, Assignment List
Trend2
1..n, Assignment List
Trend10
1..n, Assignment List

Global Protection Parameters of the Trend Recorder

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Resolution	Resolution (recording frequency)	60 min, 30 min, 15 min, 10 min, 5 min	15 min	[Device Para /Recorders /Trend rec]
Trend1	Observed Value1	1..n, TrendRecList	CT.IL1 RMS	[Device Para /Recorders /Trend rec]
Trend2	Observed Value2	1..n, TrendRecList	CT.IL2 RMS	[Device Para /Recorders /Trend rec]
Trend3	Observed Value3	1..n, TrendRecList	CT.IL3 RMS	[Device Para /Recorders /Trend rec]
Trend4	Observed Value4	1..n, TrendRecList	CT.IG meas RMS	[Device Para /Recorders /Trend rec]
Trend5	Observed Value5	1..n, TrendRecList	-.-	[Device Para /Recorders /Trend rec]
Trend6	Observed Value6	1..n, TrendRecList	-.-	[Device Para /Recorders /Trend rec]
Trend7	Observed Value7	1..n, TrendRecList	-.-	[Device Para /Recorders /Trend rec]
Trend8	Observed Value8	1..n, TrendRecList	-.-	[Device Para /Recorders /Trend rec]
Trend9	Observed Value9	1..n, TrendRecList	-.-	[Device Para /Recorders /Trend rec]

Parameter	Description	Setting range	Default	Menu path
Trend10	Observed Value10	1..n, TrendRecList	-.-	[Device Para /Recorders /Trend rec]

Trend Recorder Signals (Output States)

Signal	Description
Hand Reset	Hand Reset

Direct Commands of the Trend Recorder

Parameter	Description	Setting range	Default	Menu path
Reset	Delete all entries	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]

General Values of the Trend Recorder

Value	Description	Default	Size	Menu path
Max avail Entries	Maximum available entries in the current configuration	0	0 - 9999999999	[Operation /Count and RevData /Trend rec]

Global Values of the Trend Recorder

The »*TrendRecList*« below summarizes all signals that the User can assign.

Name	Description
-.-	No assignment
CT.IL1	Measured value: Phase current (fundamental)
CT.IL2	Measured value: Phase current (fundamental)
CT.IL3	Measured value: Phase current (fundamental)
CT.IG meas	Measured value (measured): IG (fundamental)
CT.IG calc	Measured value (calculated): IG (fundamental)
CT.IL1 RMS	Measured value: Phase current (RMS)
CT.IL2 RMS	Measured value: Phase current (RMS)
CT.IL3 RMS	Measured value: Phase current (RMS)
CT.IG meas RMS	Measured value (measured): IG (RMS)

Name	*Description*
CT.IG calc RMS	Measured value (calculated): IG (RMS)
CT.I0	Measured value (calculated): Zero current (fundamental)
CT.I1	Measured value (calculated): Positive phase sequence current (fundamental)
CT.I2	Measured value (calculated): Unbalanced load current (fundamental)
CT.%(I2/I1)	Measured value (calculated): I2/I1, phase sequence will be taken into account automatically.
CT.%(I2/I1) max	Measured value (calculated): I2/I1 maximum value, phase sequence will be taken into account automatically
CT.IL1 avg RMS	IL1 average value (RMS)
CT.IL2 avg RMS	IL2 average value (RMS)
CT.IL3 avg RMS	IL3 average value (RMS)
CT.IL1 THD	Measured value (calculated): IL1 Total Harmonic Current
CT.IL2 THD	Measured value (calculated): IL2 Total Harmonic Current
CT.IL3 THD	Measured value (calculated): IL3 Total Harmonic Current
MStart.IL1 Ib	Measured value: Phase current as multiple of Ib
ThR.I2T Used	Thermal capacity used.
URTD.Windg1	Winding 1
URTD.Windg1 max	Winding1 Maximum Value
URTD.Windg2	Winding 2
URTD.Windg2 max	Winding2 Maximum Value
URTD.Windg3	Winding 3
URTD.Windg3 max	Winding3 Maximum Value
URTD.Windg4	Winding 4
URTD.Windg4 max	Winding4 Maximum Value
URTD.Windg5	Winding 5
URTD.Windg5 max	Winding5 Maximum Value
URTD.Windg6	Winding 6
URTD.Windg6 max	Winding6 Maximum Value
URTD.MotBear1	Motor Bearing 1
URTD.MotBear1 max	Motor Bearing1 Maximum Value
URTD.MotBear2	Motor Bearing 2
URTD.MotBear2 max	Motor Bearing2 Maximum Value
URTD.LoadBear1	Load Bearing 1
URTD.LoadBear1 max	Load Bearing1 Maximum Value
URTD.LoadBear2	Load Bearing 2
URTD.LoadBear2 max	Load Bearing2 Maximum Value
URTD.Aux1	Auxiliary1
URTD.Aux1 max	Auxiliary1 Maximum Value
URTD.Aux2	Auxiliary2
URTD.Aux2 max	Auxiliary2 Maximum Value

Name	*Description*
URTD.RTD Max	Maximum temperature of all channels.
RTD.HottestWindingTemp	Hottest motor winding temperature in degrees C.
RTD.Hottest MotBearTemp	Hottest motor bearing temperature in degrees C.
RTD.Hottest LoadBearTemp	Hottest load bearing temperature in degrees C.
RTD.Hottest Aux Temp	Hottest Auxiliary temperature in degrees C.

Motor Start Recorder

Available Elements:
Start rec

The Motor Start Recorder logs information during a motor start-up. These records are stored in a fail-safe manner and the capacity allows for recording up to 5 start-ups. After 5 start-ups, every following start-up overwrites the recording of the oldest one („First in First out“ principle).

Every recording consists of a summary of information and recorded analog trends. However, the exact set of data is dependent on the ordered device variant. The summary data can be accessed using *Smart view* or via the front panel interface of the relay. This feature provides information recorded at the time of each start of the motor such as:

- Date of the motor start event
- Record number
- *IA max RMS, IB max RMS, IC max RMS, IX max RMS* – Maximum RMS phase current of the respective phase
- *Unbalance max* – Maximum current unbalance during the motor start-up
- *TIR avg* – Average current of all three phases at the time of the start-to-run transition
- *Speed* – The motor nominal speed (1 or 2)
- Time (duration) values:
  - *TSTI* – The time that elapses from the start until the current value drops below the set start-up threshold
  - *TSTR* – The time that elapses from the start until the motor is running, or – in case of an incomplete start sequence – until the trip command
- *I2T Used* – Thermal capacity used, specified as percentage of the maximum thermal capacity
- *Start success* – This is set to 1 if the motor start has been successful (and equals 0 otherwise).

Smart view allows for storing the summary information as text files, or have them printed out.

The analog trends can be viewed using the *DataVisualizer*. Examples for recorded analog trends are:

- Phase current values
- Current unbalance
- Thermal capacity
- Temperatures (in case an RTD box is fitted)

Managing Start Records

The start recorder data can be downloaded by means of *Smart view* from the device.

- Start *Smart view* if this has not been done already.
- If the data has not been downloaded from the device yet, select the menu item “Receive Start Recorder” in the “Device” menu.
- Within the navigation tree, double-click the “Operation” icon.
- Go to the [Operation / Recorders] menu. Here the user will find the “Start Rec” menu item.
- By selecting “Start Rec”, the Start Recorder Window will appear

To access data that has been stored in the device using *Smart view*, the User must select the “Receive Start Recorder” button in the upper left hand corner of the “Start Rec” window. When clicked, the *Smart view* software will retrieve the highlighted record from the device.

After selecting one of the max. 5 recordings a summary of the Start Recorder data can be retrieved (for the selected recording) by clicking the “Receive Summary Data” button in the upper left hand corner of the “Start Rec” window.

A list of all currently available Start Records is viewable by selecting the “Refresh Start Recorder” button on the start recorder.

It is possible to delete individual records that are stored on the protective device. First, select “Receive Start Recorder”, and then select the record to be deleted by clicking on the record number, followed by the selection of the “Delete Start Record” button in the upper left hand corner of the “Start Rec” window.

To permanently remove all start records within a device's start recorder, select the “Delete All Start Records” button also located in the upper left hand corner of the “Start Rec” window. This will remove all previously stored start records within the device to which the user is presently connected.

Open a Start Record file from a local storage device. Please note that it is possible to compare an archived Start Record against archived Parameter settings that are also stored on a local device. Read the “Caution” information below (page 219).

When using *Smart view* to view the Start Recorder data, the Start Recorder features can also be found by right clicking anywhere within the “Start Rec” window.

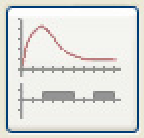
NOTICE

The “Print” button takes the user to the printing dialogue, where it is possible to export the summary into a text file. This is done the following way:

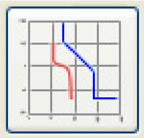
- **Retrieve the data in the “Start Rec” window, as described above.**
- **Click on the button „Receive Summary Data“.**
- **Click on the “Print” button.**
- **Click on the button “Export to file”.**
- **Enter a valid file name.**
- **Select the file path.**
- **Click on the “Save” button.**

Displaying Start Records

When a Start Record is called up, a window with the following options pops up.



View motor start data graphically in the *Data visualizer* software. In the *Data visualizer* software the user can view the RMS value of the phase currents, thermal capacity used, and temperatures measured by the URTD module if a URTD is installed and attached to the relay.



View motor start data overlayed with the Motor Protection Curves (Starting Profile Plot versus Protection limits). The user can view the average current recorded during the motor start versus protection elements such as 50P, or the Thermal Model. The user has the option to alter the displayed setting groups.
Please note that protective elements, that are not projected within the device planning, won't be visible.

The Starting Profile Plot offers two User Scenarios:

1. Adapting the protection settings to the recorded start curve. The User will see the impact of parameter changes in the Profile Plot. By means of this he can decide if the relay settings match the protection requirements.
2. Analyzing a Start Record. Since a Start Record does not include the relay settings, the User has to ensure, that backups of the relay settings are available that were valid at the time of recording.

CAUTION

Please Note that the Starting Profile Plot shows the recorded average current versus the current relay settings. The relay settings itself are not part of a Start Record.

Adaptive parameters and their impacts wont be visible within the Starting Profile.

Blockings wont be visible within the Starting Profile.

Please make sure to save the setting files together with this record to guarantee the graph represents the conditions of when this event occurred.

Global Protection Parameters of the Motor Start Recorder

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Resolution	Resolution (recording frequency)	50ms, 100ms, 1s	50ms	[Device Para /Recorders /Start rec]

Motor Start Recorder Signals (Output States)

Signal	*Description*
Storing	Signal: Data are saved

Direct Commands of the Motor Start Recorder

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ClearStartRec	Delete all start recorder records	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]
ClearStatisticRec	Delete all statistic recorder records (start trending)	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]

Statistic Recorder

The Statistic Recorder shows motor specific statistical data on a monthly base.
The Statistic Recorder can record up to 24 monthly reports. The reports are power fail safe stored.
In order to view information from the Statistic Recorder, the User has to select [Operation/Recorder/Statisticrec] from the menu tree.

By double clicking on the »Date of Record« statistics information can be viewed such as the number of starts, the number of successful starts, the average start time, the »*average I2T*« value during any start, and the average of all maximum currents value seen during each start.

Communication Protocols

SCADA Interface

Scada

Device Planning Parameters of the Serial Scada Interface

Parameter	*Description*	*Options*	*Default*	*Menu path*
Protocol	Select the SCADA protocol to be used.	do not use, Modbus RTU, Modbus TCP, Modbus TCP/RTU, DNP3 RTU, DNP3 TCP, DNP3 UDP, IEC60870-5-103, IEC61850, Profibus	do not use	[Device planning]

Signals (Output States) of the SCADA Interface

Signal	*Description*
SCADA connected	At least one SCADA System is connected to the device.
SCADA not connected	No SCADA System is connected to the device

TCP/IP Parameter

TcpIp

Global TCP/IP Parameters

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Keep Alive Time	Keep Alive Time is the duration between two keep alive transmissions in idle condition	1 - 7200s	720s	[Device Para /TCP/IP /Advanced Settings]
Keep Alive Interval	Keep Alive Interval is the duration between two successive keep alive retransmissions, if the acknowledgement to the previous keepalive transmission was not received.	1 - 60s	15s	[Device Para /TCP/IP /Advanced Settings]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Keep Alive Retry	Keep alive retry is the number of retransmissions to be carried out before declaring that the remote end is not available.	3 - 3	3	[Device Para /TCP/IP /Advanced Settings]

Modbus®

Modbus

Modbus® Protocol Configuration

The time-controlled Modbus® protocol is based on the Master-Slave working principle. This means that the substation control and protection system sends an enquiry or instruction to a certain device (slave address) which will then be answered or carried out accordingly. If the enquiry/instruction cannot be answered/carried out (e.g. because of an invalid slave address), a failure message is returned to the master.

The Master (substation control and protection system) can query information from the device, such as:

- Type of unit version
- Measuring values/Statistical measured values
- Switch operating position
- State of device
- Time and date
- State of the device's digital inputs
- Protection-/State alarms

The Master (control system) can give commands/instructions to the device, such as:

- Control of switchgear (where applicable, i.e. each acc. to the applied device version)
- Change-over of parameter set
- Reset and acknowledgement of alarms/signals
- Adjustment of date and time
- Control of alarm relays

For detailed information on data point lists and error handling, please refer to the Modbus® documentation.

To allow configuration of the devices for Modbus® connection, some default values of the control system must be available.

Modbus RTU

Part 1: Configuration of the Devices

Call up *»Device parameter/Modbus«* and set the following communication parameters there:

- Slave-address, to allow clear identification of the device.
- Baud-Rate

Also, select below indicated RS485 interface-related parameters from there, such as:

- Number of data bits
- One of the following supported communication variants: Number of data bits, even, odd, parity or no parity, number of stop bits.
- *»t-timeout«*: communication errors are only identified after expiry of a supervision time *»t-timeout«*.
- Response time (defining the period within which an enquiry from the master has to be answered).

Part 2: Hardware Connection

- For hardware connection to the control system, there is an RS485 interface at the rear side of the device (RS485, fiber optic or terminals).
- Connect bus and device (wiring).

Error Handling - Hardware Errors

Information on physical communication errors, such as:

- Baudrate Error
- Parity Error ...

can be obtained from the event recorder.

Error Handling – Errors on protocol level

If, for example, an invalid memory address is enquired, error codes will be returned by the device that need to be interpreted.

Modbus TCP

NOTICE

Establishing a connection via TCP/IP to the device is only possible if your device is equipped with an Ethernet Interface (RJ45).

Contact your IT administrator in order to establish the network connection.

Part 1: Setting the TCP/IP Parameters

Call up *»Device parameter/TCP/IP«* at the HMI (panel) and set the following parameters:

- TCP/IP address
- Subnetmask
- Gateway

Part 2: Configuration of the Devices

Call up *»Device parameter/Modbus«* and set the following communication parameters:

- Setting a Unit Identifier is only necessary if a TCP network should be coupled to a RTU network.
- If a different port than the default port 502 should be used please proceed as follows:
  - Choose “Private” within the TCP-Port-Configuration.
  - Set the port-number.
- Set the maximum accepted time of “no communication”. If this time has expired – without any comunication, the device concludes a failure within the master system.
- Allow or disallow the blocking of SCADA commands.

Part 3: Hardware Connection

- There is a RJ45 interface at the rear side of the device for the hardware connection to the control system.
- Establish the connection to the device by means of a proper Ethernet cable.

Direct Commands of the Modbus®

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Res Diagn Cr	All Modbus Diagnosis Counters will be reset.	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]

Global Protection Parameters of the Modbus®

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Slave ID	Device address (Slave ID) within the bus system. Each device address has to be unique within a bus system.	1 - 247	1	[Device Para /Modbus / Communication /RTU]
Unit ID	The Unit Identifier is used for routing. This parameter is to be set, if a Modbus RTU and a Modbus TCP network should be coupled.	1 - 255	255	[Device Para /Modbus / Communication /TCP]
TCP Port Config	TCP Port Configuration. This parameter is to be set only if the default Modubs TCP Port should not be used.	Default, Private	Default	[Device Para /Modbus / Communication /TCP]
Port	IP Port Number. And Only available if: TCP Port Config = Private In general it is recommended to keep the default value. if this is not possible then select a number out of the private range 49152-52151 or 52162-65535 that is not yet in use within your network. And Only available if: TCP Port Config = Private	502 - 65535	502	[Device Para /Modbus / Communication /TCP]
t-timeout	Within this time the answer has to be received by the SCADA system, otherwise the request will be disregarded. In that case the Scada system detects a communication failure and the Scada System has to send a new request.	0.01 - 10.00s	1s	[Device Para /Modbus / Communication /RTU]
Baud rate	Baud rate	1200, 2400, 4800, 9600, 19200, 38400	19200	[Device Para /Modbus / Communication /RTU]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Physical Settings	Digit 1: Number of bits. Digit 2: E=even parity, O=odd parity, N=no parity. Digit 3: Number of stop bits. More information on the parity: It is possible that the last data bit is followed by a parity bit which is used for recognition of communication errors. The parity bit ensures that with even parity ("EVEN") always an even number of bits with valence "1" or with odd parity ("ODD") an odd number of "1" valence bits are transmitted. But it is also possible to transmit no parity bits (here the setting is "Parity = None"). More information on the stop-bits: The end of a data byte is terminated by the stop-bits.	8E1, 8O1, 8N1, 8N2	8E1	[Device Para /Modbus / Communication /RTU]
t-call	If there is no request telegram sent from Scada to the device after expiry of this time - the device concludes a communication failure within the Scada system.	1 - 3600s	10s	[Device Para /Modbus / Communication /General Settings]
Scada CmdBlo	Activating (allowing)/ Deactivating (disallowing) the blocking of the Scada Commands	inactive, active	inactive	[Device Para /Modbus / Communication /General Settings]
Disable Latching	Disable Latching: If this parameter is active (true), none of the Modbus states will be latched. That means that trip signals wont be latched by Modbus.	inactive, active	inactive	[Device Para /Modbus / Communication /General Settings]
AllowGap	If this parameter is active (True), the user can request a set of modbus register without getting an exception, because of invalid address in the requested array. The invalid addresses have a special value 0xFAFA, but the user is responsible for ignoring invalid addresses. Attention: This special value can be valid, if address is valid.	inactive, active	inactive	[Device Para /Modbus / Communication /General Settings]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Optical rest position	Optical rest position	Light off, Light on	Light on	[Device Para /Modbus /Communication /General Settings]
Config Bin Inp1	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp1	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp2	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp2	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp3	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp3	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp4	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Latched Config Bin Inp4	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp5	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp5	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp6	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp6	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp7	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp7	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp8	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Latched Config Bin Inp8	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp9	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp9	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp10	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp10	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp11	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp11	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp12	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Latched Config Bin Inp12	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp13	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp13	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp14	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp14	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp15	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp15	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp16	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]

Parameter	Description	Setting range	Default	Menu path
Latched Config Bin Inp16	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp17	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp17	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp18	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp18	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp19	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp19	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp20	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Latched Config Bin Inp20	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp21	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp21	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp22	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp22	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp23	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp23	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp24	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]

Parameter	Description	Setting range	Default	Menu path
Latched Config Bin Inp24	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp25	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp25	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp26	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp26	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp27	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp27	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp28	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Latched Config Bin Inp28	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp29	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp29	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp30	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp30	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp31	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]
Latched Config Bin Inp31	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp32	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Modbus /Configb Registers /States]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Latched Config Bin Inp32	Latched Configurable Binary Input	inactive, active	inactive	[Device Para /Modbus /Configb Registers /States]
Mapped Meas 1	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	1..n, TrendRecList	-.-	[Device Para /Modbus /Configb Registers /Measured Values]
Mapped Meas 2	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	1..n, TrendRecList	-.-	[Device Para /Modbus /Configb Registers /Measured Values]
Mapped Meas 3	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	1..n, TrendRecList	-.-	[Device Para /Modbus /Configb Registers /Measured Values]
Mapped Meas 4	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	1..n, TrendRecList	-.-	[Device Para /Modbus /Configb Registers /Measured Values]
Mapped Meas 5	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	1..n, TrendRecList	-.-	[Device Para /Modbus /Configb Registers /Measured Values]
Mapped Meas 6	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	1..n, TrendRecList	-.-	[Device Para /Modbus /Configb Registers /Measured Values]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Mapped Meas 7	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	1..n, TrendRecList	-.-	[Device Para /Modbus /Configb Registers /Measured Values]
Mapped Meas 8	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	1..n, TrendRecList	-.-	[Device Para /Modbus /Configb Registers /Measured Values]
Mapped Meas 9	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	1..n, TrendRecList	-.-	[Device Para /Modbus /Configb Registers /Measured Values]
Mapped Meas 10	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	1..n, TrendRecList	-.-	[Device Para /Modbus /Configb Registers /Measured Values]
Mapped Meas 11	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	1..n, TrendRecList	-.-	[Device Para /Modbus /Configb Registers /Measured Values]
Mapped Meas 12	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	1..n, TrendRecList	-.-	[Device Para /Modbus /Configb Registers /Measured Values]
Mapped Meas 13	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	1..n, TrendRecList	-.-	[Device Para /Modbus /Configb Registers /Measured Values]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Mapped Meas 14	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	1..n, TrendRecList	-.-	[Device Para /Modbus /Configb Registers /Measured Values]
Mapped Meas 15	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	1..n, TrendRecList	-.-	[Device Para /Modbus /Configb Registers /Measured Values]
Mapped Meas 16	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	1..n, TrendRecList	-.-	[Device Para /Modbus /Configb Registers /Measured Values]

States of the Module Inputs of the MODBUS® Protocol

Name	*Description*	*Assignment via*
Config Bin Inp1-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp2-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp3-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp4-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]

Name	*Description*	*Assignment via*
Config Bin Inp5-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp6-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp7-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp8-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp9-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp10-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp11-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp12-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp13-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]

Name	*Description*	*Assignment via*
Config Bin Inp14-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp15-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp16-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp17-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp18-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp19-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp20-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp21-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp22-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]

Name	*Description*	*Assignment via*
Config Bin Inp23-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp24-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp25-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp26-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp27-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp28-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp29-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp30-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]
Config Bin Inp31-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]

Name	*Description*	*Assignment via*
Config Bin Inp32-I	State of the module input: Config Bin Inp	[Device Para /Modbus /Configb Registers /States]

Values of the MODBUS® Protocol

Value	*Description*	*Menu path*
Mapped Meas 1	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	[Operation /Count and RevData /Modbus /General Settings]
Mapped Meas 2	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	[Operation /Count and RevData /Modbus /General Settings]
Mapped Meas 3	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	[Operation /Count and RevData /Modbus /General Settings]
Mapped Meas 4	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	[Operation /Count and RevData /Modbus /General Settings]
Mapped Meas 5	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	[Operation /Count and RevData /Modbus /General Settings]
Mapped Meas 6	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	[Operation /Count and RevData /Modbus /General Settings]
Mapped Meas 7	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	[Operation /Count and RevData /Modbus /General Settings]

Value	*Description*	*Menu path*
Mapped Meas 8	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	[Operation /Count and RevData /Modbus /General Settings]
Mapped Meas 9	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	[Operation /Count and RevData /Modbus /General Settings]
Mapped Meas 10	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	[Operation /Count and RevData /Modbus /General Settings]
Mapped Meas 11	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	[Operation /Count and RevData /Modbus /General Settings]
Mapped Meas 12	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	[Operation /Count and RevData /Modbus /General Settings]
Mapped Meas 13	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	[Operation /Count and RevData /Modbus /General Settings]
Mapped Meas 14	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	[Operation /Count and RevData /Modbus /General Settings]
Mapped Meas 15	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	[Operation /Count and RevData /Modbus /General Settings]
Mapped Meas 16	Mapped Measured Values. They can be used to provide measured values to the Modbus Master.	[Operation /Count and RevData /Modbus /General Settings]

Counters of the MODBUS® Protocol

Parameter	*Description*
Device Type	Device Type: Device type code for relationship between device name and its Modbus code. Woodward: MRI4 - 1000 MRU4 - 1001 MRA4 - 1002 MCA4 - 1003 MRDT4 - 1005 MCDTV4 - 1006 MCDGV4 - 1007 MRM4 - 1009 MRMV4 - 1010 MCDLV4 - 1011
Comm Version	Modbus Communication version. This version number changes if something becomes incompatible between different Modbus releases.

Modbus® Signals (Output States)

NOTICE Some signals (that are for a short time active only) have to be acknowledged separately (e.g. Trip signals) by the Communication System.

Signal	*Description*
Transmission RTU	Signal: SCADA active
Transmission TCP	Signal: SCADA active
Scada Cmd 1	Scada Command
Scada Cmd 2	Scada Command
Scada Cmd 3	Scada Command
Scada Cmd 4	Scada Command
Scada Cmd 5	Scada Command
Scada Cmd 6	Scada Command
Scada Cmd 7	Scada Command
Scada Cmd 8	Scada Command
Scada Cmd 9	Scada Command
Scada Cmd 10	Scada Command
Scada Cmd 11	Scada Command
Scada Cmd 12	Scada Command
Scada Cmd 13	Scada Command
Scada Cmd 14	Scada Command

Signal	Description
Scada Cmd 15	Scada Command
Scada Cmd 16	Scada Command

Modbus® Values

Value	Description	Default	Size	Menu path
NoOfRequestsTotal	Total number of requests. Includes requests for other slaves.	0	0 - 9999999999	[Operation /Count and RevData /Modbus /RTU]
NoOfRequestsForMe	Total Number of requests for this slave.	0	0 - 9999999999	[Operation /Count and RevData /Modbus /RTU]
NoOfResponsTimeOverruns	Total number of requests with exceeded response time. Physically corrupted Frame.	0	0 - 9999999999	[Operation /Count and RevData /Modbus /RTU]
NoOfOverrunErros	Total Number of Overrun Failures. Physically corrupted Frame.	0	0 - 9999999999	[Operation /Count and RevData /Modbus /RTU]
NoOfParityErrors	Total number of parity errors. Physically corrupted Frame.	0	0 - 9999999999	[Operation /Count and RevData /Modbus /RTU]
NoOfFrameErrors	Total Number of Frame Errors. Physically corrupted Frame.	0	0 - 9999999999	[Operation /Count and RevData /Modbus /RTU]
NoOfBreaks	Number of detected communication aborts	0	0 - 9999999999	[Operation /Count and RevData /Modbus /RTU]
NoOfQueryInvalid	Total number of Request errors. Request could not be interpreted	0	0 - 9999999999	[Operation /Count and RevData /Modbus /RTU]

Value	*Description*	*Default*	*Size*	*Menu path*
NoOfInternalError	Total Number of Internal errors while interpreting the request.	0	0 - 9999999999	[Operation /Count and RevData /Modbus /RTU]
NoOfRequestsTotal	Total number of requests. Includes requests for other slaves.	0	0 - 9999999999	[Operation /Count and RevData /Modbus /TCP]
NoOfRequestsForMe	Total Number of requests for this slave.	0	0 - 9999999999	[Operation /Count and RevData /Modbus /TCP]
NoOfResponse	Total number of requests having been responded.	0	0 - 9999999999	[Operation /Count and RevData /Modbus /TCP]
NoOfQueryInvalid	Total number of Request errors. Request could not be interpreted	0	0 - 9999999999	[Operation /Count and RevData /Modbus /TCP]
NoOfInternalError	Total Number of Internal errors while interpreting the request.	0	0 - 9999999999	[Operation /Count and RevData /Modbus /TCP]

Profibus

Profibus

Part 1: Configuration of the Devices

Call up *»Device parameter/Profibus«* and set the following communication parameter:

- Slave-address, to allow clear identification of the device.

In addition to that the Master has to be provided with the GSD-file. The GSD-file can be taken from the Product-CD.

Part 2: Hardware Connection

- For hardware connection to the control system, there is optional an D-SUB interface at the rear side of the device.
- Connect bus and device (wiring).
- Up to 123 slaves can be connected.
- Terminate the Bus by means of an Terminate Resistor.

Error Handling

Information on physical communication errors, such as:

- Baudrate Error

This can be obtained from the event recorder or the status display.

Error Handling – Status LED at the rear side

The Profibus D-SUB interface at the rear side of the device is equipped with an status LED.

- Baud Search -> red flashing
- Baud Found -> green flashing
- Data Exchange -> green
- No Profibus/Unplugged, not connected -> red

Direct Commands of the Profibus

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Reset Comds	All Profibus Commands will be reset.	inactive, active	inactive	[Operation /Reset/Acknowledge /Reset]

Global Protection Parameters of the Profibus

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Config Bin Inp 1	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 1-16]
Latched 1	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 1-16]
Config Bin Inp 2	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 1-16]
Latched 2	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 1-16]
Config Bin Inp 3	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 1-16]
Latched 3	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 1-16]
Config Bin Inp 4	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 1-16]
Latched 4	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 1-16]

Parameter	Description	Setting range	Default	Menu path
Config Bin Inp 5	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 1-16]
Latched 5	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 1-16]
Config Bin Inp 6	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 1-16]
Latched 6	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 1-16]
Config Bin Inp 7	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 1-16]
Latched 7	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 1-16]
Config Bin Inp 8	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 1-16]
Latched 8	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 1-16]
Config Bin Inp 9	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 1-16]
Latched 9	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 1-16]

Parameter	Description	Setting range	Default	Menu path
Config Bin Inp 10	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 1-16]
Latched 10	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 1-16]
Config Bin Inp 11	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 1-16]
Latched 11	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 1-16]
Config Bin Inp 12	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 1-16]
Latched 12	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 1-16]
Config Bin Inp 13	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 1-16]
Latched 13	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 1-16]
Config Bin Inp 14	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 1-16]
Latched 14	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 1-16]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Config Bin Inp 15	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 1-16]
Latched 15	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 1-16]
Config Bin Inp 16	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 1-16]
Latched 16	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 1-16]
Config Bin Inp 17	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 17-32]
Latched 17	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 17-32]
Config Bin Inp 18	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 17-32]
Latched 18	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 17-32]
Config Bin Inp 19	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 17-32]
Latched 19	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 17-32]

Parameter	Description	Setting range	Default	Menu path
Config Bin Inp 20	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 17-32]
Latched 20	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 17-32]
Config Bin Inp 21	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 17-32]
Latched 21	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 17-32]
Config Bin Inp 22	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 17-32]
Latched 22	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 17-32]
Config Bin Inp 23	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 17-32]
Latched 23	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 17-32]
Config Bin Inp 24	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 17-32]
Latched 24	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 17-32]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Config Bin Inp 25	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 17-32]
Latched 25	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 17-32]
Config Bin Inp 26	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 17-32]
Latched 26	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 17-32]
Config Bin Inp 27	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 17-32]
Latched 27	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 17-32]
Config Bin Inp 28	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 17-32]
Latched 28	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 17-32]
Config Bin Inp 29	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 17-32]
Latched 29	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 17-32]

Parameter	Description	Setting range	Default	Menu path
Config Bin Inp 30	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 17-32]
Latched 30	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 17-32]
Config Bin Inp 31	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 17-32]
Latched 31	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 17-32]
Config Bin Inp 32	Virtual Digital Input. This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /Profibus /Config Bin Inp 17-32]
Latched 32	Defines whether the Input is latched. Only available if: Latched = active	inactive, active	inactive	[Device Para /Profibus /Config Bin Inp 17-32]
Slave ID	Device address (Slave ID) within the bus system. Each device address has to be unique within a bus system.	2 - 125	2	[Device Para /Profibus /Bus parameters]

Inputs of the Profibus

Name	Description	Assignment via
Assignment 1-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 1-16]
Assignment 2-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 1-16]
Assignment 3-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 1-16]

Name	*Description*	*Assignment via*
Assignment 4-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 1-16]
Assignment 5-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 1-16]
Assignment 6-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 1-16]
Assignment 7-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 1-16]
Assignment 8-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 1-16]
Assignment 9-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 1-16]
Assignment 10-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 1-16]
Assignment 11-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 1-16]
Assignment 12-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 1-16]
Assignment 13-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 1-16]
Assignment 14-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 1-16]
Assignment 15-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 1-16]
Assignment 16-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 1-16]

Name	*Description*	*Assignment via*
Assignment 17-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 17-32]
Assignment 18-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 17-32]
Assignment 19-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 17-32]
Assignment 20-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 17-32]
Assignment 21-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 17-32]
Assignment 22-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 17-32]
Assignment 23-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 17-32]
Assignment 24-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 17-32]
Assignment 25-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 17-32]
Assignment 26-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 17-32]
Assignment 27-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 17-32]
Assignment 28-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 17-32]
Assignment 29-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 17-32]

Name	Description	Assignment via
Assignment 30-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 17-32]
Assignment 31-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 17-32]
Assignment 32-I	Module input state: Scada Assignment	[Device Para /Profibus /Config Bin Inp 17-32]

Profibus Signals (Output States)

Signal	Description
Data OK	Data within the Input field are OK (Yes=1)
SubModul Err	Assignable Signal, Failure in Sub-Module, Communication Failure.
Connection active	Connection active
Scada Cmd 1	Scada Command
Scada Cmd 2	Scada Command
Scada Cmd 3	Scada Command
Scada Cmd 4	Scada Command
Scada Cmd 5	Scada Command
Scada Cmd 6	Scada Command
Scada Cmd 7	Scada Command
Scada Cmd 8	Scada Command
Scada Cmd 9	Scada Command
Scada Cmd 10	Scada Command
Scada Cmd 11	Scada Command
Scada Cmd 12	Scada Command
Scada Cmd 13	Scada Command
Scada Cmd 14	Scada Command
Scada Cmd 15	Scada Command
Scada Cmd 16	Scada Command

Profibus Values

Value	Description	Default	Size	Menu path
Fr Sync Err	Frames, that were sent from the Master to the Slave are faulty.	1	1 - 99999999	[Operation /Count and RevData /Profibus]

Value	*Description*	*Default*	*Size*	*Menu path*
crcErrors	Number of CRC errors that the ss manager has recognized in received response frames from ss (each error caused a subsystem reset)	1	1 - 99999999	[Operation /Count and RevData /Profibus]
frLossErrors	Number of frame loss errors that the ss manager recognized in received response frames from ss (each error caused a subsystem reset)	1	1 - 99999999	[Operation /Count and RevData /Profibus]
ssCrcErrors	Number of CRC errors that the subsystem has recognized in received trigger frames from host	1	1 - 99999999	[Operation /Count and RevData /Profibus]
ssResets	Number of subsystem resets/restarts from ss manager	1	1 - 99999999	[Operation /Count and RevData /Profibus]
Master ID	Device address (Master ID) within the bus system. Each device address has to be unique within a bus system.	1	1 - 125	[Operation /Status Display /Profibus /State]
HO Id PSub	Handoff Id of PbSub	0	0 - 9999999999	[Operation /Status Display /Profibus /State]
t-WatchDog	The Profibus Chip detects a communication issue if this timer is expired without any communication (Parameterising telegram).	0	0 - 9999999999	[Operation /Status Display /Profibus /State]

Value	*Description*	*Default*	*Size*	*Menu path*
Slave State	Communication State between Slave and Master.	Baud Search	Baud Search, Baud Found, PRM OK, PRM REQ, PRM Fault, CFG Fault, Clear Data, Data exchange	[Operation /Status Display /Profibus /State]
Baud rate	The baud rate that has been detected lastly, will still be shown after a connection issue.	-.-	12 Mb/s, 6 Mb/s, 3 Mb/s, 1.5 Mb/s, 0.5 Mb/s, 187500 baud, 93750 baud, 45450 baud, 19200 baud, 9600 baud, -.-	[Operation /Status Display /Profibus /State]
PNO Id	PNO Identification Number. GSD Identification Number.	0C50h	0C50h	[Operation /Status Display /Profibus /State]

IEC60870-5-103

IEC 103

IEC60870-5-103 Protocol Configuration

In order to use the IEC60870-5-103 protocol it has to be assigned to the X103 Interface within the Device Planning. The device will reboot after setting this parameter.
Moreover, the IEC103 protocol has to be activated by setting [Device Para/ IEC 103] *»Function«* to "active".

NOTICE **The parameter X103 is only available if the device is at the rear side equipped with an interface like RS485 or Fiber Optic.**

NOTICE **If the device is equipped with an Fiber Optic Interface, the Optical Rest Position has to be set within the Device Parameters .**

The time-controlled IEC60870-5-103 protocol is based on the Master-Slave working principle. This means that the substation control and protection system sends an enquiry or instruction to a certain device (slave address) which will then be answered or carried out accordingly.
The device meets the compatibility mode 2. Compatibility mode 3 is not supported.

The following IEC60870-5-103-functions will be supported:

- Initialization (Reset)
- Time Synchronization
- Reading out of time stamped, instantaneous signals
- General Queries
- Cyclic Signals
- General Commands
- Transmission of Disturbance Data
- Blocking of Monitor Direction
- Test Mode

Initialization
The communication has to be reset by a Reset Command each time that the device is turned on or that communication parameters have been changed. The "Reset CU" Command resets. The relay acts on both Reset Commands (Reset CU or Reset FCB).

The relay acts on the reset command by an identification signal ASDU 5 (Application Service Data Unit), as a reason (Cause Of Transmission, COT) for the transmission of the answer either a "Reset CU" or a "Reset FCB" will be sent depending on the type of the reset command. This information can be part of the data section of the ASDU-signal.

Name of the Manufacturer
The section for the identification of the software contains three digits of the device code for the identification of the device type. Beside the upper mentioned identification number the device generates a communication start event.

Time Synchronization
Time and date of the relay can be set by means of the time synchronization function of the IEC60870-5-103 protocol. If the time synchronization signal is send out with a confirmation request, the device will answer with a confirmation signal.

Spontaneous Events
The events that are generated by the device will be forwarded to the master with numbers for standard function types / standard information. The data point list comprises all events that can be generated by the device.

Cyclic Measurement
The device generates on a cyclic base measured values by means of ASDU 9. They can be read out via a class 2 query. Please take into account that the measured values will be send out as multiples (1.2 or 2.4 times the rated value). How to set 1.2 or 2.4 as multiplier for a value can be taken from the data point list.

The parameter “Transm priv meas val” defines if additional measurement values should be transmitted in the private part. Public and private measured values are transmitted by ASDU9. That means that either a “private” or a “public” ASDU9 will be transmitted. If this parameter is set, the ASDU9 will contain additional measured values that are an enhancement of the standard. The “private” ASDU9 is send with a fixed function type and information number that does not depend the type of device. Please refer to the data point list.

Commands
The data point list comprises a list of the supported commands. Any command will be responded by the device with a positive or negative confirmation. If the command is executable, the execution with the corresponding reason for the transmission (COT) will be lead in at first, and subsequently the execution will be confirmed with COT1 within a ASDU9.

Disturbance Recording
The disturbances recorded by the device can be read out by means described in standard IEC60870-5-103. The device is in compliance with the VDEW-Control System by transmission of an ASDU 23 without disturbance records at the beginning of an GI-Cycle.

A disturbance record contains the following information:
- Analog Measured Values, IL1, IL2, IL3, IN, Voltages VL1, VL2, VL3, VEN;
- Binary States, transmitted as marks, e.g. Alarms and Trips.
- The Transmission ratio will not be supported. The transmission ratio is included in the “Multiplier”.

Blocking the Transmission in Monitor Direction
The relay supports the function to block the transmission in monitor direction. There are two ways to activate this blocking:

- Manual activation via Direct Control parameter *»Activate Block MD«*
- External activation, by assigning a signal to the setting parameter *»Ex activate Block MD«*

Test Mode
The relay supports the test mode (Cause of Transmission 7). There are two ways to activate the test mode:
- Manual activation via Direct Control parameter *»Activate test mode«*
- External activation, by assigning a signal to the setting parameter *»Ex activate test mode«*

Global Protection Parameters of the IEC60870-5-103

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Activation or deactivation of the IEC103 communication.	inactive, active	inactive	[Device Para /IEC 103]
Slave ID	Device address (Slave ID) within the bus system. Each device address has to be unique within a bus system.	1 - 247	1	[Device Para /IEC 103]
Baud rate	Baud rate	1200, 2400, 4800, 9600, 19200, 38400, 57600	19200	[Device Para /IEC 103]
Physical Settings	Digit 1: Number of bits. Digit 2: E=even parity, O=odd parity, N=no parity. Digit 3: Number of stop bits. More information on the parity: It is possible that the last data bit is followed by a parity bit which is used for recognition of communication errors. The parity bit ensures that with even parity ("EVEN") always an even number of bits with valence "1" or with odd parity ("ODD") an odd number of "1" valence bits are transmitted. But it is also possible to transmit no parity bits (here the setting is "Parity = None"). More information on the stop-bits: The end of a data byte is terminated by the stop-bits.	8E1, 8O1, 8N1, 8N2	8E1	[Device Para /IEC 103]
t-call	If there is no request telegram sent from Scada to the device after expiry of this time - the device concludes a communication failure within the Scada system.	1 - 3600s	60s	[Device Para /IEC 103]
Transm priv meas val	Transmit additional (private) measuring values	inactive, active	inactive	[Device Para /IEC 103]
Transfer Disturb Rec	Activates the transmission of disturbance records	inactive, active	inactive	[Device Para /IEC 103]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Timezone	Selection whether the timestamps in IEC103 messages shall be given as UTC or local time. (“Local time” always includes the actual daylight saving settings.)	UTC, Local Time	UTC	[Device Para /IEC 103]
Energy Pulse Rate	The energy values are always transmitted as counter values (i.e. as integer numbers). This setting defines the unit: If “1” is set then each counter increment is 1 kWh, if “2” is set then each counter increment is 2 kWh,etc. The setting “0” has the effect that no energy values are transmitted.	0 - 100	0	[Device Para /IEC 103]
DFC-Compat.	This setting is only required for certain substation implementations. If there should be communication problems related to the Command Response Queue this setting switches the device over to a different behavior.	inactive, active	inactive	[Device Para /IEC 103]
Optical rest position	Optical rest position	Light off, Light on	Light on	[Device Para /IEC 103]
Ex activate test mode	The signal assigned to this parameter switches the IEC103 communication into Test Mode.	1..n, Assignment List	Sgen.Running	[Service /Test (Prot inhibit) /Scada /IEC 103]
Ex activate Block MD	The signal assigned to this parameter activates the blocking of IEC103 transmission in monitor direction.	1..n, Assignment List	-.-	[Service /Test (Prot inhibit) /Scada /IEC 103]

Direct Commands of the IEC60870-5-103

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Activate test mode	This Direct Control parameter switches the IEC103 communication into Test Mode (or back to nomal mode).	inactive, active	inactive	[Service /Test (Prot inhibit) /Scada /IEC 103]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Activate Block MD	This Direct Control parameter activates (or deactivates) the blocking of IEC103 transmission in monitor direction.	inactive, active	inactive	[Service /Test (Prot inhibit) /Scada /IEC 103]
Res all Diag Cr	Reset all diagnosis counters	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]

IEC60870-5-103 Input States

Name	*Description*	*Assignment via*
Ex activate test mode-I	Module input state: Test Mode of the IEC103 communication.	[Service /Test (Prot inhibit) /Scada /IEC 103]
Ex activate Block MD-I	Module input state: Activation of the blocking of IEC103 transmission in monitor direction.	[Service /Test (Prot inhibit) /Scada /IEC 103]

IEC60870-5-103 Signals (Output States)

Signal	*Description*
Scada Cmd 1	Scada Command
Scada Cmd 2	Scada Command
Scada Cmd 3	Scada Command
Scada Cmd 4	Scada Command
Scada Cmd 5	Scada Command
Scada Cmd 6	Scada Command
Scada Cmd 7	Scada Command
Scada Cmd 8	Scada Command
Scada Cmd 9	Scada Command
Scada Cmd 10	Scada Command
Transmission	Signal: SCADA active
Failure Event lost	Failure event lost
Test mode active	Signal: IEC103 communication has been switched over into Test Mode.
Block MD active	Signal: The blocking of IEC103 transmission in monitor direction has been activated.

IEC60870-5-103 Values

Value	*Description*	*Default*	*Size*	*Menu path*
NReceived	Total Number of received Messages	0	0 - 9999999999	[Operation /Count and RevData /IEC 103]
NSent	Total Number of sent Messages	0	0 - 9999999999	[Operation /Count and RevData /IEC 103]
NBadFramings	Number of bad Messages	0	0 - 9999999999	[Operation /Count and RevData /IEC 103]
NBadParities	Number of Parity Errors	0	0 - 9999999999	[Operation /Count and RevData /IEC 103]
NBreakSignals	Number of Communication Interrupts	0	0 - 9999999999	[Operation /Count and RevData /IEC 103]
NInternalError	Number of Internal Errors	0	0 - 9999999999	[Operation /Count and RevData /IEC 103]
NBadCharChecksum	Number of Checksum Errors	0	0 - 9999999999	[Operation /Count and RevData /IEC 103]

IEC61850

<u>IEC61850</u>

Introduction

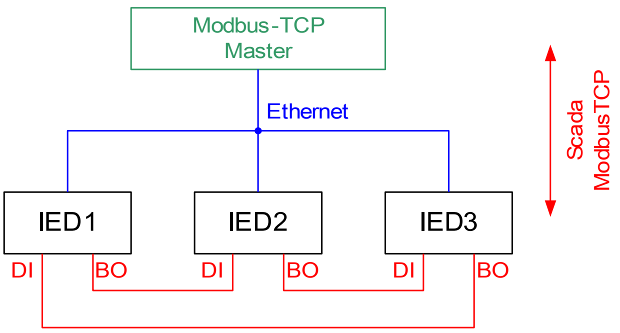
To understand the functioning and mode of operation of a substation in an IEC61850 automation environment, it is useful to compare the commissioning steps with those of a conventional substation in a Modbus TCP environment.

In a conventional substation the individual IEDs (Intelligent Electronic Devices) communicate in vertically direction with the higher level control center via SCADA. The horizontal communication is exclusively realized by wiring output relays (OR) and digital inputs (DI) among each other.

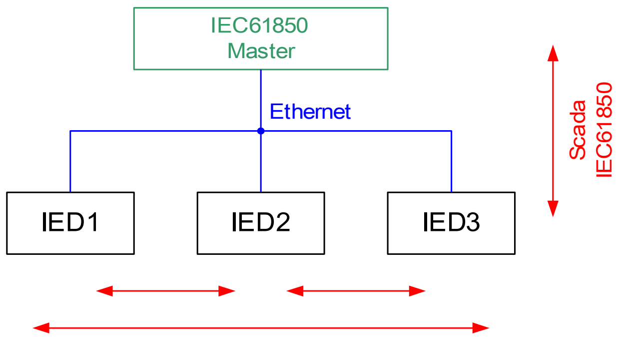
In an IEC61850 environment communication between the IEDs takes place digitally (via Ethernet) by a service called GOOSE (Generic Object Oriented Substation Event). By means of this service information about events is submitted between each IED. Therefore each IED has to know about the functional capability of all other connected IEDs.

Each IEC61850 capable device includes a description of it's own functionality and communications skills (IED Capability Description, *.ICD).

By means of a Substation Configuration Tool to describe the structure of the substation, assignment of the devices to the primary technique, etc. a virtual wiring of the IEDs among each other and with other switch gear of the substation can be done. A description of the substation configuration will be generated in form of a *.SCD file. At last this file has to be submitted to each device. Now the IEDs are able to communicate closed among each other, react to interlockings and operate switch gear.



Conventional hard wiring



GOOSE IEC61850 soft wiring

Commissioning steps for a conventional substation with modbus TCP environment:

- Parameter setting of the IEDs
- Ethernet installation
- TCP/IP settings for the IEDs
- Wiring according to wiring scheme

Commissioning steps for a substation with IEC61850 environment:

1. Parameter setting of the IEDs
   Ethernet installation
   TCP/IP settings for the IEDs

2. IEC61850 configuration (software wiring)
   a) Exporting an ICD file from each device
   b) Configuration of the substation
      (generating a SCD file)
   c) Transmit SCD file to each device

Generation/Export of a device specific ICD file

Please refer to chapter ”IEC61850“ of the Smart view Manual.

Generation/Export of a SCD file

Please refer to chapter ”IEC61850“ of the Smart view Manual.

Substation configuration, Generation of .SCD file (Station Configuration Description)

The substation configuration, i. e. connection of all logical nodes of protection and control devices, as well as switch gear usually is done with a „Substation Configuration Tool“. Therefore the ICD files of all connected IEDs in the IEC61850 environment have to be available. The result of the station wide “software wiring” can be exported in the form of a SCD file (Station Configuration Description).

Suitable Substation Configuration Tools (SCT) are available by the following Companies:

H&S, Hard- & Software Technologie GmbH & Co. KG, Dortmund (Germany) (www.hstech.de).
Applied Systems Engineering Inc. (www.ase-systems.com)
Kalki Communication Technologies Limited (www.kalkitech.com)

Import of the .SCD file into the device

Please refer to chapter ”IEC61850“ of the Smart view Manual.

IEC 61850 Virtual Outputs

Additionally to the standardized logical node status information up to 32 free configurable status information can be assigned to 32 Virtual Outputs. This can be done in the menu [Device Para/IEC61850].

Direct Commands of the IEC 61850

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ResetStatistic	Reset of all IEC61850 diagnostic counters	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]

Global Parameters of the IEC 61850

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[Device Para /IEC61850]
Deadb integr time	Deadband integration time.	0 - 300	0	[Device Para /IEC61850]

Global Parameters of the IEC 61850

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
VirtualOutput1	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput2	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput3	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput4	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
VirtualOutput5	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput6	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput7	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput8	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput9	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput10	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput11	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput12	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput13	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput14	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
VirtualOutput15	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput16	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput17	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput18	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput19	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput20	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput21	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput22	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput23	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput24	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
VirtualOutput25	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput26	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput27	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput28	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput29	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput30	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput31	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]
VirtualOutput32	Virtual Output. This signal can be assigned or visualized via the SCD file to other devices within the IEC61850 substation.	1..n, Assignment List	-.-	[Device Para /IEC61850]

States of the Inputs of the IEC 61850

Name	*Description*	*Assignment via*
VirtOut1-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut2-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut3-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut4-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut5-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut6-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut7-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut8-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut9-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut10-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut11-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut12-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut13-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut14-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut15-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut16-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut17-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut18-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]

Name	*Description*	*Assignment via*
VirtOut19-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut20-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut21-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut22-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut23-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut24-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut25-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut26-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut27-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut28-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut29-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut30-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut31-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]
VirtOut32-I	Module input state: Binary state of the Virtual Output (GGIO)	[Device Para /IEC61850]

IEC 61850 Module Signals (Output States)

Signal	*Description*
MMS Client connected	At least one MMS client is connected to the device
All Goose Subscriber active	All Goose subscriber in the device are working
VirtInp1	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp2	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp3	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp4	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp5	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp6	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp7	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp8	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp9	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp10	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp11	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp12	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp13	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp14	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp15	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp16	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp17	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp18	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp19	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp20	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp21	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp22	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp23	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp24	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp25	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp26	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp27	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp28	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp29	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp30	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp31	Signal: Virtual Input (IEC61850 GGIO Ind)
VirtInp32	Signal: Virtual Input (IEC61850 GGIO Ind)
Quality of GGIO In1	Self-Supervision of the GGIO Input
Quality of GGIO In2	Self-Supervision of the GGIO Input
Quality of GGIO In3	Self-Supervision of the GGIO Input
Quality of GGIO In4	Self-Supervision of the GGIO Input

Signal	*Description*
Quality of GGIO In5	Self-Supervision of the GGIO Input
Quality of GGIO In6	Self-Supervision of the GGIO Input
Quality of GGIO In7	Self-Supervision of the GGIO Input
Quality of GGIO In8	Self-Supervision of the GGIO Input
Quality of GGIO In9	Self-Supervision of the GGIO Input
Quality of GGIO In10	Self-Supervision of the GGIO Input
Quality of GGIO In11	Self-Supervision of the GGIO Input
Quality of GGIO In12	Self-Supervision of the GGIO Input
Quality of GGIO In13	Self-Supervision of the GGIO Input
Quality of GGIO In14	Self-Supervision of the GGIO Input
Quality of GGIO In15	Self-Supervision of the GGIO Input
Quality of GGIO In16	Self-Supervision of the GGIO Input
Quality of GGIO In17	Self-Supervision of the GGIO Input
Quality of GGIO In18	Self-Supervision of the GGIO Input
Quality of GGIO In19	Self-Supervision of the GGIO Input
Quality of GGIO In20	Self-Supervision of the GGIO Input
Quality of GGIO In21	Self-Supervision of the GGIO Input
Quality of GGIO In22	Self-Supervision of the GGIO Input
Quality of GGIO In23	Self-Supervision of the GGIO Input
Quality of GGIO In24	Self-Supervision of the GGIO Input
Quality of GGIO In25	Self-Supervision of the GGIO Input
Quality of GGIO In26	Self-Supervision of the GGIO Input
Quality of GGIO In27	Self-Supervision of the GGIO Input
Quality of GGIO In28	Self-Supervision of the GGIO Input
Quality of GGIO In29	Self-Supervision of the GGIO Input
Quality of GGIO In30	Self-Supervision of the GGIO Input
Quality of GGIO In31	Self-Supervision of the GGIO Input
Quality of GGIO In32	Self-Supervision of the GGIO Input
SPCSO1	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO2	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO3	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO4	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO5	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO6	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO7	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).

Signal	*Description*
SPCSO8	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO9	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO10	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO11	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO12	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO13	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO14	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO15	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO16	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO17	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO18	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO19	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO20	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO21	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO22	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO23	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO24	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO25	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO26	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO27	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO28	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO29	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO30	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).

Signal	*Description*
SPCSO31	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
SPCSO32	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).

IEC 61850 Module Values

Value	*Description*	*Default*	*Size*	*Menu path*
NoOfGooseRxAll	Total number of received GOOSE messages including messages for other devices (subscribed and not subscribed messages).	0	0 - 9999999999	[Operation /Count and RevData /IEC61850]
NoOfGooseRxSubscribed	Total Number of subscribed GOOSE messages including messages with incorrect content.	0	0 - 9999999999	[Operation /Count and RevData /IEC61850]
NoOfGooseRxCorrect	Total Number of subscribed and correctly received GOOSE messages.	0	0 - 9999999999	[Operation /Count and RevData /IEC61850]
NoOfGooseRxNew	Number of subscribed and correctly received GOOSE messages with new content.	0	0 - 9999999999	[Operation /Count and RevData /IEC61850]
NoOfGooseTxAll	Total Number of GOOSE messages that have been published by this device.	0	0 - 9999999999	[Operation /Count and RevData /IEC61850]
NoOfGooseTxNew	Total Number of new GOOSE messages (modified content) that have been published by this device.	0	0 - 9999999999	[Operation /Count and RevData /IEC61850]
NoOfServerRequestsAll	Total number of MMS Server requests including incorrect requests.	0	0 - 9999999999	[Operation /Count and RevData /IEC61850]
NoOfDataReadAll	Total Number of values read from this device including incorrect requests.	0	0 - 9999999999	[Operation /Count and RevData /IEC61850]
NoOfDataReadCorrect	Total Number of correctly read values from this device.	0	0 - 9999999999	[Operation /Count and RevData /IEC61850]
NoOfDataWrittenAll	Total Number of values written by this device including incorrect ones.	0	0 - 9999999999	[Operation /Count and RevData /IEC61850]

Value	*Description*	*Default*	*Size*	*Menu path*
NoOfDataWritten Correct	Total Number of correctly written values by this device.	0	0 - 9999999999	[Operation /Count and RevData /IEC61850]
NoOfDataChange Notification	Number of detected changes within the datasets that are published with GOOSE messages.	0	0 - 9999999999	[Operation /Count and RevData /IEC61850]
No of Client Connections	Number of active MMS client connections	0	0 - 9999999999	[Operation /Count and RevData /IEC61850]

Values of the IEC 61850

Value	*Description*	*Default*	*Size*	*Menu path*
GoosePublisherState	State of the GOOSE Publisher (on or off)	Off	Off, On, Error	[Operation /Status Display /IEC61850 /State]
GooseSubscriberState	State of the GOOSE Subscriber (on or off)	Off	Off, On, Error	[Operation /Status Display /IEC61850 /State]
MmsServerState	State of MMS Server (on or off)	Off	Off, On, Error	[Operation /Status Display /IEC61850 /State]

DNP3

DNP3

DNP (Distributed Network Protocol) is for data and information exchange between SCADA (Master) and IEDs (Intelligent Electronic Devices). The DNP protocol has been developed in first releases for serial communication. Due to further development of the DNP protocol, it offers now also TCP and UDP communication options via Ethernet.

DNP Device Planning

Depending on the hardware of the proctective device up to three DNP communication options are available within the Device Planning.

Call up the device planning menu.

Select (depending on device code) the appropriate SCADA Protocol.

- DNP3 RTU (via serial Port)
- DNP3 TCP (via Ethernet)
- DNP3 UDP (via Ethernet)

DNP Protocol General Settings

NOTICE

Please note that unsolicited reporting is not available for serial communication, if more than one slave is connected to the serial communication (collisions). Do not use in these cases unsolicited reporting for DNP RTU.

Unsolicited reporting is available also for serial communication, if each slave is connected via a separated connection to the Master-System. That means, the master is equipped with a separate serial interface for each slave (multi serial cards).

Call up menu [Device Para/DNP3/Communication].

The Communication (General Settings) Settings have to be set according to the needs of the SCADA (Master) – System.

Self Addressing is available for DNP-TCP. That means that the Master and Slave id are auto-detected.

Point Mapping

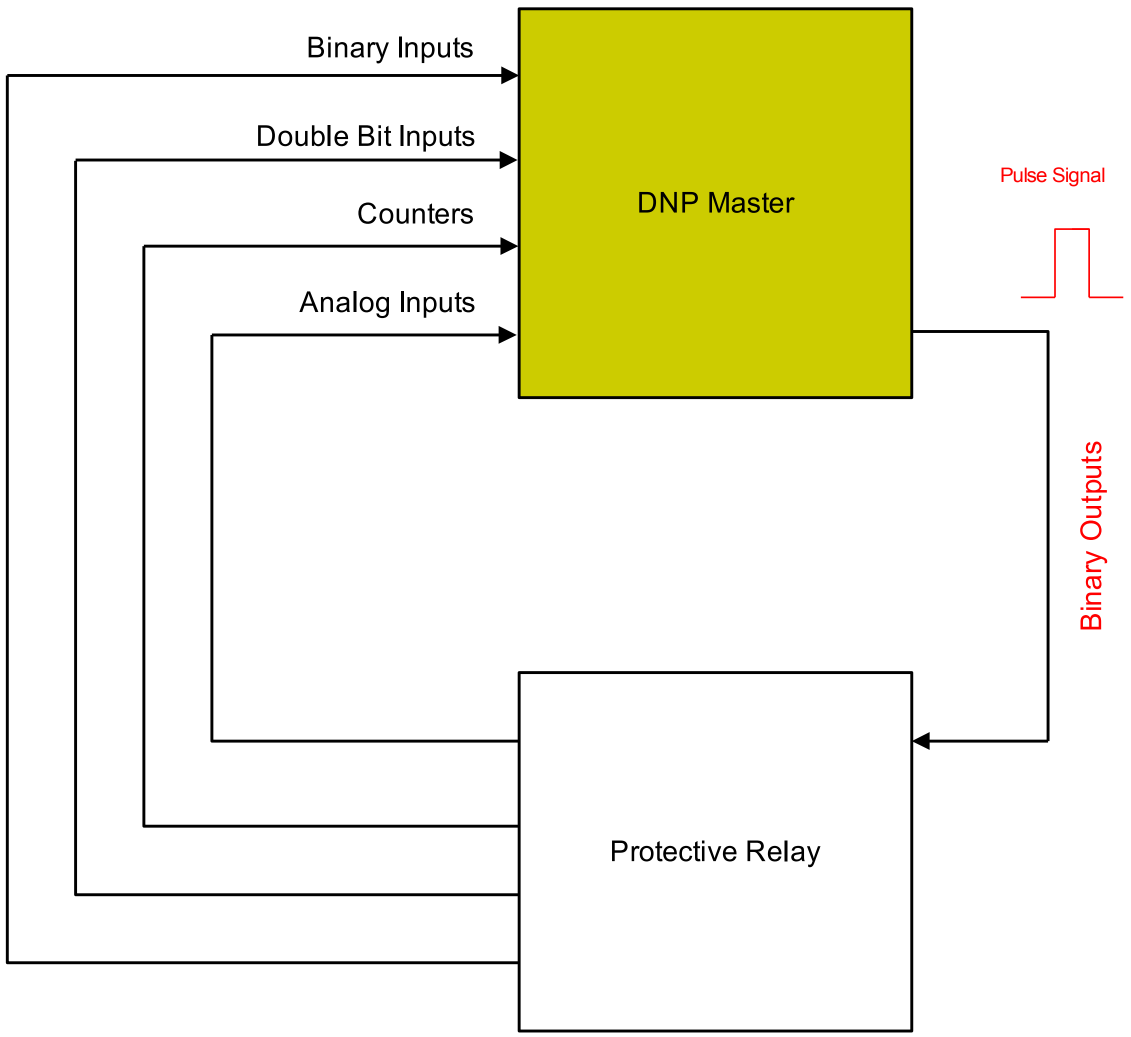
NOTICE **Please take into account that the designations of inputs and outputs are set from the Masters perspective. This way of choosing the designations is due to a definition in the DNP standard. That means for example that Binary Inputs that can be set within the Device Parameters of the DNP protocol are the "Binary Inputs" of the Master.**

Call up menu [Device Para/DNP3/Point Map]. Once the general settings of the DNP protocol are done, the point mapping is to be done as a next step.

- Binary Inputs (States to be send to the master)
- Double Bit Inputs (Breaker states to be send to the master)
- Counters (Counters to be send to the master)
- Analog Inputs (e.g. measured values to be send to the master). Please take into account that floating values have to be transmitted as integers. That means they have to be scaled (multiplied) with a scaling factor in order to bring them into the integer format.

Use Binary outputs in order to control e.g. LEDs or Relays within the protective device (via Logic).

Point Mapping

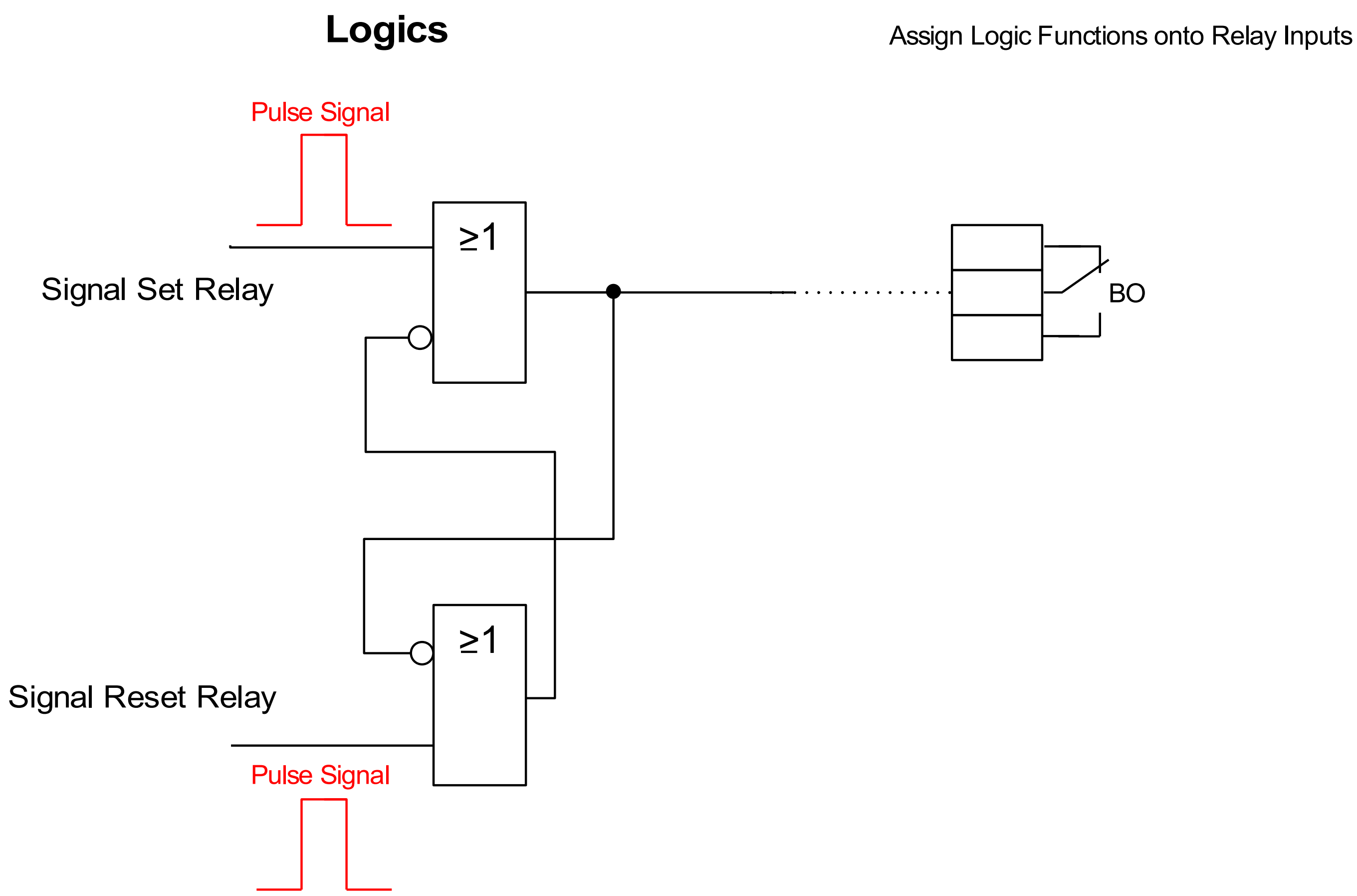


Please try to avoid gaps that will slow down the performance of the DNP communication. That means do not leave unused inputs / outputs in between used inputs / outputs (e.g. Do not use Binary Output 1 and 3 when 2 is unused).

Application Example Setting a Relay:

Binary Output signals of the DNP cannot directly be used in order to switch relays because the DNP Binary Outputs are pulse signals (by DNP definition, not steady state). Steady states can be created by means of Logic functions. The Logic Functions can be assigned onto the Relay Inputs.

Please note: You can use a Set/Reset element (Flip Flop) from Logics.



Direct Commands of the DNP

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Res all Diag Cr	Reset all diagnosis counters	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]
Slave Id	SlaveId defines the DNP3 address of this device (Outstation)	0 - 65519	1	[Device Para /DNP3 / Communication]

Parameter	Description	Setting range	Default	Menu path
Master Id	MasterId defines the DNP3 address of master (SCADA)	0 - 65519	65500	[Device Para /DNP3 /Communication]

Global Protection Parameters of the DNP

Parameter	Description	Setting range	Default	Menu path
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[Device Para /DNP3 /Communication]
IP Port Number	IP Port Number. In general it is recommended to keep the default value. if this is not possible then select a number out of the private range 49152-52151 or 52162-65535 that is not yet in use within your network.	0 - 65535	20000	[Device Para /DNP3 /Communication]
Baud rate	Baud rate for communication	1200, 2400, 4800, 9600, 19200, 38400, 57600, 115200	19200	[Device Para /DNP3 /Communication]
Frame Layout	Frame Layout	8E1, 8O1, 8N1, 8N2	8E1	[Device Para /DNP3 /Communication]
Optical rest position	Optical rest position	Light off, Light on	Light on	[Device Para /DNP3 /Communication]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
SelfAddress	Support of self (automatic) addresses	inactive, active	inactive	[Device Para /DNP3 /Communication]
DataLink confirm	Enables or disables the data layer confirmation (ack).	Never, Always, On_Large	Never	[Device Para /DNP3 /Communication]
t-DataLink confirm	Data layer confirmation timeout	0.1 - 10.0s	1s	[Device Para /DNP3 /Communication]
DataLink num retries	Number of repetition of data link packet sending after failing	0 - 255	3	[Device Para /DNP3 /Communication]
Direction Bit	Enables Direction Bit functionality. The Direction Bit is 0 for SlaveStation and 1 for MasterStation	inactive, active	inactive	[Device Para /DNP3 /Communication]
Max Frame Size	This value is used to limit the net Frame Size	64 - 255	255	[Device Para /DNP3 /Communication]
Test Link Period	This value specifies the time period when to send a Test Link-Frame	0.0 - 120.0s	0s	[Device Para /DNP3 /Communication]
AppLink confirm	Determines if the device will request that the Application Layer response be confirmed or not	Never, Always, Event	Always	[Device Para /DNP3 /Communication]
t-AppLink confirm	Application layer response timeout	0.1 - 10.0s	5s	[Device Para /DNP3 /Communication]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
AppLink num retries	The number of times the device will retransmit an Application Layer fragment	0 - 255	0	[Device Para /DNP3 /Communication]
Unsol Reporting	Enables unsolicited reporting. This is available only for DNP3 TCP connections, and for DNP3 RTU in case of a peer-to-peer connection.	inactive, active	inactive	[Device Para /DNP3 /Communication]
Unsol Reporting Timeout	Set the amount of time that the outstation will wait for an Application Layer confirmation back from the master indicating that the master received the unsolicited response message.	1.0 - 60.0s	10s	[Device Para /DNP3 /Communication]
Unsol Reporting Retry	Set the number of retries that an outstation transmits in each unsolicited response series if it does not receive confirmation back from the master.	0 - 255	2	[Device Para /DNP3 /Communication]
TestSeqNo	Test if sequence number of request is incremented. If it is not correctly incremented the request will be ignored. It is recommended to have it inactive but some older DNP implementations need it activated.	inactive, active	inactive	[Device Para /DNP3 /Communication]
TestSBO	It enables a stricter comparing of SBO and operate command. For older DNP versions it is recommanded to deactivated it.	inactive, active	active	[Device Para /DNP3 /Communication]
Timeout SBO	DNP Outputs can be controlled in a two stage procedure (SBO: Select Before Operate). These outputs are to be selected first by a select command. After this the bit is reserved for this operate request. When this timer is expired, the bit will be released.	1.0 - 60.0s	30s	[Device Para /DNP3 /Communication]
ColdRestart	Enables support for Cold Restart function.	inactive, active	inactive	[Device Para /DNP3 /Communication]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Deadb integr time	Deadband integration time.	0 - 300	1	[Device Para /DNP3 / Communication]
BinaryInput 0	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 1	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 2	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 3	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 4	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 5	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 6	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 7	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]

Parameter	Description	Setting range	Default	Menu path
BinaryInput 8	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 9	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 10	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 11	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 12	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 13	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 14	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 15	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 16	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
BinaryInput 17	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 18	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 19	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 20	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 21	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 22	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 23	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 24	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 25	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
BinaryInput 26	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 27	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 28	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 29	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 30	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 31	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 32	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 33	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 34	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
BinaryInput 35	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 36	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 37	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 38	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 39	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 40	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 41	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 42	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 43	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
BinaryInput 44	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 45	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 46	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 47	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 48	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 49	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 50	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 51	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 52	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
BinaryInput 53	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 54	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 55	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 56	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 57	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 58	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 59	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 60	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 61	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
BinaryInput 62	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput 63	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Binary Inputs]
DoubleBitInput 0	Double Bit Digital Input (DNP). This corresponds to a double bit binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Double Bit Inputs]
DoubleBitInput 1	Double Bit Digital Input (DNP). This corresponds to a double bit binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Double Bit Inputs]
DoubleBitInput 2	Double Bit Digital Input (DNP). This corresponds to a double bit binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Double Bit Inputs]
DoubleBitInput 3	Double Bit Digital Input (DNP). This corresponds to a double bit binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Double Bit Inputs]
DoubleBitInput 4	Double Bit Digital Input (DNP). This corresponds to a double bit binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Double Bit Inputs]
DoubleBitInput 5	Double Bit Digital Input (DNP). This corresponds to a double bit binary output of the protective device.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /Double Bit Inputs]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
BinaryCounter 0	Counter can be used to report counter values to the DNP master.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /BinaryCounter]
BinaryCounter 1	Counter can be used to report counter values to the DNP master.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /BinaryCounter]
BinaryCounter 2	Counter can be used to report counter values to the DNP master.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /BinaryCounter]
BinaryCounter 3	Counter can be used to report counter values to the DNP master.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /BinaryCounter]
BinaryCounter 4	Counter can be used to report counter values to the DNP master.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /BinaryCounter]
BinaryCounter 5	Counter can be used to report counter values to the DNP master.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /BinaryCounter]
BinaryCounter 6	Counter can be used to report counter values to the DNP master.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /BinaryCounter]
BinaryCounter 7	Counter can be used to report counter values to the DNP master.	1..n, Assignment List	-.-	[Device Para /DNP3 /Point map /BinaryCounter]
Analog value 0	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Scale Factor 0	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 0	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 1	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]
Scale Factor 1	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 1	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 2	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Scale Factor 2	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 2	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 3	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]
Scale Factor 3	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 3	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 4	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Scale Factor 4	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 4	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 5	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]
Scale Factor 5	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 5	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 6	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Scale Factor 6	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 6	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 7	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]
Scale Factor 7	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 7	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 8	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]

Parameter	Description	Setting range	Default	Menu path
Scale Factor 8	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 8	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 9	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]
Scale Factor 9	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 9	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 10	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Scale Factor 10	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 10	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 11	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]
Scale Factor 11	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 11	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 12	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Scale Factor 12	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 12	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 13	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]
Scale Factor 13	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 13	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 14	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Scale Factor 14	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 14	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 15	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]
Scale Factor 15	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 15	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 16	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Scale Factor 16	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 16	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 17	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]
Scale Factor 17	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 17	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 18	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Scale Factor 18	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 18	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 19	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]
Scale Factor 19	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 19	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 20	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Scale Factor 20	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 20	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 21	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]
Scale Factor 21	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 21	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 22	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Scale Factor 22	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 22	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 23	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]
Scale Factor 23	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 23	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 24	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Scale Factor 24	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 24	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 25	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]
Scale Factor 25	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 25	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 26	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Scale Factor 26	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 26	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 27	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]
Scale Factor 27	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 27	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 28	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Scale Factor 28	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 28	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 29	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]
Scale Factor 29	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 29	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 30	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]

Parameter	Description	Setting range	Default	Menu path
Scale Factor 30	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 30	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]
Analog value 31	Analog value can be used to report values to the master (DNP)	1..n, TrendRecList	-.-	[Device Para /DNP3 /Point map /Analog Input]
Scale Factor 31	The scale factor is used to convert the measured value in an integer format	0.001, 0.01, 0.1, 1, 10, 100, 1000, 10000, 100000, 1000000	1	[Device Para /DNP3 /Point map /Analog Input]
Dead Band 31	If a change of measured value is greater than the deadband value it will be reported to the master.	0.01 - 100.00%	1%	[Device Para /DNP3 /Point map /Analog Input]

Inputs of the DNP

Name	*Description*	*Assignment via*
BinaryInput0-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput1-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput2-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput3-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput4-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput5-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput6-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput7-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput8-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]

Name	*Description*	*Assignment via*
BinaryInput9-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput10-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput11-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput12-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput13-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput14-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput15-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput16-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput17-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]

Name	*Description*	*Assignment via*
BinaryInput18-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput19-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput20-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput21-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput22-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput23-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput24-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput25-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput26-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]

Name	*Description*	*Assignment via*
BinaryInput27-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput28-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput29-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput30-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput31-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput32-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput33-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput34-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput35-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]

Name	*Description*	*Assignment via*
BinaryInput36-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput37-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput38-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput39-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput40-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput41-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput42-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput43-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput44-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]

Name	*Description*	*Assignment via*
BinaryInput45-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput46-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput47-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput48-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput49-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput50-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput51-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput52-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput53-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]

Name	*Description*	*Assignment via*
BinaryInput54-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput55-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput56-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput57-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput58-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput59-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput60-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput61-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
BinaryInput62-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]

Name	*Description*	*Assignment via*
BinaryInput63-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.	[Device Para /DNP3 /Point map /Binary Inputs]
DoubleBitInput0-I	Double Bit Digital Input (DNP). This corresponds to a double bit binary output of the protective device.	[Device Para /DNP3 /Point map /Double Bit Inputs]
DoubleBitInput1-I	Double Bit Digital Input (DNP). This corresponds to a double bit binary output of the protective device.	[Device Para /DNP3 /Point map /Double Bit Inputs]
DoubleBitInput2-I	Double Bit Digital Input (DNP). This corresponds to a double bit binary output of the protective device.	[Device Para /DNP3 /Point map /Double Bit Inputs]
DoubleBitInput3-I	Double Bit Digital Input (DNP). This corresponds to a double bit binary output of the protective device.	[Device Para /DNP3 /Point map /Double Bit Inputs]
DoubleBitInput4-I	Double Bit Digital Input (DNP). This corresponds to a double bit binary output of the protective device.	[Device Para /DNP3 /Point map /Double Bit Inputs]
DoubleBitInput5-I	Double Bit Digital Input (DNP). This corresponds to a double bit binary output of the protective device.	[Device Para /DNP3 /Point map /Double Bit Inputs]

Options of the DNP

Name	*Description*
-.-	No assignment
Prot.FaultNo	Fault number
Prot.No of GridFaults	Number of grid faults: A grid fault, e.g. a short circuit, might cause several faults with trip and autoreclosing, each fault being identified by an increased fault number. In this case, the grid fault number remains the same.
SG[1].TripCmd Cr	Counter: Total number of trips of the switchgear (circuit breaker, load break switch...). Resettable with Total or All.
MStart.StartPerHour	StartPerHour

Name	Description
MStart.SPH Release	In case that the Motor is blocked by a SPH blocking, this timer needs to be expired before the blocking is released and the next motor start is permitted. The next Motor Start will increment the SPH counter again.
MStart.ColdStartPermit	Number of cold starts remaining
MStart.OCNT	Motor Operation count since last reset.
MStart.RunTime	Motor Operation time since last reset.
MStart.nEmrgOvr	Number of emergency overrides since last reset.
MStart.TRunTime	Motor Operation (Motor run time) time since last reset.
MStart.TOCS	Total Motor Operation count since last reset.
MStart.nTRNTrips	Number of transition trips since last reset.
MStart.nRevTrips	Number of reverse spinning trips since last reset.
MStart.nZSWTrips	Number of zero speed switch trips since last reset.
MStart.nISQT	Number of incomplete sequence trips since last reset.
MStart.nSPHBlocks	Number of start per hour blocks since last reset.
MStart.nTBSBlocks	Number of time between start blocks since last reset.
Sys.Operating hours Cr	Operating hours counter of the protective device
Sys.Hours Counter	Hours Counter

Selectable Switchgears of the DNP

Name	Description
-.-	No assignment
SG[1].Pos	Signal: Circuit Breaker Position (0 = Indeterminate, 1 = OFF, 2 = ON, 3 = Disturbed)

DNP Signals (Output States)

NOTICE Some signals (that are for a short time active only) have to be acknowledged separately (e.g. Trip signals) by the Communication System.

Signal	*Description*
busy	This message is set if the protocol is started. It will be reset if the protocol is shut down.
ready	The message will be set if the protocol is successfully started and ready for data exchange.
active	The communication with the Master (SCADA) is active. Note that for TCP/UDP, this state is permanently “Low” unless »DataLink confirm« is set to “Always”.
BinaryOutput0	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput1	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput2	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput3	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput4	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput5	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput6	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput7	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput8	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput9	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput10	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput11	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput12	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput13	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput14	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput15	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput16	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.

Signal	*Description*
BinaryOutput17	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput18	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput19	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput20	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput21	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput22	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput23	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput24	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput25	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput26	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput27	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput28	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput29	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput30	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
BinaryOutput31	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.

DNP Values

Value	*Description*	*Default*	*Size*	*Menu path*
NReceived	Diagnostic counter: Number of received characters	0	0 - 9999999999	[Operation /Count and RevData /DNP3]
NSent	Diagnostic counter: Number of sent characters	0	0 - 9999999999	[Operation /Count and RevData /DNP3]
NBadFramings	Diagnostic counter: Number of bad framings. A large number indicates a disturbed serial connection.	0	0 - 9999999999	[Operation /Count and RevData /DNP3]
NBadParities	Diagnostic counter: Number of parity errrors. A large number indicates a disturbed serial connection.	0	0 - 9999999999	[Operation /Count and RevData /DNP3]
NBreakSignals	Diagnostic counter: Number of break signals. A large number indicates a disturbed serial connection.	0	0 - 9999999999	[Operation /Count and RevData /DNP3]
NBadChecksum	Diagnostic counter: Number of frames received with bad checksum.	0	0 - 9999999999	[Operation /Count and RevData /DNP3]

Time Synchronization

TimeSync

The user has the possibility to synchronize the device with a central time generator. This offers the following advantages:

- The time does not drift off from the reference time. A continuously accumulating deviation from the reference time thereby will be balanced. Also refer to the chapter Specifications (Tolerances Real Time Clock).
- All time synchronized devices operate with the same time. Thus logged events of the individual devices can be compared exactly and be evaluated in conjunction (single events of the event recorder, disturbance records).

The device's time can be synchronized via the following protocols:

- IRIG-B
- SNTP
- Communication protocol Modbus (RTU or TCP)
- Communication protocol IEC60870-5-103
- Communication protocol DNP3
- Protection communication (only for line differential devices and only for one of the two interconnected devices).

The provided protocols use different hardware interfaces and differ also in their achieved time accuracy. Further information can be found in the chapter Specifications.

Used Protocol	*Hardware-Interface*	*Recommended Application*
Without time synchronization	—	Not recommended
IRIG-B	IRIG-B Terminal	Recommended, if interface available
SNTP	RJ45 (Ethernet)	Recommended alternative to IRIG-B, especially when using IEC 61850 or Modbus TCP
Modbus RTU	RS485, D-SUB or Fiber Optic	Recommended when using the Modbus RTU communication protocol and when no IRIG-B code generator is available
Modbus TCP	RJ45 (Ethernet)	Limited recommendation when the Modbus TCP communication protocol is used and no IRIG-B code generator or an SNTP server is available
IEC 60870-5-103	RS485, D-SUB or Fiber Optic	Recommended when using the IEC 10870-5-103 communication protocol and no IRIG-B code generator is available
DNP3	RS485 or RJ45 (Ethernet)	Limited recommendation when using the DNP3 communication protocol and no IRIG-B code generator or an SNTP server is available
ProtCom	X102 (Fiber Optic)	The “ProtCom” Protection Communication is available only with line differential devices, and it connects two devices with each other. Time Synchronization via “ProtCom” is recommended for only one of these two devices. (Time Synchronization of the other device should be done via another protocol, e. g. IRIG-B or SNTP.)

Accuracy of Time Synchronization

The accuracy of the device's synchronized system time depends on several factors:

- accuracy of the connected time generator
- used synchronization protocol
- when using Modbus TCP, SNTP or DNP3 TCP/UDP: Network load and data package transmission times

NOTICE

Please consider the accuracy of the used time generator. Fluctuations of the time generator's time will cause the same fluctuations of the protection relay's system time.

Selection of Timezone and Synchronization Protocol

The protection relay masters both UTC and local time. This means that the device can be synchronized with UTC time while using local time for user display.

Time Synchronization with UTC time (recommended):
Time synchronization is usually done using UTC time. This means for example that an IRIG-B time generator is sending UTC time information to the protection relay. This is the recommended use case, since here a continuous time synchronization can be ensured. There are no “leaps in time” through change of summer- and wintertime.

To achieve that the device shows the current local time, the timezone and the change between summer- and wintertime can be configured.

Please carry out the following setting steps under [Device Para/ Time]:
1.Select your local timezone in the timezone menu.
2.There also configure the switching of daylight saving time.
3.Select the used time synchronization protocol in the TimeSync menu (e.g. “IRIG-B”).
4.Set the parameters of the synchronization protocol (refer to the according chapter).

Time Synchronization with local time:
Should the time synchronization however be done using local time, then please leave the timezone to »*UTC+0 London*« and do not use switching of daylight saving time.

NOTICE **The synchronization of the relay's system time is exclusively done by the synchronization protocol selected in the menu [Device Para/ Time/ TimeSync/ Used Protocol].**

Without Time Synchronization:
To achieve that the device shows the current local time, the timezone and the change between summer- and wintertime can be configured.

Please carry out the following setting steps under [Device Para/ Time]:
1. Select your local timezone in the timezone menu.
2. There also configure the switching of daylight saving time.
3. Select »*manual*« as your used protocol in the TimeSync menu.
4. Set date and time.

Global Protection Parameters of the Time Synchronization

Parameter	Description	Setting range	Default	Menu path
DST offset	Difference to wintertime	-180 - 180min	60min	[Device Para /Time /Timezone]
DST manual	Manual setting of the Daylight Saving Time	inactive, active	active	[Device Para /Time /Timezone]
Summertime	Daylight Saving Time Only available if: DST manual = active	inactive, active	inactive	[Device Para /Time /Timezone]
Summertime m	Month of clock change summertime Only available if: DST manual = inactive	January, February, March, April, May, June, July, August, September, October, November, December	March	[Device Para /Time /Timezone]
Summertime d	Day of clock change summertime Only available if: DST manual = inactive	Sunday, Monday, Tuesday, Wednesday, Thursday, Friday, Saturday, General day	Sunday	[Device Para /Time /Timezone]
Summertime w	Place of selected day in month (for clock change summertime) Only available if: DST manual = inactive	First, Second, Third, Fourth, Last	Last	[Device Para /Time /Timezone]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Summertime h	Hour of clock change summertime Only available if: DST manual = inactive	0 - 23h	2h	[Device Para /Time /Timezone]
Summertime min	Minute of clock change summertime Only available if: DST manual = inactive	0 - 59min	0min	[Device Para /Time /Timezone]
Wintertime m	Month of clock change wintertime Only available if: DST manual = inactive	January, February, March, April, May, June, July, August, September, October, November, December	October	[Device Para /Time /Timezone]
Wintertime d	Day of clock change wintertime Only available if: DST manual = inactive	Sunday, Monday, Tuesday, Wednesday, Thursday, Friday, Saturday, General day	Sunday	[Device Para /Time /Timezone]
Wintertime w	Place of selected day in month (for clock change wintertime) Only available if: DST manual = inactive	First, Second, Third, Fourth, Last	Last	[Device Para /Time /Timezone]
Wintertime h	Hour of clock change wintertime Only available if: DST manual = inactive	0 - 23h	3h	[Device Para /Time /Timezone]
Wintertime min	Minute of clock change wintertime Only available if: DST manual = inactive	0 - 59min	0min	[Device Para /Time /Timezone]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Time Zones	Time Zones	UTC+14 Kiritimati, UTC+13 Rawaki, UTC+12.75 Chatham Island, UTC+12 Wellington, UTC+11.5 Kingston, UTC+11 Port Vila, UTC+10.5 Lord Howe Island, UTC+10 Sydney, UTC+9.5 Adelaide, UTC+9 Tokyo, UTC+8 Hong Kong, UTC+7 Bangkok, UTC+6.5 Rangoon, UTC+6 Colombo, UTC+5.75 Kathmandu, UTC+5.5 New Delhi, UTC+5 Islamabad, UTC+4.5 Kabul, UTC+4 Abu Dhabi, UTC+3.5 Tehran, UTC+3 Moscow, UTC+2 Athens, UTC+1 Berlin, UTC+0 London, UTC-1 Azores, UTC-2 Fern. d. Noronha,	UTC+0 London	[Device Para /Time /Timezone]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
TimeSync	Time synchronisation	-, IRIG-B, SNTP, Modbus, IEC60870-5-103, DNP3	-	[Device Para /Time /TimeSync /TimeSync]

Signals (Output States) of the Time Synchronization

Signal	*Description*
synchronized	Clock is synchronized.

SNTP

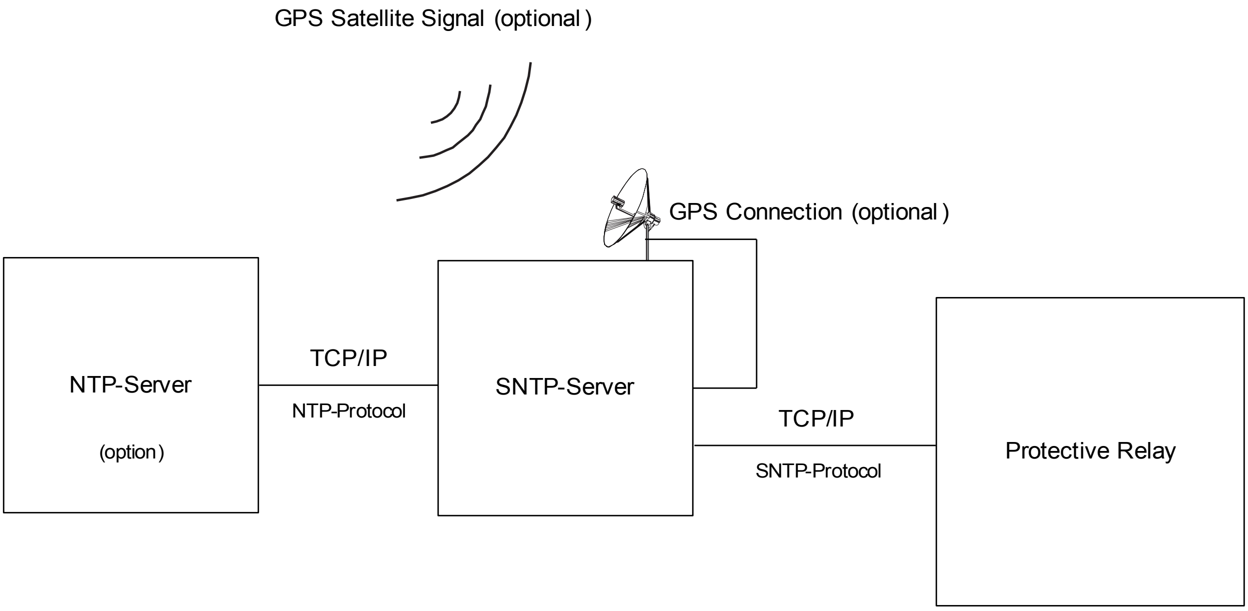
SNTP

NOTICE **Important pre-condition: The protective relay needs to have access to an SNTP server via the connected network. This server preferably should be installed locally.**

Principle – General Use

SNTP is a standard protocol for time synchronisation via a network. For this at least one SNTP server has to be available within the network. The device can be configured for one or two SNTP servers.

The protection relay's system time will be synchronised with the connected SNTP server 1-4 times per minute. In turn the SNTP server synchronises its time via NTP with other NTP servers. This is the normal case. Alternatively it can synchronise its time via GPS, radio controlled clock or the like.



Accuracy

The accuracy of the used SNTP server and the excellence of its reference clock influences the accuracy of the protection relay's clock.
For further information about accuracy refer to the chapter “Specifications”.

With each transmitted time information, the SNTP server also sends information about its accuracy:

- Stratum: The stratum indicates over how many interacting NTP-Servers the used SNTP server is connected to an atomic or radio controlled clock.
- Precision: This indicates the accuracy of the system time provided by the SNTP server.

Additionally the performance of the connected network (traffic and data package transmission times) has an influence on the accuracy of the time synchronisation.

Recommended is a locally installed SNTP server with an accuracy of ≤200 µsec. If this cannot be realised, the connected server's excellence can be checked in the menu [Operation/Status Display/TimeSync]:

- The server quality gives information about the accuracy of the used server. The quality should be GOOD or SUFFICIENT. A server with BAD quality should not be used, because this could cause fluctuations in time synchronisation.
- The network quality gives information about the network's load and data package transmission time. The quality should be GOOD or SUFFICIENT. A network with BAD quality should not be used, because this could cause fluctuations in time synchronisation.

Using two SNTP Servers

When configuring two SNTP servers, the device always synchronizes to server 1 by default.
If server 1 fails, the device automatically switches to server 2.
When (after a failure) server 1 recovers, the device switches back to server 1.

SNTP Commissioning

Activate the SNTP time synchronisation by means of the menu [Device Para/ Time/ TimeSync]:

- Select »*SNTP*« in the time synchronisation menu.
- Set the IP address of the first server in the SNTP menu.
- Set the IP address of the second server, if available.
- Set all configured servers to “active”.

Fault Analysis

If there is no SNTP signal for more than 120 sec, the SNTP status changes from “active” to “inactive” and an entry in the Event Recorder will be created.

The SNTP functionality can be checked in the menu [Operation/Status Display/TimeSync/Sntp]:
If the SNTP status is not indicated as being “active”, please proceed as follows:

- Check if the wiring is correct (Ethernet-cable connected).
- Check if a valid IP address is set in the device (Device Para/TCP/IP).
- Check if the IP address of the SNTP server is set in the device (Device Para/ Time/ TimeSync/ SNTP).
- Check if SNTP is used for time synchronization (Device Para/ Time/ TimeSync/ TimeSync).
- Check if the Ethernet connection is active (Device Para/TCP/IP/Link = Up?).
- Check if both the SNTP server and the protection device answer to a Ping.
- Check if the SNTP server is up and working.

Device Planning Parameters of the SNTP

Parameter	Description	Options	Default	Menu path
Mode	Mode	do not use, use	do not use	[Device planning]

Direct Commands of the SNTP

Parameter	Description	Setting range	Default	Menu path
Res Counter	Reset all Counters.	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]

Global Protection Parameters of the SNTP

Parameter	Description	Setting range	Default	Menu path
Server1	Server 1	inactive, active	inactive	[Device Para /Time /TimeSync /SNTP]
IP Byte1	IP1.IP2.IP3.IP4	0 - 255	0	[Device Para /Time /TimeSync /SNTP]
IP Byte2	IP1.IP2.IP3.IP4	0 - 255	0	[Device Para /Time /TimeSync /SNTP]
IP Byte3	IP1.IP2.IP3.IP4	0 - 255	0	[Device Para /Time /TimeSync /SNTP]
IP Byte4	IP1.IP2.IP3.IP4	0 - 255	0	[Device Para /Time /TimeSync /SNTP]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Server2	Server 2	inactive, active	inactive	[Device Para /Time /TimeSync /SNTP]
IP Byte1	IP1.IP2.IP3.IP4	0 - 255	0	[Device Para /Time /TimeSync /SNTP]
IP Byte2	IP1.IP2.IP3.IP4	0 - 255	0	[Device Para /Time /TimeSync /SNTP]
IP Byte3	IP1.IP2.IP3.IP4	0 - 255	0	[Device Para /Time /TimeSync /SNTP]
IP Byte4	IP1.IP2.IP3.IP4	0 - 255	0	[Device Para /Time /TimeSync /SNTP]

Signals of the SNTP

Signal	*Description*
SNTP active	Signal: If there is no valid SNTP signal for 120 sec, SNTP is regarded as inactive.

SNTP Counters

Value	*Description*	*Default*	*Size*	*Menu path*
NoOfSyncs	Total Number of Synchronizations.	0	0 - 9999999999	[Operation /Count and RevData /TimeSync /SNTP]
NoOfConnectLost	Total Number of lost SNTP Connections (no sync for 120 sec).	0	0 - 9999999999	[Operation /Count and RevData /TimeSync /SNTP]

Value	*Description*	*Default*	*Size*	*Menu path*
NoOfSmallSyncs	Service counter: Total Number of very small Time Corrections.	0	0 - 9999999999	[Operation /Count and RevData /TimeSync /SNTP]
NoOfNormSyncs	Service counter: Total Number of normal Time Corrections	0	0 - 9999999999	[Operation /Count and RevData /TimeSync /SNTP]
NoOfBigSyncs	Service counter: Total Number of big Time Corrections	0	0 - 9999999999	[Operation /Count and RevData /TimeSync /SNTP]
NoOfFiltSyncs	Service counter: Total Number of filtered Time Corrections	0	0 - 9999999999	[Operation /Count and RevData /TimeSync /SNTP]
NoOfSlowTrans	Service counter: Total Number of slow Transfers.	0	0 - 9999999999	[Operation /Count and RevData /TimeSync /SNTP]
NoOfHighOffs	Service counter: Total Number of high Offsets.	0	0 - 9999999999	[Operation /Count and RevData /TimeSync /SNTP]
NoOfIntTimeouts	Service counter: Total Number of internal timeouts.	0	0 - 9999999999	[Operation /Count and RevData /TimeSync /SNTP]
StratumServer1	Stratum of Server 1	0	0 - 9999999999	[Operation /Status Display /TimeSync /SNTP]
StratumServer2	Stratum of Server 2	0	0 - 9999999999	[Operation /Status Display /TimeSync /SNTP]

SNTP Values

Value	*Description*	*Default*	*Size*	*Menu path*
Used Server	Which Server is used for SNTP synchronization.	None	Server1, Server2, None	[Operation /Status Display /TimeSync /SNTP]
PrecServer1	Precision of Server 1	0ms	0 - 1000.00000 ms	[Operation /Status Display /TimeSync /SNTP]
PrecServer2	Precision of Server 2	0ms	0 - 1000.00000 ms	[Operation /Status Display /TimeSync /SNTP]
ServerQlty	Quality of Server used for Synchronization (GOOD, SUFFICIENT, BAD)	-	GOOD, SUFFICIENT, BAD, -	[Operation /Status Display /TimeSync /SNTP]
NetConn	Quality of Network Connection (GOOD, SUFFICIENT, BAD).	-	GOOD, SUFFICIENT, BAD, -	[Operation /Status Display /TimeSync /SNTP]

IRIG-B00X

IRIG-B

NOTICE

Requirement: An IRIG-B00X time code generator is needed. IRIG-B004 and higher will support/transmit the “year information”.

If you are using an IRIG time code that does not support the “year information” (IRIG-B000, IRIG-B001, IRIG-B002, IRIG-B003), you have to set the “year” manually within the device. In these cases the correct year information is a precondition for a properly working IRIG-B.

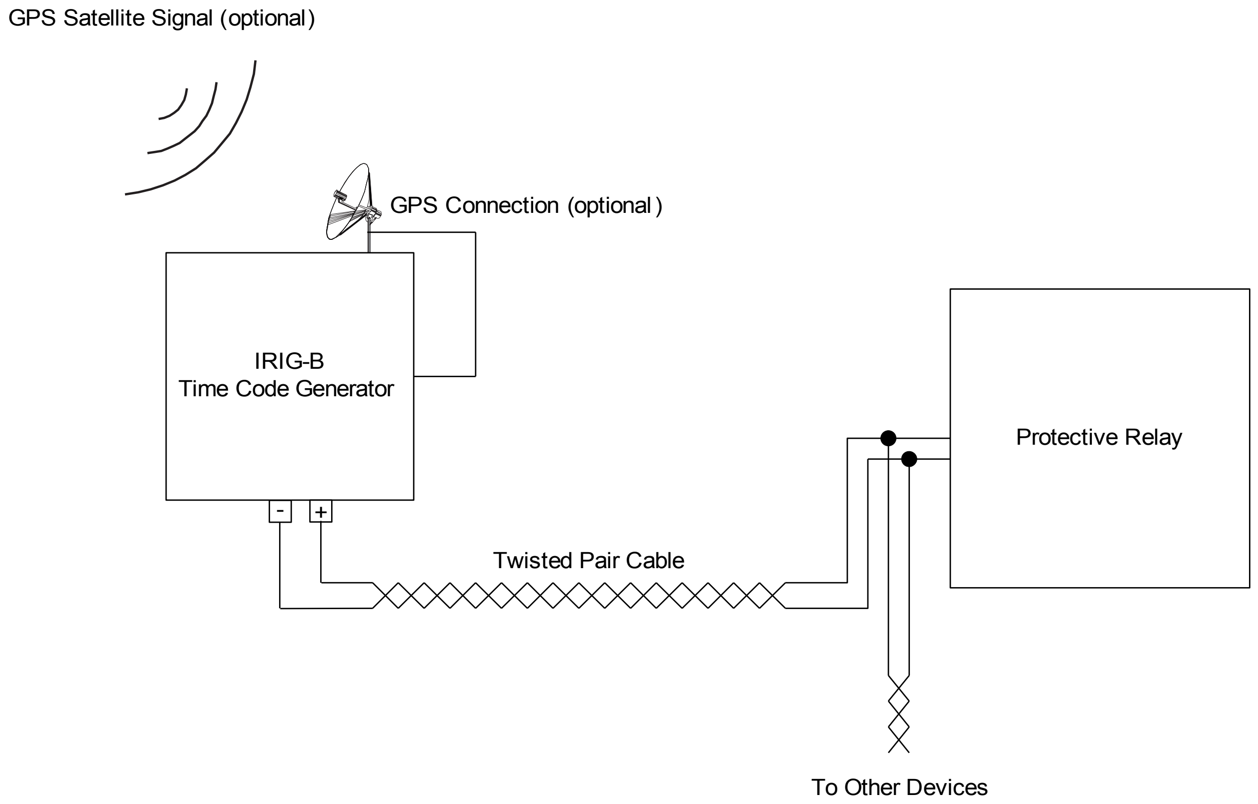
Principle - General Use

The IRIG-B standard is the most used standard to synchronize the time of protection devices in medium voltage applications.

The protection device supports IRIG-B according to the IRIG STANDARD 200-04.

This means that all time synchronization formats IRIG-B00X (IRIG-B000 / B001 / B002 / B003 / B004 / B005 / B006 / B007) are supported. It is recommended to use IRIG-B004 and higher which also transmits the “year information”.

The system time of the protection device is being synchronized with the connected IRIG-B code generator once a second. The accuracy of the used IRIG-B code generator can be increased by connecting a GPS-receiver to it.



The location of the IRIG-B interface depends to the device type. Please refer to the wiring diagram supplied with the protective device.

IRIG-B Commissioning

Activate the IRIG-B synchronization within menu [Device Para/ Time/ TimeSync]:

- Select »*IRIG-B*« in the time synchronisation menu.
- Set the time synchronization in the IRIG-B menu to »*Active*«.
- Select the IRIG-B type (choose B000 through B007).

Fault Analysis

If the device does not receive any IRIG-B time code for more than 60 s, the IRIG-B status switches from »*active*« to »*inactive*« and there is created an entry within the Event Recorder.

Check the IRIG-B functionality through the menu [Operation/ Status display/ TimeSync/ IRIG-B]:

Should the IRIG-B status not be reported as being »*active*«, please proceed as follows:

- To begin with check the IRIG-B wiring.
- Check, if the correct IRIG-B00X type is configured.

IRIG-B Control Commands

In addition to the date and time information, the IRIG-B code offers the option to transmit up to 18 control commands that can be processed by the protective device. They have to be set and issued by the IRIG-B code generator.

The protective device offers up to 18 IRIG-B assignment options for those control commands in order to carry out the assigned action. If there is a control command assigned to an action, this action is being triggered as soon as the control command is transmitted as being true. As an example there can be triggered the start of statistics or the street lighting can be switched on through a relay.

NOTICE

IRIG-B control commands are not recorded by Event and Disturbance Recorders.

If it is required to have a control signal recorded the best way is to use a Logic (1 gate) equation, because the Programmable Logic always gets recorded.

Device Planning Parameters of the IRIG-B00X

Parameter	*Description*	*Options*	*Default*	*Menu path*
Mode	Mode	do not use, use	do not use	[Device planning]

Direct Commands of the IRIG-B00X

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Res IRIG-B Cr	Resetting of the Diagnosis Counters: IRIG-B	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]

Global Protection Parameters of the IRIG-B00X

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[Device Para /Time /TimeSync /IRIG-B]
IRIG-B00X	Determination of the Type: IRIG-B00X. IRIG-B types differ in types of included “Coded Expressions” (year, control-functions, straight-binary-seconds).	IRIGB-000, IRIGB-001, IRIGB-002, IRIGB-003, IRIGB-004, IRIGB-005, IRIGB-006, IRIGB-007	IRIGB-000	[Device Para /Time /TimeSync /IRIG-B]

Signals of the IRIG-B00X (Output States)

Signal	*Description*
IRIG-B active	Signal: If there is no valid IRIG-B signal for 60 sec, IRIG-B is regarded as inactive.
High-Low Invert	Signal: The High and Low signals of the IRIG-B are inverted. This does NOT mean that the wiring is faulty. If the wiring is faulty no IRIG-B signal will be detected.
Control Signal1	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).

Signal	*Description*
Control Signal2	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
Control Signal3	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
Control Signal4	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
Control Signal5	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
Control Signal6	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
Control Signal7	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
Control Signal8	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
Control Signal9	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
Control Signal10	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
Control Signal11	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
Control Signal12	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
Control Signal13	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
Control Signal14	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
Control Signal15	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
Control Signal16	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
Control Signal17	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
Control Signal18	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).

IRIG-B00X Values

Value	*Description*	*Default*	*Size*	*Menu path*
NoOfFramesOK	Total Number valid Frames.	0	0 - 65535	[Operation /Count and RevData /TimeSync /IRIG-B]
NoOfFrameErrors	Total Number of Frame Errors. Physically corrupted Frame.	0	0 - 65535	[Operation /Count and RevData /TimeSync /IRIG-B]
Edges	Edges: Total number of rising and falling edges. This signal indicates if a signal is available at the IRIG-B input.	0	0 - 65535	[Operation /Count and RevData /TimeSync /IRIG-B]

Parameters

Parameter setting and planning can be done:

- directly at the device or
- by way of the *Smart view* software.

Parameter Definitions

Device Parameters

Device Parameters are part of the Parameter Tree. By means of them you can (depending on the type of device):

- Set cutoff levels,
- Configure Digital Inputs,
- Configure Output Relays,
- Assign LEDs,
- Assign Acknowledgment Signals,
- Configure Statistics,
- Configure Protocol Parameters,
- Adapt HMI Settings,
- Configure Recorders (reports),
- Set Date and Time,
- Change Passwords,
- Check the version (build) of the device.

Field Parameters

Field Parameters are part of the Parameter Tree. Field Parameters comprise the essential, basic settings of your switchboard such as rated frequency, transformer ratios.

Protection Parameters

Protection Parameters are part of the Parameter Tree. This tree comprises:

- ***Global Protection Parameters are part of the Protection Parameters:*** All settings and assignments that are done within the Global Parameter Tree are valid independent of the Setting Groups. They have to be set once only. In addition to that they comprise the CB Management.

- ***The Parameter Setting Switch is part of the Protection Parameters:*** You can either direct switch onto a certain parameter setting group or you can determine the conditions for switching onto another parameter setting group.

- ***Setting Group Parameters are part of the Protection Parameters:*** By means of the Parameter Setting Group Parameters you can individually adapt your protective device to the current conditions or grid conditions. They can be individually set in each Setting group.

Device Planning Parameters

Device Planning Parameters are part of the Parameter Tree.

- ***Improving the Usability (clearness):*** All protection modules that are currently not needed can be
- de-protected (switched to invisible) by means of Device Planning. In Menu Device Planning you can adapt the scope of functionality of the protective device exactly to your needs. You can improve the usability by de-projecting all modules that are currently not needed.

- ***Adapting the device to your application:*** For those modules that you need, determine how they should work (e.g. directional, non-directional, <, >...).

Direct Commands

Direct Commands are part of the Device Parameter Tree but they are ***NOT*** part of the parameter file. They will be executed directly (e.g. Resetting of a Counter).

State of the Module Inputs

Module Inputs are part of the Parameter Tree. The State of the Module Input is context-dependent.

By means of the Module Inputs influence can be taken on the Modules. You can assign Signals onto ***Module Inputs***. The state of the signals that are assigned to an input can be taken from the Status Display. Module Inputs can be identified by an ***„-I“*** at the end of the name.

Signals

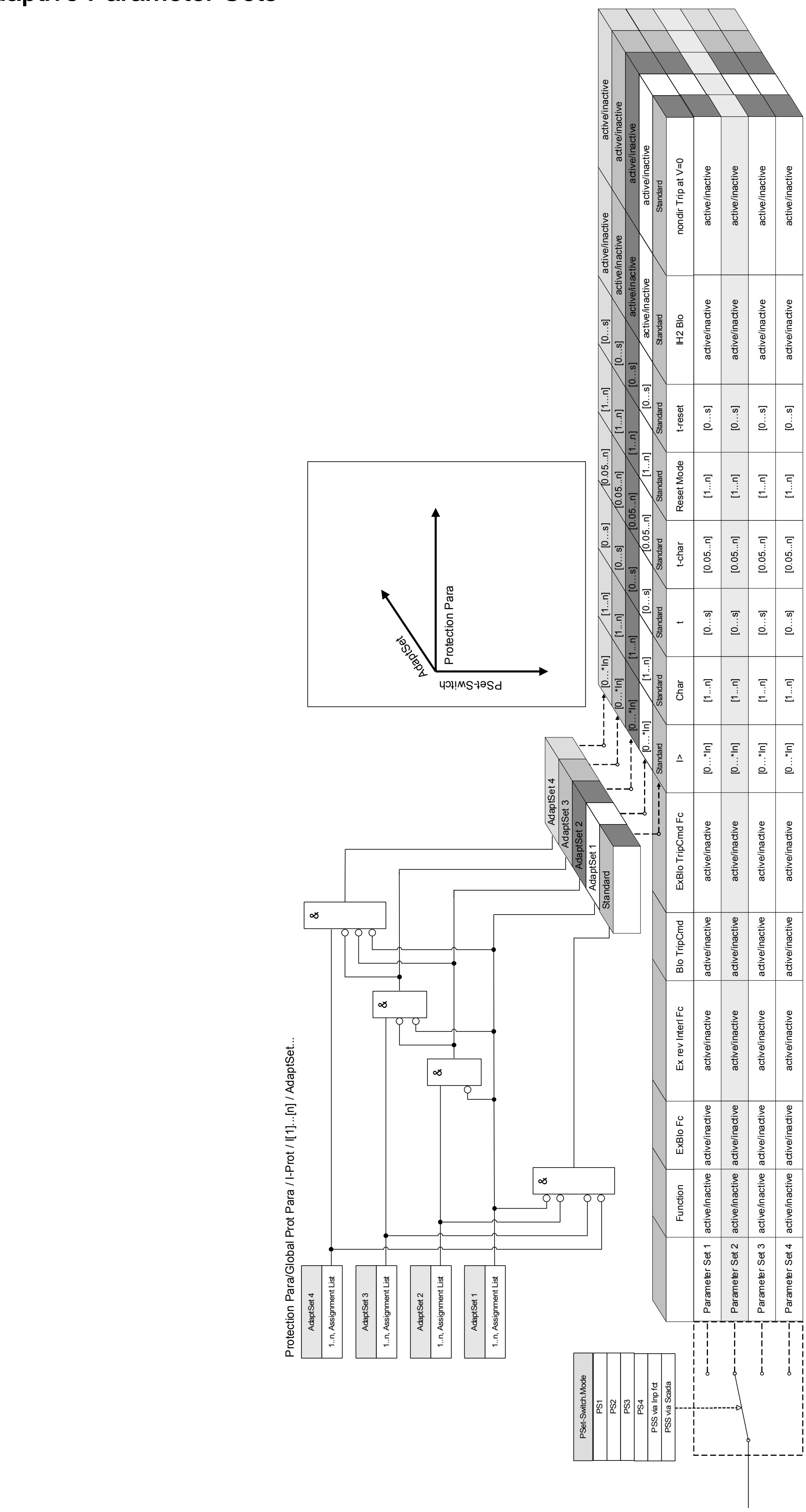
Signals are part of the Parameter Tree. The state of the signal is context-dependent.

- ***Signals*** represent the state of your installation/equipment (e.g. Position Indicators of the Circuit Breaker).

- ***Signals*** are assessments of the state of the grid and the equipment (System OK, Transformer failure detected...).

- ***Signals*** represent decisions that are taken by the device (e.g. Trip command) based on your parameter settings.

Adaptive Parameter Sets



Adaptive Parameter Sets are part of the Parameter Tree.
By means of ***Adaptive Parameter Sets*** you can modify temporarily single parameters within the parameter setting groups.

NOTICE **Adaptive Parameters fall back automatically, if the acknowledged signal, that has activated them, has fallen back. Please take into account that Adaptive Set 1 is dominant to Adaptive Set 2. Adaptive Set 2 is dominant to Adaptive Set 3. Adaptive Set 3 is dominant to Adaptive Set 4.**

NOTICE **In order to increase the usability (clearness) Adaptive Parameter Sets become visible if an corresponding activation signals has been assigned (Smart view 2.0 and higher).**

Example: In order to use Adaptive Parameters within Protective Element I[1] please proceed as follows:

- Assign within the Global Parameter tree within Protective Element I[1] an activation signal for AdaptiveParameterSet 1.
- AdaptiveParameterSet 1 becomes now visible within the Protection Parameter Sets for element I[1].

By means of additional activation signals further Adaptive Parameter Sets can be used.

The functionality of the IED (relay) can be enhanced / adapted by means of ***Adaptive Parameters*** in order to meet the requirements of modified states of the grid or the power supply system respectively to manage unpredictable events.

Moreover, the adaptive parameter can also be used to realize various special protective functions or to expand the existing function modules in a simple way without to redesign the existing hardware or software platform costly.

The ***Adaptive Parameter*** feature allows, besides a standard parameter set, one of the four parameter sets labeled from 1 to 4, to be used for example in a time overcurrent element under the control of the configurable Set Control Logics. The dynamical switch-over of the adaptive parameter set is only active for a particular element when its adaptive set control logic is configured and only as long as the activation signal is true.

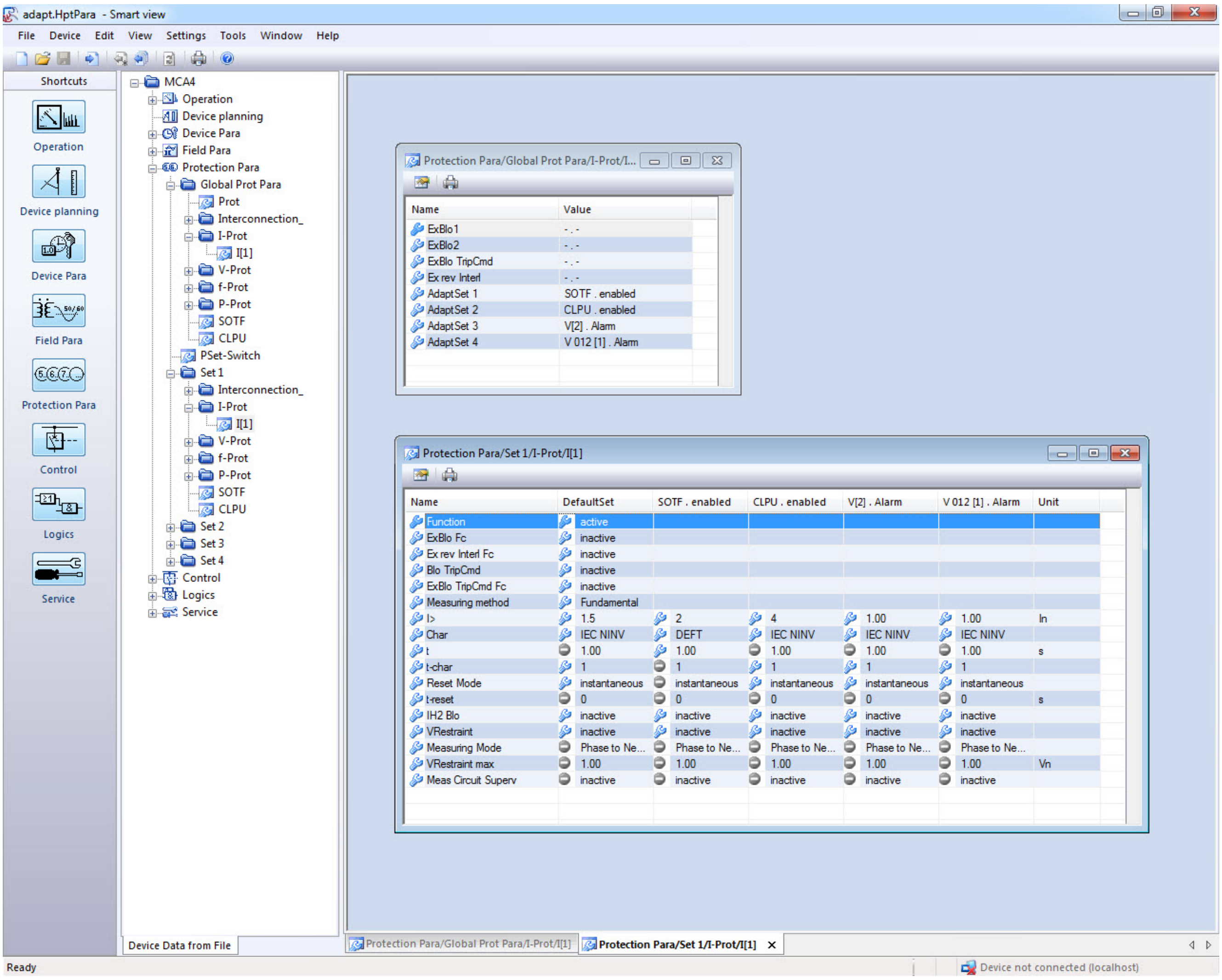
For some protection elements such as time overcurrent and instantaneous overcurrent (50P, 51P, 50G, 51G…), besides the “default” setting there exist another 4 “alternative” settings for pickup value, curve type, time dial, reset mode set values which can be switched-over dynamically by means of the configurable adaptive setting control logics in the single set parameter.

If the ***Adaptive Parameter*** feature is not used, the adaptive set control logics will not be selected (assigned). The protective elements work in this case just like a normal protection using the “Default” settings. If one of the ***Adaptive Set*** Control logics” is assigned to a logic function, the protective element will be “switched-over” to the corresponding adaptive settings if the assigned logic function is asserted and will fall back to the “Default” Setting if the assigned signal that has been activated the ***Adaptive Set*** has fallen back.

Application Example

During a Switch-OnTo-Fault condition, it is usually requested to make the embedded protective function tripping the faulted line faster, instantaneously or sometimes non-directionally.

Such a Switch-OnTo-Fault application can easily be realized using the ***Adaptive Parameter*** features above mentioned: The standard time overcurrent protection element (e.g. 51P) normally works with an inverse curve type (e.g. ANSI Type A), while in case of *SOTF* condition, it should trip instantaneously. If the *SOTF* logic function »SOTF ENABLED« is detecting a manual circuit breaker close condition the relay switches to ***AdaptiveSet1*** if the signal »SOTF.ENABLED« is assigned to ***AdaptiveSet1***. The corresponding ***AdaptiveSet1*** will become active and that means e.g. »*curve type = DEFT«* and »*t = 0«* sec.



The screenshot above shows the adaptive setting configurations following applications based on only one simple overcurrent protection element:

1. Standard Set: Default settings
2. Adaptive Set 1: *SOTF* application (Switch-Onto-Fault)
3. Adaptive Set 2: *CLPU* application (Cold Load Pickup)
4. Adaptive Set 3: Voltage-Controlled time overcurrent protection (ANSI 51V)
5. Adaptive Set 4: Negative- Phase- Sequence- Voltage-Controlled time overcurrent protection

Application Examples

- The output signal of the *Switch Onto Fault* module can be used to activate an ***Adaptive Parameter Set*** that sensibilizes the overcurrent protection.
- The output signal of the *Cold Load Pickup* module can be used to activate an ***Adaptive Parameter Set*** that desensitizes the overcurrent protection.
- By means of ***Adaptive Parameter Sets*** an Adaptive *Auto Reclosure* can be realized. After a reclosure attempt the tripping thresholds or tripping curves of the overcurrent protection can be adapted.
- Depending on undervoltage the overcurrent protection can be modified (Voltage Controlled).
- The earth overcurrent protection can be modified by the residual voltage.
- Matching the ground current protective settings dynamically and automatically according to the single-phase load diversity (Adaptive relay Setting – Normal Setting/Alternative Setting)

NOTICE **Adaptive Parameter Sets are only available for devices with current protection modules.**

Adaptive Parameter Set Activation Signals

Name	*Description*
-.-	No assignment
ExP[1].Alarm	Signal: Alarm
ExP[2].Alarm	Signal: Alarm
ExP[3].Alarm	Signal: Alarm
ExP[4].Alarm	Signal: Alarm
CTS.Alarm	Signal: Alarm Current Transformer Measuring Circuit Supervision
DI Slot X1.DI 1	Signal: Digital Input
DI Slot X1.DI 2	Signal: Digital Input
DI Slot X1.DI 3	Signal: Digital Input
DI Slot X1.DI 4	Signal: Digital Input
DI Slot X1.DI 5	Signal: Digital Input
DI Slot X1.DI 6	Signal: Digital Input
DI Slot X1.DI 7	Signal: Digital Input
DI Slot X1.DI 8	Signal: Digital Input
DI Slot X1.DI 1	Signal: Digital Input
DI Slot X1.DI 2	Signal: Digital Input
DI Slot X1.DI 3	Signal: Digital Input
DI Slot X1.DI 4	Signal: Digital Input
Modbus.Scada Cmd 1	Scada Command
Modbus.Scada Cmd 2	Scada Command
Modbus.Scada Cmd 3	Scada Command
Modbus.Scada Cmd 4	Scada Command
Modbus.Scada Cmd 5	Scada Command
Modbus.Scada Cmd 6	Scada Command
Modbus.Scada Cmd 7	Scada Command
Modbus.Scada Cmd 8	Scada Command
Modbus.Scada Cmd 9	Scada Command
Modbus.Scada Cmd 10	Scada Command
Modbus.Scada Cmd 11	Scada Command
Modbus.Scada Cmd 12	Scada Command
Modbus.Scada Cmd 13	Scada Command
Modbus.Scada Cmd 14	Scada Command
Modbus.Scada Cmd 15	Scada Command
Modbus.Scada Cmd 16	Scada Command
IEC61850.VirtInp1	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp2	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp3	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp4	Signal: Virtual Input (IEC61850 GGIO Ind)

Name	*Description*
IEC61850.VirtInp5	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp6	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp7	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp8	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp9	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp10	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp11	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp12	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp13	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp14	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp15	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp16	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp17	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp18	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp19	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp20	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp21	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp22	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp23	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp24	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp25	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp26	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp27	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp28	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp29	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp30	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp31	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp32	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.SPCSO1	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO2	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO3	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO4	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO5	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO6	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO7	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).

Name	*Description*
IEC61850.SPCSO8	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO9	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO10	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO11	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO12	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO13	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO14	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO15	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO16	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC 103.Scada Cmd 1	Scada Command
IEC 103.Scada Cmd 2	Scada Command
IEC 103.Scada Cmd 3	Scada Command
IEC 103.Scada Cmd 4	Scada Command
IEC 103.Scada Cmd 5	Scada Command
IEC 103.Scada Cmd 6	Scada Command
IEC 103.Scada Cmd 7	Scada Command
IEC 103.Scada Cmd 8	Scada Command
IEC 103.Scada Cmd 9	Scada Command
IEC 103.Scada Cmd 10	Scada Command
Profibus.Scada Cmd 1	Scada Command
Profibus.Scada Cmd 2	Scada Command
Profibus.Scada Cmd 3	Scada Command
Profibus.Scada Cmd 4	Scada Command
Profibus.Scada Cmd 5	Scada Command
Profibus.Scada Cmd 6	Scada Command
Profibus.Scada Cmd 7	Scada Command
Profibus.Scada Cmd 8	Scada Command
Profibus.Scada Cmd 9	Scada Command
Profibus.Scada Cmd 10	Scada Command
Profibus.Scada Cmd 11	Scada Command
Profibus.Scada Cmd 12	Scada Command
Profibus.Scada Cmd 13	Scada Command
Profibus.Scada Cmd 14	Scada Command
Profibus.Scada Cmd 15	Scada Command

Name	*Description*
Profibus.Scada Cmd 16	Scada Command
Logics.LE1.Gate Out	Signal: Output of the logic gate
Logics.LE1.Timer Out	Signal: Timer Output
Logics.LE1.Out	Signal: Latched Output (Q)
Logics.LE1.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE2.Gate Out	Signal: Output of the logic gate
Logics.LE2.Timer Out	Signal: Timer Output
Logics.LE2.Out	Signal: Latched Output (Q)
Logics.LE2.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE3.Gate Out	Signal: Output of the logic gate
Logics.LE3.Timer Out	Signal: Timer Output
Logics.LE3.Out	Signal: Latched Output (Q)
Logics.LE3.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE4.Gate Out	Signal: Output of the logic gate
Logics.LE4.Timer Out	Signal: Timer Output
Logics.LE4.Out	Signal: Latched Output (Q)
Logics.LE4.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE5.Gate Out	Signal: Output of the logic gate
Logics.LE5.Timer Out	Signal: Timer Output
Logics.LE5.Out	Signal: Latched Output (Q)
Logics.LE5.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE6.Gate Out	Signal: Output of the logic gate
Logics.LE6.Timer Out	Signal: Timer Output
Logics.LE6.Out	Signal: Latched Output (Q)
Logics.LE6.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE7.Gate Out	Signal: Output of the logic gate
Logics.LE7.Timer Out	Signal: Timer Output
Logics.LE7.Out	Signal: Latched Output (Q)
Logics.LE7.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE8.Gate Out	Signal: Output of the logic gate
Logics.LE8.Timer Out	Signal: Timer Output
Logics.LE8.Out	Signal: Latched Output (Q)
Logics.LE8.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE9.Gate Out	Signal: Output of the logic gate
Logics.LE9.Timer Out	Signal: Timer Output
Logics.LE9.Out	Signal: Latched Output (Q)
Logics.LE9.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE10.Gate Out	Signal: Output of the logic gate
Logics.LE10.Timer Out	Signal: Timer Output
Logics.LE10.Out	Signal: Latched Output (Q)

Name	*Description*
Logics.LE10.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE11.Gate Out	Signal: Output of the logic gate
Logics.LE11.Timer Out	Signal: Timer Output
Logics.LE11.Out	Signal: Latched Output (Q)
Logics.LE11.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE12.Gate Out	Signal: Output of the logic gate
Logics.LE12.Timer Out	Signal: Timer Output
Logics.LE12.Out	Signal: Latched Output (Q)
Logics.LE12.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE13.Gate Out	Signal: Output of the logic gate
Logics.LE13.Timer Out	Signal: Timer Output
Logics.LE13.Out	Signal: Latched Output (Q)
Logics.LE13.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE14.Gate Out	Signal: Output of the logic gate
Logics.LE14.Timer Out	Signal: Timer Output
Logics.LE14.Out	Signal: Latched Output (Q)
Logics.LE14.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE15.Gate Out	Signal: Output of the logic gate
Logics.LE15.Timer Out	Signal: Timer Output
Logics.LE15.Out	Signal: Latched Output (Q)
Logics.LE15.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE16.Gate Out	Signal: Output of the logic gate
Logics.LE16.Timer Out	Signal: Timer Output
Logics.LE16.Out	Signal: Latched Output (Q)
Logics.LE16.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE17.Gate Out	Signal: Output of the logic gate
Logics.LE17.Timer Out	Signal: Timer Output
Logics.LE17.Out	Signal: Latched Output (Q)
Logics.LE17.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE18.Gate Out	Signal: Output of the logic gate
Logics.LE18.Timer Out	Signal: Timer Output
Logics.LE18.Out	Signal: Latched Output (Q)
Logics.LE18.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE19.Gate Out	Signal: Output of the logic gate
Logics.LE19.Timer Out	Signal: Timer Output
Logics.LE19.Out	Signal: Latched Output (Q)
Logics.LE19.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE20.Gate Out	Signal: Output of the logic gate
Logics.LE20.Timer Out	Signal: Timer Output
Logics.LE20.Out	Signal: Latched Output (Q)

Name	*Description*
Logics.LE20.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE21.Gate Out	Signal: Output of the logic gate
Logics.LE21.Timer Out	Signal: Timer Output
Logics.LE21.Out	Signal: Latched Output (Q)
Logics.LE21.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE22.Gate Out	Signal: Output of the logic gate
Logics.LE22.Timer Out	Signal: Timer Output
Logics.LE22.Out	Signal: Latched Output (Q)
Logics.LE22.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE23.Gate Out	Signal: Output of the logic gate
Logics.LE23.Timer Out	Signal: Timer Output
Logics.LE23.Out	Signal: Latched Output (Q)
Logics.LE23.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE24.Gate Out	Signal: Output of the logic gate
Logics.LE24.Timer Out	Signal: Timer Output
Logics.LE24.Out	Signal: Latched Output (Q)
Logics.LE24.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE25.Gate Out	Signal: Output of the logic gate
Logics.LE25.Timer Out	Signal: Timer Output
Logics.LE25.Out	Signal: Latched Output (Q)
Logics.LE25.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE26.Gate Out	Signal: Output of the logic gate
Logics.LE26.Timer Out	Signal: Timer Output
Logics.LE26.Out	Signal: Latched Output (Q)
Logics.LE26.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE27.Gate Out	Signal: Output of the logic gate
Logics.LE27.Timer Out	Signal: Timer Output
Logics.LE27.Out	Signal: Latched Output (Q)
Logics.LE27.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE28.Gate Out	Signal: Output of the logic gate
Logics.LE28.Timer Out	Signal: Timer Output
Logics.LE28.Out	Signal: Latched Output (Q)
Logics.LE28.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE29.Gate Out	Signal: Output of the logic gate
Logics.LE29.Timer Out	Signal: Timer Output
Logics.LE29.Out	Signal: Latched Output (Q)
Logics.LE29.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE30.Gate Out	Signal: Output of the logic gate
Logics.LE30.Timer Out	Signal: Timer Output
Logics.LE30.Out	Signal: Latched Output (Q)

Name	Description
Logics.LE30.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE31.Gate Out	Signal: Output of the logic gate
Logics.LE31.Timer Out	Signal: Timer Output
Logics.LE31.Out	Signal: Latched Output (Q)
Logics.LE31.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE32.Gate Out	Signal: Output of the logic gate
Logics.LE32.Timer Out	Signal: Timer Output
Logics.LE32.Out	Signal: Latched Output (Q)
Logics.LE32.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE33.Gate Out	Signal: Output of the logic gate
Logics.LE33.Timer Out	Signal: Timer Output
Logics.LE33.Out	Signal: Latched Output (Q)
Logics.LE33.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE34.Gate Out	Signal: Output of the logic gate
Logics.LE34.Timer Out	Signal: Timer Output
Logics.LE34.Out	Signal: Latched Output (Q)
Logics.LE34.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE35.Gate Out	Signal: Output of the logic gate
Logics.LE35.Timer Out	Signal: Timer Output
Logics.LE35.Out	Signal: Latched Output (Q)
Logics.LE35.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE36.Gate Out	Signal: Output of the logic gate
Logics.LE36.Timer Out	Signal: Timer Output
Logics.LE36.Out	Signal: Latched Output (Q)
Logics.LE36.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE37.Gate Out	Signal: Output of the logic gate
Logics.LE37.Timer Out	Signal: Timer Output
Logics.LE37.Out	Signal: Latched Output (Q)
Logics.LE37.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE38.Gate Out	Signal: Output of the logic gate
Logics.LE38.Timer Out	Signal: Timer Output
Logics.LE38.Out	Signal: Latched Output (Q)
Logics.LE38.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE39.Gate Out	Signal: Output of the logic gate
Logics.LE39.Timer Out	Signal: Timer Output
Logics.LE39.Out	Signal: Latched Output (Q)
Logics.LE39.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE40.Gate Out	Signal: Output of the logic gate
Logics.LE40.Timer Out	Signal: Timer Output
Logics.LE40.Out	Signal: Latched Output (Q)

Name	Description
Logics.LE40.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE41.Gate Out	Signal: Output of the logic gate
Logics.LE41.Timer Out	Signal: Timer Output
Logics.LE41.Out	Signal: Latched Output (Q)
Logics.LE41.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE42.Gate Out	Signal: Output of the logic gate
Logics.LE42.Timer Out	Signal: Timer Output
Logics.LE42.Out	Signal: Latched Output (Q)
Logics.LE42.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE43.Gate Out	Signal: Output of the logic gate
Logics.LE43.Timer Out	Signal: Timer Output
Logics.LE43.Out	Signal: Latched Output (Q)
Logics.LE43.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE44.Gate Out	Signal: Output of the logic gate
Logics.LE44.Timer Out	Signal: Timer Output
Logics.LE44.Out	Signal: Latched Output (Q)
Logics.LE44.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE45.Gate Out	Signal: Output of the logic gate
Logics.LE45.Timer Out	Signal: Timer Output
Logics.LE45.Out	Signal: Latched Output (Q)
Logics.LE45.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE46.Gate Out	Signal: Output of the logic gate
Logics.LE46.Timer Out	Signal: Timer Output
Logics.LE46.Out	Signal: Latched Output (Q)
Logics.LE46.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE47.Gate Out	Signal: Output of the logic gate
Logics.LE47.Timer Out	Signal: Timer Output
Logics.LE47.Out	Signal: Latched Output (Q)
Logics.LE47.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE48.Gate Out	Signal: Output of the logic gate
Logics.LE48.Timer Out	Signal: Timer Output
Logics.LE48.Out	Signal: Latched Output (Q)
Logics.LE48.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE49.Gate Out	Signal: Output of the logic gate
Logics.LE49.Timer Out	Signal: Timer Output
Logics.LE49.Out	Signal: Latched Output (Q)
Logics.LE49.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE50.Gate Out	Signal: Output of the logic gate
Logics.LE50.Timer Out	Signal: Timer Output
Logics.LE50.Out	Signal: Latched Output (Q)

Name	*Description*
Logics.LE50.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE51.Gate Out	Signal: Output of the logic gate
Logics.LE51.Timer Out	Signal: Timer Output
Logics.LE51.Out	Signal: Latched Output (Q)
Logics.LE51.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE52.Gate Out	Signal: Output of the logic gate
Logics.LE52.Timer Out	Signal: Timer Output
Logics.LE52.Out	Signal: Latched Output (Q)
Logics.LE52.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE53.Gate Out	Signal: Output of the logic gate
Logics.LE53.Timer Out	Signal: Timer Output
Logics.LE53.Out	Signal: Latched Output (Q)
Logics.LE53.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE54.Gate Out	Signal: Output of the logic gate
Logics.LE54.Timer Out	Signal: Timer Output
Logics.LE54.Out	Signal: Latched Output (Q)
Logics.LE54.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE55.Gate Out	Signal: Output of the logic gate
Logics.LE55.Timer Out	Signal: Timer Output
Logics.LE55.Out	Signal: Latched Output (Q)
Logics.LE55.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE56.Gate Out	Signal: Output of the logic gate
Logics.LE56.Timer Out	Signal: Timer Output
Logics.LE56.Out	Signal: Latched Output (Q)
Logics.LE56.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE57.Gate Out	Signal: Output of the logic gate
Logics.LE57.Timer Out	Signal: Timer Output
Logics.LE57.Out	Signal: Latched Output (Q)
Logics.LE57.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE58.Gate Out	Signal: Output of the logic gate
Logics.LE58.Timer Out	Signal: Timer Output
Logics.LE58.Out	Signal: Latched Output (Q)
Logics.LE58.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE59.Gate Out	Signal: Output of the logic gate
Logics.LE59.Timer Out	Signal: Timer Output
Logics.LE59.Out	Signal: Latched Output (Q)
Logics.LE59.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE60.Gate Out	Signal: Output of the logic gate
Logics.LE60.Timer Out	Signal: Timer Output
Logics.LE60.Out	Signal: Latched Output (Q)

Name	*Description*
Logics.LE60.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE61.Gate Out	Signal: Output of the logic gate
Logics.LE61.Timer Out	Signal: Timer Output
Logics.LE61.Out	Signal: Latched Output (Q)
Logics.LE61.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE62.Gate Out	Signal: Output of the logic gate
Logics.LE62.Timer Out	Signal: Timer Output
Logics.LE62.Out	Signal: Latched Output (Q)
Logics.LE62.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE63.Gate Out	Signal: Output of the logic gate
Logics.LE63.Timer Out	Signal: Timer Output
Logics.LE63.Out	Signal: Latched Output (Q)
Logics.LE63.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE64.Gate Out	Signal: Output of the logic gate
Logics.LE64.Timer Out	Signal: Timer Output
Logics.LE64.Out	Signal: Latched Output (Q)
Logics.LE64.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE65.Gate Out	Signal: Output of the logic gate
Logics.LE65.Timer Out	Signal: Timer Output
Logics.LE65.Out	Signal: Latched Output (Q)
Logics.LE65.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE66.Gate Out	Signal: Output of the logic gate
Logics.LE66.Timer Out	Signal: Timer Output
Logics.LE66.Out	Signal: Latched Output (Q)
Logics.LE66.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE67.Gate Out	Signal: Output of the logic gate
Logics.LE67.Timer Out	Signal: Timer Output
Logics.LE67.Out	Signal: Latched Output (Q)
Logics.LE67.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE68.Gate Out	Signal: Output of the logic gate
Logics.LE68.Timer Out	Signal: Timer Output
Logics.LE68.Out	Signal: Latched Output (Q)
Logics.LE68.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE69.Gate Out	Signal: Output of the logic gate
Logics.LE69.Timer Out	Signal: Timer Output
Logics.LE69.Out	Signal: Latched Output (Q)
Logics.LE69.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE70.Gate Out	Signal: Output of the logic gate
Logics.LE70.Timer Out	Signal: Timer Output
Logics.LE70.Out	Signal: Latched Output (Q)

Name	Description
Logics.LE70.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE71.Gate Out	Signal: Output of the logic gate
Logics.LE71.Timer Out	Signal: Timer Output
Logics.LE71.Out	Signal: Latched Output (Q)
Logics.LE71.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE72.Gate Out	Signal: Output of the logic gate
Logics.LE72.Timer Out	Signal: Timer Output
Logics.LE72.Out	Signal: Latched Output (Q)
Logics.LE72.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE73.Gate Out	Signal: Output of the logic gate
Logics.LE73.Timer Out	Signal: Timer Output
Logics.LE73.Out	Signal: Latched Output (Q)
Logics.LE73.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE74.Gate Out	Signal: Output of the logic gate
Logics.LE74.Timer Out	Signal: Timer Output
Logics.LE74.Out	Signal: Latched Output (Q)
Logics.LE74.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE75.Gate Out	Signal: Output of the logic gate
Logics.LE75.Timer Out	Signal: Timer Output
Logics.LE75.Out	Signal: Latched Output (Q)
Logics.LE75.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE76.Gate Out	Signal: Output of the logic gate
Logics.LE76.Timer Out	Signal: Timer Output
Logics.LE76.Out	Signal: Latched Output (Q)
Logics.LE76.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE77.Gate Out	Signal: Output of the logic gate
Logics.LE77.Timer Out	Signal: Timer Output
Logics.LE77.Out	Signal: Latched Output (Q)
Logics.LE77.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE78.Gate Out	Signal: Output of the logic gate
Logics.LE78.Timer Out	Signal: Timer Output
Logics.LE78.Out	Signal: Latched Output (Q)
Logics.LE78.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE79.Gate Out	Signal: Output of the logic gate
Logics.LE79.Timer Out	Signal: Timer Output
Logics.LE79.Out	Signal: Latched Output (Q)
Logics.LE79.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE80.Gate Out	Signal: Output of the logic gate
Logics.LE80.Timer Out	Signal: Timer Output
Logics.LE80.Out	Signal: Latched Output (Q)

Name	*Description*
Logics.LE80.Out inverted	Signal: Negated Latched Output (Q NOT)

Parameter Setting at the HMI

Every parameter belongs to an access area. Editing and changing of a parameter requires a sufficient access authorization.
The User can obtain the required access authorizations by unlocking access areas in advance of parameter changes or context-dependent. In the following sections both options will be explained.

Option 1: Direct Authorization for an Access Area

Call up menu [Device Para\Access level].

Select the required access level respectively navigate to the required access authorization (level). Enter the required password. If the correct password has been entered, the required access authorization will be obtained. In order to do the parameter changes please proceed as follows:

- Move to the parameter you want to change by using the Softkeys. If the parameter is selected, the lower right corner of the display should show a »Wrench« symbol.

This symbol indicates, that the parameter is unlocked and can be edited, because the required access authorization is available. Confirm the Softkey »Wrench«, in order to edit the parameter. Change the parameter.

Now you can:

- save the change you made and have them adopted by the system or:
- change additional parameters and save finally all the altered parameters and have them adopted by the system.

To save parameter changes immediately,

- press the »OK« key for saving changed parameters directly and to have them adopted by the device. Confirm the parameter changes by pressing the »Yes« Softkey or dismiss by pressing »No«.

To change additional parameters and save afterwards,

- move to other parameters and change them

NOTICE

A star symbol in front of the changed parameters indicates that the modifications have only been saved temporarily, they are not yet finally stored and adopted by the device.
In order to make things easier to follow, especially where complex parameter changes are involved, on every superior/higher-ranking menu level the intended change of the parameter is indicated by the star symbol (star trace). This makes it possible to control or follow up from the main menu level at any time where parameter changes have been made and have not been saved finally.
In addition to the star trace to the temporary saved parameter changes, a general parameter changing symbol is faded-in at the left corner of the display,

and so it is possible from each point of the menu tree to see that there are parameter changes still not adopted by the device.

Press the »OK« key to initiate the final storage of all parameter changes. Confirm the parameter changes by pressing the »Yes« softkey or dismiss by pressing Softkey »No«.

NOTICE

If the display shows a Key Symbol instead of a Wrench-Symbol, this will indicate, that the required access authorization is not available.

In order to edit this parameter, a password is required, that provides the required authorization.

NOTICE

Plausibility check: In order to prevent obvious wrong settings the device monitors constantly all temporary saved parameter changes. If the device detects an implausibility, this is indicated by a question mark in front of the respective parameter.
In order to make things easier to follow up, especially where complex parameter changes are involved, on every superior/higher-ranking menu level, above the temporarily saved parameters an invalidity is indicated by the question mark (plausibility trace). This makes it possible to control or follow from the main menu level at any time where implausibilities are intended to be saved.

In addition to the question mark trace to the temporary saved implausible parameter changes a general implausibility symbol/question mark is faded-in at the left corner of the display, and so it is possible to see from each point of the menu tree that implausibilities have been detected by the device.

A star/parameter change indication is always overwritten by the question mark/implausibility symbol.

If a device detects an implausibility, it rejects saving and adopting of the parameters.

Option 2: Context-dependent Access Authorization

Navigate to the parameter, that is to be changed. If the parameter is selected, the lower right corner of the display shows a »*Key«*-Symbol.

This symbol indicates, that the device is still within the *»Read Only Lv0«*-Level, or that the current level does not provide sufficient access rights to allow editing of this parameter.

Press this Softkey and enter the password[1)] that provides access to this parameter.
Please change the parameter settings.

1) This page provides also information, which password/access authorization is required to do changes on this parameter.

Now you can:

- save the change you made and have them adopted by the system or:
- change additional parameters and save finally all the altered parameters and have them adopted by the system.

To save parameter changes immediately,

- press the »OK« key for saving changed parameters directly and to have them adopted by the device. Confirm the parameter changes by pressing the »Yes« Softkey or dismiss by pressing »No«.

To change additional parameters and save afterwards,

- move to other parameters and change them

NOTICE

A star symbol in front of the changed parameters indicates that the modifications have only been saved temporary, they are not yet finally stored and adopted by the device.
In order to make things easier to follow up, especially where complex parameter changes are involved, on every superior/higher-ranking menu level the intended change of the parameter is indicated by the star symbol (star trace). This makes it possible to control or follow from the main menu level at any time where parameter changes have been made and have not been saved finally.
In addition to the star trace to the temporary saved parameter changes, a general parameter changing symbol is faded-in at the left corner of the display, and so it is possible from each point of the menu tree to see that there are parameter changes still not adopted by the device.

Press the »OK« key to initiate the final storage of all parameter changes. Confirm the parameter changes by pressing the »Yes« Softkey or dismiss by pressing Softkey »No«.

NOTICE

Plausibility check: In order to prevent obvious wrong settings the device monitors constantly all temporary saved parameter changes. If the device detects an implausibility, this is indicated by a question mark in front of the respective parameter.
In order to make things easier to follow up, especially where complex parameter changes are involved, on every superior/higher-ranking menu level, above the temporary saved parameters an invalidity is indicated by the question mark (plausibility trace). This makes it possible to control or follow from the main menu level at any time where implausibilities are intended to be saved.

In addition to the question mark trace to the temporary saved implausible parameter changes a general implausibility symbol/question mark is faded-in at the left corner of the display, and so it is possible to see from each point of the menu tree that implausibilities have been detected by the device.

A star/parameter change indication is always overwritten by the question mark/implausibility symbol.

If a device detects an implausibility, it rejects saving and adopting of the parameters.

Setting Groups

Within the menu »Protection Para/P-Set Switch« you have the following possibilities:

- To set one of the four setting groups active manually.
- To assign a signal to each setting group that sets this group to active.
- Scada switches the setting groups.

NOTICE **Switching over to another (already configured) setting group is done very quickly (usually within a time of approx. 10 ms).**

Option	*Setting Group Switch*
Manual Selection	Switch over, if another setting group is chosen manually within the menu »Protection Para/P-Set Switch«
Via Input Function (e.g. Digital Input)	Switch over not until the request is clear. That means, if there is more or less than one request signal active, no switch over will be executed. Example: • DI3 is assigned onto Parameter set 1. DI3 is active "1". • DI4 is assigned onto Parameter set 2. DI4 is inactive "0". Now the device should switch from parameter set 1 to parameter set 2. Therefore at first DI3 has to become inactive "0". Than DI4 has to be active "1". If DI4 becomes again inactive „0", parameter set 2 will remain active "1" as long as there is no clear request (e.g. DI3 becomes active "1", all the other assignments are inactive "0")
Via SCADA	Switch over if there is a clear SCADA request. Otherwise no switch over will be executed.

NOTICE ***Setting group switch:*** **Whenever another setting group gets activated, all memory-related values (e.g. timers) are reset for all protection functions.**

Configuration change: **Whenever changes are made to the settings of protection parameters (device planning, global parameters or setting group parameters for more than one setting group) all protection functionality is completely deactivated for a short time. This means that all protection modules are inactive for some time, so that they can be restarted with the new settings. This way it is made sure that all protection behavior is consistent with respect to the new settings.**

An *exception* from this is a configuration change that is restricted to settings from only one setting group. In this case all protection functions are only reset (exactly as for a setting group switch, see above).

Signals that can be used for PSS

Name	*Description*
-.-	No assignment
CTS.Alarm	Signal: Alarm Current Transformer Measuring Circuit Supervision
DI Slot X1.DI 1	Signal: Digital Input
DI Slot X1.DI 2	Signal: Digital Input
DI Slot X1.DI 3	Signal: Digital Input
DI Slot X1.DI 4	Signal: Digital Input
DI Slot X1.DI 5	Signal: Digital Input
DI Slot X1.DI 6	Signal: Digital Input
DI Slot X1.DI 7	Signal: Digital Input
DI Slot X1.DI 8	Signal: Digital Input
DI Slot X1.DI 1	Signal: Digital Input
DI Slot X1.DI 2	Signal: Digital Input
DI Slot X1.DI 3	Signal: Digital Input
DI Slot X1.DI 4	Signal: Digital Input
Logics.LE1.Gate Out	Signal: Output of the logic gate
Logics.LE1.Timer Out	Signal: Timer Output
Logics.LE1.Out	Signal: Latched Output (Q)
Logics.LE1.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE2.Gate Out	Signal: Output of the logic gate
Logics.LE2.Timer Out	Signal: Timer Output
Logics.LE2.Out	Signal: Latched Output (Q)
Logics.LE2.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE3.Gate Out	Signal: Output of the logic gate
Logics.LE3.Timer Out	Signal: Timer Output
Logics.LE3.Out	Signal: Latched Output (Q)
Logics.LE3.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE4.Gate Out	Signal: Output of the logic gate
Logics.LE4.Timer Out	Signal: Timer Output
Logics.LE4.Out	Signal: Latched Output (Q)
Logics.LE4.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE5.Gate Out	Signal: Output of the logic gate
Logics.LE5.Timer Out	Signal: Timer Output
Logics.LE5.Out	Signal: Latched Output (Q)
Logics.LE5.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE6.Gate Out	Signal: Output of the logic gate
Logics.LE6.Timer Out	Signal: Timer Output
Logics.LE6.Out	Signal: Latched Output (Q)
Logics.LE6.Out inverted	Signal: Negated Latched Output (Q NOT)

Name	*Description*
Logics.LE7.Gate Out	Signal: Output of the logic gate
Logics.LE7.Timer Out	Signal: Timer Output
Logics.LE7.Out	Signal: Latched Output (Q)
Logics.LE7.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE8.Gate Out	Signal: Output of the logic gate
Logics.LE8.Timer Out	Signal: Timer Output
Logics.LE8.Out	Signal: Latched Output (Q)
Logics.LE8.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE9.Gate Out	Signal: Output of the logic gate
Logics.LE9.Timer Out	Signal: Timer Output
Logics.LE9.Out	Signal: Latched Output (Q)
Logics.LE9.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE10.Gate Out	Signal: Output of the logic gate
Logics.LE10.Timer Out	Signal: Timer Output
Logics.LE10.Out	Signal: Latched Output (Q)
Logics.LE10.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE11.Gate Out	Signal: Output of the logic gate
Logics.LE11.Timer Out	Signal: Timer Output
Logics.LE11.Out	Signal: Latched Output (Q)
Logics.LE11.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE12.Gate Out	Signal: Output of the logic gate
Logics.LE12.Timer Out	Signal: Timer Output
Logics.LE12.Out	Signal: Latched Output (Q)
Logics.LE12.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE13.Gate Out	Signal: Output of the logic gate
Logics.LE13.Timer Out	Signal: Timer Output
Logics.LE13.Out	Signal: Latched Output (Q)
Logics.LE13.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE14.Gate Out	Signal: Output of the logic gate
Logics.LE14.Timer Out	Signal: Timer Output
Logics.LE14.Out	Signal: Latched Output (Q)
Logics.LE14.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE15.Gate Out	Signal: Output of the logic gate
Logics.LE15.Timer Out	Signal: Timer Output
Logics.LE15.Out	Signal: Latched Output (Q)
Logics.LE15.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE16.Gate Out	Signal: Output of the logic gate
Logics.LE16.Timer Out	Signal: Timer Output
Logics.LE16.Out	Signal: Latched Output (Q)
Logics.LE16.Out inverted	Signal: Negated Latched Output (Q NOT)

Name	*Description*
Logics.LE17.Gate Out	Signal: Output of the logic gate
Logics.LE17.Timer Out	Signal: Timer Output
Logics.LE17.Out	Signal: Latched Output (Q)
Logics.LE17.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE18.Gate Out	Signal: Output of the logic gate
Logics.LE18.Timer Out	Signal: Timer Output
Logics.LE18.Out	Signal: Latched Output (Q)
Logics.LE18.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE19.Gate Out	Signal: Output of the logic gate
Logics.LE19.Timer Out	Signal: Timer Output
Logics.LE19.Out	Signal: Latched Output (Q)
Logics.LE19.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE20.Gate Out	Signal: Output of the logic gate
Logics.LE20.Timer Out	Signal: Timer Output
Logics.LE20.Out	Signal: Latched Output (Q)
Logics.LE20.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE21.Gate Out	Signal: Output of the logic gate
Logics.LE21.Timer Out	Signal: Timer Output
Logics.LE21.Out	Signal: Latched Output (Q)
Logics.LE21.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE22.Gate Out	Signal: Output of the logic gate
Logics.LE22.Timer Out	Signal: Timer Output
Logics.LE22.Out	Signal: Latched Output (Q)
Logics.LE22.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE23.Gate Out	Signal: Output of the logic gate
Logics.LE23.Timer Out	Signal: Timer Output
Logics.LE23.Out	Signal: Latched Output (Q)
Logics.LE23.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE24.Gate Out	Signal: Output of the logic gate
Logics.LE24.Timer Out	Signal: Timer Output
Logics.LE24.Out	Signal: Latched Output (Q)
Logics.LE24.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE25.Gate Out	Signal: Output of the logic gate
Logics.LE25.Timer Out	Signal: Timer Output
Logics.LE25.Out	Signal: Latched Output (Q)
Logics.LE25.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE26.Gate Out	Signal: Output of the logic gate
Logics.LE26.Timer Out	Signal: Timer Output
Logics.LE26.Out	Signal: Latched Output (Q)
Logics.LE26.Out inverted	Signal: Negated Latched Output (Q NOT)

Name	*Description*
Logics.LE27.Gate Out	Signal: Output of the logic gate
Logics.LE27.Timer Out	Signal: Timer Output
Logics.LE27.Out	Signal: Latched Output (Q)
Logics.LE27.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE28.Gate Out	Signal: Output of the logic gate
Logics.LE28.Timer Out	Signal: Timer Output
Logics.LE28.Out	Signal: Latched Output (Q)
Logics.LE28.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE29.Gate Out	Signal: Output of the logic gate
Logics.LE29.Timer Out	Signal: Timer Output
Logics.LE29.Out	Signal: Latched Output (Q)
Logics.LE29.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE30.Gate Out	Signal: Output of the logic gate
Logics.LE30.Timer Out	Signal: Timer Output
Logics.LE30.Out	Signal: Latched Output (Q)
Logics.LE30.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE31.Gate Out	Signal: Output of the logic gate
Logics.LE31.Timer Out	Signal: Timer Output
Logics.LE31.Out	Signal: Latched Output (Q)
Logics.LE31.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE32.Gate Out	Signal: Output of the logic gate
Logics.LE32.Timer Out	Signal: Timer Output
Logics.LE32.Out	Signal: Latched Output (Q)
Logics.LE32.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE33.Gate Out	Signal: Output of the logic gate
Logics.LE33.Timer Out	Signal: Timer Output
Logics.LE33.Out	Signal: Latched Output (Q)
Logics.LE33.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE34.Gate Out	Signal: Output of the logic gate
Logics.LE34.Timer Out	Signal: Timer Output
Logics.LE34.Out	Signal: Latched Output (Q)
Logics.LE34.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE35.Gate Out	Signal: Output of the logic gate
Logics.LE35.Timer Out	Signal: Timer Output
Logics.LE35.Out	Signal: Latched Output (Q)
Logics.LE35.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE36.Gate Out	Signal: Output of the logic gate
Logics.LE36.Timer Out	Signal: Timer Output
Logics.LE36.Out	Signal: Latched Output (Q)
Logics.LE36.Out inverted	Signal: Negated Latched Output (Q NOT)

Name	*Description*
Logics.LE37.Gate Out	Signal: Output of the logic gate
Logics.LE37.Timer Out	Signal: Timer Output
Logics.LE37.Out	Signal: Latched Output (Q)
Logics.LE37.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE38.Gate Out	Signal: Output of the logic gate
Logics.LE38.Timer Out	Signal: Timer Output
Logics.LE38.Out	Signal: Latched Output (Q)
Logics.LE38.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE39.Gate Out	Signal: Output of the logic gate
Logics.LE39.Timer Out	Signal: Timer Output
Logics.LE39.Out	Signal: Latched Output (Q)
Logics.LE39.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE40.Gate Out	Signal: Output of the logic gate
Logics.LE40.Timer Out	Signal: Timer Output
Logics.LE40.Out	Signal: Latched Output (Q)
Logics.LE40.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE41.Gate Out	Signal: Output of the logic gate
Logics.LE41.Timer Out	Signal: Timer Output
Logics.LE41.Out	Signal: Latched Output (Q)
Logics.LE41.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE42.Gate Out	Signal: Output of the logic gate
Logics.LE42.Timer Out	Signal: Timer Output
Logics.LE42.Out	Signal: Latched Output (Q)
Logics.LE42.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE43.Gate Out	Signal: Output of the logic gate
Logics.LE43.Timer Out	Signal: Timer Output
Logics.LE43.Out	Signal: Latched Output (Q)
Logics.LE43.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE44.Gate Out	Signal: Output of the logic gate
Logics.LE44.Timer Out	Signal: Timer Output
Logics.LE44.Out	Signal: Latched Output (Q)
Logics.LE44.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE45.Gate Out	Signal: Output of the logic gate
Logics.LE45.Timer Out	Signal: Timer Output
Logics.LE45.Out	Signal: Latched Output (Q)
Logics.LE45.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE46.Gate Out	Signal: Output of the logic gate
Logics.LE46.Timer Out	Signal: Timer Output
Logics.LE46.Out	Signal: Latched Output (Q)
Logics.LE46.Out inverted	Signal: Negated Latched Output (Q NOT)

Name	*Description*
Logics.LE47.Gate Out	Signal: Output of the logic gate
Logics.LE47.Timer Out	Signal: Timer Output
Logics.LE47.Out	Signal: Latched Output (Q)
Logics.LE47.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE48.Gate Out	Signal: Output of the logic gate
Logics.LE48.Timer Out	Signal: Timer Output
Logics.LE48.Out	Signal: Latched Output (Q)
Logics.LE48.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE49.Gate Out	Signal: Output of the logic gate
Logics.LE49.Timer Out	Signal: Timer Output
Logics.LE49.Out	Signal: Latched Output (Q)
Logics.LE49.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE50.Gate Out	Signal: Output of the logic gate
Logics.LE50.Timer Out	Signal: Timer Output
Logics.LE50.Out	Signal: Latched Output (Q)
Logics.LE50.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE51.Gate Out	Signal: Output of the logic gate
Logics.LE51.Timer Out	Signal: Timer Output
Logics.LE51.Out	Signal: Latched Output (Q)
Logics.LE51.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE52.Gate Out	Signal: Output of the logic gate
Logics.LE52.Timer Out	Signal: Timer Output
Logics.LE52.Out	Signal: Latched Output (Q)
Logics.LE52.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE53.Gate Out	Signal: Output of the logic gate
Logics.LE53.Timer Out	Signal: Timer Output
Logics.LE53.Out	Signal: Latched Output (Q)
Logics.LE53.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE54.Gate Out	Signal: Output of the logic gate
Logics.LE54.Timer Out	Signal: Timer Output
Logics.LE54.Out	Signal: Latched Output (Q)
Logics.LE54.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE55.Gate Out	Signal: Output of the logic gate
Logics.LE55.Timer Out	Signal: Timer Output
Logics.LE55.Out	Signal: Latched Output (Q)
Logics.LE55.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE56.Gate Out	Signal: Output of the logic gate
Logics.LE56.Timer Out	Signal: Timer Output
Logics.LE56.Out	Signal: Latched Output (Q)
Logics.LE56.Out inverted	Signal: Negated Latched Output (Q NOT)

Name	*Description*
Logics.LE57.Gate Out	Signal: Output of the logic gate
Logics.LE57.Timer Out	Signal: Timer Output
Logics.LE57.Out	Signal: Latched Output (Q)
Logics.LE57.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE58.Gate Out	Signal: Output of the logic gate
Logics.LE58.Timer Out	Signal: Timer Output
Logics.LE58.Out	Signal: Latched Output (Q)
Logics.LE58.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE59.Gate Out	Signal: Output of the logic gate
Logics.LE59.Timer Out	Signal: Timer Output
Logics.LE59.Out	Signal: Latched Output (Q)
Logics.LE59.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE60.Gate Out	Signal: Output of the logic gate
Logics.LE60.Timer Out	Signal: Timer Output
Logics.LE60.Out	Signal: Latched Output (Q)
Logics.LE60.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE61.Gate Out	Signal: Output of the logic gate
Logics.LE61.Timer Out	Signal: Timer Output
Logics.LE61.Out	Signal: Latched Output (Q)
Logics.LE61.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE62.Gate Out	Signal: Output of the logic gate
Logics.LE62.Timer Out	Signal: Timer Output
Logics.LE62.Out	Signal: Latched Output (Q)
Logics.LE62.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE63.Gate Out	Signal: Output of the logic gate
Logics.LE63.Timer Out	Signal: Timer Output
Logics.LE63.Out	Signal: Latched Output (Q)
Logics.LE63.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE64.Gate Out	Signal: Output of the logic gate
Logics.LE64.Timer Out	Signal: Timer Output
Logics.LE64.Out	Signal: Latched Output (Q)
Logics.LE64.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE65.Gate Out	Signal: Output of the logic gate
Logics.LE65.Timer Out	Signal: Timer Output
Logics.LE65.Out	Signal: Latched Output (Q)
Logics.LE65.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE66.Gate Out	Signal: Output of the logic gate
Logics.LE66.Timer Out	Signal: Timer Output
Logics.LE66.Out	Signal: Latched Output (Q)
Logics.LE66.Out inverted	Signal: Negated Latched Output (Q NOT)

Name	Description
Logics.LE67.Gate Out	Signal: Output of the logic gate
Logics.LE67.Timer Out	Signal: Timer Output
Logics.LE67.Out	Signal: Latched Output (Q)
Logics.LE67.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE68.Gate Out	Signal: Output of the logic gate
Logics.LE68.Timer Out	Signal: Timer Output
Logics.LE68.Out	Signal: Latched Output (Q)
Logics.LE68.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE69.Gate Out	Signal: Output of the logic gate
Logics.LE69.Timer Out	Signal: Timer Output
Logics.LE69.Out	Signal: Latched Output (Q)
Logics.LE69.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE70.Gate Out	Signal: Output of the logic gate
Logics.LE70.Timer Out	Signal: Timer Output
Logics.LE70.Out	Signal: Latched Output (Q)
Logics.LE70.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE71.Gate Out	Signal: Output of the logic gate
Logics.LE71.Timer Out	Signal: Timer Output
Logics.LE71.Out	Signal: Latched Output (Q)
Logics.LE71.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE72.Gate Out	Signal: Output of the logic gate
Logics.LE72.Timer Out	Signal: Timer Output
Logics.LE72.Out	Signal: Latched Output (Q)
Logics.LE72.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE73.Gate Out	Signal: Output of the logic gate
Logics.LE73.Timer Out	Signal: Timer Output
Logics.LE73.Out	Signal: Latched Output (Q)
Logics.LE73.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE74.Gate Out	Signal: Output of the logic gate
Logics.LE74.Timer Out	Signal: Timer Output
Logics.LE74.Out	Signal: Latched Output (Q)
Logics.LE74.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE75.Gate Out	Signal: Output of the logic gate
Logics.LE75.Timer Out	Signal: Timer Output
Logics.LE75.Out	Signal: Latched Output (Q)
Logics.LE75.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE76.Gate Out	Signal: Output of the logic gate
Logics.LE76.Timer Out	Signal: Timer Output
Logics.LE76.Out	Signal: Latched Output (Q)
Logics.LE76.Out inverted	Signal: Negated Latched Output (Q NOT)

Name	*Description*
Logics.LE77.Gate Out	Signal: Output of the logic gate
Logics.LE77.Timer Out	Signal: Timer Output
Logics.LE77.Out	Signal: Latched Output (Q)
Logics.LE77.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE78.Gate Out	Signal: Output of the logic gate
Logics.LE78.Timer Out	Signal: Timer Output
Logics.LE78.Out	Signal: Latched Output (Q)
Logics.LE78.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE79.Gate Out	Signal: Output of the logic gate
Logics.LE79.Timer Out	Signal: Timer Output
Logics.LE79.Out	Signal: Latched Output (Q)
Logics.LE79.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE80.Gate Out	Signal: Output of the logic gate
Logics.LE80.Timer Out	Signal: Timer Output
Logics.LE80.Out	Signal: Latched Output (Q)
Logics.LE80.Out inverted	Signal: Negated Latched Output (Q NOT)

Setting Lock

By means of the *Setting Lock*, parameter settings can be locked against any changes as long as the assigned signal is true (active). The *Setting Lock* can be activated within menu
[Field Para/General Settings/Lock Settings].

Bypass of the Setting Lock

The setting lock can be overwritten (temporarily) in case that the status of the signal that activates the setting lock cannot be modified or should not be modified (spare key).

The *Setting Lock* can be bypassed by means of the Direct Control Parameter »*Setting Lock Bypass*«
[Field Para/General Settings/Setting Lock Bypass]. The protective device will fall back into the *Setting Lock* either:

- Directly after a parameter change has been saved, else
- 10 minutes after the bypass has been activated.

Device Parameters

Sys

Date and Time

In menu *»Device parameters/Date/Time«* you can set date and time.

Version

Within this menu *»Device parameters/Version«* you can obtain information on the soft- and hardware version.

Display of ANSI-Codes

The display of ANSI codes can be activated within menu *»Device parameters/HMI//Display ANSI device numbers«*

TCP/IP Settings

Within menu *»Device Para / TCP/IP/TCP/IP Config«* the TCP/IP settings have to be set.

The first-time setting of the TCP/IP Parameters can be done at the panel (HMI) only.

NOTICE **Establishing a connection via TCP/IP to the device is only possible if your device is equipped with an Ethernet Interface (RJ45).**

Contact your IT administrator in order to establish the network connection.

Set the TCP/IP Parameters

Call up *»Device parameter/TCP/IP«* at the HMI (panel) and set the following parameters:

- TCP/IP address
- Subnetmask
- Gateway

Direct Commands of the System Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Ack BO LED Scd TCmd	Reset the binary output relays, LEDs, SCADA and the Trip Command.	inactive, active	inactive	[Operation / Reset/Acknowledge /Acknowledge]
Ack LED	All acknowledgeable LEDs will be acknowledged.	inactive, active	inactive	[Operation / Reset/Acknowledge /Acknowledge]
Ack BO	All acknowledgeable binary output relays will be acknowledged.	inactive, active	inactive	[Operation / Reset/Acknowledge /Acknowledge]
Ack Scada	SCADA will be acknowledged.	inactive, active	inactive	[Operation / Reset/Acknowledge /Acknowledge]
Res OperationsCr	Reset all counters in history group operations	inactive, active	inactive	[Operation / Reset/Acknowledge /History]
Res AlarmCr	Reset all counters in history group alarms	inactive, active	inactive	[Operation / Reset/Acknowledge /History]
Res TripCmdCr	Reset all counters in history group trips	inactive, active	inactive	[Operation / Reset/Acknowledge /History]
Res TotalCr	Reset all counters in history group total	inactive, active	inactive	[Operation / Reset/Acknowledge /History]

Parameter	Description	Setting range	Default	Menu path
Res All	Reset of all Counters	inactive, active	inactive	[Operation / Reset/Acknowledge /History]
Reboot	Rebooting the device.	no, yes	no	[Service /General]
Setting Lock Bypass	Short-period unlock of the Setting Lock	inactive, active	inactive	[Field Para /General Settings]

CAUTION

CAUTION, rebooting the device manually will release the Supervision Contact.

Global Protection Parameters of the System

Parameter	Description	Setting range	Default	Menu path
PSet-Switch	Switching Parameter Set	PS1, PS2, PS3, PS4, PSS via Inp fct, PSS via Scada	PS1	[Protection Para /PSet-Switch]
PS1: activated by	This Setting Group will be the active one if: The Parameter Setting Group Switch is set to "Switch via Input" and the other three input functions are inactive at the same time. In case that there is more than one input function active, no Parameter Setting Group Switch will be executed. In case all input functions are inactive, the device will keep working with the Setting Group that was activated lastly. Only available if: PSet-Switch = PSS via Inp fct	1..n, PSS	-.-	[Protection Para /PSet-Switch]

Parameter	Description	Setting range	Default	Menu path
PS2: activated by	This Setting Group will be the active one if: The Parameter Setting Group Switch is set to "Switch via Input" and the other three input functions are inactive at the same time. In case that there is more than one input function active, no Parameter Setting Group Switch will be executed. In case all input functions are inactive, the device will keep working with the Setting Group that was activated lastly. Only available if: PSet-Switch = PSS via Inp fct	1..n, PSS	-.-	[Protection Para /PSet-Switch]
PS3: activated by	This Setting Group will be the active one if: The Parameter Setting Group Switch is set to "Switch via Input" and the other three input functions are inactive at the same time. In case that there is more than one input function active, no Parameter Setting Group Switch will be executed. In case all input functions are inactive, the device will keep working with the Setting Group that was activated lastly. Only available if: PSet-Switch = PSS via Inp fct	1..n, PSS	-.-	[Protection Para /PSet-Switch]
PS4: activated by	This Setting Group will be the active one if: The Parameter Setting Group Switch is set to "Switch via Input" and the other three input functions are inactive at the same time. In case that there is more than one input function active, no Parameter Setting Group Switch will be executed. In case all input functions are inactive, the device will keep working with the Setting Group that was activated lastly. Only available if: PSet-Switch = PSS via Inp fct	1..n, PSS	-.-	[Protection Para /PSet-Switch]
Ack via »C« key	Select which acknowledgeable elements can be reset via pressing the »C« key.	Nothing, Ack LEDs, Ack LEDs, relays, Ack Everything	Ack LEDs	[Device Para /Acknowledge]
Remote Reset	Enables or disables the option to acknowledge from external/remote via signals (assignments) and SCADA.	inactive, active	active	[Device Para /Acknowledge]
Ack LED	All acknowledgeable LEDs will be acknowledged if the state of the assigned signal becomes true. Only available if: Remote Reset = active	1..n, Assignment List	-.-	[Device Para /Acknowledge]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Ack BO	All acknowledgeable binary output relays will be acknowledged if the state of the assigned signal becomes true. Only available if: Remote Reset = active	1..n, Assignment List	-.-	[Device Para /Acknowledge]
Ack Scada	SCADA will be acknowledged if the state of the assigned signal becomes true. Only available if: Remote Reset = active	1..n, Assignment List	-.-	[Device Para /Acknowledge]
Scaling	Display of the measured values as primary, secondary or per unit values	Per unit values, Primary values, Secondary values	Per unit values	[Device Para /Measurem Display /General Settings]
Program Mode	Program Mode	Either Motor Stopped or Running, Motor Stop	Either Motor Stopped or Running	[Field Para /General Settings]

System Module Input States

Name	*Description*	*Assignment via*
Ack LED-I	Module input state: LEDs acknowledgement by digital input	[Device Para /Acknowledge]
Ack BO-I	Module input state: Acknowledgement of the binary Output Relays	[Device Para /Acknowledge]
Ack Scada-I	Module input state: Acknowledge Scada via digital input. The replica that SCADA has got from the device is to be reset.	[Device Para /Acknowledge]
PS1-I	State of the module input respectively of the signal, that should activate this Parameter Setting Group.	[Protection Para /PSet-Switch]
PS2-I	State of the module input respectively of the signal, that should activate this Parameter Setting Group.	[Protection Para /PSet-Switch]
PS3-I	State of the module input respectively of the signal, that should activate this Parameter Setting Group.	[Protection Para /PSet-Switch]
PS4-I	State of the module input respectively of the signal, that should activate this Parameter Setting Group.	[Protection Para /PSet-Switch]
Internal test state	Auxiliary state for testing purposes.	[]

System Module Signals

Signal	*Description*
Reboot	Signal: Rebooting the device: 1=Normal Start-up; 2=Reboot by the Operator; 3=Reboot by means of Super Reset; 4=outdated; 5=outdated; 6=Unknown Error Source; 7=Forced Reboot (initiated by the main processor); 8=Exceeded Time Limit of the Protection Cycle; 9= Forced Reboot (initiated by the digital signal processor); 10=Exceeded Time Limit of the Measured Value Processing; 11=Sags of the Supply Voltage; 12=Illegal Memory Access.
Act Set	Signal: Active Parameter Set
PS 1	Signal: Parameter Set 1
PS 2	Signal: Parameter Set 2
PS 3	Signal: Parameter Set 3
PS 4	Signal: Parameter Set 4
PSS manual	Signal: Manual Switch over of a Parameter Set
PSS via Scada	Signal: Parameter Set Switch via Scada. Write into this output byte the integer of the parameter set that should become active (e.g. 4 => Switch onto parameter set 4).
PSS via Inp fct	Signal: Parameter Set Switch via input function
min 1 param changed	Signal: At least one parameter has been changed
Setting Lock Bypass	Signal: Short-period unlock of the Setting Lock
Param to be saved	Number of parameters to be saved. 0 means that all parameter changes are overtaken.
Ack LED	Signal: LEDs acknowledgement
Ack BO	Signal: Acknowledgement of the Binary Outputs
Ack Counter	Signal: Reset of all Counters
Ack Scada	Signal: Acknowledge Scada
Ack TripCmd	Signal: Reset Trip Command
Ack LED-HMI	Signal: LEDs acknowledgement :HMI
Ack BO-HMI	Signal: Acknowledgement of the Binary Outputs :HMI
Ack Counter-HMI	Signal: Reset of all Counters :HMI
Ack Scada-HMI	Signal: Acknowledge Scada :HMI
Ack TripCmd-HMI	Signal: Reset Trip Command :HMI
Ack LED-Sca	Signal: LEDs acknowledgement :SCADA
Ack BO-Sca	Signal: Acknowledgement of the Binary Outputs :SCADA
Ack Counter-Sca	Signal: Reset of all Counters :SCADA
Ack Scada-Sca	Signal: Acknowledge Scada :SCADA
Ack TripCmd-Sca	Signal: Reset Trip Command :SCADA
Res OperationsCr	Signal:: Res OperationsCr
Res AlarmCr	Signal:: Res AlarmCr
Res TripCmdCr	Signal:: Res TripCmdCr
Res TotalCr	Signal:: Res TotalCr

Special Values of the System Module

Value	*Description*	*Menu path*
Build	Build	[Device Para /Version]
DM-Version	Version	[Device Para /Version]
Operating hours Cr	Operating hours counter of the protective device	[Operation /Count and RevData /Sys]
Hours Counter	Hours Counter	[Operation /History /TotalCr]

Field Parameters

<u>Field Para</u>

Within the field parameters you can set all parameters, that are relevant for the primary side and the mains operational method like frequency, primary and secondary values...

General Field Parameters

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Phase Sequence	Phase Sequence direction	ABC, ACB	ABC	[Field Para /General Settings]
f	Nominal frequency	50Hz, 60Hz	50Hz	[Field Para /General Settings]

Field Parameters – Current Related

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
CT pri	Nominal current of the primary side of the current transformers.	1 - 50000A	10A	[Field Para /CT]
CT sec	Nominal current of the secondary side of the current transformers.	1A, 5A	1A	[Field Para /CT]
CT dir	Protection functions with directional feature can only work properly if the connection of the current transformers is free of wiring errors. If all current transformers are connected to the device with an incorrect polarity, the wiring error can be compensated by this parameter. This parameter turns the current vectors by 180 degrees.	0°, 180°	0°	[Field Para /CT]
ECT pri	This parameter defines the primary nominal current of the connected earth current transformer. If the earth current is measured via the Holmgreen connection, the primary value of the phase current transformer must be entered here.	1 - 50000A	50A	[Field Para /CT]
ECT sec	This parameter defines the secondary nominal current of the connected earth current transformer. If the earth current is done via the Holmgreen connection, the primary value of the phase current transformer must be entered here.	1A, 5A	1A	[Field Para /CT]
ECT dir	Earth fault protection with directional feature depends also on the correct wiring of the earth current transformer. An incorrect polarity/wiring can be corrected by means of the settings "0°" or "180°". The operator has the possibility of turning the current vector by 180 degrees (change of sign) without modification of the wiring. This means, that - in terms of figures - the determined current indicator was turned by 180° by the device.	0°, 180°	0°	[Field Para /CT]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
IL1, IL2, IL3 Cutoff Level	The Current shown in the Display or within the PC Software will be displayed as zero, if the Current falls below this Cutoff Level. This parameter has no impact on recorders.	0.0 - 0.100In	0.005In	[Device Para /Measurem Display /Current]
IG meas Cutoff Level	The measured Earth Current shown in the Display or within the PC Software will be displayed as zero, if the measured Earth Current falls below this Cutoff Level. This parameter has no impact on recorders.	0.0 - 0.100In	0.005In	[Device Para /Measurem Display /Current]
IG calc Cutoff Level	The calculated Earth Current shown in the Display or within the PC Software will be displayed as zero, if the calculated Earth Current falls below this Cutoff Level. This parameter has no impact on recorders.	0.0 - 0.100In	0.005In	[Device Para /Measurem Display /Current]
I012 Cutoff Level	The Symmetrical Component shown in the Display or within the PC Software will be displayed as zero, if the Symmetrical Component falls below this Cutoff Level. This parameter has no impact on recorders.	0.0 - 0.100In	0.005In	[Device Para /Measurem Display /Current]

Blockings

The device provides a function for temporary and permanent blocking of the complete protection functionality or of single protection stages.

WARNING **Make absolutely sure that no illogical or even life-threatening blockings are allocated.**

Make sure that you do not carelessly deactivate protection functions which have to be available according to the protection concept.

Permanent Blocking

Switching ON or OFF the complete protection functionality
In module *»Protection«* the complete protection of the device can be switched on or off. Set the parameter *Function* to *»active«* or *»inactive«* in module *»Prot«*.

WARNING **Only if in module »Prot« the parameter *Function* is = *»active«*, the protection is activated; i.e. with *»Function«* = *»inactive«,* no protection function is operating. Then the device cannot protect any components.**

Switching modules ON or OFF
Each of the modules can be switched on or off (permanently). This is achieved when the parameter »*Function«* is set to »active« or »inactive« in the respective module.

Activating or deactivating the tripping command of a protection stage permanently
In each of the protection stages the tripping command to the CB can be permanently blocked. For this purpose the parameter *»TripCmd Blo«* has to be set to *»active«*.

Temporary Blocking

To block the complete protection of the device temporarily by a signal

In module *»Prot«* the complete protection of the device can be blocked temporarily by a signal. On condition that a module-external blocking is permitted *»ExBlo Fc=active«*. In addition to this, a related blocking signal from the »assignment list« must have been assigned. For the time the allocated blocking signal is active, the module is blocked.

WARNING **If the module *»Prot«* is blocked, the complete protection function does not work. As long as the blocking signal is active, the device cannot protect any components.**

To block a complete protection module temporarily by an active assignment

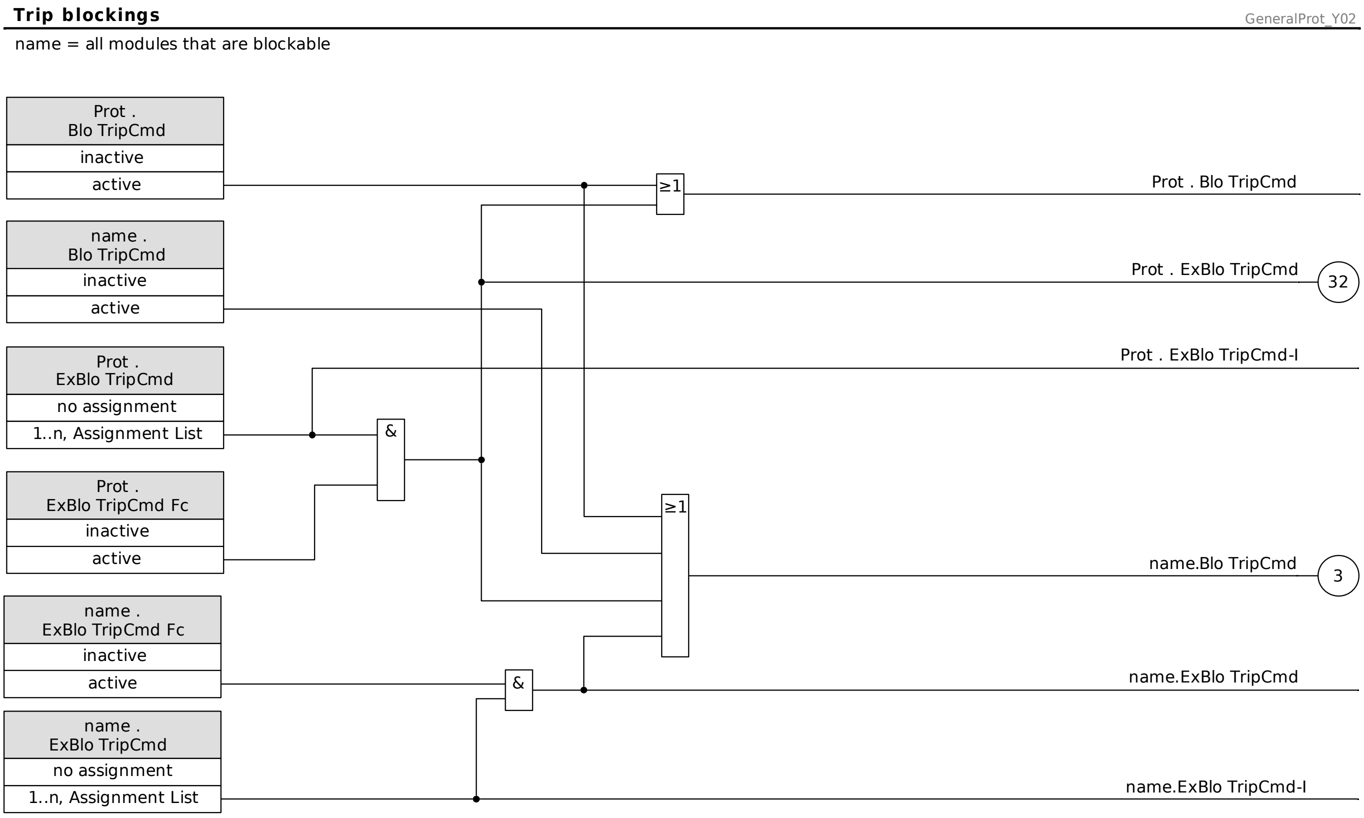
- In order to establish a temporary blockage of a protection module, the parameter *»ExBlo Fc«* of the module has to be set to *»active«*. This gives the permission: »This module can be blocked«.
- Within the general protection parameters a signal has to be additionally chosen from the »ASSIGNMENT LIST«. The blocking only becomes active when the assigned signal is active.

To block the tripping command of a protection stage temporarily by an active assignment.

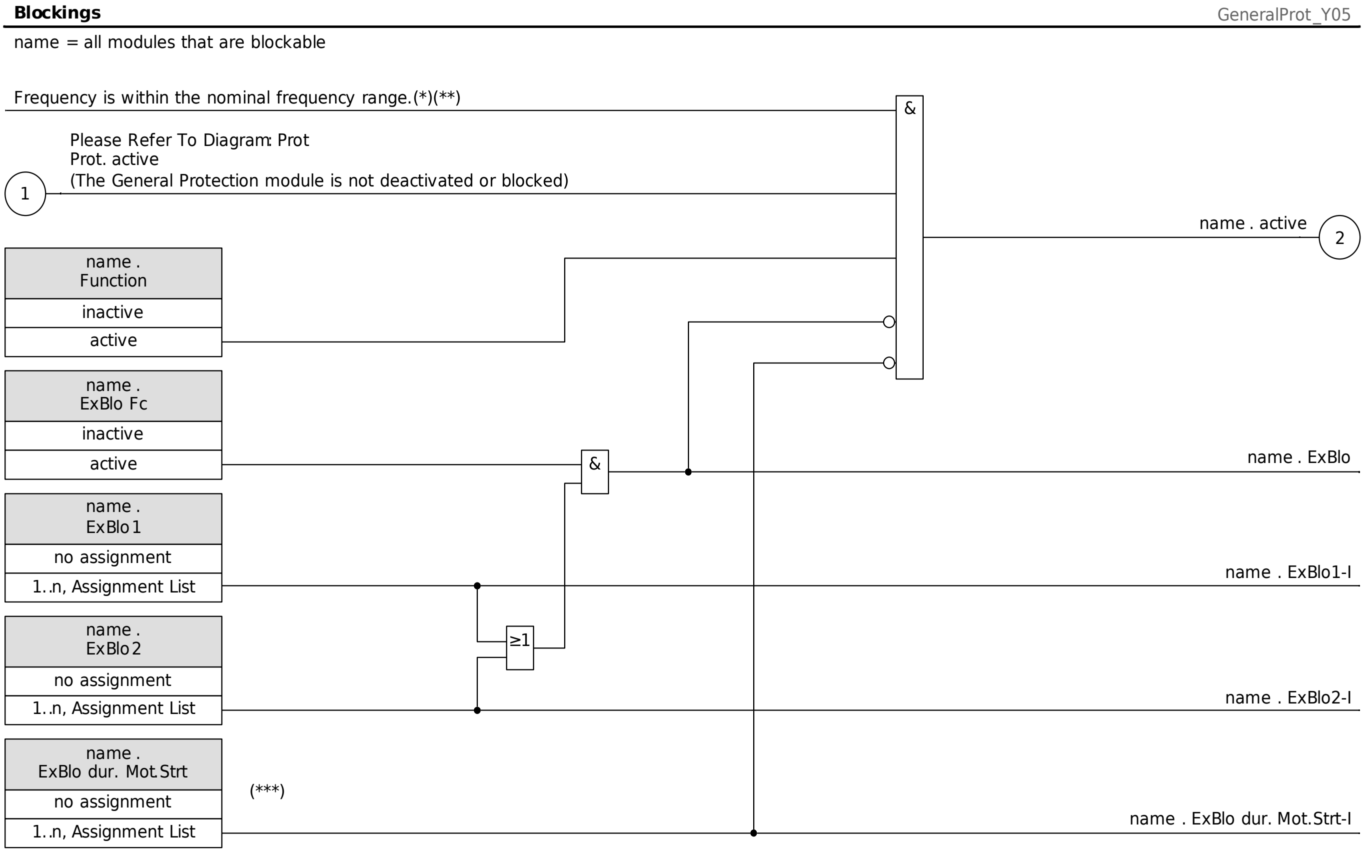
The tripping command of any of the protection modules can be blocked from external. In this case, external does not only mean from outside the device, but also from outside the module. Not only real external signals are permitted to be used as blocking signals, as for example, the state of a digital input, but you can also choose any other signal from the »assignment list«.

- In order to establish a temporary blockage of a protection stage, the parameter *»ExBlo TripCmd Fc«* of the module has to be set to *»active«*. This gives the permission: »The tripping command of this stage can be blocked«.
- Within the general protection parameters, a signal has to be chosen additionally and assigned to the parameter *»ExBlo«* from the »assignment list«. If the selected signal is activated, the temporary blockage becomes effective.

To Activate or Deactivate the Tripping Command of a Protection Module



Activate, Deactivate respectively Block Temporarily Protection Functions



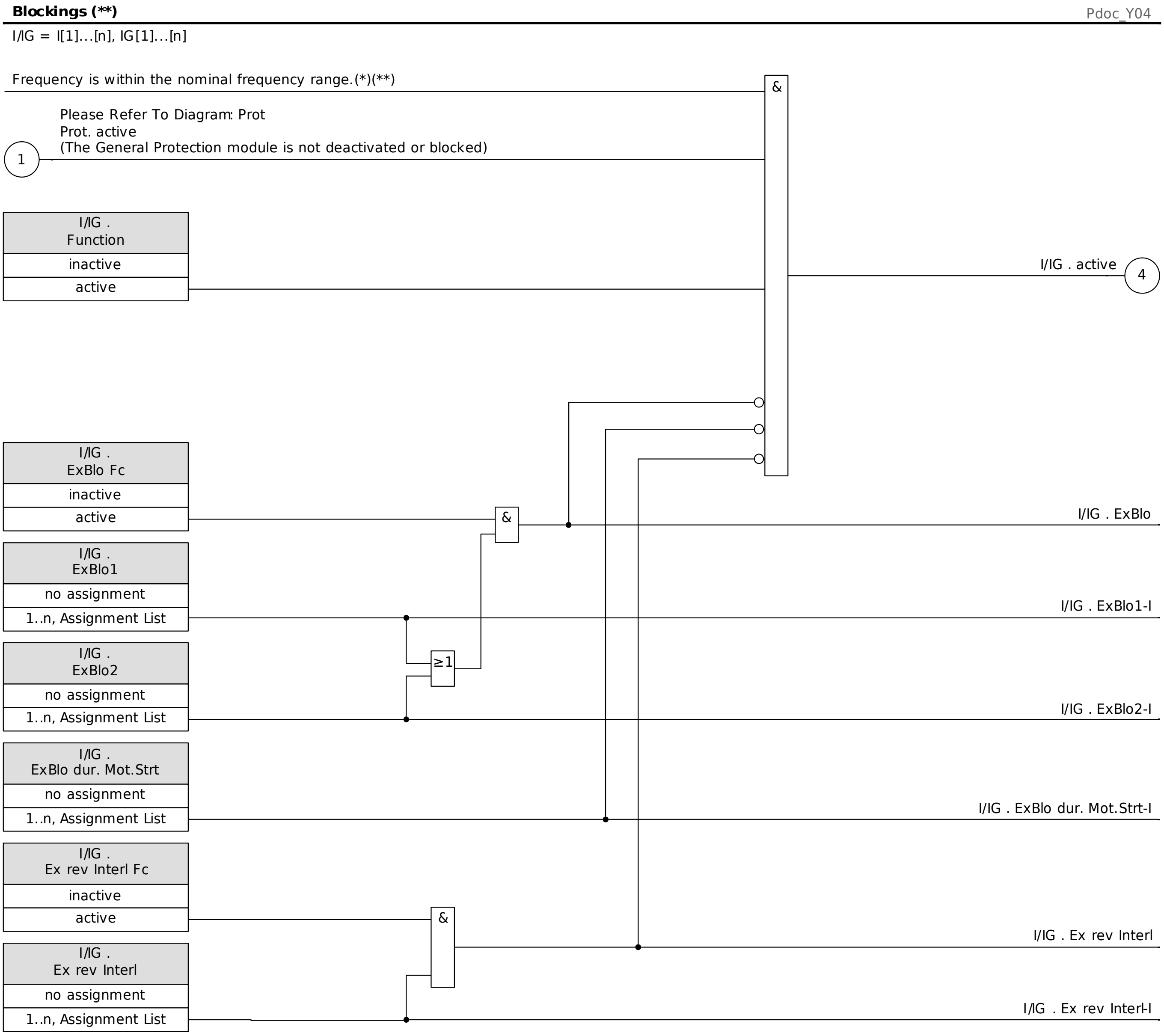
(*) All protective elements will be blocked that are using fundamental or harmonics measured values, if the frequency leaves the nominal frequency range. Protective elements that are using RMS values will remain active.

(**) This applies to devices that offer wide frequency range measurement only.

(***) Applies only to protective elements that are blocked during motor start.

Current protective functions cannot only be blocked permanently (»*function = inactive*«) or temporarily by any blocking signal from the »assignment list«, but also by *»reverse Interlocking«*.

All other protection functions can be activated, deactivated or blocked in the same manner.



(*) All protective elements will be blocked that are using fundamental or harmonics measured values, if the frequency leaves the nominal frequency range. Protective elements that are using RMS values will remain active.

(**) This applies to devices that offer wide frequency range measurement only.

Module: Protection (Prot)

Prot

The module »Module General Protection« (»Prot«) serves as outer frame for all other protection modules, i. e. they are all enclosed by this module.

WARNING **If in the »Prot« module the parameter [Protection Para / Global Prot Para / Prot] *»Function«* is set on "inactive" or in case the module is blocked, then no protective function of the device is effective.**

Blocking all Protective Elements Permanently

In order to allow (the principle use) of blocking the entire protection call up the menu [Protection/Para/Global Prot Para/Prot]:

- Set the parameter »*Function = inactive*«.

Blocking all Protective Elements Temporarily

In order to allow (the principle use) of blocking the entire protection call up the menu [Protection/Para/Global Prot Para/Prot]:

- Set the parameter »*ExBlo Fc = active*«;
- Choose an assignment for »*ExBlo1*«; and
- Optionally choose an assignment for »*ExBlo2*«.

If one of the signals becomes true, then the entire protection will be blocked as long as one of these signals are true.

Blocking all Trip Commands Permanently

In order to allow (the principle use) of blocking the entire protection call up the menu [Protection/Para/Global Prot Para/Prot]:

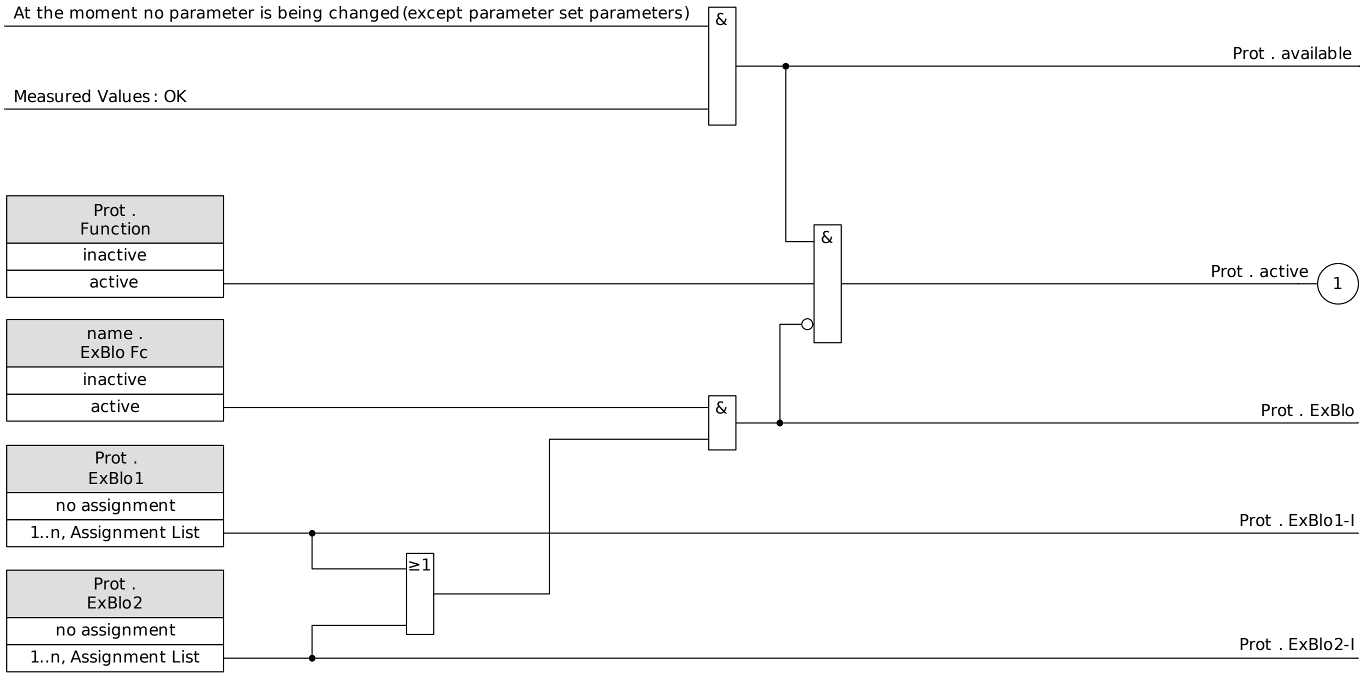
- Set the parameter »*Blo TripCmd = active*«.

Blocking all Trip Commands Temporarily

In order to allow (the principle use) of blocking the entire protection, call up the menu [Protection/Para/Global Prot Para/Prot]:

- Set the parameter »*ExBlo TripCmd Fc= active*«.
- Choose an assignment for »*ExBlo TripCmd*«. All Trip commands will be blocked temporarily if this assginment becomes true.

Prot – active GeneralProt_Y01



General Alarms and General Trips

Each protective element generates it´s own alarm and trip signals. All alarms and trip decision are passed on to the master module *»Prot«.*

If a protective element picks up, respectively has decided about a trip, two signals will be issued:

1. The module or the protection stage issues an alarm e.g. »I[1].ALARM« or »I[1].TRIP«.

2. The master module *»Prot«* collects/summarizes the signals and issues an alarm or a trip signal »PROT.ALARM« »PROT.TRIP«.

Further examples: »PROT.ALARM L1« is a collective signal (OR-connected) for all alarms issued by any of the protective elements concerning Phase L1.

»PROT.TRIP L1« is a collective signal (OR-connected) for all trips issued by any of the protective elements concerning Phase L1.

»PROT.ALARM« is the collective alarm signal OR-ed from all protection elements.»PROT.TRIP« is the collective alarm signal OR-ed from all protection elements.

The trip commands of a the protective elements have to be assigned within the Circuit Breaker Manager *CB Manager*. Only those trip decisions that are assigned within the *CB Manager* are isssued to the Circuit Breaker.

WARNING

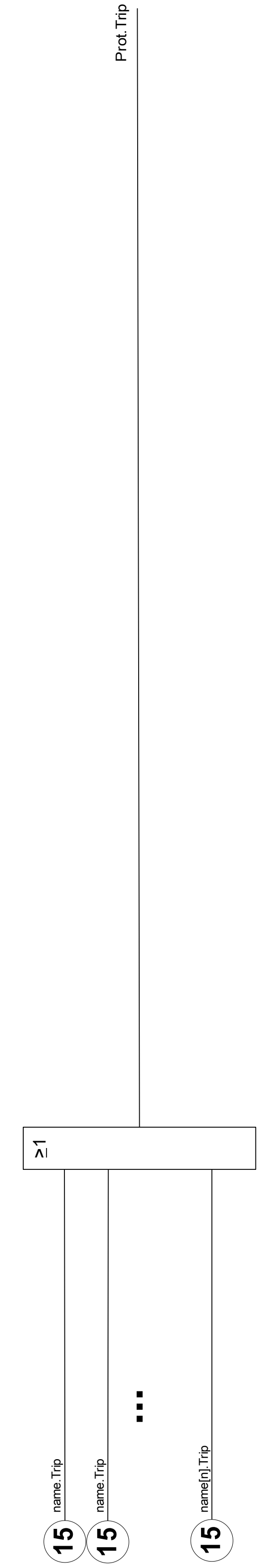
Caution: Trip commands that are not assigned within the Circuit Breaker Manager (CB Manager) are not issued to a circuit breaker.

The CB Manager issues the trip commands to a circuit breaker.

Assign within the Circuit Breaker Manager all trip commands that have to switch a circuit breaker.

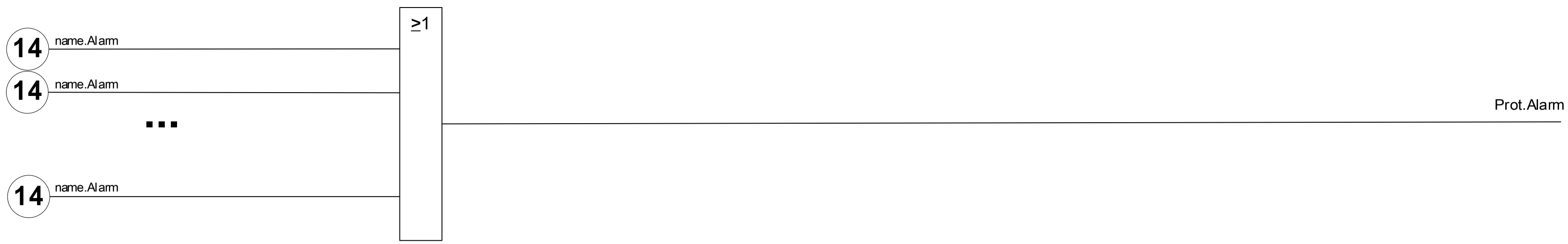
Prot.Trip

name = Each trip of an active, trip authorized protection module will lead to a general trip.



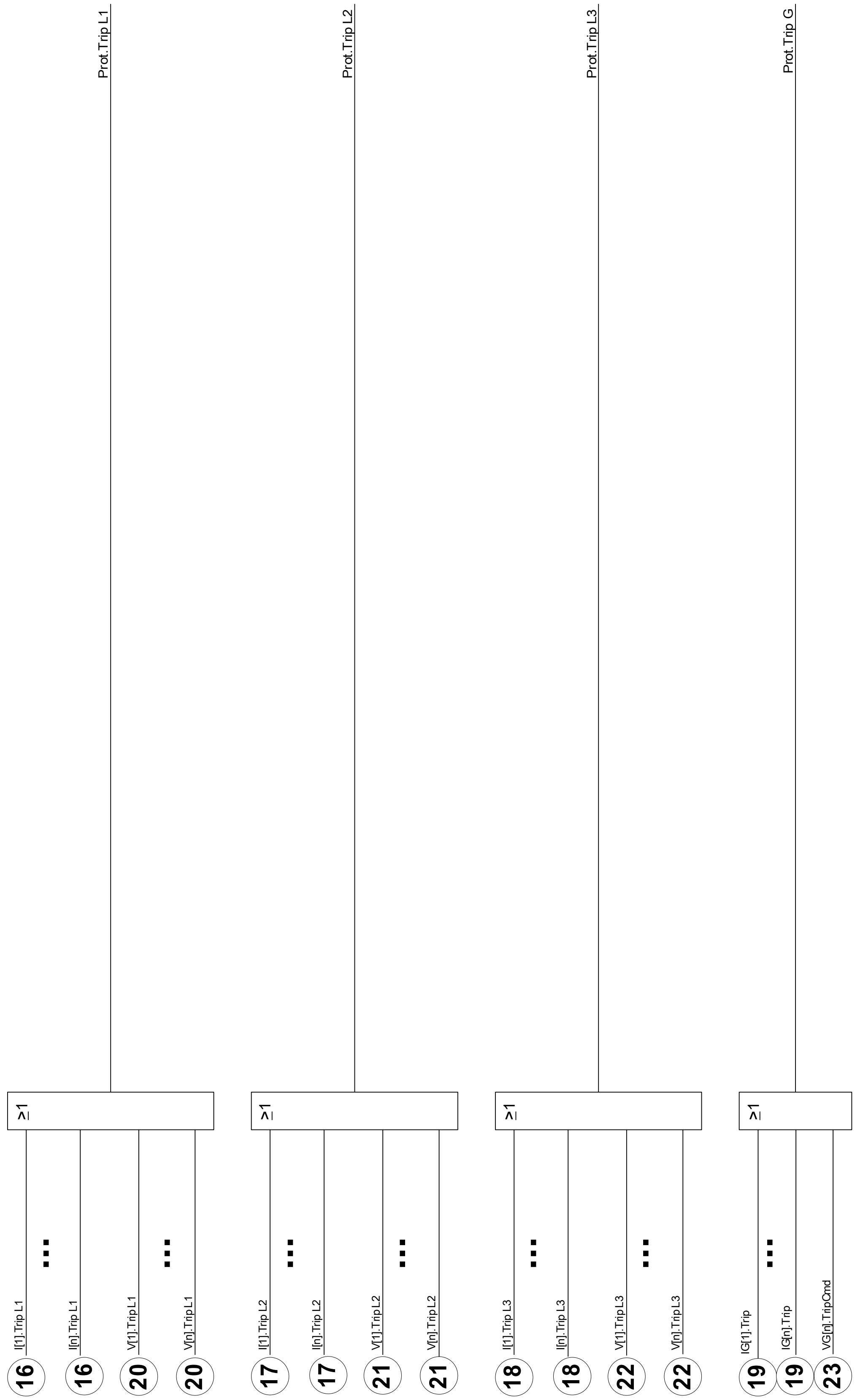
Prot.Alarm

name = Each alarm of a module (except from supervision modules but including CBF) will lead to a general alarm (collective alarm).



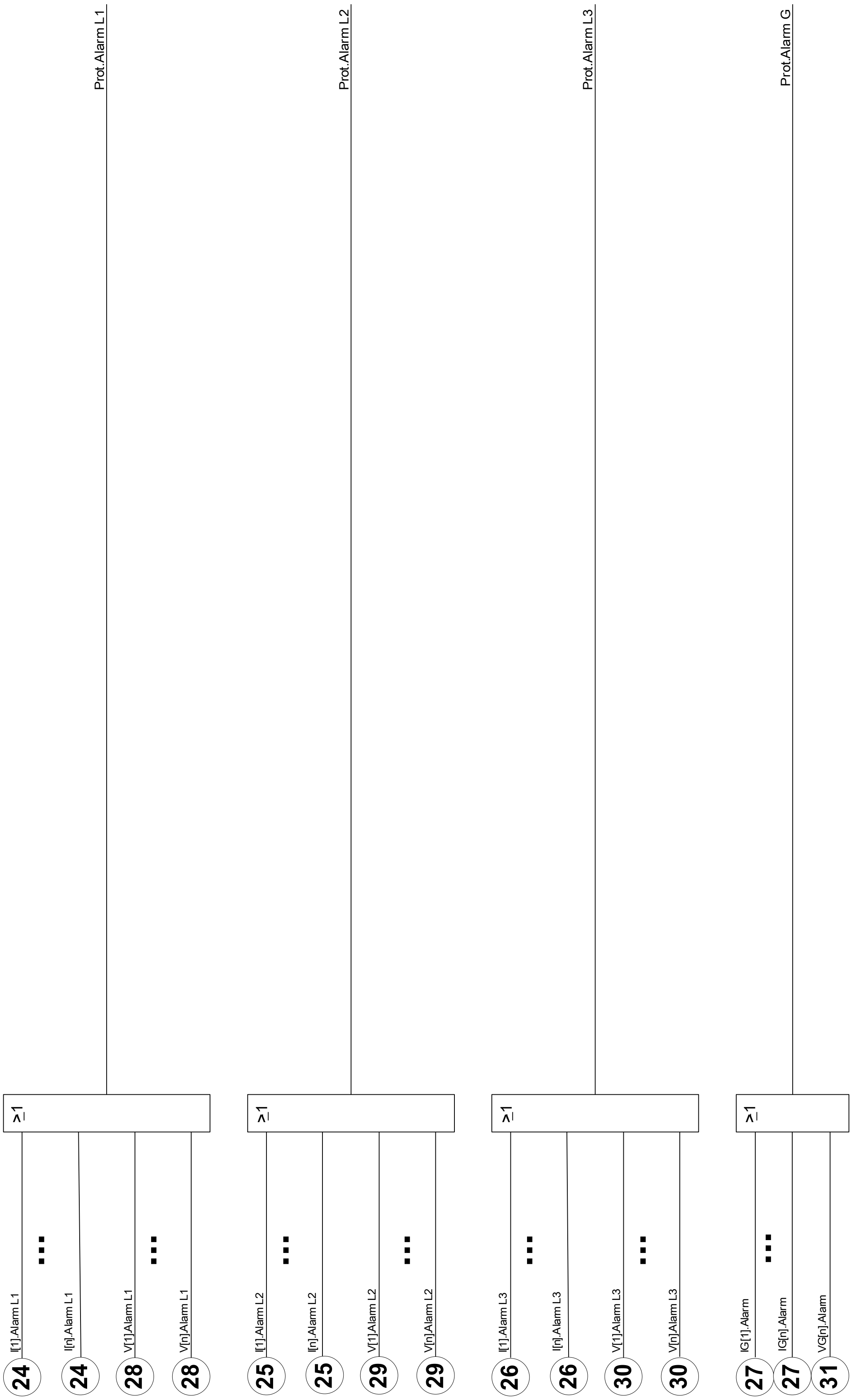
Prot.Trip

Each phase selective trip of a trip authorized module (I, IG, V, VX depending on the device type) will lead to a phase selective general trip.



Prot.Alarm

Each phase selective alarm of a module (I, IG, V, VX depending on the device type) will lead to a phase selective general alarm (collective alarm).



Direct Commands of the Protection Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Res FaultNo a GridFaultNo	Resetting of fault number and grid fault number.	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]

Global Protection Parameters of the Protection Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	active	[Protection Para /Global Prot Para /Prot]
ExBlo Fc	Activate (allow) the external blocking of the global protection functionality of the device.	inactive, active	inactive	[Protection Para /Global Prot Para /Prot]
ExBlo1	If external blocking of this module is activated (allowed), the global protection functionality of the device will be blocked if the state of the assigned signal becomes true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /Prot]
ExBlo2	If external blocking of this module is activated (allowed), the global protection functionality of the device will be blocked if the state of the assigned signal becomes true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /Prot]
Blo TripCmd	Permanent blocking of the Trip Command of the entire Protection.	inactive, active	inactive	[Protection Para /Global Prot Para /Prot]
ExBlo TripCmd Fc	Activate (allow) the external blocking of the trip command of the entire device.	inactive, active	inactive	[Protection Para /Global Prot Para /Prot]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ExBlo TripCmd	If external blocking of the tripping command is activated (allowed), the tripping command of the entire device will be blocked if the state of the assigned signal becomes true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /Prot]

Protection Module Input States

Name	*Description*	*Assignment via*
ExBlo1-I	Module input state: External blocking1	[Protection Para /Global Prot Para /Prot]
ExBlo2-I	Module input state: External blocking2	[Protection Para /Global Prot Para /Prot]
ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command	[Protection Para /Global Prot Para /Prot]

Protection Module Signals (Output States)

Signal	*Description*
available	Signal: Protection is available
active	Signal: active
ExBlo	Signal: External Blocking
Blo TripCmd	Signal: Trip Command blocked
ExBlo TripCmd	Signal: External Blocking of the Trip Command
Alarm L1	Signal: General-Alarm L1
Alarm L2	Signal: General-Alarm L2
Alarm L3	Signal: General-Alarm L3
Alarm G	Signal: General-Alarm - Earth fault
Alarm	Signal: General Alarm
Trip L1	Signal: General Trip L1
Trip L2	Signal: General Trip L2
Trip L3	Signal: General Trip L3
Trip G	Signal: General Trip Ground fault
Trip	Signal: General Trip
Res FaultNo a GridFaultNo	Signal: Resetting of fault number and grid fault number.

Protection Module Values

Parameter	*Description*
FaultNo	Fault number
No of GridFaults	Number of grid faults: A grid fault, e.g. a short circuit, might cause several faults with trip and autoreclosing, each fault being identified by an increased fault number. In this case, the grid fault number remains the same.
Trip	Initial reason of trip. It is transferred as an integer value in the MODBUS register 5004 and essentially corresponds to the “Trip” entry in the fault record, i. e. to the name of the protective module that tripped first. Look up the definition of these integer values (i. e. the mapping trip code number-->module name) in the “Cause of Trip” table within the SCADA documentation.

Switchgear/Breaker – Manager

WARNING WARNING Misconfiguration of the switchgear can result in death or serious injury.

Beside protection functions, protective relays more and more will take care about controlling switchgear, like circuit breakers, load break switches, disconnectors and ground connectors.

The Switchgear/Breaker-Manager of this protective device is designed to manage one switchgear.

The correct configuration is an indispensable precondition for the proper functioning of the protective device. This also is the case, when the switchgear is not controlled, but supervised only.

Single Line Diagram

The user can create and modify Single Lines (pages) by means of the *Page Editor*.
The Single Lines (Control Pages) have to be loaded into the protective device by means of *Smart view*.
For details on the creation, modification and upload of Single Lines (Control Pages) please refer to the manual "page_editor_uk.pdf" or contact the technical support. The manual can be accessed via the *Page Editor* help menu.

The single line diagram includes the graphically description of the switchgear and its designation (name) as well as its features (short circuit proof or not ...). For displaying in the devices software, the switchgears' designations (e. g. QA1, QA2, instead of SG[x]) will be taken from the single line diagram (configuration file).

The configuration file includes the single line diagram and the switchgear properties. Switchgear properties and single line diagram are coupled via the configuration file.

Switchgear Configuration

Wiring

At first the switchgears' positioning indicators have to be connected to the digital inputs of the protection device.

One of the position indicators (either the »Aux ON*«* or the »Aux OFF*«)* contact has to be connected necessarily. It is recommended to connect both contacts.

Thereafter the command outputs (relay outputs) have to be connected with the switchgear.

NOTICE

Please observe the following option: In the general settings of a circuit breaker, the ON/OFF commands of a protection element can be issued to the same output relays, where the other control commands are issued.
If the commands are issued to different relays output relays the amount of wiring increases.

Assignment of Position Indications

The position indication is needed by the device to get (evaluate) the information about the current status /position of the breaker. The switchgears' position is shown in the devices display. Each position change results in a change of the switchgear symbol.

NOTICE

For the detection of a switchgear's position always two separate Aux contacts are recommended! If only one Aux contact is used, no intermediate or disturbed positions can be detected.
A reduced transition supervision (time between issue of the command and position feedback indication of the switchgear) is also possible by one Aux contact.

In the menu [Control/Bkr/Pos Indicators wiring] the assignments for the position indications have to be set.

Detection of switchgear position with two Aux contacts – ***Aux ON and Aux OFF (recommended!)***

For detection of position the switchgear is provided with Aux contacts (Aux ON and Aux OFF). It is recommended to use both contacts to detect intermediate and disturbed positions too.

The protection device continuously supervises the status of the inputs *»Aux ON-I«* and *»Aux OFF-I«.*
These signals are validated based on the supervision timers »*t-Move ON«* and »*t-Move OFF«* validation functions.
As a result, the switchgear position will be detected by the following signals:

- Pos ON
- Pos OFF
- Pos Indeterm
- Pos Disturb.
- Pos (State=0,1,.2 or 3)

Supervision of the ON command

When an ON command is initiated, the »*t-Move ON«* timer will be started. While the timer is running, the »POS INDETERM« State will become true. If the command is executed and properly fed back from the switchgear before the timer has run down, »POS ON« will become true. Otherwise, if the timer has expired »POS DISTURB« will become true.

Supervision of the OFF command

When an OFF command is initiated, the »*t-Move OFF«* timer will be started. While the timer is running, the »POS INDETERM« State will become true. If the command is executed and properly fed back before the timer has run down, »POS OFF« will become true. Otherwise, if the timer has expired »POS DISTURB« will become true.

The following table shows how switchgear positions are validated:

States of the Digital Inputs		***Validated Switchgear Positions***				
Aux ON-I	*Aux OFF-I*	*POS ON*	*POS OFF*	*POS Indeterm*	*POS Disturb*	*POS State*
0	0	0	0	1 (while a Moving timer is running)	0 (while a Moving timer is running)	0 Intermediate
1	1	0	0	1 (while a Moving timer is running)	0 (while a Moving timer is running)	0 Intermediate
0	1	0	1	0	0	1 OFF
1	0	1	0	0	0	2 ON
0	0	0	0	0 (Moving timer elapsed)	1 (Moving timer elapsed)	3 Disturbed
1	1	0	0	0 (Moving timer elapsed)	1 (Moving timer elapsed)	3 Disturbed

Single Position Indication ***Aux ON or Aux OFF***

If the single pole indication is used, the »SI SINGLECONTACTIND« will become true.

The moving time supervision works only in one direction. If the Aux OFF signal is connected to the device, only the “OFF command” can be supervised and if the Aux ON signal is connected to the device, only the “ON command” can be supervised.

Single Position Indication – ***Aux ON***

If only the Aux ON signal is used for the Status Indication of an “ON command”, the switch command will also start the moving time, the position indication indicates an INTERMEDIATE position during this time interval. When the switchgear reaches the end position indicated by the signals »POS ON« and »CES SUCCESF« before the moving time has elapsed the signal Pos Indeterm disappears.

If the moving time elapsed before the switchgear has reached the end position, the switching operation was not successful and the Position Indication will change to POS Disturb and the signal Pos Indeterm disappears.

The following table shows how breaker positions are validated based on ***Aux ON****:*

States of the Digital Input		***Validated Switchgear Positions***				
Aux ON-I	*Aux OFF-I*	*POS ON*	*POS OFF*	*POS Indeterm*	*POS Disturb*	*POS State*
0	Not wired	0	0	1 (while t-Move ON is running)	0 (while t-Move ON is running)	0 Intermediate
0	Not wired	0	1	0	0	1 OFF
1	Not wired	1	0	0	0	2 ON

If there is no digital input assigned to the *»Aux On«* contact, the position indication will have the value 3 (disturbed).

*Single Position Indication – **Aux OFF***

If only the Aux OFF signal is used for the monitoring of the “OFF command”, the switch command will start the moving timer. The Position Indication will indicate an INTERMEDIATE position. When the the switchgear reaches its end position before the moving timer elapses, and »CES succesf« will be indicated. At the same time the signal »Pos Indeterm« disappears.
If the moving time elapsed before the switchgear has reached the OFF position, the switching operation was not successful and the Position Indication will change to »Pos Disturb« and the signal »Pos Indeterm« disappears.

*The following table shows how breaker positions are validated based on **Aux OFF**:*

States of the Digital Input		***Validated Switchgear Positions***				
Aux ON-I	*Aux OFF-I*	*POS ON*	*POS OFF*	*POS Indeterm*	*POS Disturb*	*POS State*
Not wired	0	0	0	1 (while t-Move OFF is running)	0 (while t-Move OFF is running)	0 Intermediate
Not wired	1	0	1	0	0	1 OFF
Not wired	0	1	0	0	0	2 ON

If there is no digital input assigned to the *»Aux OFF«* contact, the position indication will have the value 3 (disturbed).

Setting of Supervision Times

In the menu [Control/Bkr/General Settings] the supervision times of the individual switchgear have to be set. Dependent on the type of switchgear it can be necessary to set further parameters.

Interlockings

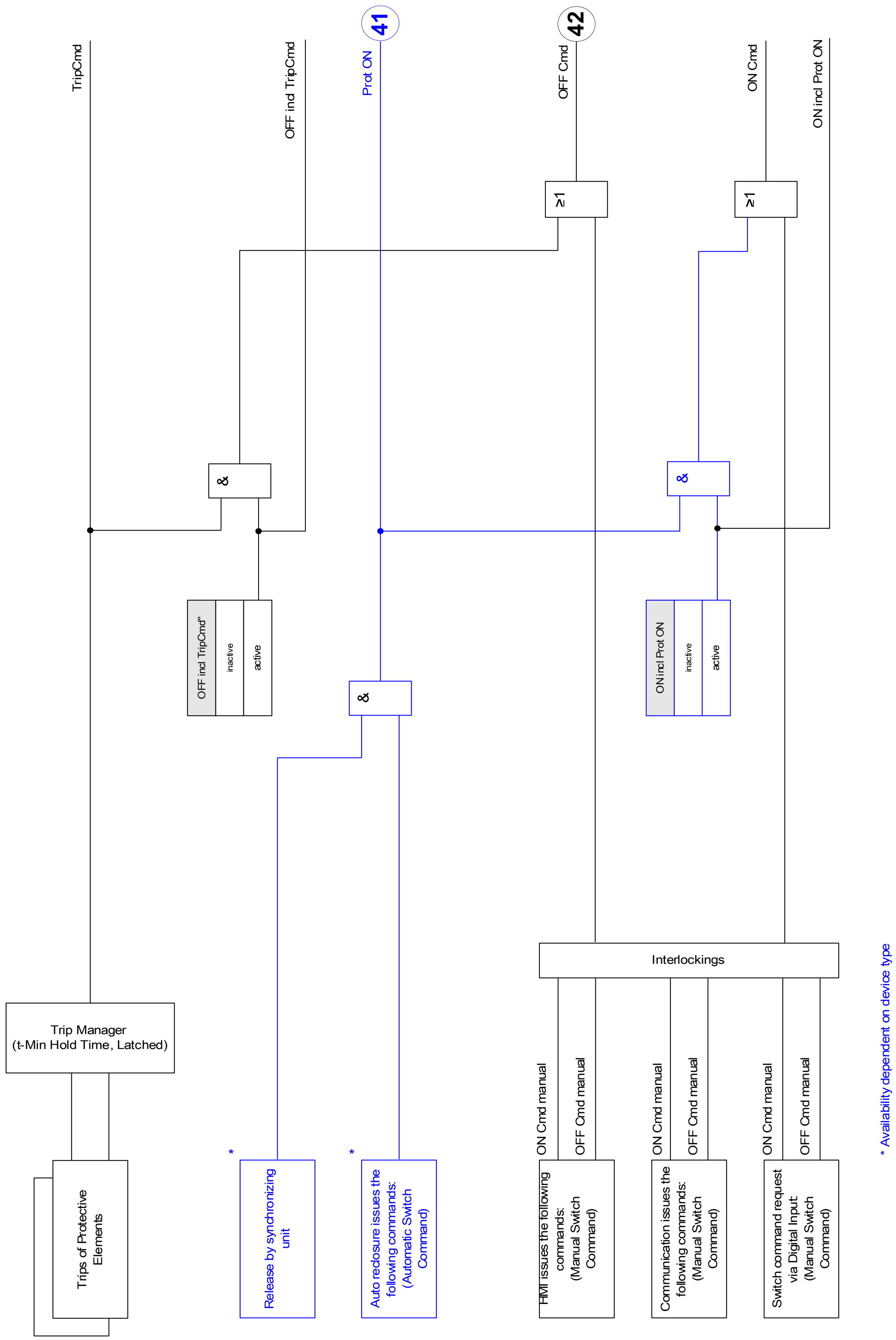
To avoid faulty operations, interlockings have to be provided. This can be realised mechanically, or electrically within the menu [Control/Bkr/General Settings] .

For a controllable switchgear up to three interlockings can be assigned in both switching directions (ON/OFF). These interlockings prevent switching in the corresponding direction.

The protection OFF command and the reclosing command of the AR* module are always executed without interlockings. For the case, that a protection OFF command must not be issued, this must be blocked separately.

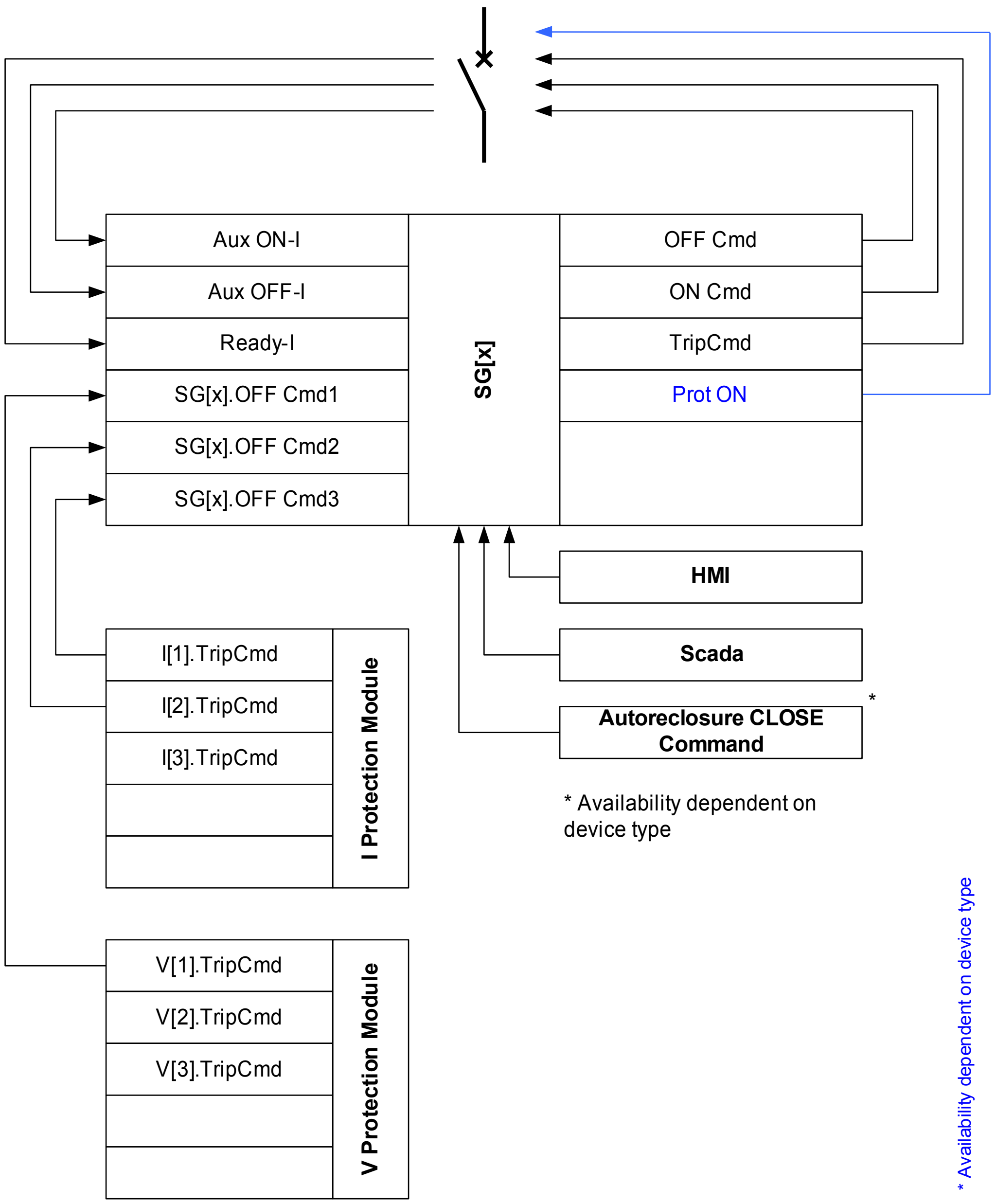
Further interlockings can be realised by means of the Logic module.

*=availability depends on ordered device.


TripCmd
OFF incl TripCmd
Prot ON
41
OFF Cmd
42
ON Cmd
ON incl Prot ON
≥1
≥1
&
&
&
OFF incl TripCmd"
inactive
active
ON incl Prot ON
inactive
active
Interlockings
Trip Manager
(t-Min Hold Time, Latched)
Trips of Protective Elements
*
Release by synchronizing unit
*
Auto reclosure issues the following commands: (Automatic Switch Command)
ON Cmd manual
OFF Cmd manual
HMI issues the following commands: (Manual Switch Command)
ON Cmd manual
OFF Cmd manual
Communication issues the following commands: (Manual Switch Command)
ON Cmd manual
OFF Cmd manual
Switch command request via Digital Input: (Manual Switch Command)
* Availability dependent on device type

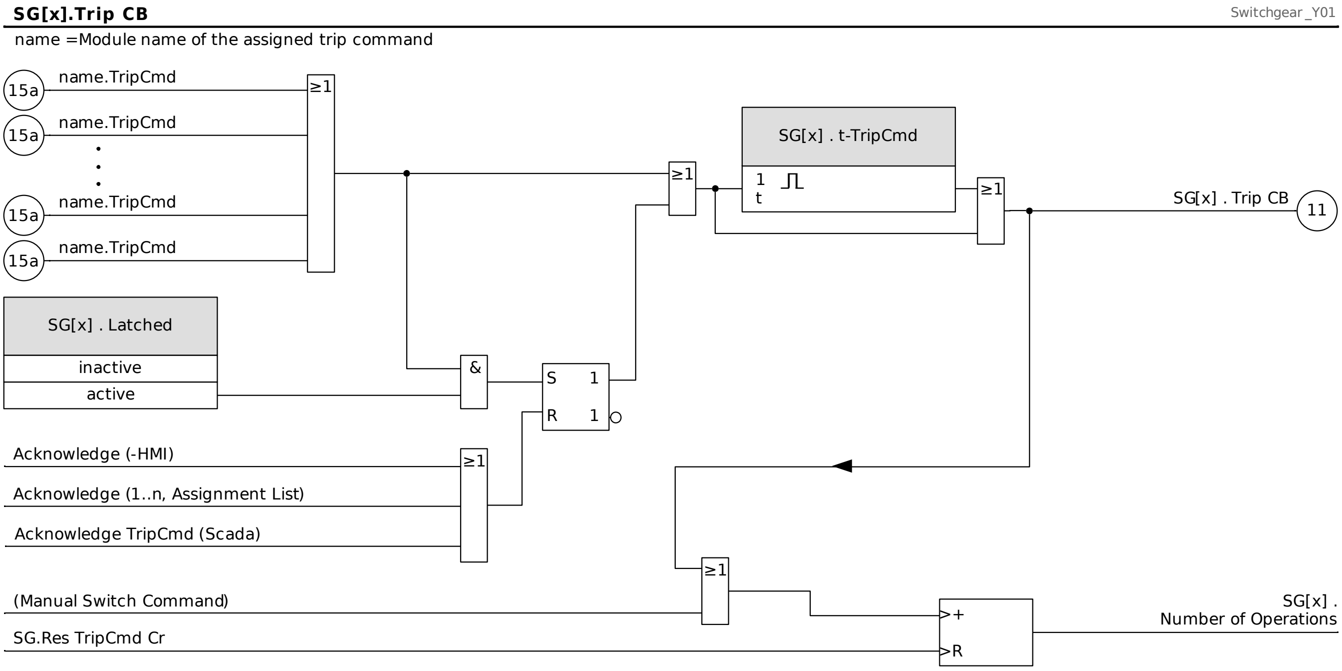
Trip Manager – Assignment of commands

The trip commands of the protection elements have to be assigned within menu [Control/Bkr/Trip Manager] to the switchgear (presumed, that the switchgear is make/break capable) .
In the Trip Manger all tripping commands are combined by an "OR" logic. The actual tripping command to the switchgear is exclusively given by the Trip Manager. This means, that only tripping commands which are assigned in the Trip Manager lead to an operation of the switchgear. In addition to that, the User can set the minimum hold time of the tripping command within this module and define whether the tripping command is latched or not.



The exact name of the Switchgear is defined in the Single Line file.

↓



Ex ON/OFF

If the switchgear should be opened or closed by an external signal, the User can assign one signal that will trigger the ON and one signal that will trigger the OFF command (e.g. digital inputs or output signals of the Logics) within menu [Control/Bkr/Ex ON/OFF Cmd] . An OFF command has priority. ON commands are slope oriented, OFF commands are level oriented

Synchronised Switching*

*=availability depends on ordered device type

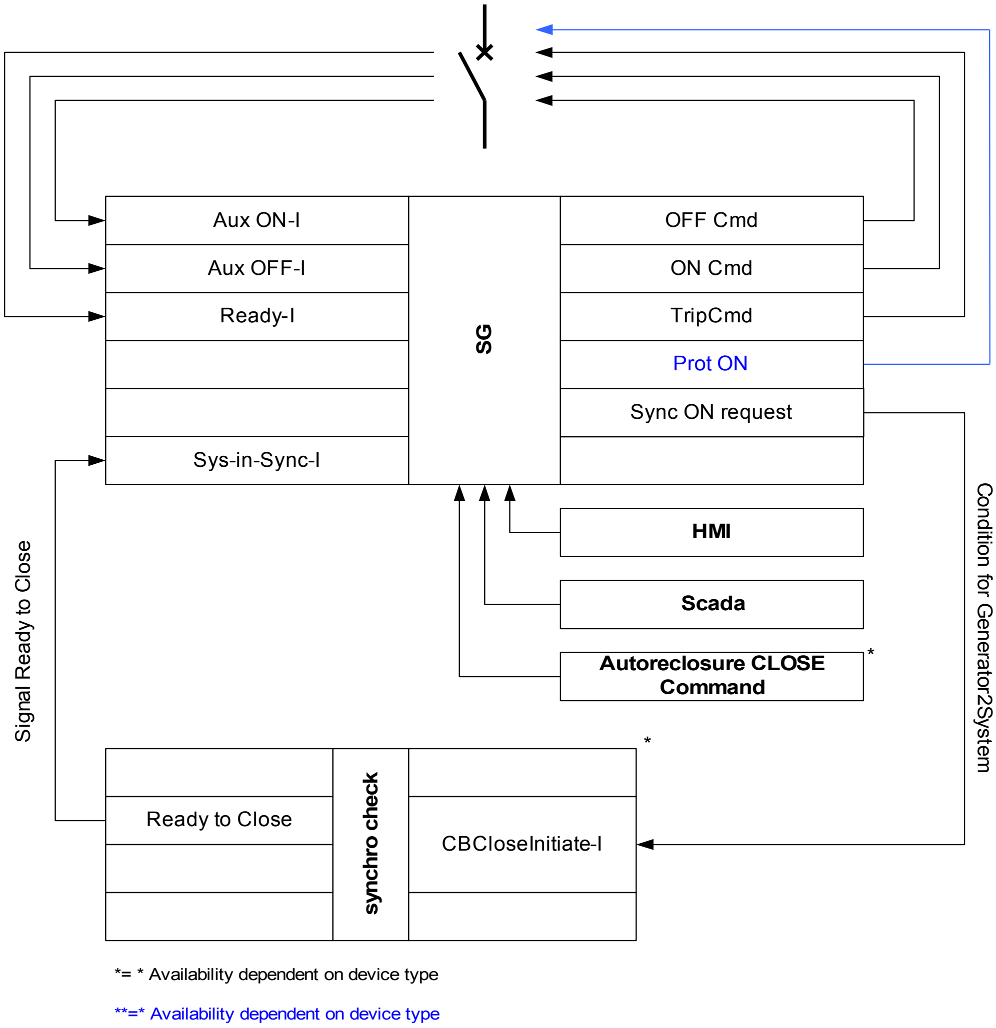
Before a switchgear may connect two mains sections, synchronism of these sections must be assured.

In the submenu [Synchronous Switching] the parameter »Synchronism« defines which signal indicates synchronism.

If the synchronism condition shall be evaluated by the internal Synch-Check module the signal *»Sync. Ready to Close«* (release by synch-check module) has to be assigned. Alternatively a digital input or a logic output can be assigned.

In the synchronisation mode “Generator-to-System” additionally the synchronism request has to be assigned to the Sync-check function in the menu [Protection Para\Global Prot Para\Sync].

If a synchronism signal is assigned, the switching command will only be executed, when the synchronism signal will become true within the maximum supervision time »*t-MaxSyncSuperv«.* This supervision time will be started with the issued ON command. If no synchronism signal has been assigned, the synchronism release is permanently.



Switching Authority

For the Switching Authority [Control\General Settings], the following general settings are possible:

NONE:	No control function;
LOCAL:	Control only via push buttons at the panel;
REMOTE:	Control only via SCADA, digital inputs, or internal signals; and
LOCAL&REMOTE:	Control via push buttons, SCADA, digital inputs, or internal signals.

Non interlocked Switching

For test purposes, during commissioning and temporarily operations, interlockings can be disabled.

WARNING **WARNING: Non interlocked Switching can lead to serious injuries or death!**

For non interlocked switching the menü [Control\General Settings] provides the following options:

- Non interlocked switching for one single command
- Permanent
- Non interlocked switching for a certain time
- Non interlocked switching, activated by an assigned signal

The set time for non interlocked switching applies also for the „single Operation“ mode.

Manual Manipulation of the Switchgear Position

In case of faulty position indication contacts (Aux contacts) or broken wires, the position indication resulted from the assigned signals can be manipulated (overwritten) manually, to keep the ability to switch the affected switchgear. A manipulated switchgearposition will be indicated on the display by an exclamation mark “!” beside the switchgear symbol.

WARNING **WARNING: Manipulation of the Switchgear Position can lead to serious injuries or death!**

Double Operation Locking

All control commands to any switchgear in a bay have to be processed sequentially. During a running control command no other command will be handled.

Switch Direction Control

Switching command are validated before execution. When the switchgear is already in the desired position, the switch command will not be issued again. An opened circuit breaker cannot be opened again. This also applies for switching command at the HMI or via SCADA.

Anti Pumping

By pressing the ON command softkey only a single switching ON impulse will be issued independent, how low the softkey is actuated. The switchgear will close only once per close command.

Counters of the Command Excecution Supervision

Parameter	*Description*
CES SAuthority	Command Execution Supervision: Number of rejected Commands because of missing switching authority.
CES DoubleOperating	Command Execution Supervision: Number of rejected Commands because a second switch command is in conflict with a pending one.
CES No. of rej. Com	Command Execution Supervision: Number of rejected Commands because Locked by ParaSystem

Switchgear Wear

NOTICE **NOTICE:** Current related functions of the swichtgear wear element (e.g. breaker wear curve) are available in devices only, that offer minimum one current measurement (card).

Switchgear Wear Features

The sum of the accumulated interrupted currents.

A »SGwear Slow Switchgear« might indicate malfunction at an early stage.

The protective relay will calculate the »SG OPEN Capacity*«* continuously. 100% means, that switchgear maintenance is mandatory now.

The protective relay will make a alarm decision based on the curve that the user provides.

The relay will monitor the frequency of ON/OFF cycles. The User can set thresholds for the maximum allowed sum of interrupt currents and the maximum allowed sum of interrupt currents per hour. By means of this alarm, excessive switchgear operations can be detected at an early stage.

Slow Switchgear Alarm

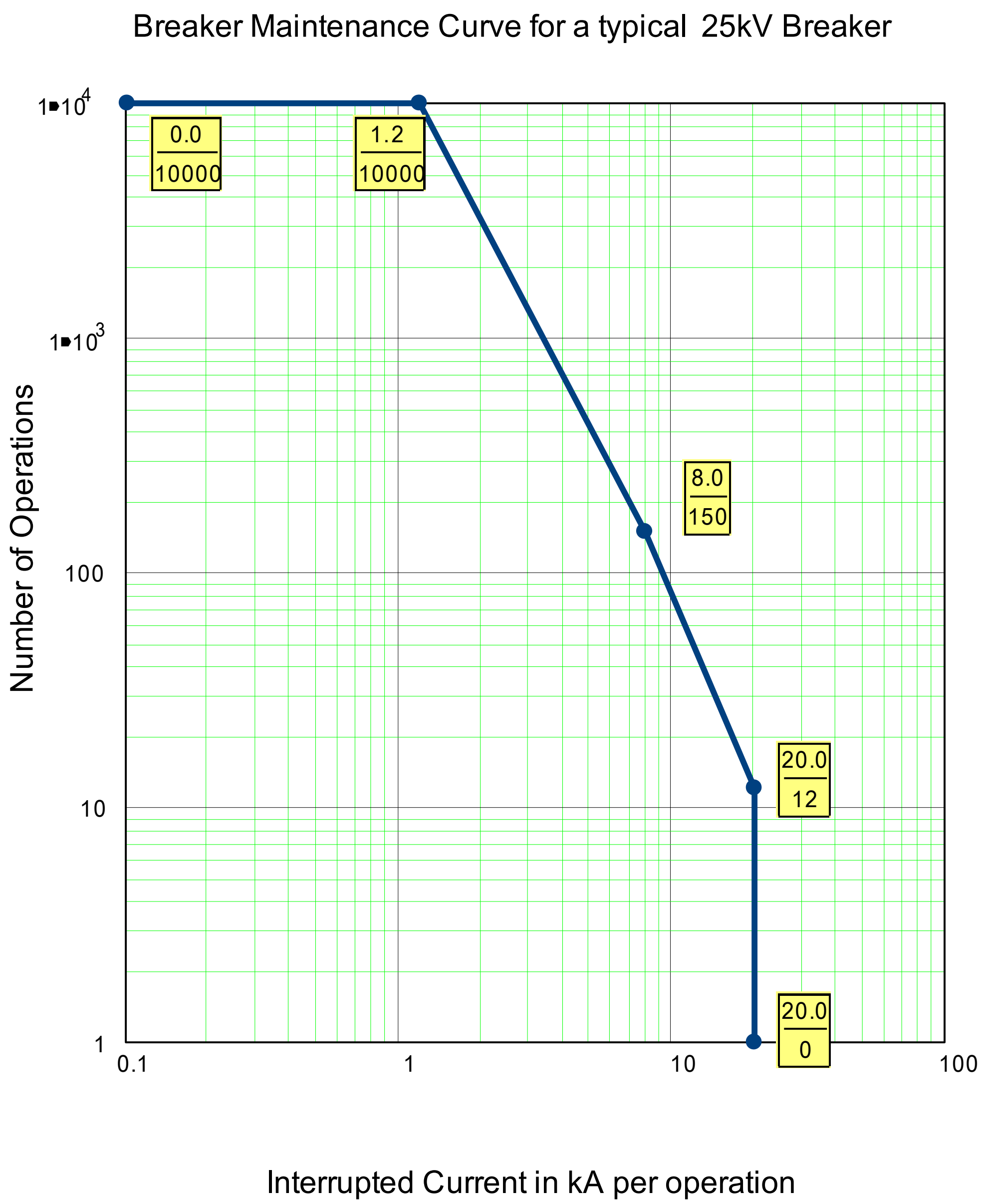
An increase of the close or opening time of the switchgear is an indication for the maintenance need. If the measured time exceeds the time »*t-Move OFF«* or »*t-Move ON«,* the signal »SGwear Slow Switchgear« will be activated.

Switchgear Wear Curve

In order to keep the switchgear in good working condition, the switchgear needs to be monitored. The switchgear health (operation life) depends above all on:

- The number of CLOSE/OPEN cycles.
- The amplitudes of the interrupting currents.
- The frequency that the switchgear operates (Operations per hour).

The User has to maintain the switchgear accordingly to the maintenance schedule that is to be provided by the manufacturer (switchgear operation statistics). By means of up to ten points that the user can replicate the switchgear wear curve within menu [Control/SG/SG[x]/SGW] . Each point has two settings: the interrupt current in kilo amperes and the allowed operation counts. No matter how many points are used, the operation counts the last point as zero. The protective relay will interpolate the allowed operations based on the switchgear wear curve. When the interrupted current is greater than the interrupt current at the last point, the protective relay will assume zero operation counts.



Global Protection Parameters of the Breaker Wear Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Operations Alarm	Service Alarm, too many Operations	1 - 100000	9999	[Control /SG /SG[1] /SG Wear]
Isum Intr Alarm	Alarm, the Sum (Limit) of interrupting currents has been exceeded.	0.00 - 2000.00kA	100.00kA	[Control /SG /SG[1] /SG Wear]
Isum Intr ph Alm	Alarm, the per hour Sum (Limit) of interrupting currents has been exceeded.	0.00 - 2000.00kA	100.00kA	[Control /SG /SG[1] /SG Wear]
SGwear Curve Fc	The Circuit Breaker (load-break switch) Wear Curve defines the maximum allowed CLOSE/OPEN cycles depending on the brake currents. If the circuit breaker maintenance curve is exceeded, an alarm will be issued. The breaker maintenance curve is to be taken from the technical data sheet of the breaker manufactor. By means of the available points this curve is to be replicated.	inactive, active	inactive	[Control /SG /SG[1] /SG Wear]
WearLevel Alarm	Threshold for the Alarm Only available if:SGwear Curve Fc = active	0.00 - 100.00%	80.00%	[Control /SG /SG[1] /SG Wear]
WearLevel Lockout	Threshold for the Lockout Level Only available if:SGwear Curve Fc = active	0.00 - 100.00%	95.00%	[Control /SG /SG[1] /SG Wear]
Current1	Interrupted Current Level #1 Only available if:SGwear Curve Fc = active	0.00 - 2000.00kA	0.00kA	[Control /SG /SG[1] /SG Wear]
Count1	Open Counts Allowed #1 Only available if:SGwear Curve Fc = active	1 - 32000	10000	[Control /SG /SG[1] /SG Wear]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Current2	Interrupted Current Level #2 Only available if:SGwear Curve Fc = active	0.00 - 2000.00kA	1.20kA	[Control /SG /SG[1] /SG Wear]
Count2	Open Counts Allowed #2 Only available if:SGwear Curve Fc = active	1 - 32000	10000	[Control /SG /SG[1] /SG Wear]
Current3	Interrupted Current Level #3 Only available if:SGwear Curve Fc = active	0.00 - 2000.00kA	8.00kA	[Control /SG /SG[1] /SG Wear]
Count3	Open Counts Allowed #3 Only available if:SGwear Curve Fc = active	1 - 32000	150	[Control /SG /SG[1] /SG Wear]
Current4	Interrupted Current Level #4 Only available if:SGwear Curve Fc = active	0.00 - 2000.00kA	20.00kA	[Control /SG /SG[1] /SG Wear]
Count4	Open Counts Allowed #4 Only available if:SGwear Curve Fc = active	1 - 32000	12	[Control /SG /SG[1] /SG Wear]
Current5	Interrupted Current Level #5 Only available if:SGwear Curve Fc = active	0.00 - 2000.00kA	20.00kA	[Control /SG /SG[1] /SG Wear]
Count5	Open Counts Allowed #5 Only available if:SGwear Curve Fc = active	1 - 32000	1	[Control /SG /SG[1] /SG Wear]
Current6	Interrupted Current Level #6 Only available if:SGwear Curve Fc = active	0.00 - 2000.00kA	20.00kA	[Control /SG /SG[1] /SG Wear]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Count6	Open Counts Allowed #6 Only available if:SGwear Curve Fc = active	1 - 32000	1	[Control /SG /SG[1] /SG Wear]
Current7	Interrupted Current Level #7 Only available if:SGwear Curve Fc = active	0.00 - 2000.00kA	20.00kA	[Control /SG /SG[1] /SG Wear]
Count7	Open Counts Allowed #7 Only available if:SGwear Curve Fc = active	1 - 32000	1	[Control /SG /SG[1] /SG Wear]
Current8	Interrupted Current Level #8 Only available if:SGwear Curve Fc = active	0.00 - 2000.00kA	20.00kA	[Control /SG /SG[1] /SG Wear]
Count8	Open Counts Allowed #8 Only available if:SGwear Curve Fc = active	1 - 32000	1	[Control /SG /SG[1] /SG Wear]
Current9	Interrupted Current Level #9 Only available if:SGwear Curve Fc = active	0.00 - 2000.00kA	20.00kA	[Control /SG /SG[1] /SG Wear]
Count9	Open Counts Allowed #9 Only available if:SGwear Curve Fc = active	1 - 32000	1	[Control /SG /SG[1] /SG Wear]
Current10	Interrupted Current Level #10 Only available if:SGwear Curve Fc = active	0.00 - 2000.00kA	20.00kA	[Control /SG /SG[1] /SG Wear]
Count10	Open Counts Allowed #10 Only available if:SGwear Curve Fc = active	1 - 32000	1	[Control /SG /SG[1] /SG Wear]

Breaker Wear Signals (Output States)

Signal	*Description*
Operations Alarm	Signal: Service Alarm, too many Operations
Isum Intr trip: IL1	Signal: Maximum permissible Summation of the interrupting (tripping) currents exceeded: IL1
Isum Intr trip: IL2	Signal: Maximum permissible Summation of the interrupting (tripping) currents exceeded: IL2
Isum Intr trip: IL3	Signal: Maximum permissible Summation of the interrupting (tripping) currents exceeded: IL3
Isum Intr trip	Signal: Maximum permissible Summation of the interrupting (tripping) currents exceeded in at least one phase.
Res TripCmd Cr	Signal: Resetting of the Counter: total number of trip commands
Res Sum trip	Signal: Reset summation of the tripping currents
WearLevel Alarm	Signal: Threshold for the Alarm
WearLevel Lockout	Signal: Threshold for the Lockout Level
Res CB OPEN capacity	Signal: Reset of the wear maintenance curve (i. e. of the counter for the Circuit Breaker OPEN capacity.
Isum Intr ph Alm	Signal: Alarm, the per hour Sum (Limit) of interrupting currents has been exceeded.
Res Isum Intr ph Alm	Signal: Reset of the Alarm, "the per hour Sum (Limit) of interrupting currents has been exceeded".

Breaker Wear Counter Values

Value	*Description*	*Default*	*Size*	*Menu path*
TripCmd Cr	Counter: Total number of trips of the switchgear (circuit breaker, load break switch...). Resettable with Total or All.	0	0 - 200000	[Operation /Count and RevData /Control /SG[1]]

Breaker Wear Values

Value	*Description*	*Default*	*Size*	*Menu path*
Sum trip IL1	Summation of the tripping currents phase	0.00A	0.00 - 1000.00A	[Operation /Count and RevData /Control /SG[1]]
Sum trip IL2	Summation of the tripping currents phase	0.00A	0.00 - 1000.00A	[Operation /Count and RevData /Control /SG[1]]

Value	*Description*	*Default*	*Size*	*Menu path*
Sum trip IL3	Summation of the tripping currents phase	0.00A	0.00 - 1000.00A	[Operation /Count and RevData /Control /SG[1]]
Isum Intr per hour	Sum per hour of interrupting currents.	0.00kA	0.00 - 1000.00kA	[Operation /Count and RevData /Control /SG[1]]
CB OPEN capacity	Used capacity of the circuit breaker. (100% means that the circuit breaker has to be maintained.)	0.0%	0.0 - 100.0%	[Operation /Count and RevData /Control /SG[1]]

Direct Commands of the Breaker Wear Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Res TripCmd Cr	Resetting of the Counter: total number of trip commands	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]
Res Sum trip	Reset summation of the tripping currents	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]
Res Isum Intr per hour	Reset of the Sum per hour of interrupting currents.	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]
Res CB OPEN capacity	Reset the CB OPEN capacity. (Remark: A »CB OPEN capacity« value of 100% means that the circuit breaker has to be maintained.)	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]

Control Parameters

Ctrl

Direct Commands of the Control Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Switching Authority	Switching Authority	None, Local, Remote, Local and Remote	Local	[Control /General Settings]
NonInterl	DC for Non-Interlocking	inactive, active	inactive	[Control /General Settings]

Global Protection Parameters of the Control Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Res NonIL	Resetmode Non-Interlocking	single Operation, timeout, permanent	single Operation	[Control /General Settings]
Timeout NonIL	Timeout Non-Interlocking Only available if: Res NonIL<>permanent	2 - 3600s	60s	[Control /General Settings]
NonIL Assign	Assignment Non-Interlocking	1..n, Assignment List	-.-	[Control /General Settings]

Control Moduel Input States

Name	*Description*	*Assignment via*
NonInterl-I	Non-Interlocking	[Control /General Settings]

Signals of the Control Module

Signal	*Description*
Local	Switching Authority: Local
Remote	Switching Authority: Remote

Signal	*Description*
NonInterl	Non-Interlocking is active
SG Indeterm	Minimum one Switchgear is moving (Position cannot be determined).
SG Disturb	Minimum one Switchgear is disturbed.

Synchronization inputs

Parameter	*Description*
-.-	No assignment

Assignable Trip Commands (Trip Manager)

Name	*Description*
-.-	No assignment
MStart.TripCmd	Signal: Trip Command
I[1].TripCmd	Signal: Trip Command
I[2].TripCmd	Signal: Trip Command
I[3].TripCmd	Signal: Trip Command
I[4].TripCmd	Signal: Trip Command
I[5].TripCmd	Signal: Trip Command
I[6].TripCmd	Signal: Trip Command
IG[1].TripCmd	Signal: Trip Command
IG[2].TripCmd	Signal: Trip Command
IG[3].TripCmd	Signal: Trip Command
IG[4].TripCmd	Signal: Trip Command
ThR.TripCmd	Signal: Trip Command
Jam[1].TripCmd	Signal: Trip Command
Jam[2].TripCmd	Signal: Trip Command
I<[1].TripCmd	Signal: Trip Command
I<[2].TripCmd	Signal: Trip Command
I<[3].TripCmd	Signal: Trip Command
I2>[1].TripCmd	Signal: Trip Command
I2>[2].TripCmd	Signal: Trip Command
ExP[1].TripCmd	Signal: Trip Command
ExP[2].TripCmd	Signal: Trip Command
ExP[3].TripCmd	Signal: Trip Command
ExP[4].TripCmd	Signal: Trip Command
RTD.TripCmd	Signal: Trip Command

Controlled Circuit Breaker

SG[1]

Direct Commands of a Controlled Circuit Breaker

Parameter	Description	Setting range	Default	Menu path
Manipulate Position	WARNING! Fake Position - Manual Position Manipulation	inactive, Pos OFF, Pos ON	inactive	[Control /SG /SG[1] /General Settings]
Res SGwear Sl SG	Resetting the slow Switchgear Alarm	inactive, active	inactive	[Operation /Reset/Acknowledge /Reset]
Ack TripCmd	Acknowledge Trip Command	inactive, active	inactive	[Operation /Reset/Acknowledge /Acknowledge]

Global Protection Parameters of a Controlled Circuit Breaker

Parameter	Description	Setting range	Default	Menu path
Aux ON	The CB is in ON-position if the state of the assigned signal is true (52a).	1..n, DI-LogicList	-.-	[Control /SG /SG[1] /Pos Indicatrs Wirng]
Aux OFF	The CB is in OFF-position if the state of the assigned signal is true (52b).	1..n, DI-LogicList	-.-	[Control /SG /SG[1] /Pos Indicatrs Wirng]
Ready	Circuit breaker is ready for operation if the state of the assigned signal is true. This digital input can be used by some protective elements (if they are available within the device) like Auto Reclosure (AR), e.g. as a trigger signal.	1..n, DI-LogicList	-.-	[Control /SG /SG[1] /Pos Indicatrs Wirng]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Removed	The withdrawable circuit breaker is Removed Dependency	1..n, DI-LogicList	-.-	[Control /SG /SG[1] /Pos Indicatrs Wirng]
Interl ON1	Interlocking of the ON command	1..n, Assignment List	-.-	[Control /SG /SG[1] /Interlockings]
Interl ON2	Interlocking of the ON command	1..n, Assignment List	MStart.Blo	[Control /SG /SG[1] /Interlockings]
Interl ON3	Interlocking of the ON command	1..n, Assignment List	-.-	[Control /SG /SG[1] /Interlockings]
Interl OFF1	Interlocking of the OFF command	1..n, Assignment List	-.-	[Control /SG /SG[1] /Interlockings]
Interl OFF2	Interlocking of the OFF command	1..n, Assignment List	-.-	[Control /SG /SG[1] /Interlockings]
Interl OFF3	Interlocking of the OFF command	1..n, Assignment List	-.-	[Control /SG /SG[1] /Interlockings]
SCmd ON	Switching ON Command, e.g. the state of the Logics or the state of the digital input	1..n, DI-LogicList	-.-	[Control /SG /SG[1] /Ex ON/OFF Cmd]
SCmd OFF	Switching OFF Command, e.g. the state of the Logics or the state of the digital input	1..n, DI-LogicList	-.-	[Control /SG /SG[1] /Ex ON/OFF Cmd]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
t-TripCmd	Minimum hold time of the OFF-command (circuit breaker, load break switch)	0 - 300.00s	0.2s	[Control /SG /SG[1] /Trip Manager]
Latched	Defines whether the Binary Output Relay will be Latched when it picks up.	inactive, active	inactive	[Control /SG /SG[1] /Trip Manager]
Ack TripCmd	Ack TripCmd	1..n, Assignment List	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd1	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	MStart.TripCmd	[Control /SG /SG[1] /Trip Manager]
Off Cmd2	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	I[1].TripCmd	[Control /SG /SG[1] /Trip Manager]
Off Cmd3	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	I[2].TripCmd	[Control /SG /SG[1] /Trip Manager]
Off Cmd4	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	I2>[1].TripCmd	[Control /SG /SG[1] /Trip Manager]
Off Cmd5	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	ThR.TripCmd	[Control /SG /SG[1] /Trip Manager]
Off Cmd6	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	Jam[1].TripCmd	[Control /SG /SG[1] /Trip Manager]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Off Cmd7	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	I<[1].TripCmd	[Control /SG /SG[1] /Trip Manager]
Off Cmd8	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd9	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd10	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd11	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd12	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd13	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd14	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd15	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Off Cmd16	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd17	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd18	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd19	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd20	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd21	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd22	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd23	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd24	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Off Cmd25	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd26	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd27	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd28	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd29	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
Off Cmd30	Off Command to the Circuit Breaker if the state of the assigned signal becomes true.	1..n, Trip Cmds	-.-	[Control /SG /SG[1] /Trip Manager]
OFF incl TripCmd	The OFF Command includes the OFF Command issued by the Protection module.	inactive, active	active	[Control /SG /SG[1] /General Settings]
t-Move ON	Time to move to the ON Position	0.01 - 100.00s	0.1s	[Control /SG /SG[1] /General Settings]
t-Move OFF	Time to move to the OFF Position	0.01 - 100.00s	0.1s	[Control /SG /SG[1] /General Settings]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
t-Dwell	Dwell time	0 - 100.00s	0s	[Control /SG /SG[1] /General Settings]

Controlled Circuit Breaker Input States

Name	*Description*	*Assignment via*
Aux ON-I	Module Input State: Position indicator/check-back signal of the CB (52a)	[Control /SG /SG[1] /Pos Indicatrs Wirng]
Aux OFF-I	Module input state: Position indicator/check-back signal of the CB (52b)	[Control /SG /SG[1] /Pos Indicatrs Wirng]
Ready-I	Module input state: CB ready	[Control /SG /SG[1] /Pos Indicatrs Wirng]
Removed-I	State of the module input: The withdrawable circuit breaker is Removed	[Control /SG /SG[1] /Pos Indicatrs Wirng]
Ack TripCmd-I	State of the module input: Acknowledgement Signal (only for automatic acknowledgement) Module input signal	[Control /SG /SG[1] /Trip Manager]
Interl ON1-I	State of the module input: Interlocking of the ON command	[Control /SG /SG[1] /Interlockings]
Interl ON2-I	State of the module input: Interlocking of the ON command	[Control /SG /SG[1] /Interlockings]

Name	*Description*	*Assignment via*
Interl ON3-I	State of the module input: Interlocking of the ON command	[Control /SG /SG[1] /Interlockings]
Interl OFF1-I	State of the module input: Interlocking of the OFF command	[Control /SG /SG[1] /Interlockings]
Interl OFF2-I	State of the module input: Interlocking of the OFF command	[Control /SG /SG[1] /Interlockings]
Interl OFF3-I	State of the module input: Interlocking of the OFF command	[Control /SG /SG[1] /Interlockings]
SCmd ON-I	State of the module input: Switching ON Command, e.g. the state of the Logics or the state of the digital input	[Control /SG /SG[1] /Ex ON/OFF Cmd]
SCmd OFF-I	State of the module input: Switching OFF Command, e.g. the state of the Logics or the state of the digital input	[Control /SG /SG[1] /Ex ON/OFF Cmd]

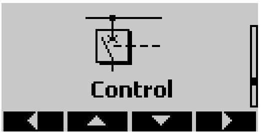
Signals of a Controlled Circuit Breaker

Signal	*Description*
SI SingleContactInd	Signal: The Position of the Switchgear is detected by one auxiliary contact (pole) only. Thus indeterminate and disturbed Positions cannot be detected.
Pos not ON	Signal: Pos not ON
Pos ON	Signal: Circuit Breaker is in ON-Position
Pos OFF	Signal: Circuit Breaker is in OFF-Position
Pos Indeterm	Signal: Circuit Breaker is in Indeterminate Position
Pos Disturb	Signal: Circuit Breaker Disturbed - Undefined Breaker Position. The Position Indicators contradict themselves. After expiring of a supervision timer this signal becomes true.
Pos	Signal: Circuit Breaker Position (0 = Indeterminate, 1 = OFF, 2 = ON, 3 = Disturbed)
Ready	Signal: Circuit breaker is ready for operation.
t-Dwell	Signal: Dwell time

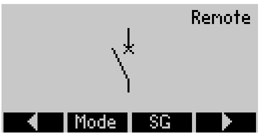
Signal	*Description*
Removed	Signal: The withdrawable circuit breaker is Removed
Interl ON	Signal: One or more IL_On inputs are active.
Interl OFF	Signal: One or more IL_Off inputs are active.
CES succesf	Signal: Command Execution Supervision: Switching command executed successfully.
CES Disturbed	Signal: Command Execution Supervision: Switching Command unsuccessful. Switchgear in disturbed position.
CES Fail TripCmd	Signal: Command Execution Supervision: Command execution failed because trip command is pending.
CES SwitchDir	Signal: Command Execution Supervision respectively Switching Direction Control: This signal becomes true, if a switch command is issued even though the switchgear is already in the requested position. Example: A switchgear that is already OFF should be switched OFF again (doubly). The same applies to CLOSE commands.
CES ON d OFF	Signal: Command Execution Supervision: On Command during a pending OFF Command.
CES SG not ready	Signal: Command Execution Supervision: Switchgear not ready
CES Fiel Interl	Signal: Command Execution Supervision: Switching Command not executed because of field interlocking.
CES SG removed	Signal: Command Execution Supervision: Switching Command unsuccessful, Switchgear removed.
TripCmd	Signal: Trip Command
Ack TripCmd	Signal: Acknowledge Trip Command
OFF incl TripCmd	Signal: The OFF Command includes the OFF Command issued by the Protection module.
Position Ind manipul	Signal: Position Indicators faked
SGwear Slow SG	Signal: Alarm, the circuit breaker (load-break switch) becomes slower
Res SGwear Sl SG	Signal: Resetting the slow Switchgear Alarm
ON Cmd	Signal: ON Command issued to the switchgear. Depending on the setting the signal may include the ON command of the Prot module.
OFF Cmd	Signal: OFF Command issued to the switchgear. Depending on the setting the signal may include the OFF command of the Prot module.
ON Cmd manual	Signal: ON Cmd manual
OFF Cmd manual	Signal: OFF Cmd manual

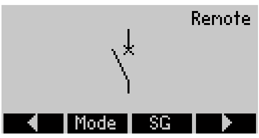
Control - Example: Switching of a Circuit Breaker

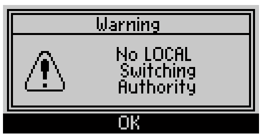
The following example shows how to switch a circuit breaker via the HMI at the device.

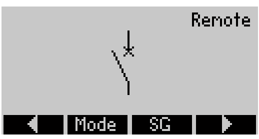
	Change into the menu »Control« or alternatively push the »CTRL« button at the device front.

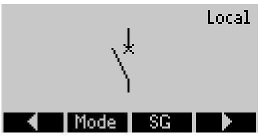
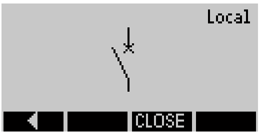
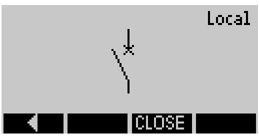
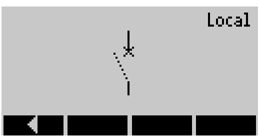
	Change to the control page by pushing the »right arrow« softkey.

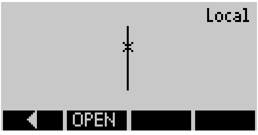
	**Information only:** On the control page the current switchgear positions is displayed. By means of the softkey »Mode« it can be switched to the menu »General Settings«. In this menu switching authority and interlockings can be set. By means of the softkey »SG« it can be switched to the menu »SG«. In this menu specific settings for the switch gear can be done.

	To execute a switching operation, change into the switching menu by pushing the right arrow softkey button.

	Executing a switching command via the devices HMI is only possible when the switching authority is set to »Local«. If no switching authority is given, this has to be set first to »Local« or »Local and Remote«. With the softkey »OK« it can be switched back to the single line diagram page.

	Pushing the softkey »Mode« leads to the menu »General Settings«.

	In this menu the switching authority can be changed.
	Select between »Local« or »Local and Remote«.
	Now it is possible to execute switching commands at the HMI.
	Push the »right arrow« softkey to get to the control page.
	The circuit breaker is opened, therefore it can be closed only. After pushing the softkey »CLOSE« a confirmation window appears.
	When you are sure to proceed with the switching operation, press the softkey »YES«.
	The switching command will be given to the circuit breaker. The display shows the intermediate position of the switchgear.

	It will be shown on the display when the switchgear reaches the new end position. Further possible switching operations (OPEN) will be displayed by softkeys.
	Notice: For the case, the switchgear does not reach the new end position within the set supervision time the following Warning appears on the display.

Protective Elements

MStart - Motor Starting and Control [48,66]

Available elements:
MStart

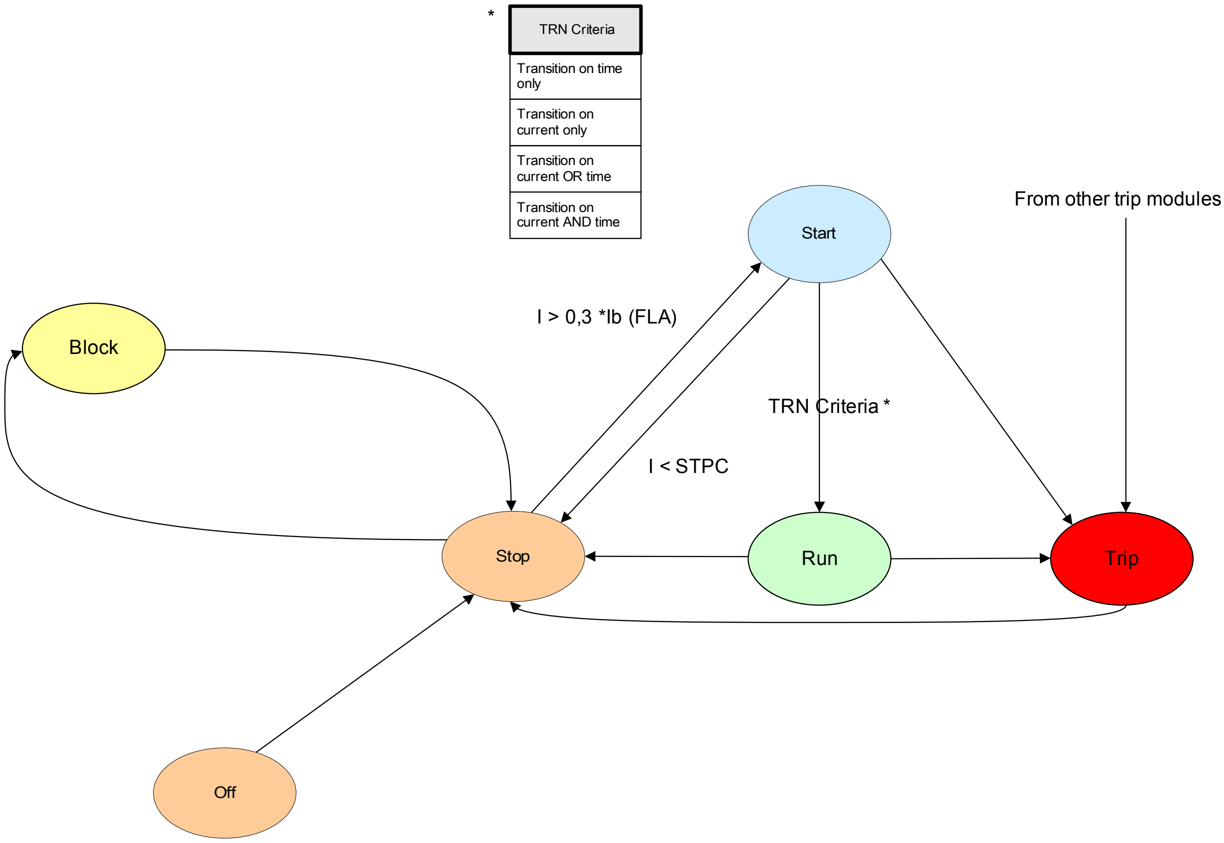
General – Principle Use

The motor start control logic is the core control and protective function for a motor protection device. The logic comprises:

- Motor Operation States,
- Motor Start Control
- Motor Start Blockings
- Motor Start / Transition Trips
- Motor Cold Warm Detection
- Emergency Override.

Motor Operation States

Motor Operation States



The basic motor operation states can be classified as four states that include:

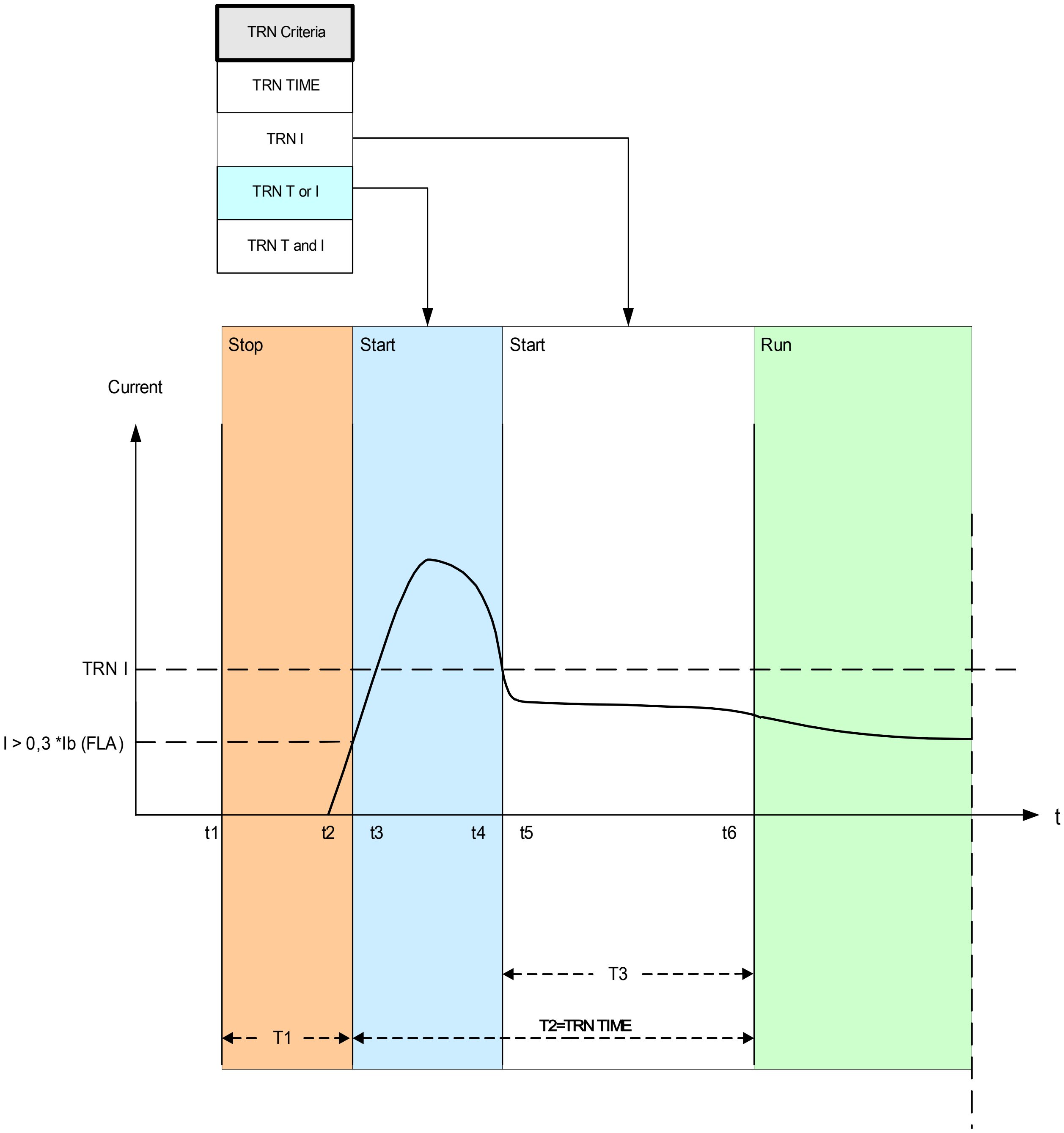
1. Start cycle;
2. Run cycle;
3. Stop cycle; and
4. Trip state.

Under normal conditions, the motor operations should go through »stop«, »start«, »run«, and »stop« cycles that are referred to as a complete operation sequence; while under certain abnormal conditions, the motor could go from »start« to »stop«, or »start« to »trip«, or »run« to »trip«.

If other protection trips occur at either the »start« or »run« cycle, the motor will be forced to go to »trip« mode. After motor currents are terminated, the motor will go into the »stop« cycle.

Start Control

The parameters for the Start Control have to be set within menu [Protection Para\MStart\StartControl]



T1: Stop Cycle

t4-t3: Start Cycle if TRNC is selected

t6-t3: Start Cycle if TRNT is selected

The Start Control Module drawing shows an example of how the protective device reacts to a normal operating-cycle current profile. Initially, the motor is stopped and the current is zero. As long as the protective device is not in a »trip« state, it permits contactor energization by closing its trip contact in series with the contactor. The contactor is energized by the operator or process control system through a normal two-wire or three-wire motor control scheme, external to the protective device. The protective device declares a motor start when it senses a motor current that exceeds 30% of the »*Ib«* (FLA) setting. Meanwhile, the transition timer »*TRNT«* begins to run. The protective device also monitors the large starting current, noting when the current falls below the transition level »*TRNC«*.

The Start to Run transition is based on the setting »*TRN Criteria«*, which has four transition behaviors for the User to select:

•TRN T	-	Transition to RUN after time setting TRNT only. Current is ignored.
•TRN C	-	Transition when starting current drops below the setting only. If the time set in TRNT expires before the current transition, the motor trips.
•TRN T or C	-	Transition on time or current, whichever comes first.
•TRN T and C	-	Transition on time and current. Both must occur, and the current must drop below the setting before the time delay expires. If the timer expires before the current falls below the set transition level, the motor trips.

If there is no transition trip, the protective device relay declares a successful transition to »RUN« cycle and the corresponding transition signal(s) (current or time, or both, depending on the settings and motor current) is set. The transition signal(s) is the part of the global output list, which can be assigned to any module input or relay output. If it is assigned to a relay output, it can control a reduced-voltage starter, switching to full running voltage.

Even if the transition control output contact is not used, the transition function can provide clear indications of the actual state of the motor (»START« versus »RUN«) on the front panel display and via data communications. A good way to do this is to use the settings of TRN Criteria = TRN T or C and TRNC = 130% of »*Ib«* (FLA). Modify the latter, if needed, to lie at a transition value between the starting current and post-start maximum load current. Set the transition timer well beyond the normal start time to avoid a transition trip.

Start Delays

The parameters for the Start Delays have to be set within menu [Protection Para\MStart\Start Delay Timer]

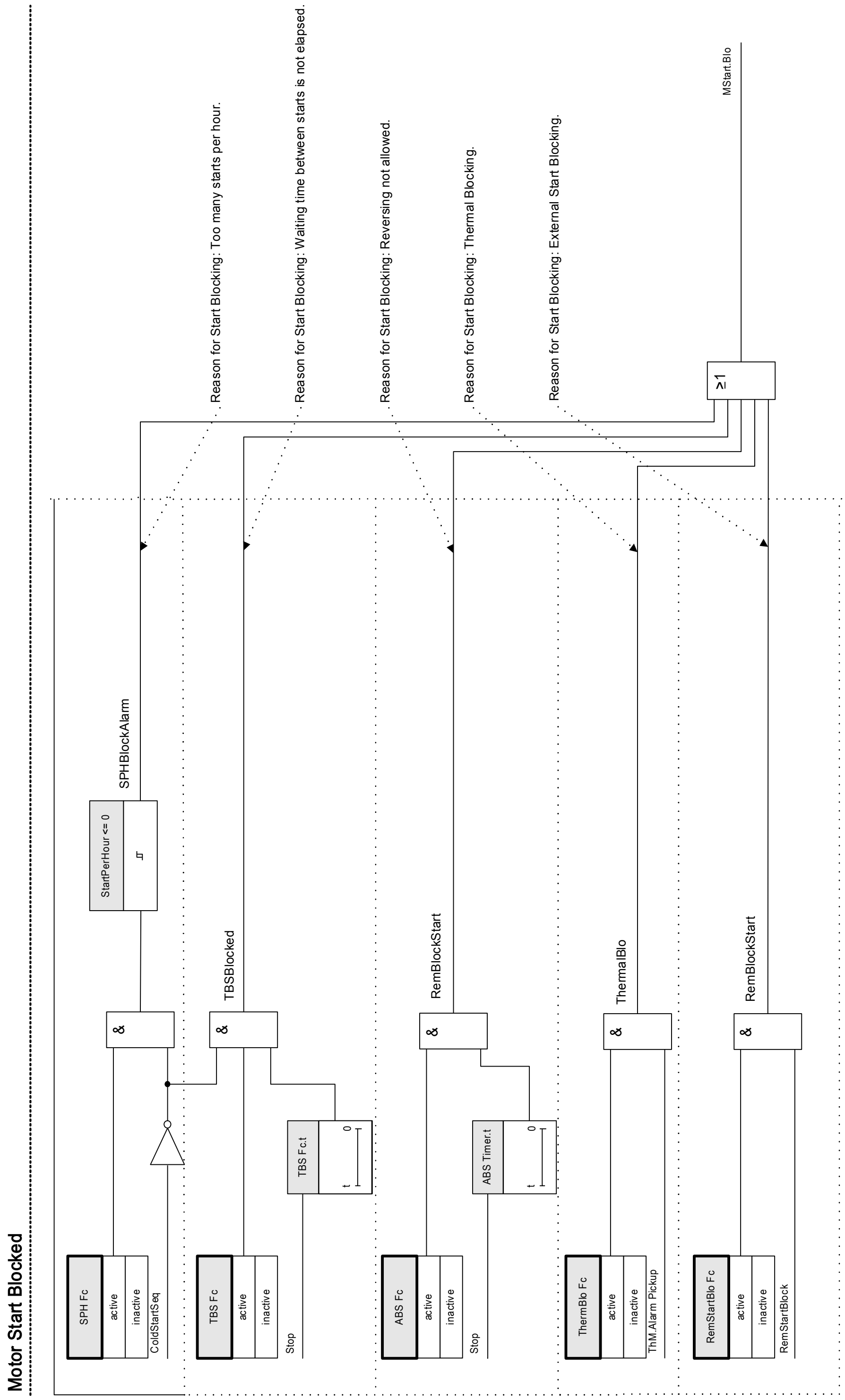
When the protective device declares a »START«, all start timers of the enabled functions begin to time. Each of these timers blocks the respective function until the set delay expires. These start timers are affected by transitions - they run for the set time, which may be less than or greater than the time of transition. These start delay timers include:

- IOC (Instantaneous overcurrent start delay);
- GOC (Ground fault start delay);
- UnderLoad (Underload trip and alarm start delay);
- IUnbalance (Current unbalance trip and alarm start delay);
- JAM (Jam trip and alarm start delay); and
- Generic1 to Generic5 (Generic start delay).

Note that the generic start delays are not tied to anything, and they can be used to block anything at the User's choice.

Motor Start Blocked

A Motor Start can be blocked by certain events, if any of the following conditions are noted - motor starts limit, starting frequency, thermal and mechanical constraints. The User may choose to use the states to block the motor from starting or use it as an alarm or indication.



Blocking Conditions

The reasons for a Motor Start Blocking are as follows:

The Motor Start will be blocked due to:

- There are too many starts per hour (if configured).
- The waiting time between starts is not elapsed (if configured).
- If the Anti Backspin protection detects a reversing of the motor (reversing not allowed, if configured).
- The thermal model blocks the motor (if configured).
- External Blocking becomes active (if configured).

When any of Anti-Backspin, thermal, and external blocks are on, the »*MStart.Blo*« signal will be set. The »*TBS*« and »SPH« can turn on the »*MStart.Blo*« signal only if the motor is not in a cold start sequence; »*NOCS*« block can not cause the »*MStart.Blo*« signal to be set.

Start Limits

Because motor starting consumes a considerable amount of thermal energy compared to its normal load conditions, the number of starts in a given time period must be monitored and controlled. The protective device has three functions that contribute to the start limits monitoring. These are:

- TBS (Time between Starts);
- SPH (Starts per Hour); and
- NOCS (Number of Cold Starts).

Most motors can tolerate some number of consecutive cold starts before the time between starts is enforced. The protective device treats a start as the first in a sequence of cold starts if the motor has been stopped for at least the time period that is the greatest of »*one hour*« and »*TBS*«. Subsequent starts are treated as additional cold starts in the same sequence, only if they run no more than ten minutes, until the set number of cold starts is reached. Once the motor is in the cold starting sequence, it will ignore »*TBS*« and »*SPH*« limits. The cold start sequence will be terminated if the motor has run for more than ten minutes for a cold start before it exhausts »*NOCS*«, then starts after this are subject to time and count limits imposed by »*TBS*« and »*SPH*«. If the motor reaches the »*NOCS*« limit in a cold start sequence, »*NOCS*« block signal will be set and »*TBS*« will start to time. When »*TBS*« reaches its limit while the »NOCS« block signal is still set, the cold start sequence will be terminated and the »*NOCS*« block will be released. Meanwhile, the »*SPH*« will start to count at the last start in the complete cold start sequence.

Stop Cycle

The run cycle continues until the motor current level falls below the Stop Current Threshold setting current on all three phases. Then a stop is declared. The start limits (also referred as Jogging start limits) and the anti-backspin time delay (ABS) are checked. If blocking conditions exist, the protective device can be configured to block a motor from starting. Remaining jogging block times are displayed and counted down, indicating how long to wait. If there are no such starting block conditions in effect, the protective device is ready for a new start.

Anti-Backspin Delay Time (ABS)

»ABS« sets the time in seconds before a motor restart is permitted after a trip or stop condition. This function can be set to »*inactive*«.

This function is used with a motor driving a pump working into a head, or any other load that tends to spin in a reverse direction (backspin) when the motor is de-energized. It blocks starting during the time when the motor might be rotating in reverse following a trip. Also, this function may be used simply to set idle time (time between stop and start) before a restart is permitted.

External Start Blocking

A motor can be blocked through a digital input. If this feature is enabled, the User must make sure that both the Motor Start and Digital Input modules are configured properly.

Thermal Block

Besides the previously mentioned start monitoring and controlling means, the motor can be blocked if the thermal capacity used exceeds the alarm level. It is the User's choice to turn on or off this feature and set an appropriate alarm level in the thermal model module.

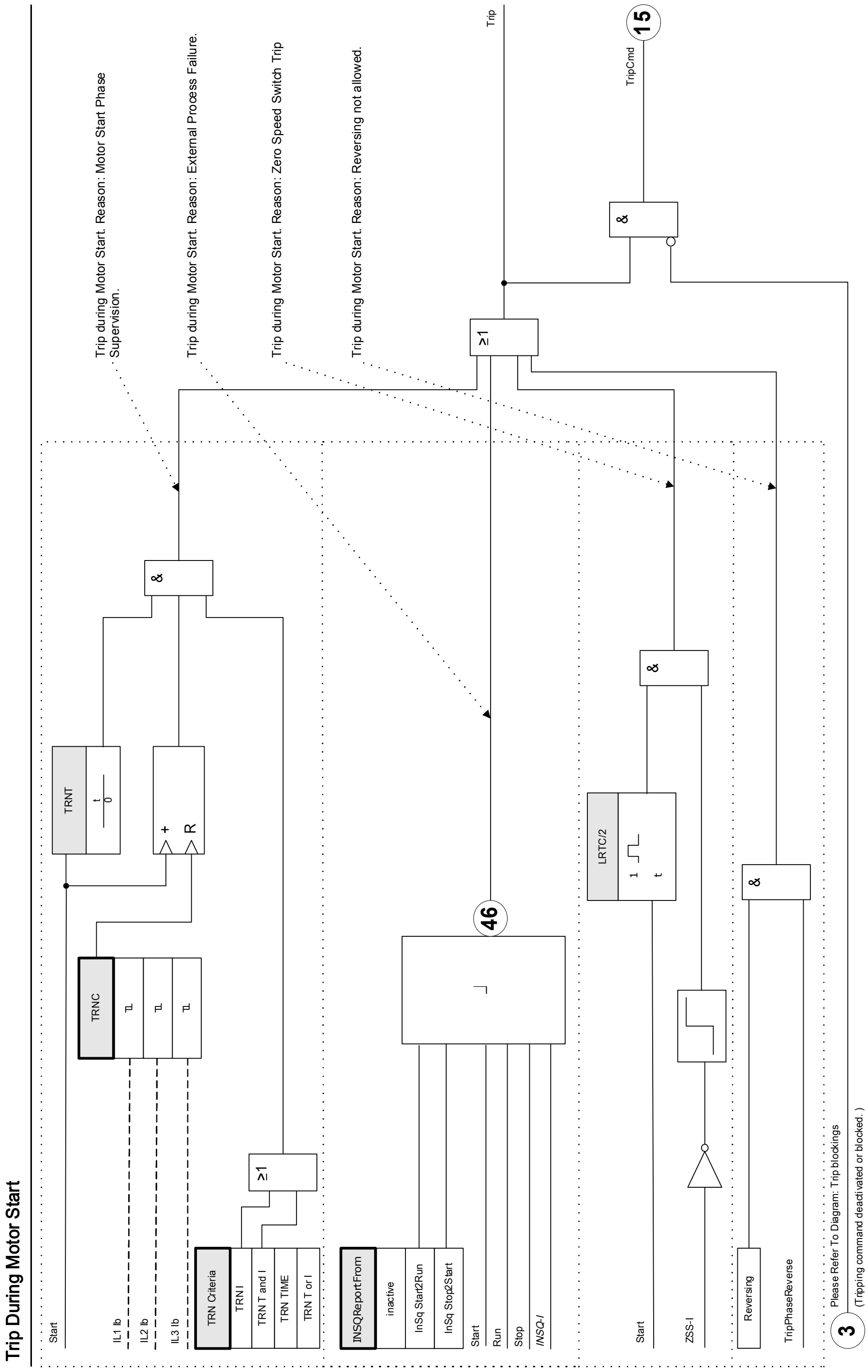
Forced Starting

It is recommended that the User wires the »MStart.Blo« output to the motor trip circuit for preventing the motor from starting under these blocked conditions. If the User chooses not to do this for their applications, a Forced Starting signal will be set when the motor is started with the blocked conditions. This signal can only be reset manually though *Smart view* or from the front panel (please refer to section Emergency Override).

Motor Start / Transition Trips

The Motor will be tripped during the start phase, in case that:

- The Start Control detects an unsuccessful Start. (Please see section Start Control Module)
- There is an Incomplete Start Sequence. The device detects via an digital input, that the external process is not properly started.
- If a reverse direction is detected but reversing is not allowed.
- If case of a Zero Speed Switch trip.

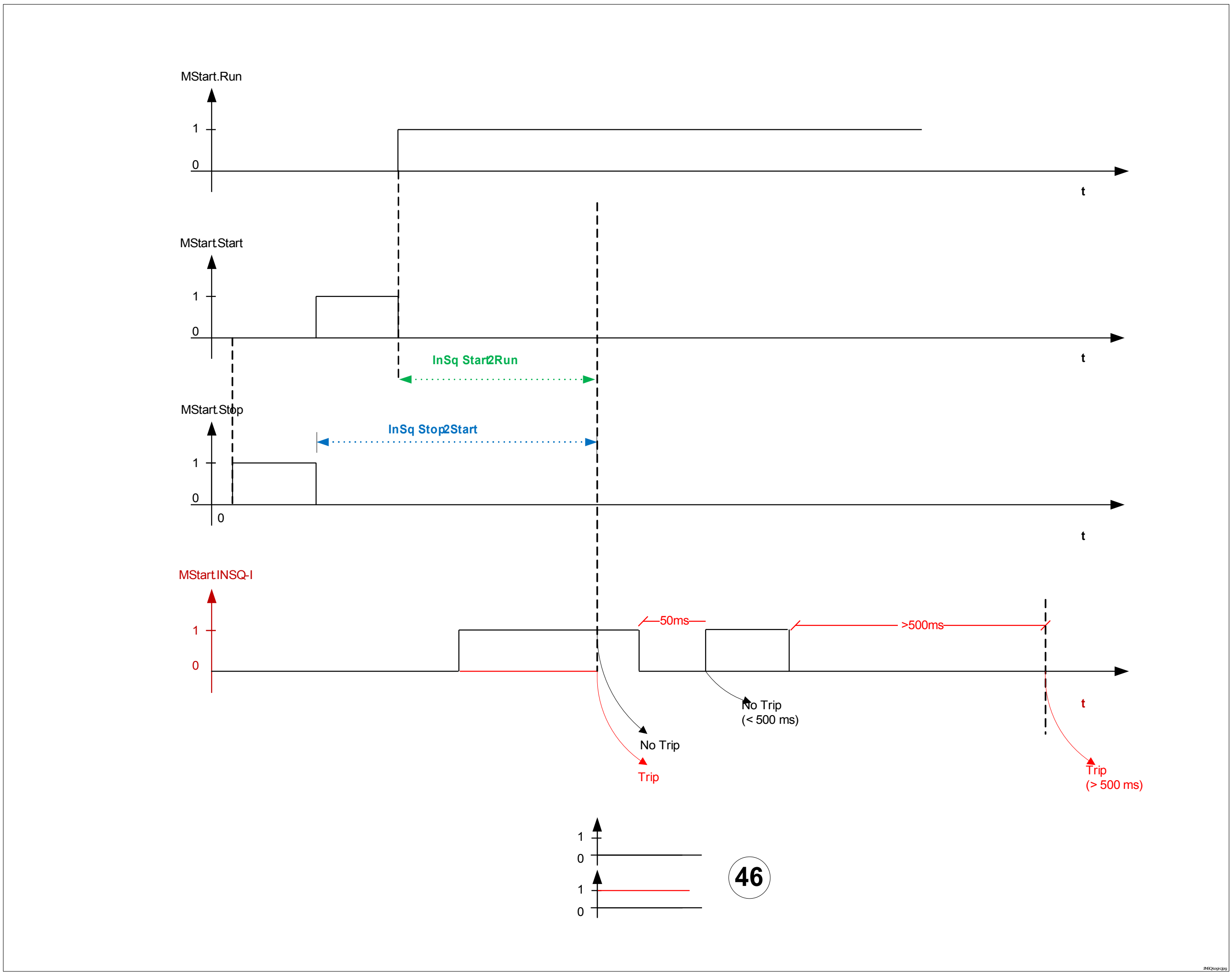


Incomplete Sequence Report Back Time (INSQ)

The incomplete sequence function requires an input from the report back contact from the process that the motor is running. Shortly after the motor starts, the report back contact provides an indication that the process has started to operate as expected. If the process does not start up correctly, the contact does not close within the expected time. If a problem develops later on, the report back contact opens. In either case, the open contact state indicates that the motor should be tripped.

To use this function, set a time limit for report back here and define the start of report back timing. Connect the report back contact to one of the protective device Discrete Inputs. If this input is not energized before the set time expires, the relay will trip on an “Incomplete Sequence”.

Note that the input must be energized continuously after the time delay has expired to hold off this trip. Otherwise, if the incomplete sequence report back contact changes state for a period greater than 0.5 seconds, the relay will trip on an incomplete sequence. This delay allows for any momentary transient switching that may occur in the process report back contact, such as that which can occur in an open transition reduced voltage start.

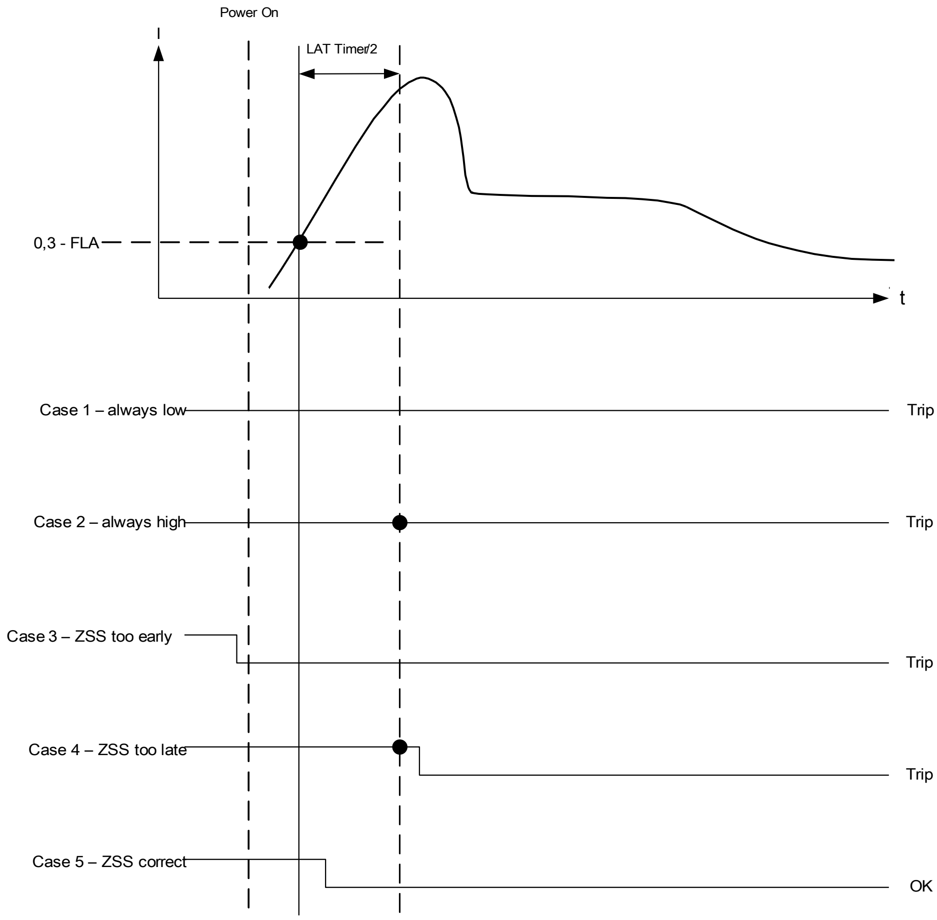


Zero Speed Switch (ZSS ON or OFF)

ZSS enables the function that verifies if the motor begins to physically spin after a start. It requires a zero-speed switch (digital switch) on the motor, which is closed at rest and opens as the rotor reaches (5%-10%) its normal speed. Connect the zero-speed switch contact to one of the protective device Digital Inputs. If the contact fails to open within »*LRT/2«* (one-half of locked-rotor time) after a start, the relay trips with a zero-speed switch trip message.

This protection is always useful, but is essential if the Long Acceleration Time (LAT) function setting is used.

With ZSS being enabled and being mapped to one of the digital inputs, the protective device checks the ZSS input status at the very moment it sees a start - it wants to sense the initially closed zero-speed switch, which opens shortly thereafter as the motor spins. If it fails to find the closed contact, it trips immediately. Check the wiring and contact for problems.



Long Acceleration Time (LAT)

When the LAT function is enabled, the »*LAT«* timer is used to set a time interval during which the motor is permitted to accelerate a high-inertia load, which is longer than the locked-rotor time. This function can be (and usually should be) set to »*inactive«*. If the thermal-model accumulator bucket fills to 100% during the long acceleration time, it is limited to that value and the thermal trip is held off until the LAT timer expires. By then, the thermal bucket level must have decreased (thermal model cooled) below 100% or the motor trips.

The LAT function should be used but not limited only on motors with a zero-speed switch (a normally-closed contact that opens when the motor actually begins to spin). Connect the zero-speed switch contact to one of the protective device Digital Inputs. The Zero-Speed Switch function must be enabled (ZSS ON). The protective device requires the zero-speed switch to open within LRT/2 (one-half of locked-rotor time) after a start, or the motor is tripped by the ZSS function. This protects a completely stalled motor from being damaged when the LAT timer blocks the locked-rotor thermal trip.

CAUTION **The long acceleration time (LAT) function can block the critical LRC-LRT rotor thermal protection during a start and destroy the motor. Turn LAT OFF unless absolutely needed and the motor's suitability for this starting duty has been confirmed. Use only with zero speed switch function ZSS ON and switch input connected to protect a stalled motor.**

The User can temporarily defeat the I2t thermal protection limit after a start by setting a Long Acceleration Time delay. This can be a dangerous setting that blocks thermal tripping and holds the bucket at a 100% level if the load takes a long time to reach running speed. An example is a motor spinning a large centrifuge. In using LAT, the User can take advantage of the partial cooling from airflow produced by the motor spinning at below-normal speed, as compared to unfanned heating of a locked rotor. The motor must be rated for this severe starting duty. Also, the User must ensure that the motor actually has begun to spin well before the locked-rotor time has expired. This is accomplished by connecting a zero-speed switch to a Digital Input and turning on ZSS function. The zero-speed switch is a contact that is closed when the motor is at rest, and opens as the motor begins to spin, usually at 5-10% of running speed. If ZSS is set to ON and the protective device relay does not sense the contact open in one-half the locked-rotor time setting, it trips the motor.

WARNING **Turn OFF LAT unless the application specifically demands it. Use a zero speed switch with LAT. Using an LAT setting greater than locked rotor time without a zero speed switch temporarily defeats thermal protection and damages the motor if the rotor actually is locked.**

If »*LAT*« is used, check the settings of transition time »*TRNT*« and jam start delay to be sure they are coordinated with the prolonged starting cycle.

Anti-Backspin Delay Time (ABS)

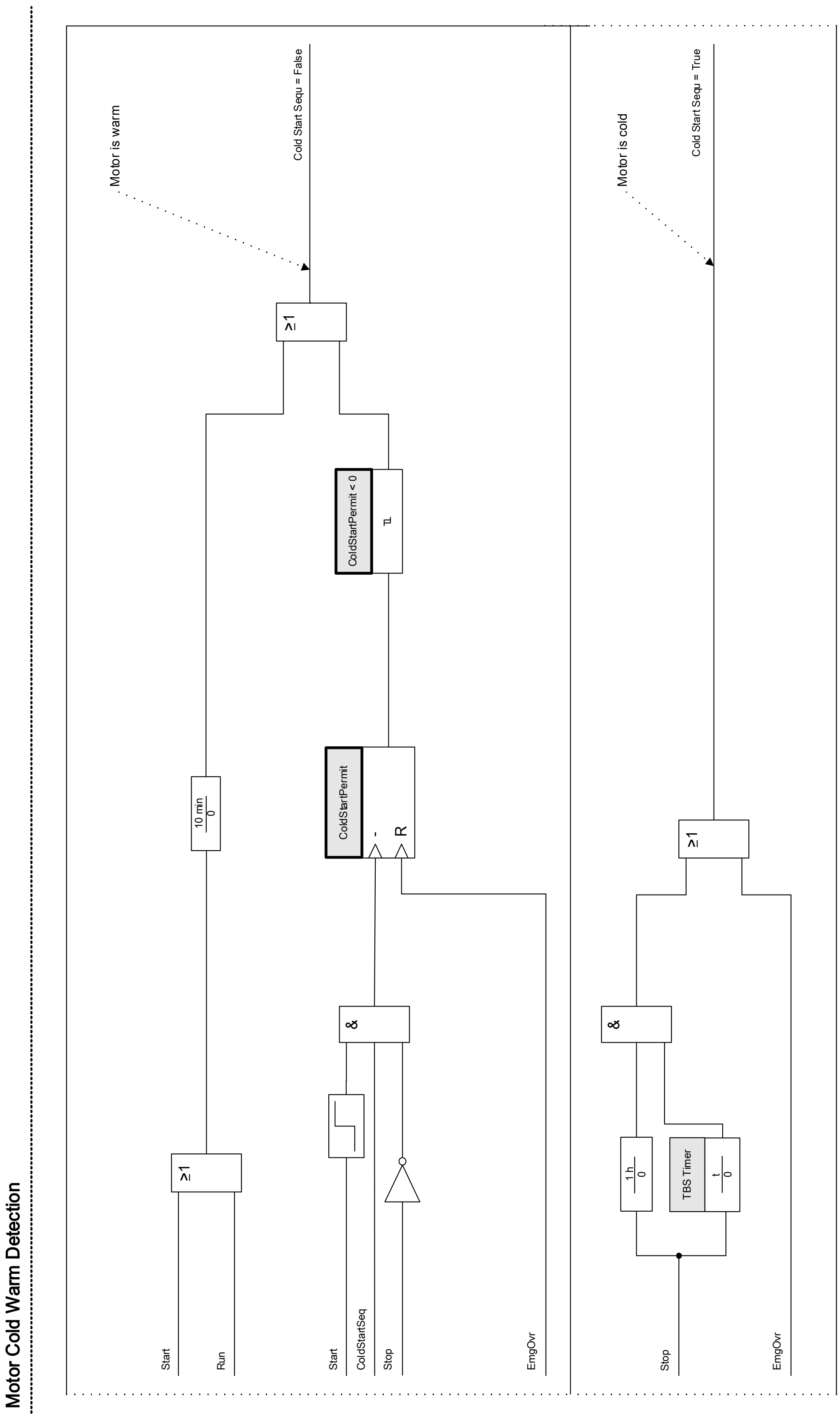
»ABS« sets the time in seconds before a motor restart is permitted after a trip or stop condition. This function can be set to »*inactive*«.

This function is used with a motor driving a pump working into a head, or any other load that tends to spin in a reverse direction (backspin) when the motor is de-energized. It blocks starting during the time when the motor might be rotating in reverse following a trip. Also, this function may be used simply to set idle time (time between stop and start) before a restart is permitted.

Motor Cold Warm Detection

The motor will be considered as cold (»COLD SEQU = TRUE«) after being in the »stop« mode for more than one hour if the time between starts timer is set to a lower value than 1 hour.

Else, the motor will fall back into the »cold« state if the time between starts timer is elapsed. By means of the Emergency Override function, the motor can be forced to switch to the cold state.



Emergency Override

The Emergency Override function can be enabled or disabled in the following menu [Protection Para\Global Prot Para\MStart\Start Control\EMGOVR]. Also it can be determined whether this function can be executed by a DI or by a softkey at the HMI or both.

If enabled, an emergency override can be executed by pushing the »*Emrg Override*« Softkey at the front panel. In any case, an emergency override can be performed by a remote contact connected to any one of the digital inputs programmed as »*EMG OVR*«, or via front panel under [Operations\Reset\EMGOVR] menu. The as-shipped setting is disabled.

Emergency override allows a panic restart of a tripped motor without completely disabling protection. When the override request is received, the thermal-model accumulator bucket is drained to its initial level of 40°C (104°F). Cold starts are fully restored.

The motor protection is now in the state it would be in if the motor had been standing for a long time prior to the moment of the override. This allows an immediate restart of the motor. The override can also delay an impending thermal trip of a running motor. The emergency override action is counted in the history record, and noted with its time tag in the logbook record.

CAUTION

The emergency override function clears and restarts all protective functions of the protective device. Using this function can damage the motor. Use it only for true emergencies, when it is known what caused the trip. Override permits the risk of motor damage to avoid an even more dangerous process situation caused by the tripping of the motor.

Global Protection Parameters of the Motor Start Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Reversing	Reversing or non reversing starter. This option will affect the sequence current calculations.	inactive, active	inactive	[Field Para /Motor Nominal Values]
Ib	Full load current (amperes). Set to maximum stator continuous RMS current primary (actual motor winding) amperes in each phase. Use motor nameplate or manufacturers data. Note that the ratio Ib/CT prim must lie between 0.25 and 1.5 in order to have reliable motor protection.	10 - 6000A	10A	[Field Para /Motor Nominal Values]
LRC	Set to the locked-rotor current (the current the motor draws when stalled), in times of Ib. Use motor nameplate or manufacturers data.	3.00 - 12.00Ib	3.00Ib	[Field Para /Motor Nominal Values]
LRTC	Specifies how long a locked-rotor or stall condition can be maintained before the motor is damaged, in seconds, for a cold start. Use motor nameplate or manufacturers data.	1 - 120s	1s	[Field Para /Motor Nominal Values]
STPC	Stop current threshold, in percent of Ib, if the actual current is below the threshold for at least 300 milliseconds. If a stop state occurs, the jogging functions Starts per Hour Allowed (SPH), Time Between Starts (TBS) and Anti-Backspin (ABS) are enforced. All phases of the current must be below this level before a stop will be declared.	0.02 - 0.20Ib	0.02Ib	[Field Para /Motor Nominal Values]
k-Factor	The k-Factor is to be calculated by the maximum allowed continuous current over the rated current transformer current (e.g. 1.2 times rated motor current over rated transformer current).	0.25 - 1.50	0.85	[Field Para /Motor Nominal Values]
ExBlo TripCmd	External blocking of the Trip Command of the module/the stage, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /MStart /Start Control]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
RemStartBlo Fc	RemStartBlo Fc	inactive, active	inactive	[Protection Para /Global Prot Para /MStart /Start Control]
ThermBlo Fc	ThermBlo Fc	inactive, active	inactive	[Protection Para /Global Prot Para /MStart /Start Control]
TRN Criteria	Start transition criterion	TRN I, TRN TIME, TRN T and I, TRN T or I	TRN T and I	[Protection Para /Global Prot Para /MStart /Start Control]
TRNT	Motor start transition time limit Only available if: TRN Criteria = TRN T and I Or TRN Criteria = TRN TIME	0 - 1200s	10s	[Protection Para /Global Prot Para /MStart /Start Control]
TRNC	Motor start transitions current level in Ib% Only available if: TRN Criteria = TRN T and I Or TRN Criteria = TRN I	0.10 - 3.00Ib	1.30Ib	[Protection Para /Global Prot Para /MStart /Start Control]
NOCS	Number of cold starts limit	1 - 5	1	[Protection Para /Global Prot Para /MStart /Start Control]
TBS Fc	Time Between Starts on/off	inactive, active	inactive	[Protection Para /Global Prot Para /MStart /Start Control]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
TBS Timer	Time Between Starts Limit Only available if: TBS Fc = active	1 - 240min	60min	[Protection Para /Global Prot Para /MStart /Start Control]
SPH Fc	Starts Per Hour	inactive, active	inactive	[Protection Para /Global Prot Para /MStart /Start Control]
SPH	SPH Only available if: SPH Fc = active	1 - 10	1	[Protection Para /Global Prot Para /MStart /Start Control]
INSQReportFrom	INcomplete SeQuence report time starting point	inactive, InSq Start2Run, InSq Stop2Start	inactive	[Protection Para /Global Prot Para /MStart /Start Control]
INSQReportTime	INSQ Report back time Only available if: INSQReportFrom = active	1 - 240s	1s	[Protection Para /Global Prot Para /MStart /Start Control]
LAT Fc	Long Time Acceleration Timer	inactive, active	inactive	[Protection Para /Global Prot Para /MStart /Start Control]

Parameter	Description	Setting range	Default	Menu path
LAT Timer	Large motors with a high inertia may experience starting currents that exceed the locked rotor current and time. The protective relay has logic and provisions for a zero speed switch input to differentiate between a stall and start condition. If the motor is spinning then the relay will not trip on the normal locked rotor time allowing the motor to start. Only available if: LAT Fc = active	1 - 1200s	1200s	[Protection Para /Global Prot Para /MStart /Start Control]
ABS Fc	For certain applications, such as pumping a fluid up a pipe, the motor may be driven backward for a period of time after it stops. The protective relay provides an anti-backspin timer to prevent starting the motor while it is spinning in the reverse direction. The timer begins counting from the moment a stop is declared by the relay.	inactive, active	inactive	[Protection Para /Global Prot Para /MStart /Start Control]
ABS Timer	For certain applications, such as pumping a fluid up a pipe, the motor may be driven backward for a period of time after it stops. The protective relay provides an anti-backspin timer to prevent starting the motor while it is spinning in the reverse direction. The timer begins counting from the moment a stop is declared by the relay. Only available if: ABS Fc = active	1 - 3600s	3600s	[Protection Para /Global Prot Para /MStart /Start Control]
ZSS	Zero Speed Switch	inactive, active	inactive	[Protection Para /Global Prot Para /MStart /Start Control]
EmgOvr	Emergency override options. Signal has to be active in order to release the thermal capacity of the motor. Please notice that by doing this you run the risk of damaging the motor. “EMGOVR” has to be set to “DI” or “DI or UI” for this input to take effect.	inactive, DI, HMI, DI or HMI	inactive	[Protection Para /Global Prot Para /MStart /Start Control]
RemStartBlock	Remote Motor Start Blocking Only available if: RemStartBlo Fc = active	1..n, Dig Inputs	-.-	[Protection Para /Global Prot Para /MStart /Motor Inputs]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
EmgOvr	Emergency Override. Signal has to be active in order to release the thermal capacity of the motor. Please notice that by doing this you run the risk of damaging the motor. “EMGOVR” has to be set to “DI” or “DI or UI” for this input to take effect	1..n, Dig Inputs	-.-	[Protection Para /Global Prot Para /MStart /Motor Inputs]
INSQ	INcomplete SeQuence Only available if: INSQReportFrom = active	1..n, Dig Inputs	-.-	[Protection Para /Global Prot Para /MStart /Motor Inputs]
ZSS	Zero Speed Switch Only available if: ZSS = active	1..n, Dig Inputs	-.-	[Protection Para /Global Prot Para /MStart /Motor Inputs]
STPC Blo	With this setting a Digital Input keeps the Motor in the RUN mode, even when the motor current drops below STPC (motor stop current).	1..n, Dig Inputs	-.-	[Protection Para /Global Prot Para /MStart /Motor Inputs]
t-Blo-IOC	Phase Overcurrent Start Delay.Phase Overcurrent elements are blocked for the time programmed under this parameter, while the motor is starting.	0.03 - 1.00s	0.05s	[Protection Para /Global Prot Para /MStart /Start Delay Timer]
t-Blo-GOC	Ground Overcurrent Start Delay. Ground Overcurrent elements are blocked for the time programmed under this parameter, while the motor is starting	0.03 - 1.00s	0.08s	[Protection Para /Global Prot Para /MStart /Start Delay Timer]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
t-Blo-I<	Underload Start Delay. 37[x] elements are blocked for the time programmed under this parameter, while the motor is starting	0 - 1200s	60s	[Protection Para /Global Prot Para /MStart /Start Delay Timer]
t-Blo-I2>	Current Unbalance Start Delay. 46[x] elements are blocked for the time programmed under this parameter, while the motor is starting	0.03 - 1200.00s	10.00s	[Protection Para /Global Prot Para /MStart /Start Delay Timer]
t-Blo-JAM	Jam Start Delay. 50J[x] elements are blocked for the time programmed under this parameter, while the motor is starting	0.03 - 1200.00s	60.00s	[Protection Para /Global Prot Para /MStart /Start Delay Timer]
t-Blo-Generic1	t-Blo-Generic1	0 - 1200s	0s	[Protection Para /Global Prot Para /MStart /Start Delay Timer]
t-Blo-Generic2	t-Blo-Generic2	0 - 1200s	0s	[Protection Para /Global Prot Para /MStart /Start Delay Timer]
t-Blo-Generic3	t-Blo-Generic3	0 - 1200s	0s	[Protection Para /Global Prot Para /MStart /Start Delay Timer]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
t-Blo-Generic4	t-Blo-Generic4	0 - 1200s	0s	[Protection Para /Global Prot Para /MStart /Start Delay Timer]
t-Blo-Generic5	t-Blo-Generic5	0 - 1200s	0s	[Protection Para /Global Prot Para /MStart /Start Delay Timer]

Motor Start Module Input States

Name	*Description*	*Assignment via*
ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command	[Protection Para /Global Prot Para /MStart /Start Control]
RemStartBlock-I	State of the module input: Remote Motor Start Blocking	[Protection Para /Global Prot Para /MStart /Motor Inputs]
EmgOvr-I	State of the module input: Emergency Override. Signal has to be active in order to release the thermal capacity of the motor. Please notice that by doing this you run the risk of damaging the motor. “EMGOVR” has to be set to “DI” or “DI or UI” for this input to take effect	[Protection Para /Global Prot Para /MStart /Motor Inputs]
INSQ-I	State of the module input: INcomplete SeQuence	[Protection Para /Global Prot Para /MStart /Motor Inputs]
ZSS-I	State of the module input: Zero Speed Switch	[Protection Para /Global Prot Para /MStart /Motor Inputs]
STPC Blo-I	State of the module input: With this setting a Digital Input keeps the Motor in the RUN mode, even when the motor current drops below STPC (motor stop current).	[Protection Para /Global Prot Para /MStart /Motor Inputs]

Motor Start Module Signals (Output States)

Signal	*Description*
active	Signal: active
Blo TripCmd	Signal: Trip Command blocked
Trip	Signal: Trip
TripCmd	Signal: Trip Command
Start	Signal: Motor is in start mode
Run	Signal: Motor is in run mode
Stop	Signal: Motor is in stop mode
Blo	Signal: Motor is blocked for starting or transition to Run mode
NOCSBlocked	Signal: Motor is prohibited to start due to number of cold start limits
SPHBlocked	Signal: Motor is prohibited to start due to starts per hour limits
SPHBlockAlarm	Signal: Motor is prohibited to start due to starts per hour limits, would come active in the next stop
TBSBlocked	Signal: Motor is prohibited to start due to time between starts limits
ThermalBlo	Signal: Thermal block
RemBlockStart	Signal: Motor is prohibited to start due to external blocking through digital input DI
TransitionTrip	Signal: Start transition fail trip
ZSSTrip	Signal: Zero speed trip (possible locked rotor)
INSQSP2STFaill	Signal: Fail to transit from stop to start based on reported back time
INSQSt2RunFail	Signal: Fail to transit from start to run based on reported back time
LATBlock	Signal: Long acceleration timer enforced
ColdStartSeq	Signal: Motor cold start sequence flag
ForcedStart	Signal: Motor being forced to start
TripPhaseReverse	Signal: Relay tripped because of phase reverse detection
EmergOverrideDI	Signal: Emergency override start blocking through digital input DI
EmergOverrideUI	Signal: Emergency override start blocking through front panel
ABSActive	Signal: Anti-backspin is active. For certain applications, such as pumping a fluid up a pipe, the motor may be driven backward for a period of time after it stops. The anti-backspin timer prevents starting the motor while it is spinning in the reverse direction.
Blo-GOCStart	Signal: Ground Instantaneous Overcurrent Start Delay. GOC (Instantaneous Overcurrent) elements are blocked for the time programmed under this parameter
Blo-IOCStart	Signal: Phase Instantaneous Overcurrent Start Delay. IOC (Instantaneous Overcurrent) elements are blocked for the time programmed under this parameter
Blo-I<Start	Signal: Underload Start Delay. Underload(Instantaneous Overcurrent) elements are blocked for the time programmed under this parameter
Blo-JamStart	Signal: JAM Start Delay. JAM(Instantaneous Overcurrent) elements are blocked for the time programmed under this parameter
Blo-I2>Start	Signal: Motor start block current unbalance signal

Signal	*Description*
Blo-Generic1	Generic Start Delay. This value can be used to block any protective element.1
Blo-Generic2	Generic Start Delay. This value can be used to block any protective element.2
Blo-Generic3	Generic Start Delay. This value can be used to block any protective element.3
Blo-Generic4	Generic Start Delay. This value can be used to block any protective element.4
Blo-Generic5	Generic Start Delay. This value can be used to block any protective element.5
I_Transit	Signal: Current transition signal
T_Transit	Signal: Time transition signal
MotorStopBlo	Signal: Motor stop block other protection functions
Rotating forward	Signal: Rotation Direction forward
Rotating backward	Signal: Rotation Direction reverse

Direct Commands of the Motor Start Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
EmergOverHMI	Emergency override through front display Only available if: EmgOvr = active	inactive, active	inactive	[Operation / Reset/Acknowledge /EmgOvr]
RstForcedStart	Reset Forced Start flag	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]

Motor Start Module Counter Values

Value	*Description*	*Default*	*Size*	*Menu path*
WaitTimeStarts	Wait time between starts remained	0s	0 - 9999999999s	[Operation /Measured Values /Motor]
ColdStartPermit	Number of cold starts remaining	0	0 - 9999999999	[Operation /Measured Values /Motor]
StartPerHour	StartPerHour	0	0 - 9999999999	[Operation /Measured Values /Motor]
SPH Release	In case that the Motor is blocked by a SPH blocking, this timer needs to be expired before the blocking is released and the next motor start is permitted. The next Motor Start will increment the SPH counter again.	0min	0 - 9999999999 min	[Operation /Measured Values /Motor]
AntiBackSpin	Anti-BackspinTimer	0s	0 - 9999999999s	[Operation /Measured Values /Motor]
IL1 Ib	Measured value: Phase current as multiple of Ib	0Ib	0 - 1000Ib	[Operation /Measured Values /Current RMS]
IL2 Ib	Measured value: Phase current as multiple of Ib	0Ib	0 - 1000Ib	[Operation /Measured Values /Current RMS]
IL3 Ib	Measured value: Phase current as multiple of Ib	0Ib	0 - 1000Ib	[Operation /Measured Values /Current RMS]
I3 P (%Ib) avg	Average RMS current of all 3 phases as percentages of Ib	0Ib	0 - 1000Ib	[Operation /Measured Values /Current RMS]
OCNT	Motor Operation count since last reset.	0	0 - 65535	[Operation /History /OperationsCr]

Value	*Description*	*Default*	*Size*	*Menu path*
HighestStartI	Highest starting phase current. The time stamp indicates the point in time when the maximum current has occurred.	0A	0 - 99999999A	[Operation /History /OperationsCr]
HighestRunI	Highest running phase current. The time stamp indicates the point in time when the maximum current has occurred.	0A	0 - 999999A	[Operation /History /OperationsCr]
nEmrgOvr	Number of emergency overrides since last reset.	0	0 - 65535	[Operation /History /OperationsCr]
nISQT	Number of incomplete sequence trips since last reset.	0	0 - 65535	[Operation /History /TripCmdCr]
nSPHBlocks	Number of start per hour blocks since last reset.	0	0 - 65535	[Operation /History /TripCmdCr]
nTBSBlocks	Number of time between start blocks since last reset.	0	0 - 65535	[Operation /History /TripCmdCr]
nTRNTrips	Number of transition trips since last reset.	0	0 - 65535	[Operation /History /TripCmdCr]
nZSWTrips	Number of zero speed switch trips since last reset.	0	0 - 65535	[Operation /History /TripCmdCr]
nRevTrips	Number of reverse spinning trips since last reset.	0	0 - 65535	[Operation /History /TripCmdCr]
TOCS	Total Motor Operation count since last reset.	0	0 - 65535	[Operation /History /TotalCr]

Motor Start Module Values

Value	*Description*	*Menu path*
I3 PRMS avg	Average RMS current of all 3 phases	[Operation /Measured Values /Current RMS]
RunTime	Motor Operation time since last reset.	[Operation /History /OperationsCr]
Highest%I2/I1	Highest %I2/I1 value since last reset. The time stamp indicates the point in time when the maximum unbalanced load has occurred.	[Operation /History /OperationsCr]
TRunTime	Motor Operation (Motor run time) time since last reset.	[Operation /History /TotalCr]

Motor Start Module Statistics

Value	*Description*	*Menu path*
IL1 max Ib	IL1 maximum value as multiple of Ib	[Operation /Statistics /Max /Current]
IL1 avg Ib	IL1 average value as multiple of Ib	[Operation /Statistics /Demand /Current Demand]
IL1 min Ib	IL1 minimum value as multiple of Ib	[Operation /Statistics /Min /Current]
IL2 max Ib	IL2 maximum value as multiple of Ib	[Operation /Statistics /Max /Current]
IL2 avg Ib	IL2 average value as multiple of Ib	[Operation /Statistics /Demand /Current Demand]

Value	Description	Menu path
IL2 min Ib	IL2 minimum value as multiple of Ib	[Operation /Statistics /Min /Current]
IL3 max Ib	IL3 maximum value as multiple of Ib	[Operation /Statistics /Max /Current]
IL3 avg Ib	IL3 average value as multiple of Ib	[Operation /Statistics /Demand /Current Demand]
IL3 min Ib	IL3 minimum value as multiple of Ib	[Operation /Statistics /Min /Current]
I3P Fla Demand	RMS current of all 3 phases calculated in a fixed demand window as percentages of Ib	[Operation /Statistics /Demand /Current Demand]

Protection elements that might be blocked by the Motor Start Module

These protection elements can be blocked during the motor start.

Name	Description
-.-	No assignment
MStart.Blo-GOCStart	Signal: Ground Instantaneous Overcurrent Start Delay. GOC (Instantaneous Overcurrent) elements are blocked for the time programmed under this parameter
MStart.Blo-IOCStart	Signal: Phase Instantaneous Overcurrent Start Delay. IOC (Instantaneous Overcurrent) elements are blocked for the time programmed under this parameter
MStart.Blo-I<Start	Signal: Underload Start Delay. Underload(Instantaneous Overcurrent) elements are blocked for the time programmed under this parameter
MStart.Blo-JamStart	Signal: JAM Start Delay. JAM(Instantaneous Overcurrent) elements are blocked for the time programmed under this parameter
MStart.Blo-I2>Start	Signal: Motor start block current unbalance signal
MStart.Blo-Generic1	Generic Start Delay. This value can be used to block any protective element.1
MStart.Blo-Generic2	Generic Start Delay. This value can be used to block any protective element.2
MStart.Blo-Generic3	Generic Start Delay. This value can be used to block any protective element.3
MStart.Blo-Generic4	Generic Start Delay. This value can be used to block any protective element.4
MStart.Blo-Generic5	Generic Start Delay. This value can be used to block any protective element.5

Name	*Description*
MStart.Blo-U2>	Signal: Motor start block voltage unbalance signal.
MStart.Blo-UnderV Start	Signal: Undervoltage Start Delay. Undervoltage elements are blocked for the time programmed under this parameter
MStart.Block-OverVStart	Signal: Overvoltage Start Delay. Overvoltage elements are blocked for the time programmed under this parameter
MStart.Blo-PowerStart	Signal: Power Start Delay. Power elements are blocked for the time programmed under this parameter
MStart.Blo-PFacStart	Signal: Power Factor Start Delay. Power Factor elements are blocked for the time programmed under this parameter
MStart.Blo-FrqStart	Signal: Frequency Start Delay. Frequency elements are blocked for the time programmed under this parameter

I< - Undercurrent [37]

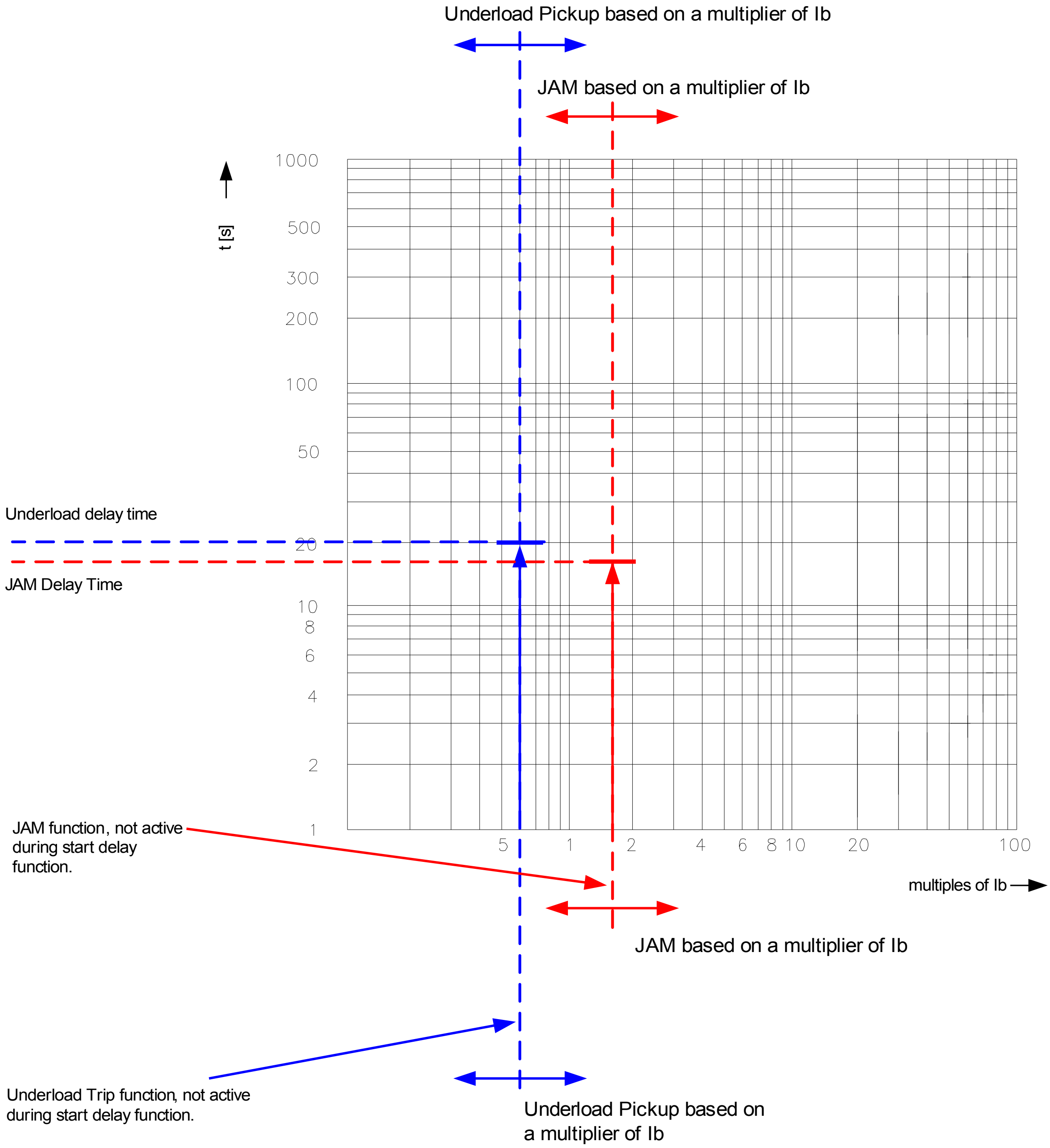
Available Elements:
I<[1] ,I<[2] ,I<[3]

Functional Description

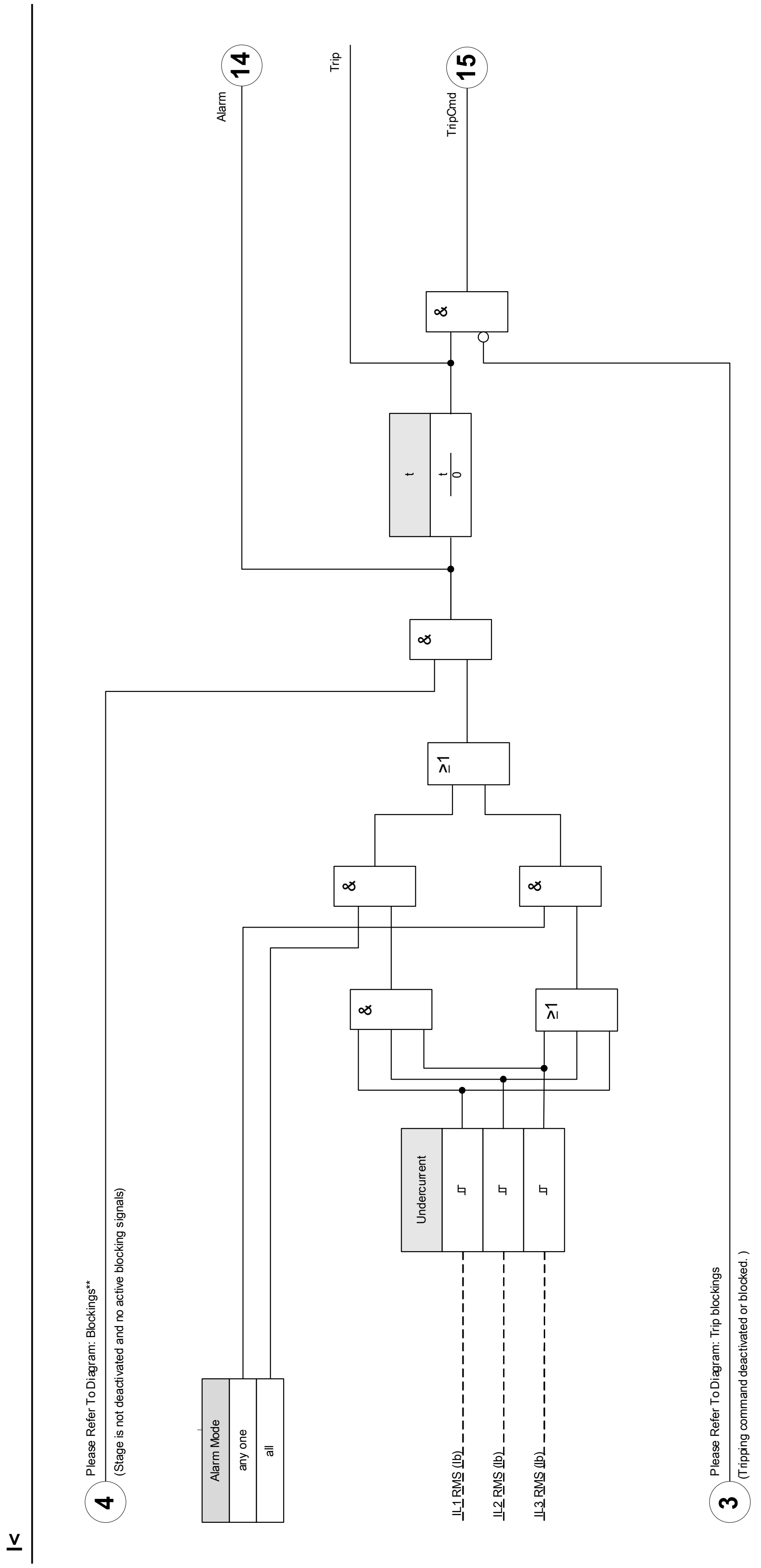
When the motor is running, a current reduction might indicate a malfunction in the load. *Underload* protection recognizes mechanical problems, such as a blocked flow or loss of back pressure in a pump, or a broken drive belt or drive shaft.

Refer to the underload protection limit - the left vertical line in the "Underload and Jam Trip Function example". In the example, the underload trip is set at 60% of Ib (FLA). The protective device can be configured for underload alarm (if the trip command is blocked) and underload trip .

Underload and JAM Trip Function



These would be represented by two such vertical lines, both below the normal load current. Be sure to set the alarm level ***above*** the trip level. Each element has its own delay timer. Use the start delay to block tripping until the load stabilizes after a start. Use run delays to avoid nuisance alarms or trips for load transients.


I<
4
Please Refer To Diagram: Blockings**
(Stage is not deactivated and no active blocking signals)
Alarm Mode
any one
all
IL1 RMS (Ib)
IL2 RMS (Ib)
IL3 RMS (Ib)
Undercurrent
&
≥1
t
3
Please Refer To Diagram: Trip blockings
(Tripping command deactivated or blocked.)
Alarm
14
Trip
TripCmd
15

Device Planning Parameters of the Underload Module

Parameter	*Description*	*Options*	*Default*	*Menu path*
Mode	Mode	do not use, use	I<[1]: use I<[2]: do not use I<[3]: do not use	[Device planning]

Global Protection Parameters of the Underload Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ExBlo1	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /Underload-Prot /I<[1]]
ExBlo2	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /Underload-Prot /I<[1]]
ExBlo dur. Mot.Strt	External blocking of the module, if the state of the assigned signal is true. This way it is possible to block the module during the motor start phase.	1..n, Trip Cmds	MStart.Blo-I<Start	[Protection Para /Global Prot Para /Underload-Prot /I<[1]]
ExBlo TripCmd	External blocking of the Trip Command of the module/the stage, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /Underload-Prot /I<[1]]

Setting Group Parameters of the Underload Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[Protection Para /<1..4> /Underload-Prot /I<[1]]
ExBlo Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /Underload-Prot /I<[1]]
Blo TripCmd	Permanent blocking of the Trip Command of the module/stage.	inactive, active	inactive	[Protection Para /<1..4> /Underload-Prot /I<[1]]
ExBlo TripCmd Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo TripCmd Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /Underload-Prot /I<[1]]
Undercurrent	Underload Pickup based on a multiplier of Ib	0.05 - 0.90Ib	0.50Ib	[Protection Para /<1..4> /Underload-Prot /I<[1]]
Alarm Mode	Indicates if one, two of three or all phases are required for operation	any one, all	any one	[Protection Para /<1..4> /Underload-Prot /I<[1]]
t	Tripping delay	0.4 - 1200.0s	10.0s	[Protection Para /<1..4> /Underload-Prot /I<[1]]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
MeasCircSv Curr	Measuring Circuit Supervision Curent	inactive, active	inactive	[Protection Para /<1..4> /Underload-Prot /I<[1]]

Underload Module Input States

Name	*Description*	*Assignment via*
ExBlo1-I	Module input state: External blocking1	[Protection Para /Global Prot Para /Underload-Prot /I<[1]]
ExBlo2-I	Module input state: External blocking2	[Protection Para /Global Prot Para /Underload-Prot /I<[1]]
ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command	[Protection Para /Global Prot Para /Underload-Prot /I<[1]]

Underload Module Signals (Output States)

Signal	*Description*
active	Signal: active
ExBlo	Signal: External Blocking
Blo TripCmd	Signal: Trip Command blocked
ExBlo TripCmd	Signal: External Blocking of the Trip Command
Alarm	Signal: Alarm
Trip	Signal: Trip
TripCmd	Signal: Trip Command

Underload Module Counter Values

Value	*Description*	*Default*	*Size*	*Menu path*
NumberOfAlarms	Number of alarms since last reset.	0	0 - 9999999999	[Operation /History /AlarmCr]
NumberOfTripCmds	Number of trip commands since last reset	0	0 - 9999999999	[Operation /History /TripCmdCr]

Commissioning: Undercurrent [ANSI 37]

Object to be tested
•Testing the pick-up value for Undercurrent protection
•Testing the trip delay
•Testing the fallback ratio

Necessary means
•3-phase current source
•Ammemeter
•Timer for measuring of the tripping time

Procedure

Testing the threshold values(single-phase, three phase)
Feed in a testing current significantly greater than the pick-up value.
For testing the threshold values and fallback values, the test current has to be decreased until the relay is energized. When comparing the displayed values with those of the ammeter, the deviation must be within the permissible tolerances.

Testing the trip delay
For testing the trip delay, a timer is to be connected to the contact of the associated trip relay. Feed in a testing current significantly greater than the pick-up value, the test current has to be decreased suddenly below the threshold value. The timer is started when the limiting value of the tripping current falls below the threshold and the operating time is elapsed and it is stopped when the relay trips.

Testing the fallback ratio
Enlarge the measuring quantity to more than 103% of the trip value. The relay must only fall back at 103% of the trip value at the earliest.

Successful test result
The measured tripping delays, threshold values and fallback ratio comply with those specified in the adjustment list. Permissible deviations/tolerances can be ftaken from Technical Data.

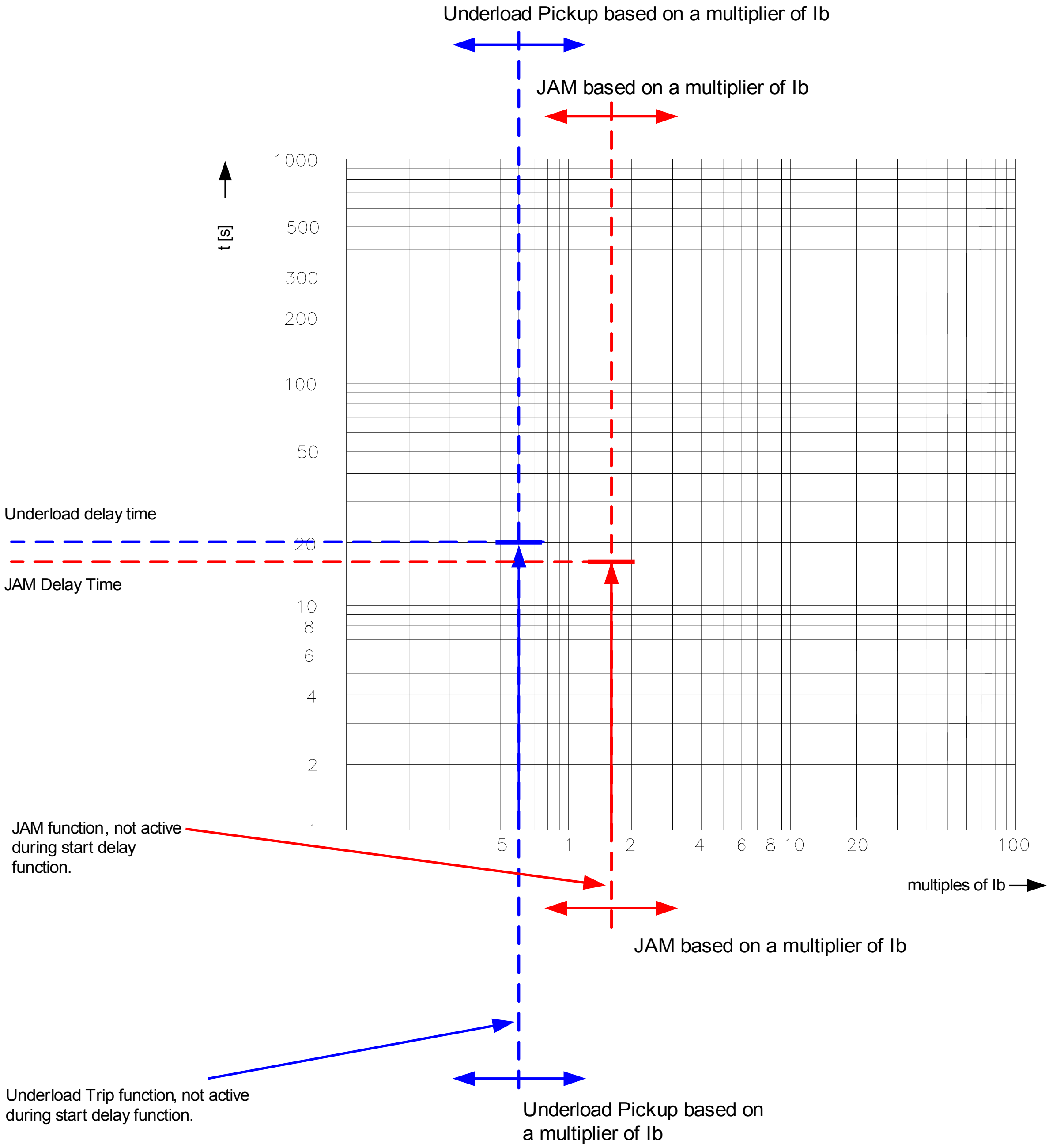
JAM [51LR]

Elements
Jam[1] ,Jam[2]

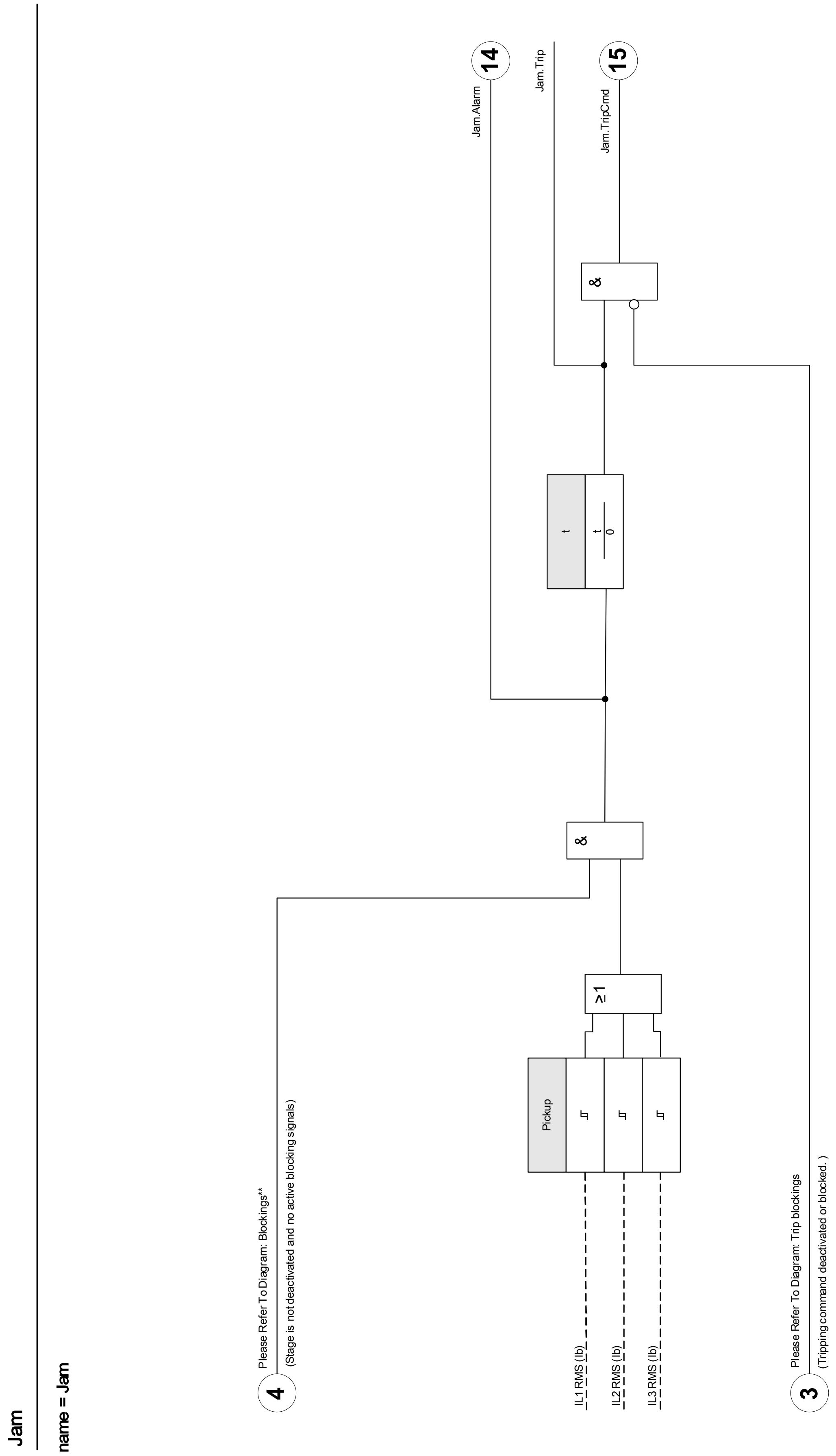
Functional Description

When the motor is running, a current increase above normal load may be an indication of a malfunction in the load. *JAM* protection recognizes mechanical problems, such as broken drive gears. Refer to the *JAM* protection limit (the right vertical line in the "Underload and JAM Trip Function" curve example). In this curve example, the JAM trip is set at 150% of Ib (FLA).

Underload and JAM Trip Function



The protective device issues an alarm when the pickup is exceeded. If the timer has elapsed, a trip signal will be issued. In the "Underload and JAM Trip Function" curve, the »TRIP« settings are represented by vertical lines, well above the normal load current. This curve also applies to JAM setting configured as an alarm element (blocked trip command). The trips are held off by the delay timer »*t*« . Use the start delay to block tripping and alarming until the motor current drops to continuous load level. Use run delays to avoid nuisance alarms or trips for load transients.



Jam
name = Jam
4
Please Refer To Diagram: Blockings**
(Stage is not deactivated and no active blocking signals)
IL1 RMS (Ib)
IL2 RMS (Ib)
IL3 RMS (Ib)
Pickup
≥1
&
t
t
0
Jam.Alarm
14
Jam.Trip
&
Jam.TripCmd
15
3
Please Refer To Diagram: Trip blockings
(Tripping command deactivated or blocked.)

Device Planning Parameters for JAM Protection

Parameter	*Description*	*Options*	*Default*	*Menu path*
Mode	Mode	do not use, use	Jam[1]: use Jam[2]: do not use	[Device planning]

Global Protection Parameters for JAM Protection

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ExBlo1	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /JAM-Prot /Jam[1]]
ExBlo2	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /JAM-Prot /Jam[1]]
ExBlo dur. Mot.Strt	External blocking of the module, if the state of the assigned signal is true. This way it is possible to block the module during the motor start phase.	1..n, Trip Cmds	MStart.Blo-JamStart	[Protection Para /Global Prot Para /JAM-Prot /Jam[1]]
ExBlo TripCmd	External blocking of the Trip Command of the module/the stage, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /JAM-Prot /Jam[1]]

Setting Group Parameters for JAM Protection

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[Protection Para /<1..4> /JAM-Prot /Jam[1]]
ExBlo Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /JAM-Prot /Jam[1]]
Blo TripCmd	Permanent blocking of the Trip Command of the module/stage.	inactive, active	inactive	[Protection Para /<1..4> /JAM-Prot /Jam[1]]
ExBlo TripCmd Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo TripCmd Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /JAM-Prot /Jam[1]]
Pickup	JAM based on a multiplier of Ib	1.00 - 12.00Ib	Jam[1]: 10Ib Jam[2]: 10.00Ib	[Protection Para /<1..4> /JAM-Prot /Jam[1]]
t	Tripping delay	0.0 - 1200.0s	2.0s	[Protection Para /<1..4> /JAM-Prot /Jam[1]]

JAM Protection Module Input States

Name	*Description*	*Assignment via*
ExBlo1-I	Module input state: External blocking1	[Protection Para /Global Prot Para /JAM-Prot /Jam[1]]
ExBlo2-I	Module input state: External blocking2	[Protection Para /Global Prot Para /JAM-Prot /Jam[1]]
ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command	[Protection Para /Global Prot Para /JAM-Prot /Jam[1]]

JAM Protection Signals (Output States)

Signal	*Description*
active	Signal: active
ExBlo	Signal: External Blocking
Blo TripCmd	Signal: Trip Command blocked
ExBlo TripCmd	Signal: External Blocking of the Trip Command
Alarm	Signal: Alarm
Trip	Signal: Trip
TripCmd	Signal: Trip Command

JAM Protection Values

Value	*Description*	*Default*	*Size*	*Menu path*
NumberOfAlarms	Number of alarms since last reset.	0	0 - 9999999999	[Operation /History /AlarmCr]
NumberOfTripCmds	Number of trip commands since last reset	0	0 - 9999999999	[Operation /History /TripCmdCr]

Commissioning: JAM [51LR]

Object to be tested
•Testing the pick-up value for JAM protection
•Testing the trip delay
•Testing the fallback ratio

Necessary means
•3-phase current source
•Ammeter
•Timer for measuring of the tripping time

Procedure

Testing the threshold values(single-phase)
Feed in a testing current significantly smaller than the pick-up value.
For testing the threshold values and fallback values, the test current has to be increased until the relay is energized. When comparing the displayed values with those of the ammeter, the deviation must be within the permissible tolerances.

Testing the tripping delay
For testing the trip delay, a timer is to be connected to the contact of the associated trip relay. Feed in a testing current significantly smaller than the pick-up value, the test current has to be increased suddenly above the threshold value. The timer is started when the limiting value of the tripping current exceeded the threshold and the operating time is elapsed and it is stopped when the relay trips.

Testing the fallback ratio
Enlarge the measuring quantity to less than 97% of the trip value. The relay must only fall back at 98% of the trip value at the earliest.

Successful test result
The measured tripping delays, threshold values and fallback ratio comply with those values, specified in the adjustment list. Permissible deviations/tolerances can be found under Technical data.

LRC - Locked Rotor during Start

Functional Description

The Locked-rotor protection function is an integral part of the thermal model and is used to protect the motor in the event that the motor fails to start or accelerate after being energized. The heating in the motor during this period of time can behigher significantly than the heating at rated current, ranging from 10 to 50 times the normal rated heating. The time that a motor can remain at a standstill after being energized varies with the applied voltage and has an I^2T limit.

When determining the heat in the motor during this period of time, both the negative and positive sequence currents are used in the equation that approximates the heat generated in a locked rotor condition. The heat can be approximated by the equation:

$$I^2_H = I_1^2 + K\, I_2^2$$

where :

I_1	=	the per unit stator positive sequence current;
K	=	weighting factor for the value of I_2 resulting from the disproportionate heating caused by the negative sequence current component due to skin effect in the rotor bar; and
I_2	=	per unit stator negative sequence current.

Settings for the Locked Rotor Current can be found under the [Field Parameters]. The LRC value is a multiplier of Ib (FLA).

MLS - Mechanical Load Shedding

Available elements:
MLS

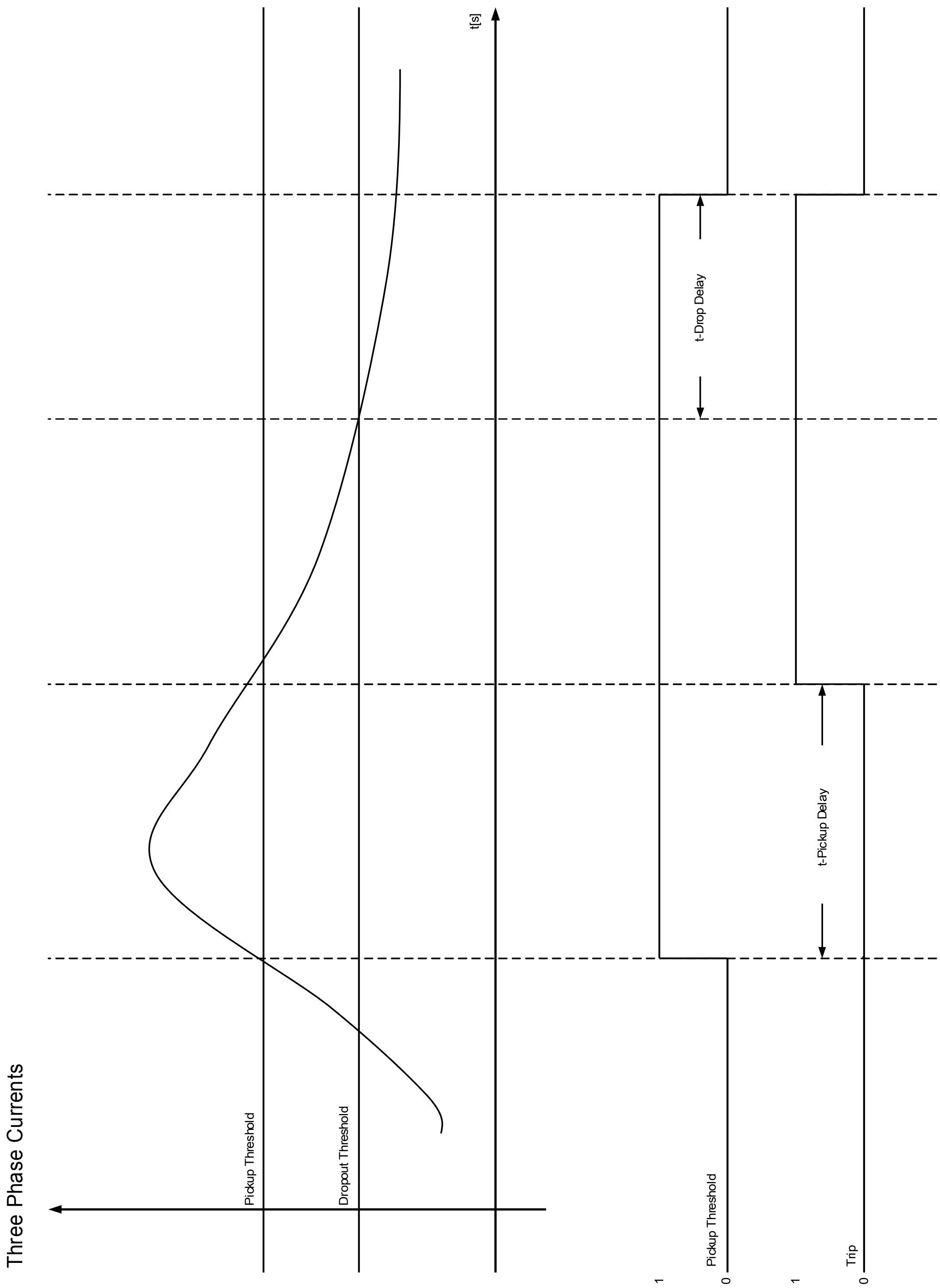
Functional Description

In some applications, the protective device can forestall a JAM alarm or trip, or a thermal trip, by sending a signal to the process to reduce loading. The load-shedding function, if enabled, closes or opens a relay contact to shed process load when the motor load current goes above the Load-shed threshold, for a time exceeding the »*t-Pickup Delay*«. The pickup-delay can be used to stop or reduce the flow of material into the driven process until the load current falls below the threshold. The »*t-Drop Delay*« is the timer that has to elapse before the normal flow of material will be fed again into the process.

Set the load-shed drop current comfortably below the JAM trip level. It may be useful to set it below the Ultimate Trip Current, particularly if Remote Temperature Detection is not used.

The load shed function is only active during the »RUN« state of the motor.

Note : Load Shedding function is only active when motor is in RUN mode.



Device Planning Parameters of the Load Shedding

Parameter	*Description*	*Options*	*Default*	*Menu path*
Mode	Mode	do not use, use	use	[Device planning]

Global Protection Parameters of the Load Shedding

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ExBlo1	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /MLS]
ExBlo2	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /MLS]

Setting Group Parameters of the Load Shedding

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[Protection Para /<1..4> /MLS]
ExBlo Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /MLS]
Pickup Threshold	Mechanical load shedding pickup current as multiplier of Ib	0.50 - 1.50Ib	0.90Ib	[Protection Para /<1..4> /MLS]
t-Pickup Delay	Trip delay time	0.0 - 5.0s	1.0s	[Protection Para /<1..4> /MLS]
Dropout Threshold	Mechanical load reclosure current (Dropout of Load shedding) as multiplier of Ib	0.50 - 1.50Ib	0.50Ib	[Protection Para /<1..4> /MLS]
t-Drop Delay	Dropout delay time	0.0 - 5.0s	1.0s	[Protection Para /<1..4> /MLS]

Load Shedding Input States

Name	*Description*	*Assignment via*
ExBlo1-I	Module input state: External blocking1	[Protection Para /Global Prot Para /MLS]
ExBlo2-I	Module input state: External blocking2	[Protection Para /Global Prot Para /MLS]

Load Shedding Signals (Output States)

Signal	*Description*
active	Signal: active
ExBlo	Signal: External Blocking
Alarm	Signal: Alarm
Trip	Signal: Trip

Commissioning: Mechanical Load Shedding

Object to be tested
•Testing the pick-up and drop-out tresholds
•Testing the delay times

Necessary means
•3-phase current source
•Ammemeter
•Timer for measuring of the tripping times

Procedure

Testing the threshold values (three-phase)
This test is only possible, if the motor is in run mode.

Testing pick-up threshold
The drop-out delay time should be “0s” for this test.
Feed in a testing current significantly lower than the threshold of the mechanical load shedding. The test current has to be increased until the relay is energized. When comparing the measured values with those of the ammeter, the deviation must be within the permissible tolerances.

Testing drop-out threshold
For testing the drop-out threshold the testing current has to be significantly greater than the pick-up threshold value. The test current has to be decreased until the relay is falls back. When comparing the measured values with those of the ammeter, the deviation must be within the permissible tolerances.

Testing the delay times
This test is only possible, if the motor is in run mode.

Testing the trip delay
For testing the pick-up delay , a timer is to be connected to the contact of the associated trip relay. Feed in a testing current significantly lower than the pick-up value, the test current has to be increased suddenly above the threshold. The timer is started when the limiting value of the tripping current exceeded the threshold and it is stopped when the relay trips and the operating time is elapsed.

Testing the drop-out delay
For testing the drop-out threshold, the testing current has to be significantly greater than the pick-up threshold. A timer is to be connected to the contact of the associated trip relay. The test current has to be decreased suddenly below the drop-out threshold. The timer has to be started when the limiting value of the tripping current falls below the threshold and it has to be stopped when the relay falls back.

Successful test result
The measured tripping delays and threshold values comply with those values, specified in the adjustment list. Permissible deviations/tolerances can be found under Technical data.

UTC - Ultimate Trip Current

Functional Description

The Ultimate Trip Current (UTC) sets the current level at which a trip eventually occurs and is settable to a value as a multiples of »*Ib*« (Full Load Amps (FLA)). This value represents the vertical line on the upper portion of the non-RTD as shown in the protection trip curve labeled “Motor Protection Curve Example 2 (without RTD)”. The ultimate trip current setting in this example is at 1 times the of »*Ib*« (FLA).

The user has to set the k-Factor which can be calculated by the following formula:

$$k_{Factor} = \frac{UTC}{CT_{PRI}} = \frac{Overload_{factor} \cdot I_b}{CT_{PRI}}$$

Please note that the settings for k-Factor and Ib have to be set within the *Field Parameter* menu.

The »Overload *Factor*« is found on the motor nameplate or in the manufacturer’s data. Note that the relay does not trip at the moment the current goes above »*UTC«* during motor running. Instead, it models the gradual stator heating for currents above »*UTC*« , and trips only after some time has passed. The trip time depends on a variety of setting and operating factors, including the motor nameplate data contained in other setting values.

Use a conservative value. In this case, a lower value of »UTC« than that dictated by the »*k-Factor*« if the motor ambient temperatures may rise above 40ºC (104ºF) and the optional *URTD* Module is not used, otherwise stator insulation damage or loss of motor life may occur. Also, consider lowering the »*UTC*« value if the motor is suitably rated, yet additional safety is critical for the application.

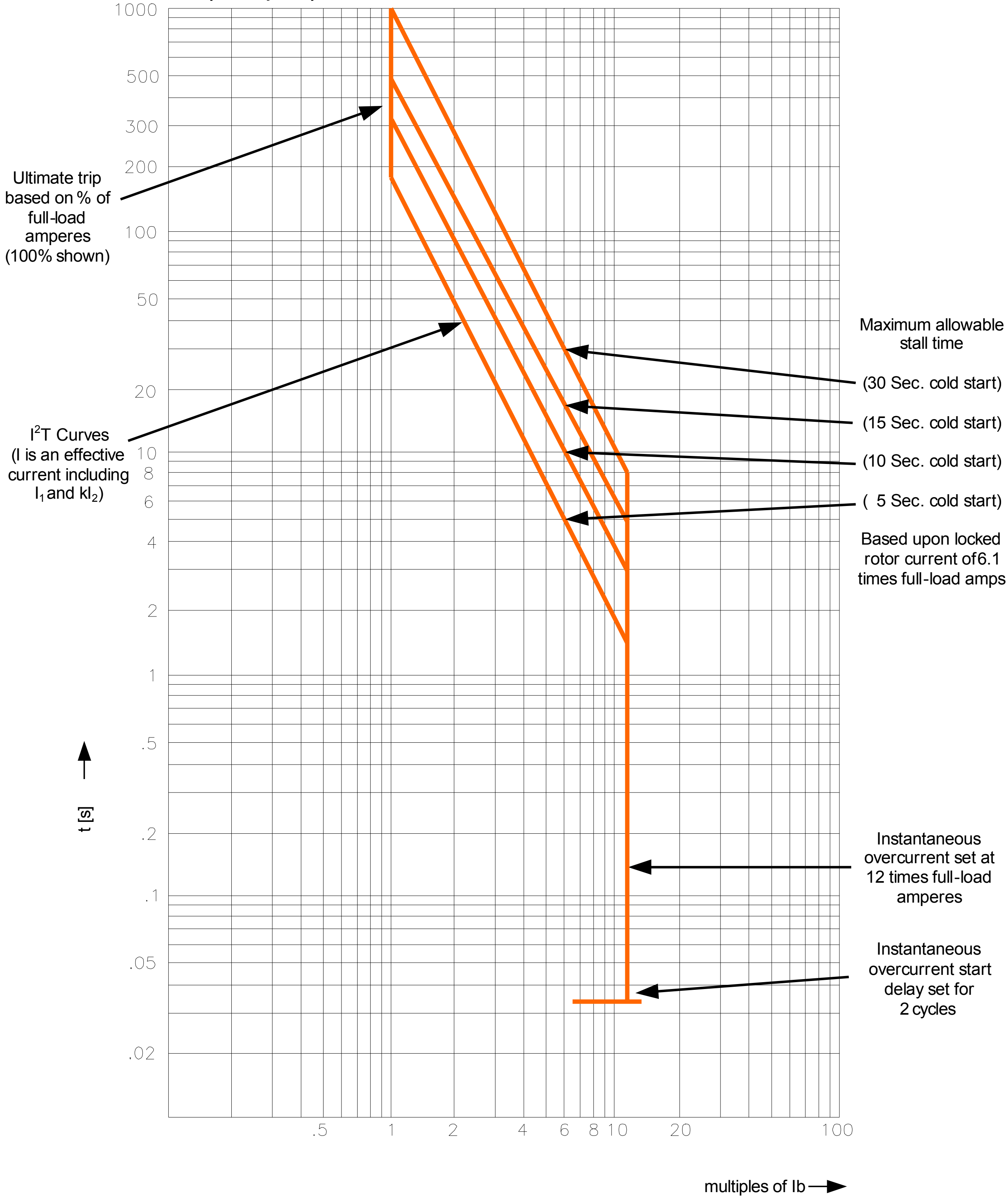
CAUTION **If UTC is set above 100% times the service factor, motor damage could result.**

In systems where an RTD is used the »*UTC*« pick-up point is biased by the measured temperature. This is shown in the example trip curve labeled “Motor Protection Curve Example 3” (with RTD) were you will see a shift in the »*UTC*« value to 2 times of »*Ib«* (FLA)

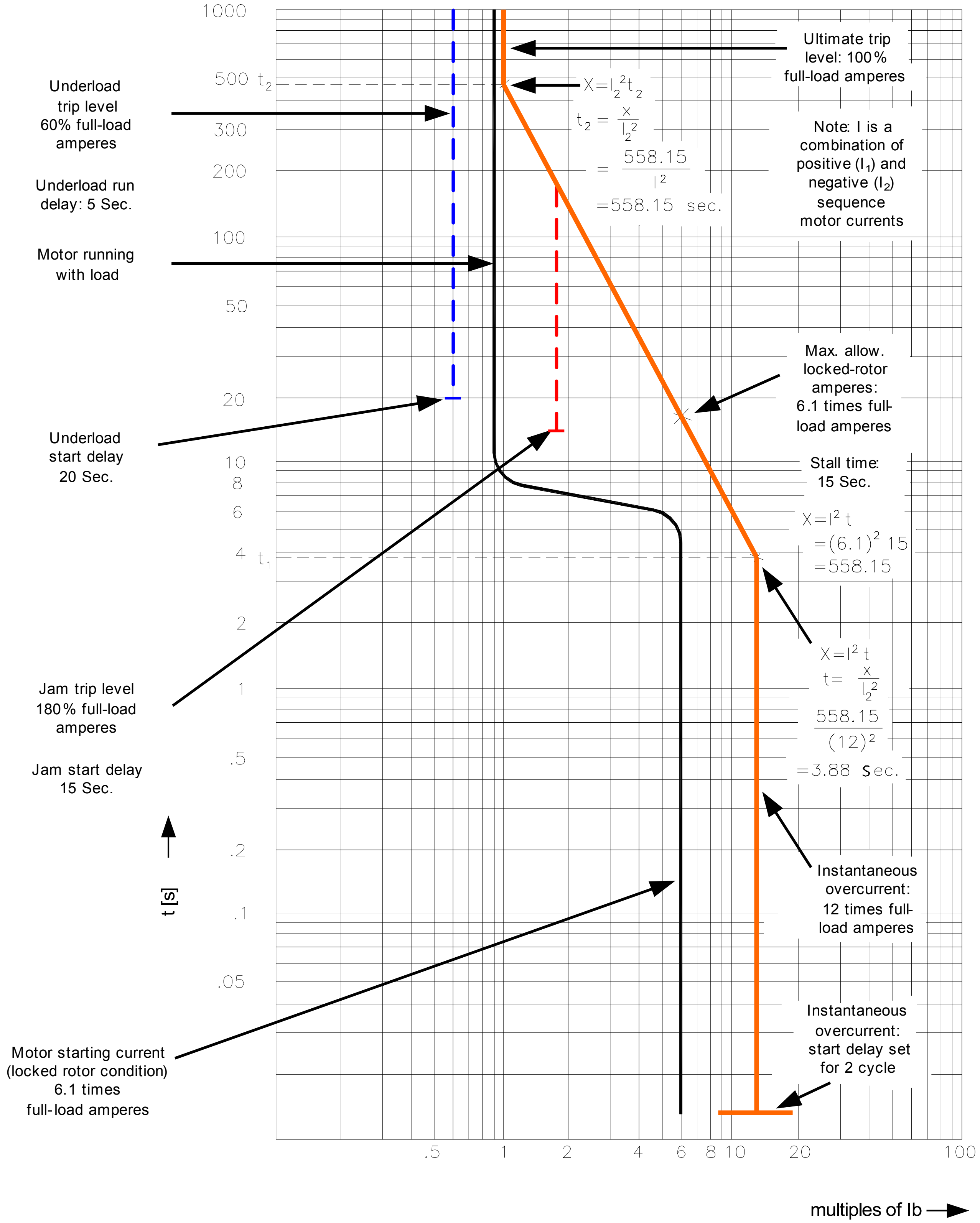
If stator temperature measurements are available, the algorithm may keep from tripping, even if the effective current is above the ultimate trip current setting, depending on stator temperature reports. It is still important to set a correct ultimate trip current so that the motor is well protected. If the RTDs, the module, or its communications to the relay fail, the algorithm falls back to use of »UTC«. Also, note that if all RTD channels are set to »*OFF*«, the algorithm reverts to the non-RTD calculation, which is based strictly on »*UTC*« .

Motor Protection Curves

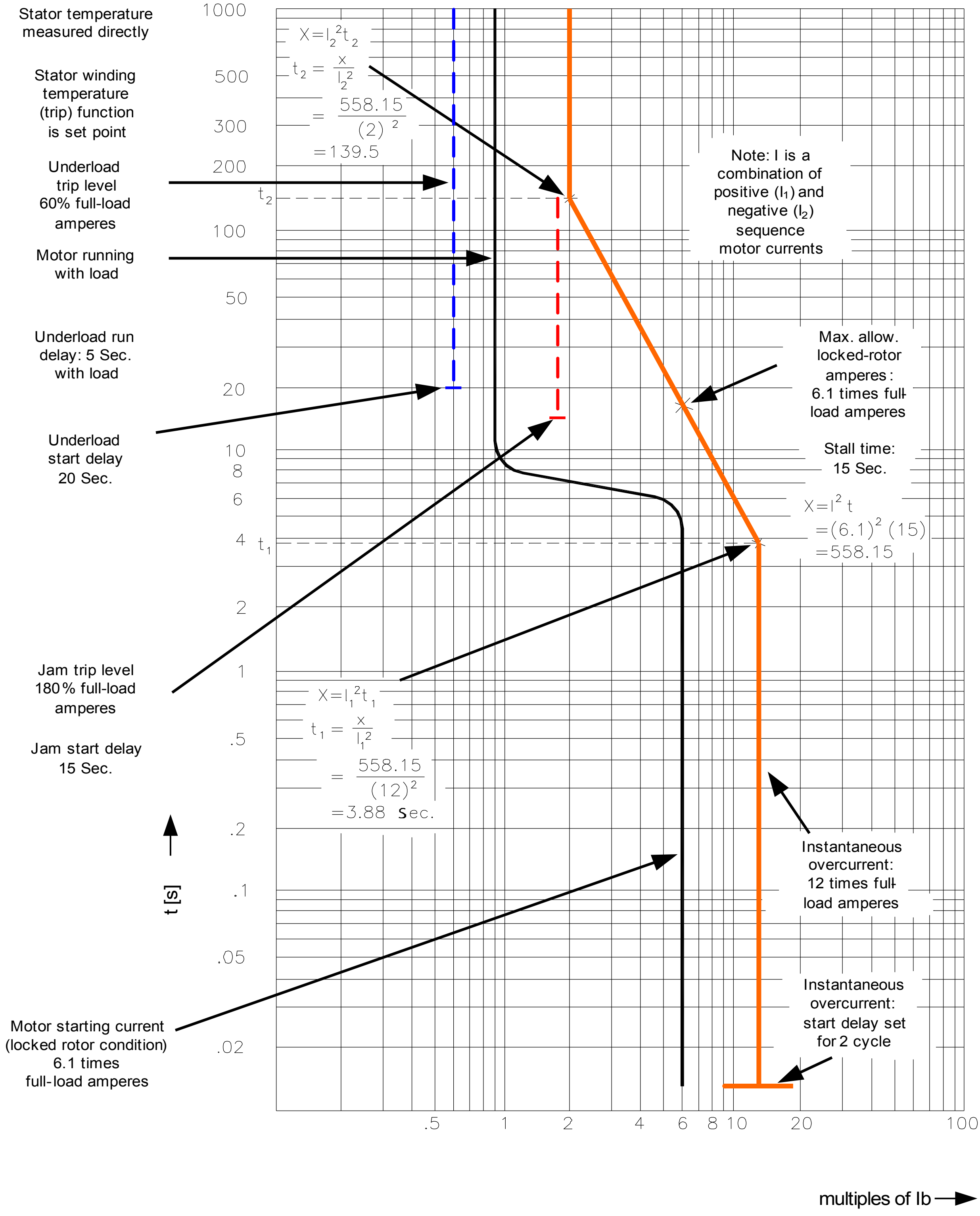
Motor Protection Curve (Example 1)



Motor Protection Curve (Example 2 - without RTDs)



Motor Protection Curve (Example 3 - with RTDs)



I>> - IOC Function

The instantaneous overcurrent function (IOC) or 50P is intended to protect in the event of a high-current fault. The example IOC setting used in the Motor Protection Curve (see the Motor Protection Curve Examples in the Ultimate Trip Current Section) is 12 times (1,200%) of FLA. In general the instantaneous IOC should be at least 1.5 times LRC (Locked Rotor Current), well above the locked rotor current that is normally seen at the moment of a start.

IOC should trip fast and therefore no run or pickup delay is provided. A start delay is set at a minimum of 0.03 sec or more if needed to block IOC tripping on magnetizing inrush when the motor is first energized. An additional IOC tripping delay setting is set at a default of zero seconds.

IOC Trip Level

The IOC sets the instantaneous overcurrent trip limit in percentage of »*Ib*« (FLA) above at which the relay trips. This trip type can be set to inactive to deactivate this protective device element. For currents clearly above the setting, the IOC function picks up in 1.5 power cycles or less (at 50 Hz).

IOC Start Delay (IOCSD)

This setting sets the number of power cycles after a start is recognized until the IOC trip and alarm functions are enabled. Use this delay to inhibit IOC tripping on a current peak caused by magnetic inrush when the motor is first energized (usually two to three cycles).

I - Overcurrent Protection [50, 51,51Q, 51V*]

Available stages:
I[1] ,I[2] ,I[3] ,I[4] ,I[5] ,I[6]

WARNING **If you are using inrush blockings the tripping delay of the current protection functions must be at least 30ms or more in order to prevent faulty trippings.**

NOTICE **All overcurrent protective elements are identically structured.**

NOTICE **This module offers Adaptive Parameter Sets.**
Parameters can be modified within parameter sets dynamically by means of Adaptive Parameter Sets.
Please refer to chapter Parameter / Adaptive Parameter Sets.

The following table shows the application options of the Overcurrent Protection element

Applications of the I-Protection Module	Setting in	Option
ANSI 50 – Overcurrent protection, non-directional	Device Planning menu	Measuring Mode: Fundamental/TrueRMS/negative phase sequence current (I2)
ANSI 51 – Short circuit protection, non-directional	Device Planning menu	Measuring Mode: Fundamental/TrueRMS/negative phase sequence current (I2)

ANSI 51V – Voltage restraint overcurrent protection*	Parameter Set: VRestraint = active	Measuring Mode: Fundamental/TrueRMS/negative phase sequence current (I2) Measuring Channel: Phase to Phase/Phase to Neutral
ANSI 51Q Negative Phase Sequence Overcurrent Protection	Parameter Set: Measuring Method =I2 (Negative Sequence Current)	
51C Voltage controlled overcurrent protection* (**Please refer to the chapter Parameter/Adaptive Parameter**)	Adaptive Parameters	Measuring Mode: Fundamental/TrueRMS/negative phase sequence current (I2) Measuring Channel: (in voltage protection module) Phase to Phase/Phase to Neutral

*=available only for devices that offer voltage measurement.

Measuring Mode

For all protection elements it can be determined, whether the measurement is done on basis of the »*Fundamental*« or if »*TrueRMS*« measurement is used.

Alternatively the »*Measuring Mode*« can be set to »*I2*«. In this case the negative phase sequence current will be measured. This is to detect unbalanced faults.

*Voltage restraint overcurrent protection 51V**

When the Parameter »*VRestraint*« is set to active the overcurrent protection element works voltage restraint. That means, the overcurrent pickup threshold will be lowered during voltage drops. This results in a more sensitive overcurrent protection. For the voltage threshold »*VRestraint max*« additionally the »*Measuring Channel*« can be determined.

*=available only for devices that offer voltage measurement.

Measuring Channel

With the parameter »*Measuring Channel*« it can be determined, whether the »*Phase to Phase*« voltage or the »*Phase to Neutral*« voltage is measured.

For each element the following characteristics are available:

- DEFT (UMZ) – *Definite Time-Overcurrent*
- NINV (IEC/AMZ) – *IEC Normal Inverse*
- VINV (IEC/AMZ) – *IEC Very Inverse*
- LINV (IEC/AMZ) – *IEC Long Time Inverse*
- EINV (IEC/AMZ) – *IEC Extremely Inverse*
- MINV (ANSI/AMZ) – *ANSI Moderately Inverse*
- VINV (ANSI/AMZ) – *ANSI Very Inverse*
- EINV (ANSI/AMZ) – *ANSI Extremely Inverse*
- RINV – *R Inverse*
- Thermal Flat
- IT
- I2T
- I4T

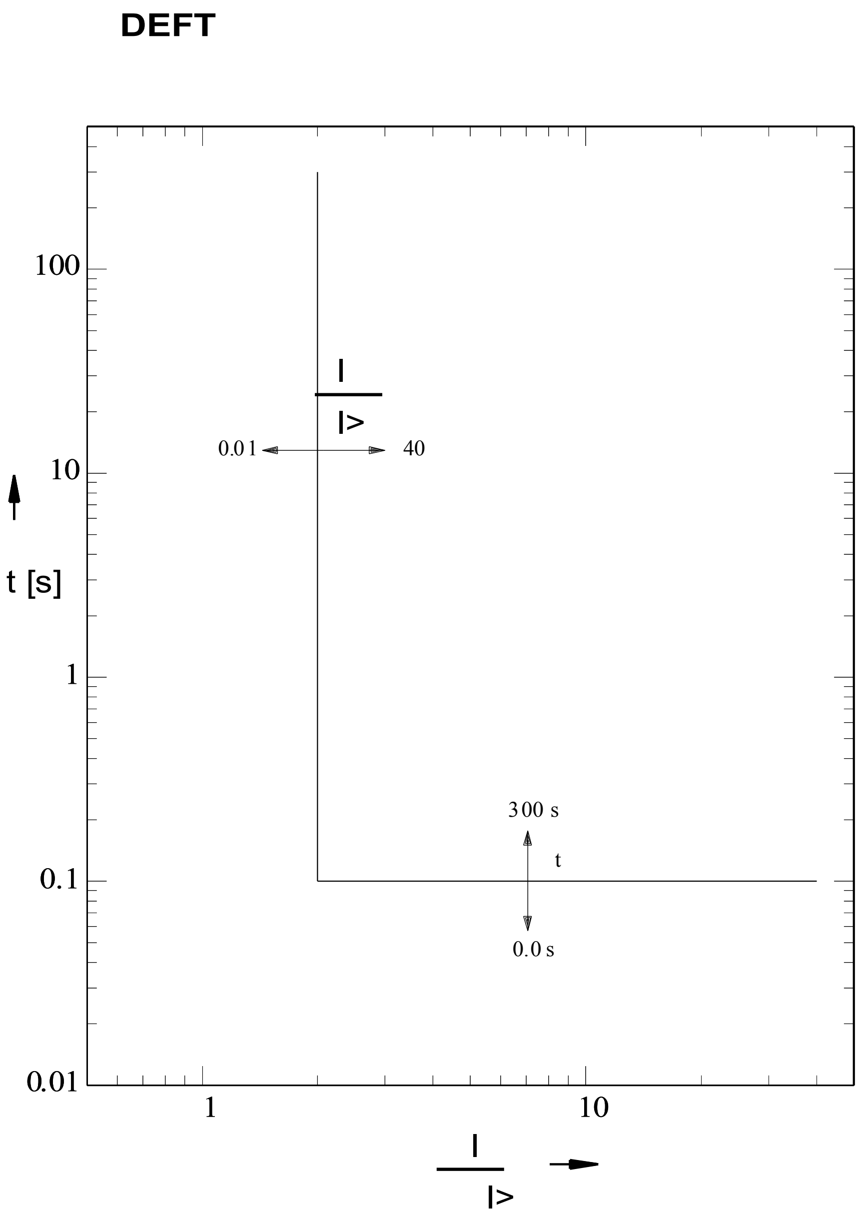
Explanation:

t = Tripping delay

t-char = Time multiplier/tripping characteristic factor. The setting range depends on the selected tripping curve.
I = Fault current

I> = If the pickup value is exceeded, the module/element starts to time out to trip .

DEFT – *Definite Time-Overcurrent*



IEC Normal Inverse

NOTICE **Various reset modes are available: Resetting via characteristic, delayed and instantaneous.**

Remark: For $I > 20 \cdot I_>$, the curve stops decreasing, the t-values are kept constant at the value for $I = 20 \cdot I_>$.

»Char« = IEC NINV

Reset

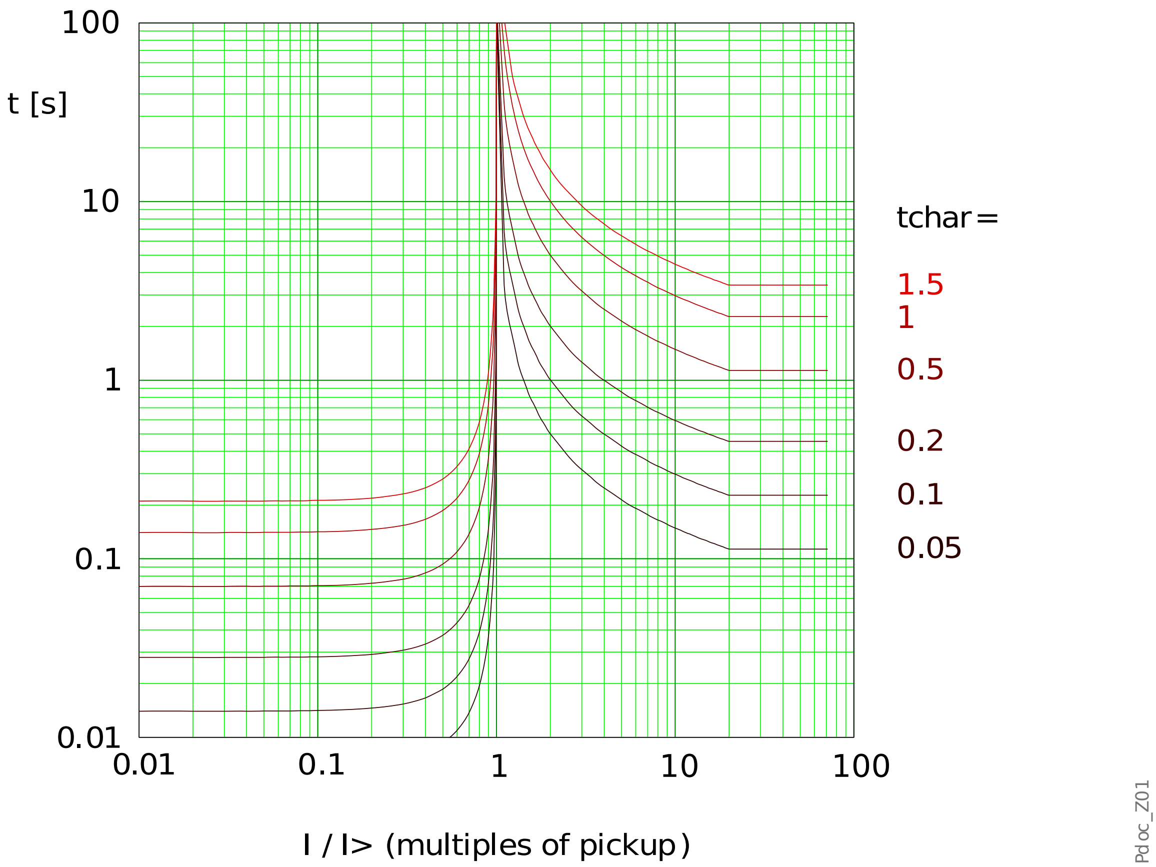
$$t = \frac{0.14}{1-\left(\frac{I}{I>}\right)^2} \cdot tchar$$

If: $\frac{I}{I>} < 1$

Trip

$$t = \frac{0.14}{\left(\frac{I}{I>}\right)^{0.02} - 1} \cdot tchar$$

If: $1 < \frac{I}{I>} \leq 20$



IEC Very Inverse

NOTICE **Various reset modes are available:**
Resetting via characteristic, delayed and instantaneous.

Remark: For $I > 20 \cdot I_>$, the curve stops decreasing, the t-values are kept constant at the value for $I = 20 \cdot I_>$.

»*Char*« = IEC VINV

Reset

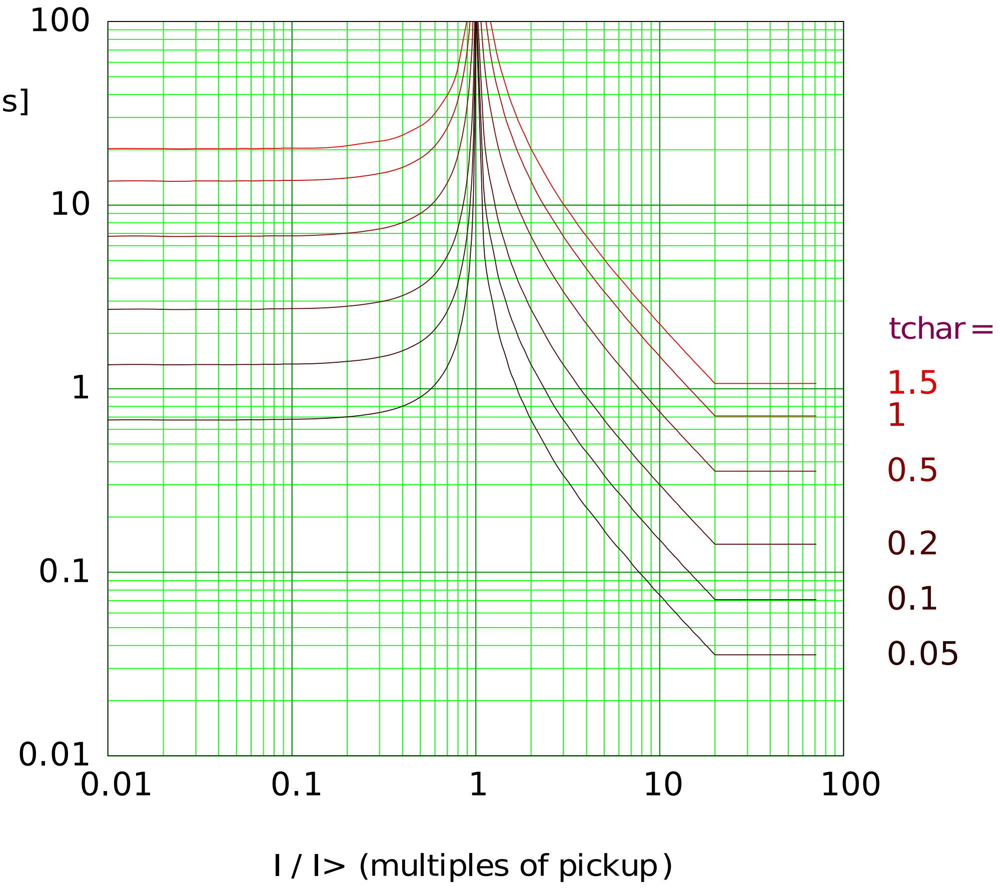
$$t = \frac{13.5}{1 - \left(\frac{I}{I>}\right)^2} \cdot tchar$$

If: $$\frac{I}{I>} < 1$$

Trip

$$t = \frac{13.5}{\frac{I}{I>} - 1} \cdot tchar$$

If: $$1 < \frac{I}{I>} \leq 20$$



Pd oc_Z02

IEC Extremely Inverse

NOTICE **Various reset modes are available:**
Resetting via characteristic, delayed and instantaneous.

Remark: For $I > 20 \cdot I_>$, the curve stops decreasing, the t-values are kept constant at the value for $I = 20 \cdot I_>$.

»*Char*« = IEC EINV

Reset

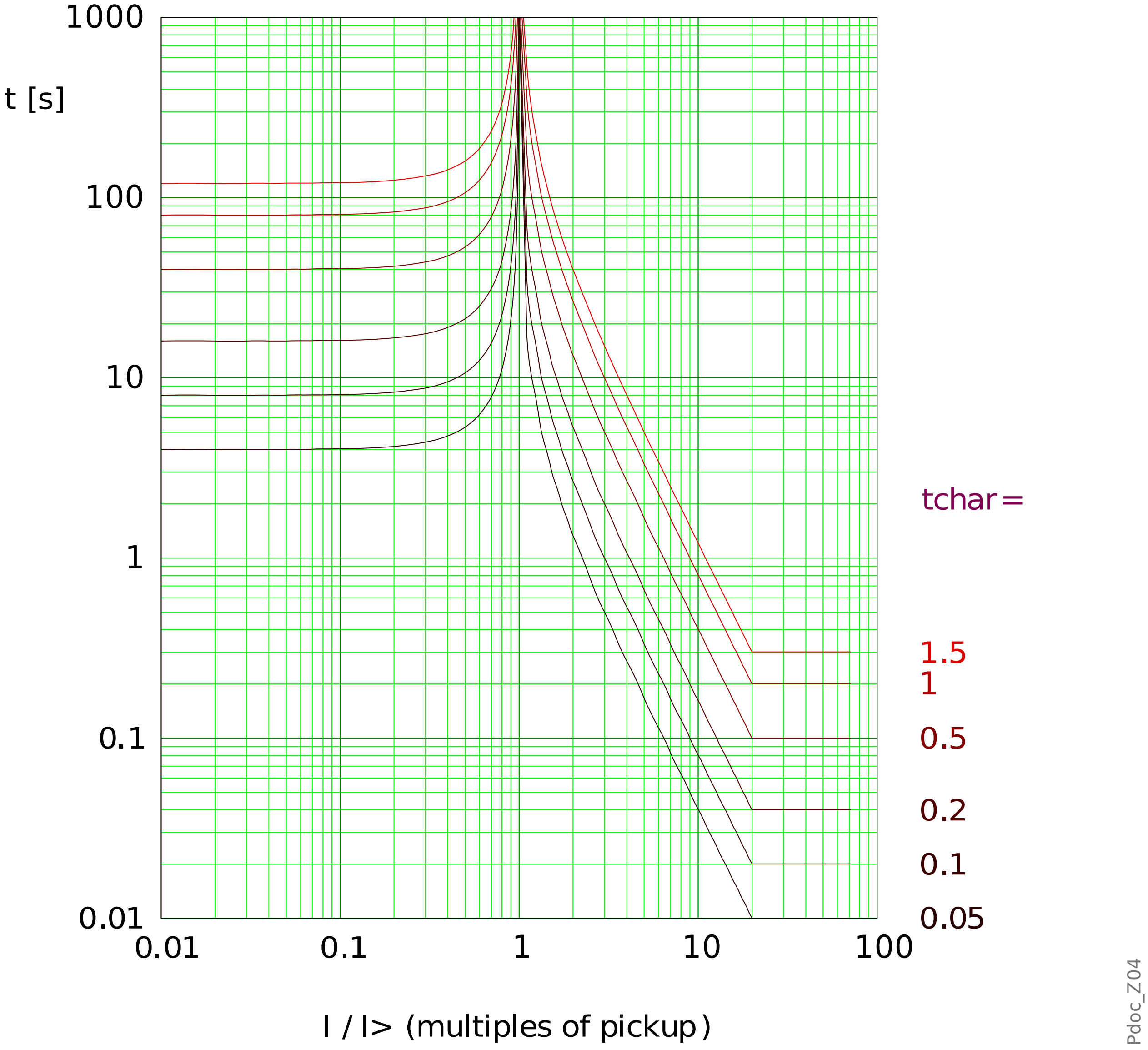
$$t = \frac{80}{1-\left(\frac{I}{I>}\right)^2} \cdot tchar$$

If: $\frac{I}{I>} < 1$

Trip

$$t = \frac{80}{\left(\frac{I}{I>}\right)^2 - 1} \cdot tchar$$

If: $1 < \frac{I}{I>} \leq 20$



IEC Long Time Inverse

NOTICE **Various reset modes are available: Resetting via characteristic, delayed and instantaneous.**

Remark: For $I > 20 \cdot I_>$, the curve stops decreasing, the t-values are kept constant at the value for $I = 20 \cdot I_>$.

»*Char*« = IEC LINV

Reset

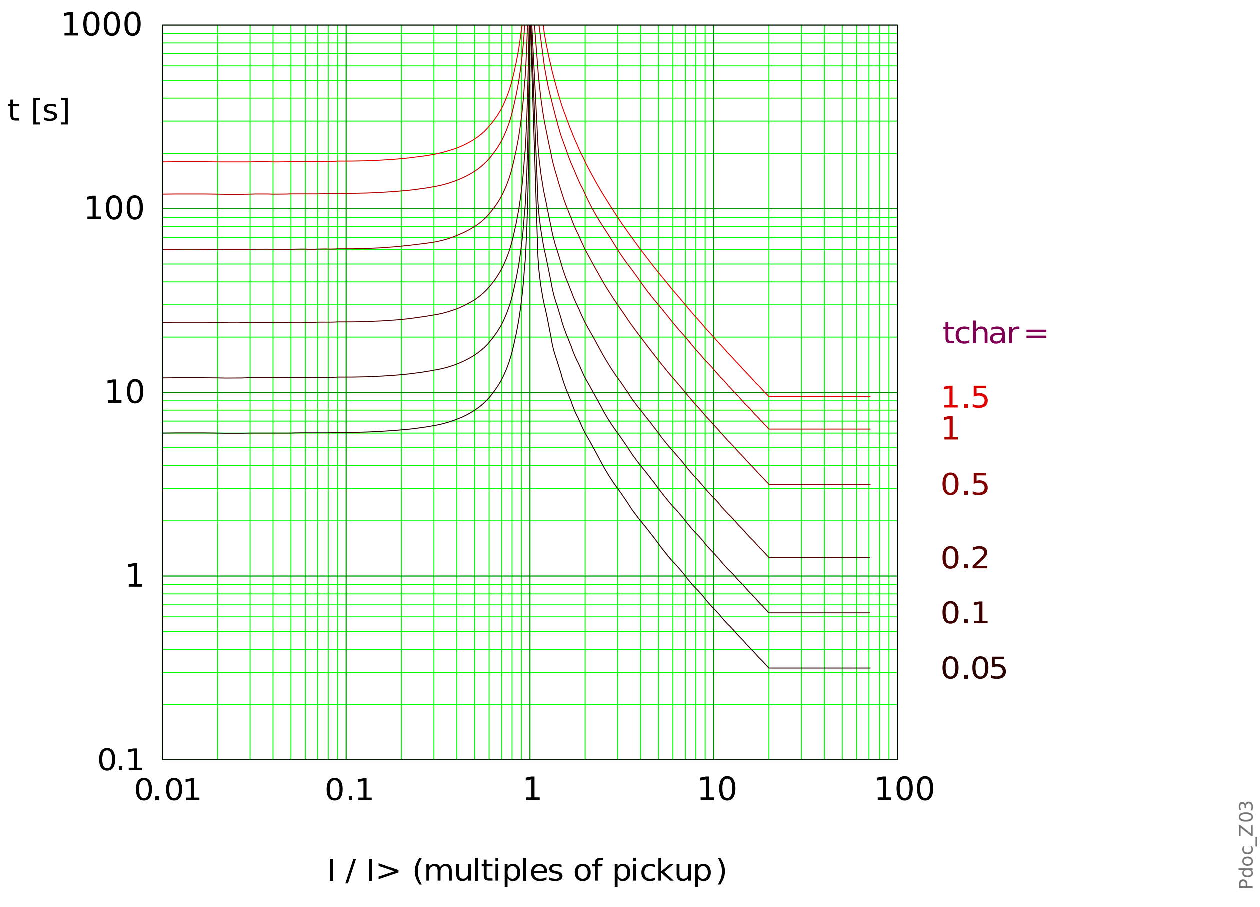
$$t = \frac{120}{1-\left(\frac{I}{I>}\right)^2} \cdot tchar$$

If: $\frac{I}{I>} < 1$

Trip

$$t = \frac{120}{\frac{I}{I>} - 1} \cdot tchar$$

If: $1 < \frac{I}{I>} \leq 20$



ANSI Moderately Inverse

NOTICE **Various reset modes are available:**
Resetting via characteristic, delayed and instantaneous.

Remark: For $I > 20 \cdot I_>$, the curve stops decreasing, the t-values are kept constant at the value for $I = 20 \cdot I_>$.

***»Char«* = ANSI MINV**

Reset

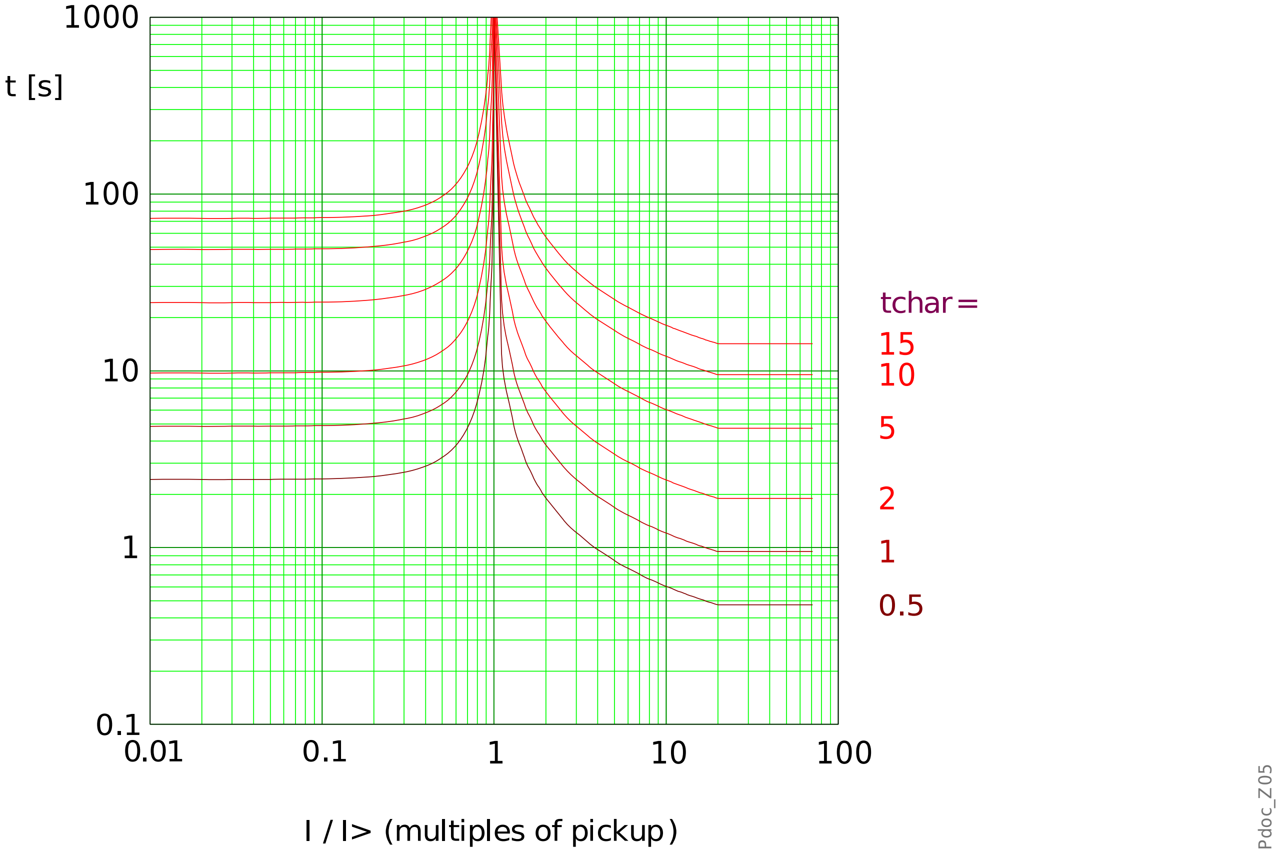
$$t = \frac{4.85}{1-\left(\frac{I}{I>}\right)^2} \cdot tchar$$

If: $\frac{I}{I>} < 1$

Trip

$$t = \left(\frac{0.0515}{\left(\frac{I}{I>}\right)^{0.02} - 1} + 0.1140\right) \cdot tchar$$

If: $1 < \frac{I}{I>} \leq 20$



ANSI Very Inverse

NOTICE **Various reset modes are available:**
Resetting via characteristic, delayed and instantaneous.

Remark: For $I > 20 \cdot I_>$, the curve stops decreasing, the t-values are kept constant at the value for $I = 20 \cdot I_>$.

»Char« = ANSI VINV

Reset

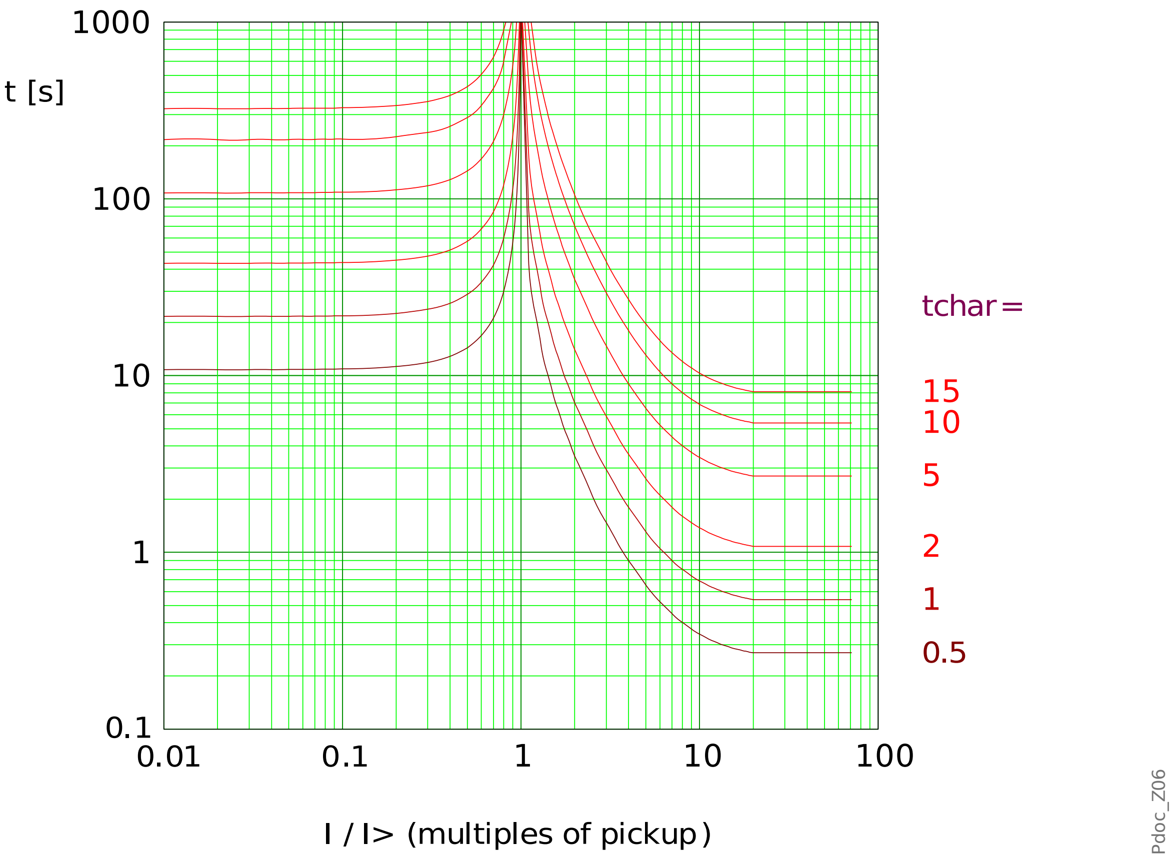
$$t = \frac{21.6}{1-\left(\frac{I}{I>}\right)^2} \cdot tchar$$

If: $\frac{I}{I>} < 1$

Trip

$$t = \left(\frac{19.61}{\left(\frac{I}{I>}\right)^2 - 1} + 0.491\right) \cdot tchar$$

If: $1 < \frac{I}{I>} \leq 20$



ANSI Extremely Inverse

NOTICE **Various reset modes are available:**
Resetting via characteristic, delayed and instantaneous.

Remark: For $I > 20 \cdot I_>$, the curve stops decreasing, the t-values are kept constant at the value for $I = 20 \cdot I_>$.

***»Char«* = ANSI EINV**

Reset

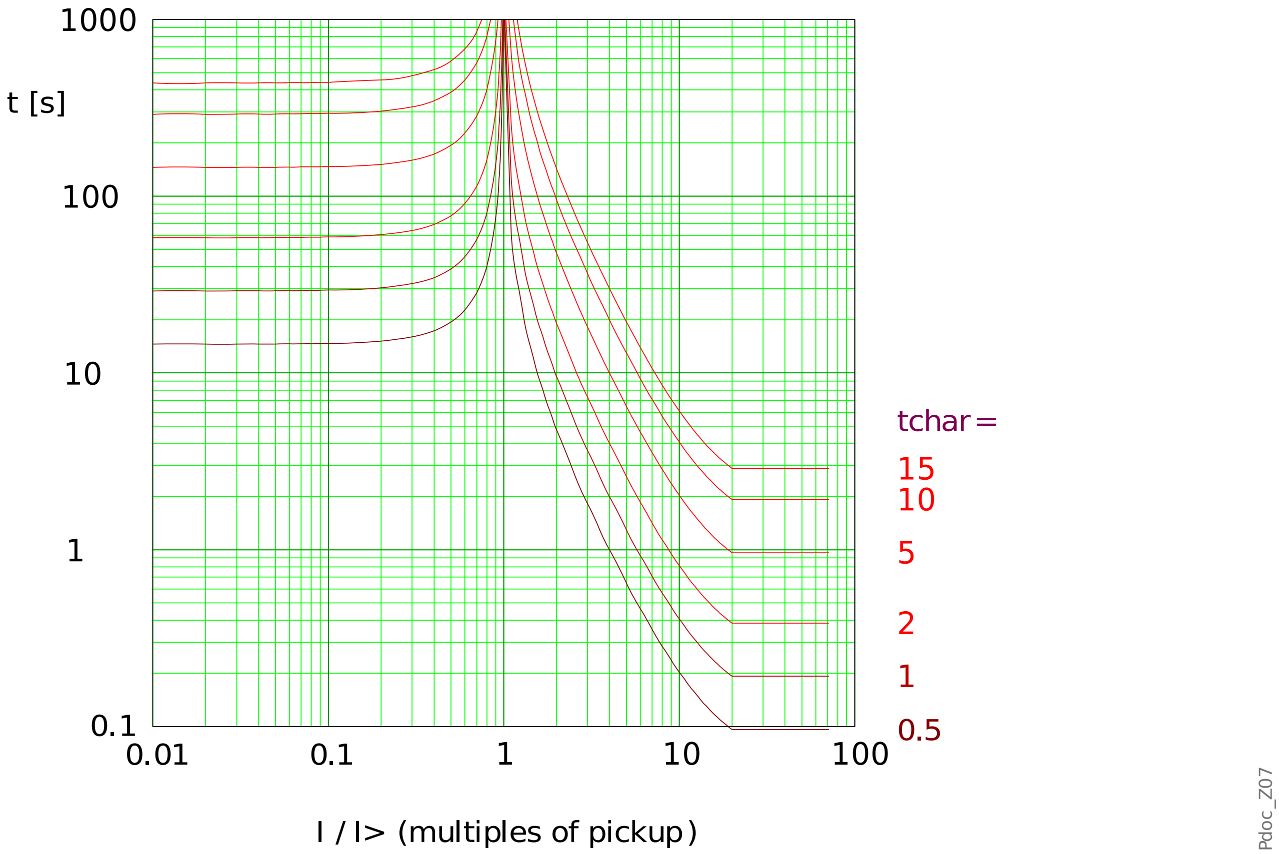
$$t = \frac{29.1}{1-\left(\frac{I}{I>}\right)^2} \cdot tchar$$

If: $\frac{I}{I>} < 1$

Trip

$$t = \left(\frac{28.2}{\left(\frac{I}{I>}\right)^2 - 1} + 0.1217\right) \cdot tchar$$

If: $1 < \frac{I}{I>} \leq 20$



R Inverse

NOTICE **Various reset modes are available:**
Resetting via characteristic, delayed and instantaneous.

Remark: For $I > 20 \cdot I_>$, the curve stops decreasing, the t-values are kept constant at the value for $I = 20 \cdot I_>$.

»Char« = RINV

Reset

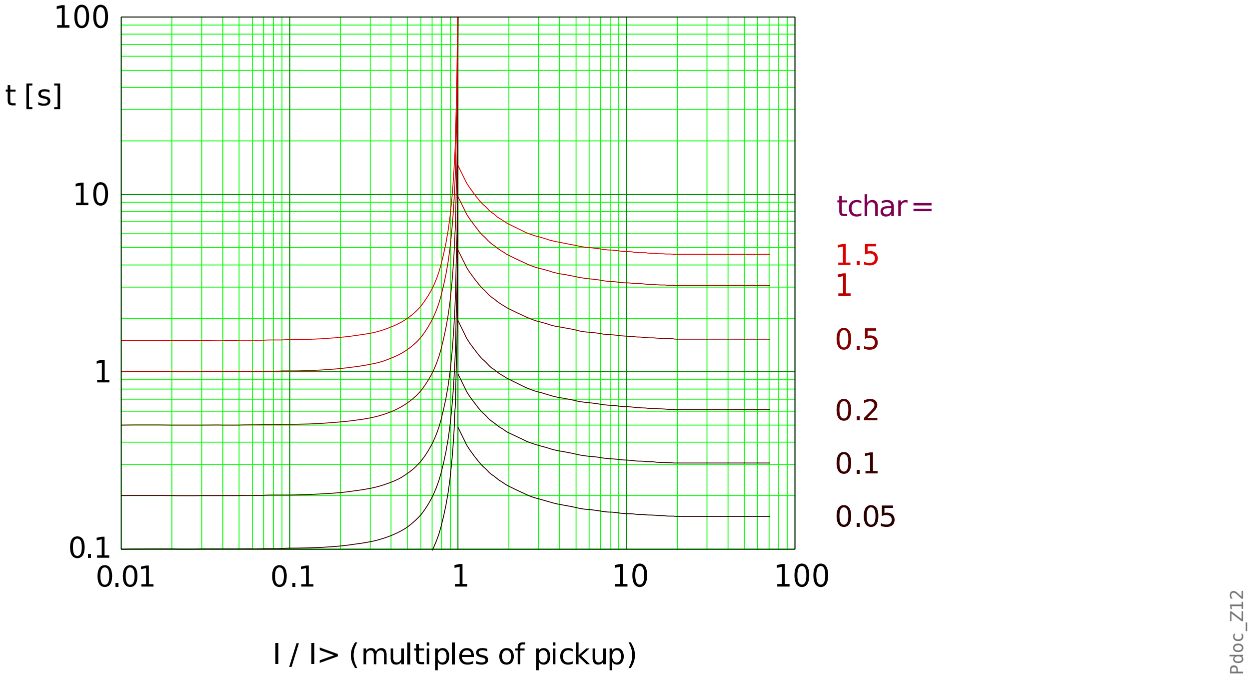
$$t = \frac{1.0}{1-\left(\frac{I}{I>}\right)^2} \cdot tchar$$

If: $\frac{I}{I>} < 1$

Trip

$$t = \frac{1.0}{0.339-0.236 \cdot \left(\frac{I}{I>}\right)^{-1}} \cdot tchar$$

If: $1 < \frac{I}{I>} \leq 20$

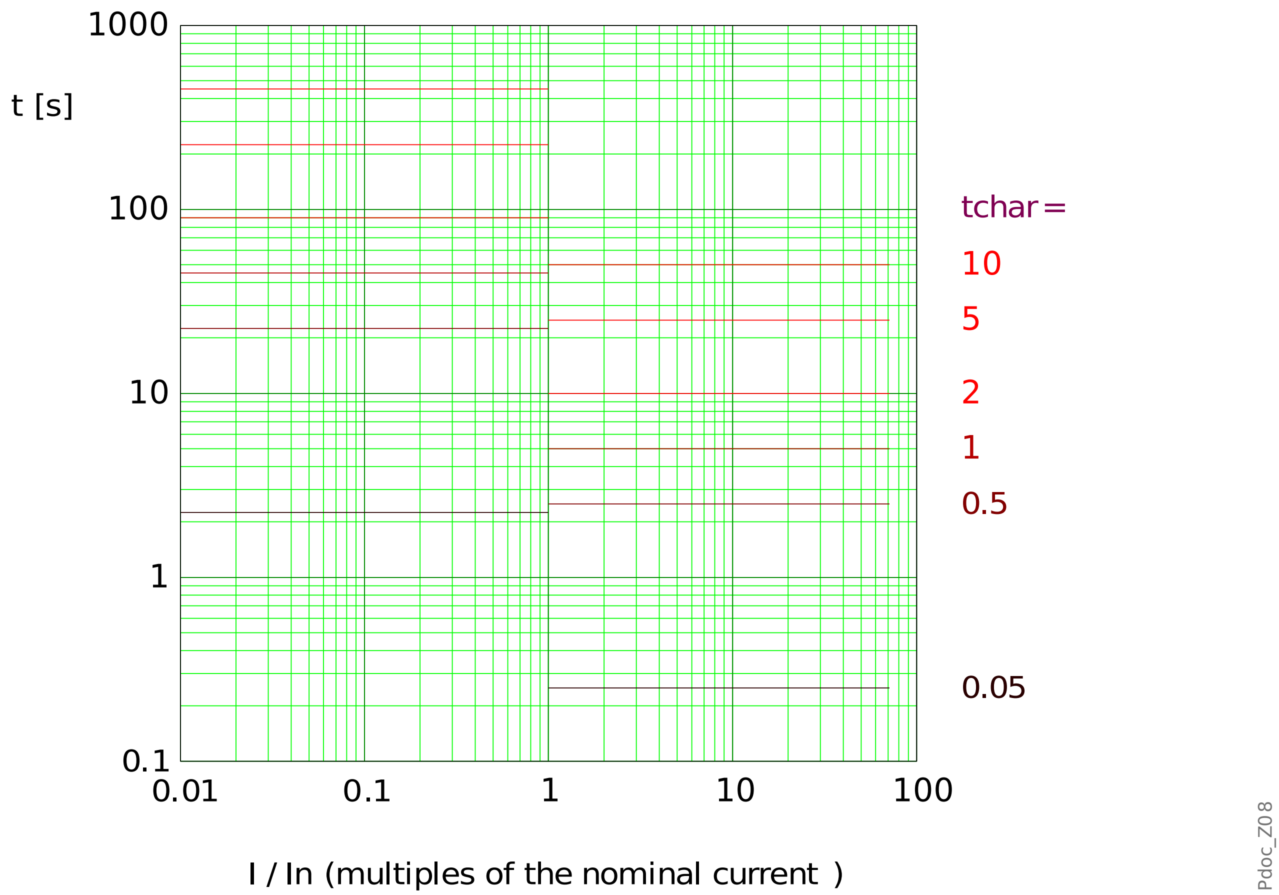


Thermal Flat Curve

NOTICE Various reset modes are available:
Resetting via characteristic, delayed and instantaneous.

***»Char«* = Therm Flat**

Reset	Trip
$t = (5\cdot 3^2)\cdot tchar$	$t = (5\cdot 3^0)\cdot tchar$
If: $\frac{I}{In} < 1$	If: $1 < \frac{I}{In}$



Thermal Curve IT

NOTICE Various reset modes are available:
Resetting via characteristic, delayed and instantaneous.

»Char« = IT

Reset

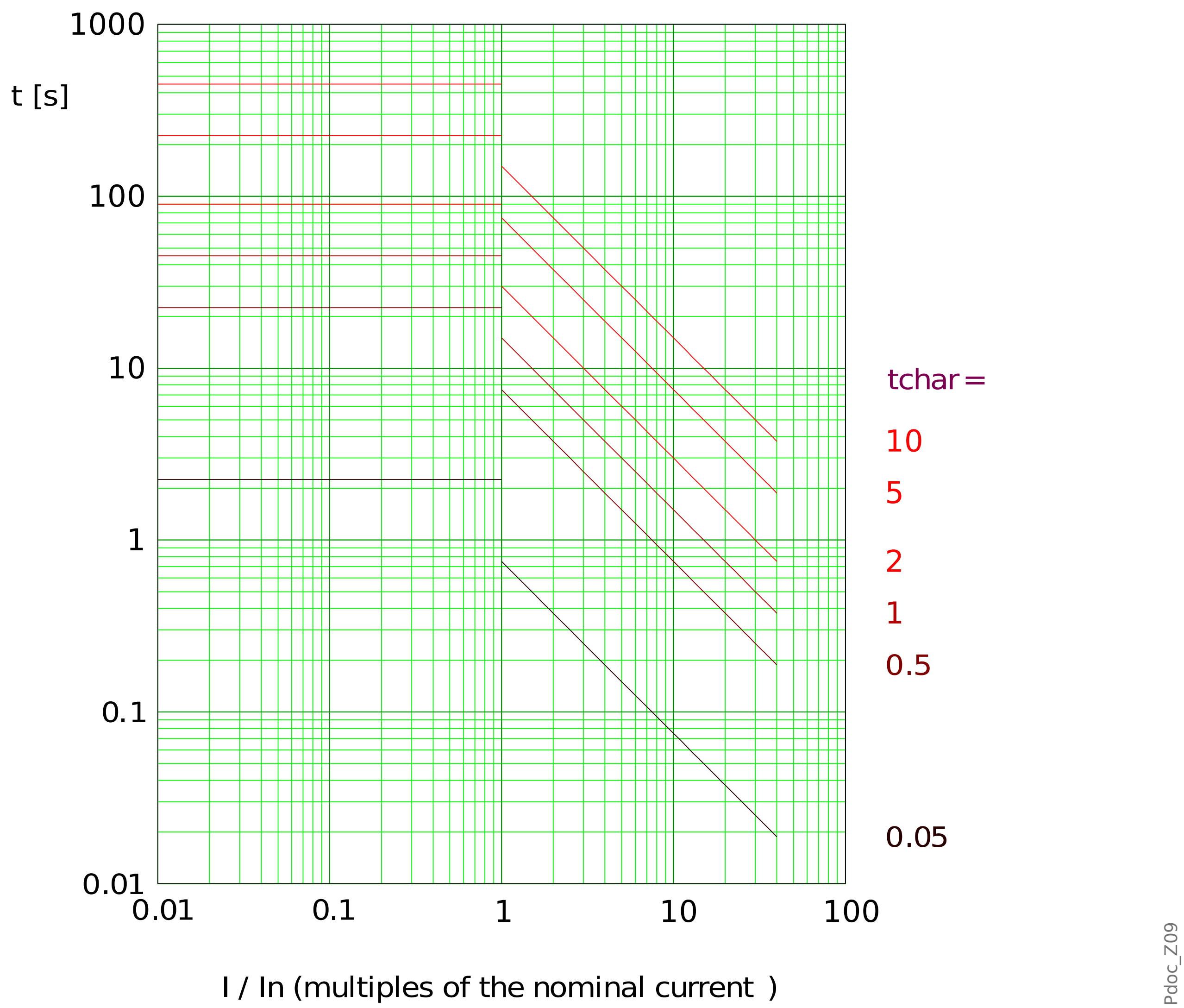
$$t = (5 \cdot 3^2) \cdot tchar$$

If: $\frac{I}{In} < 1$

Trip

$$t = \frac{5 \cdot 3^1}{\left(\frac{I}{In}\right)^1} \cdot tchar$$

If: $1 < \frac{I}{In}$



Thermal Curve I2T

NOTICE **Various reset modes are available:**
Resetting via characteristic, delayed and instantaneous.

***»Char«* = I2T**

Reset

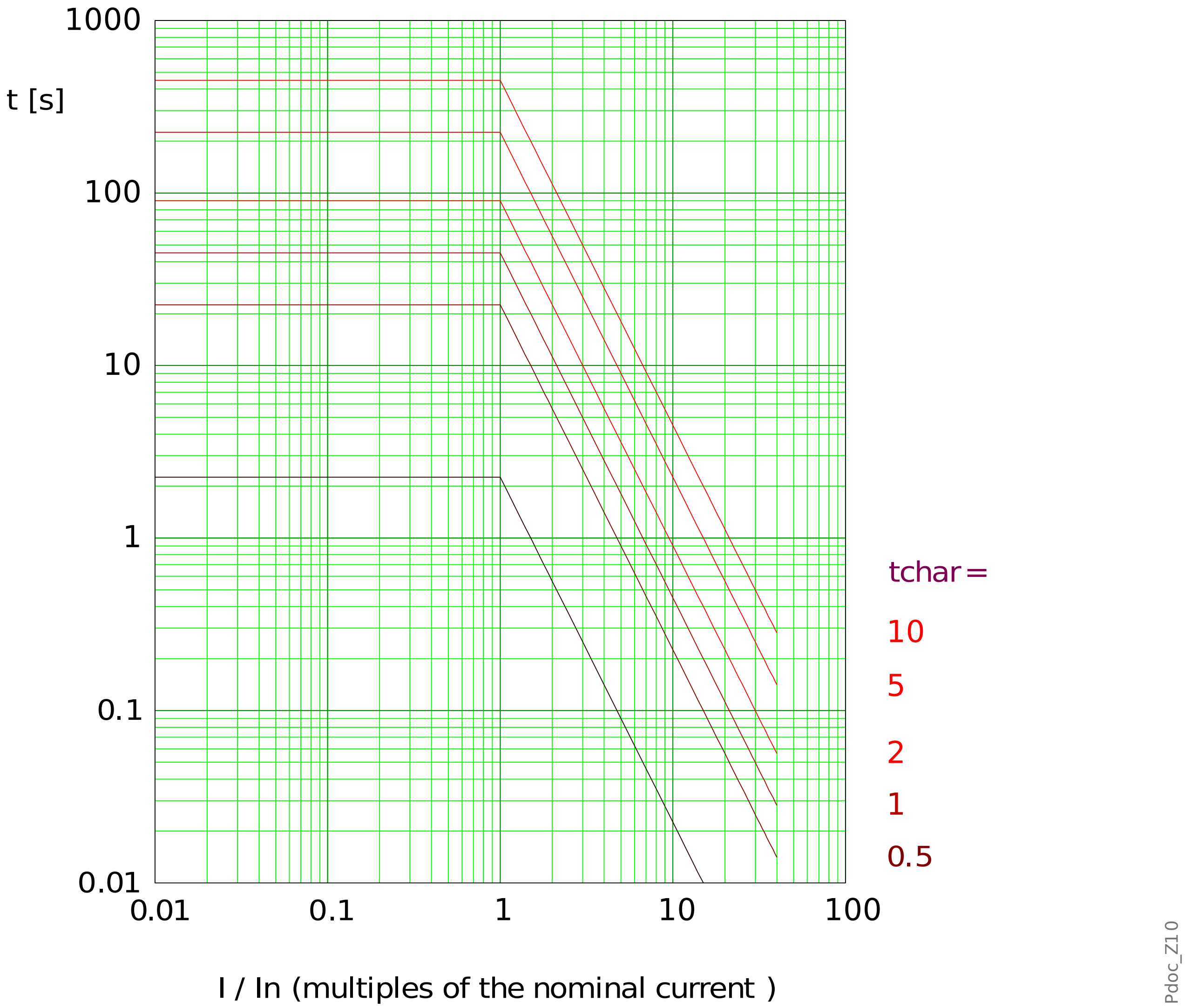
$$t = (5 \cdot 3^2) \cdot tchar$$

If: $\frac{I}{In} < 1$

Trip

$$t = \frac{5 \cdot 3^2}{\left(\frac{I}{In}\right)^2} \cdot tchar$$

If: $1 < \frac{I}{In}$



Thermal Curve I4T

NOTICE Various reset modes are available:
Resetting via characteristic, delayed and instantaneous.

»*Char*« = I4T

Reset

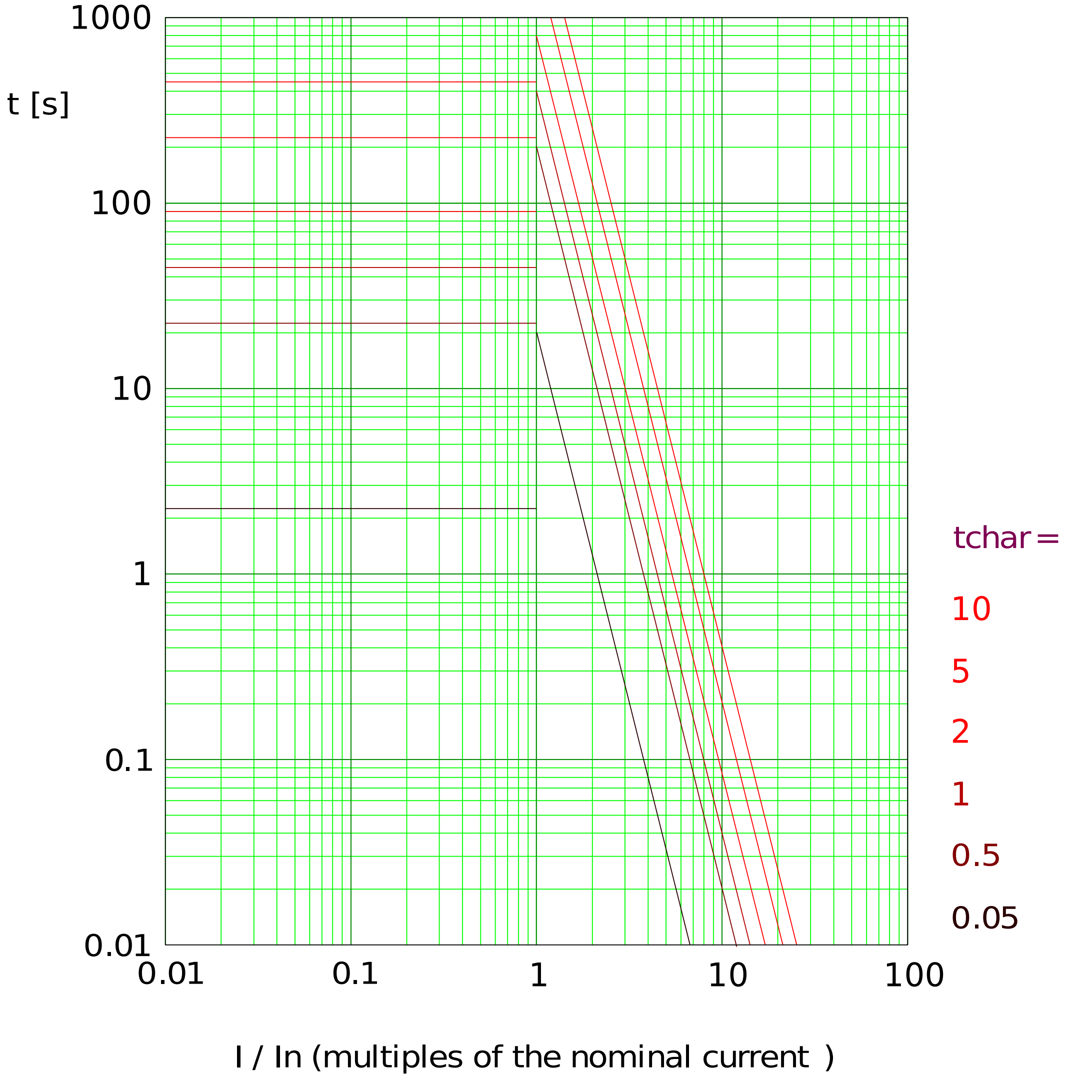
$$t = (5 \cdot 3^2) \cdot tchar$$

If: $\frac{I}{In} < 1$

Trip

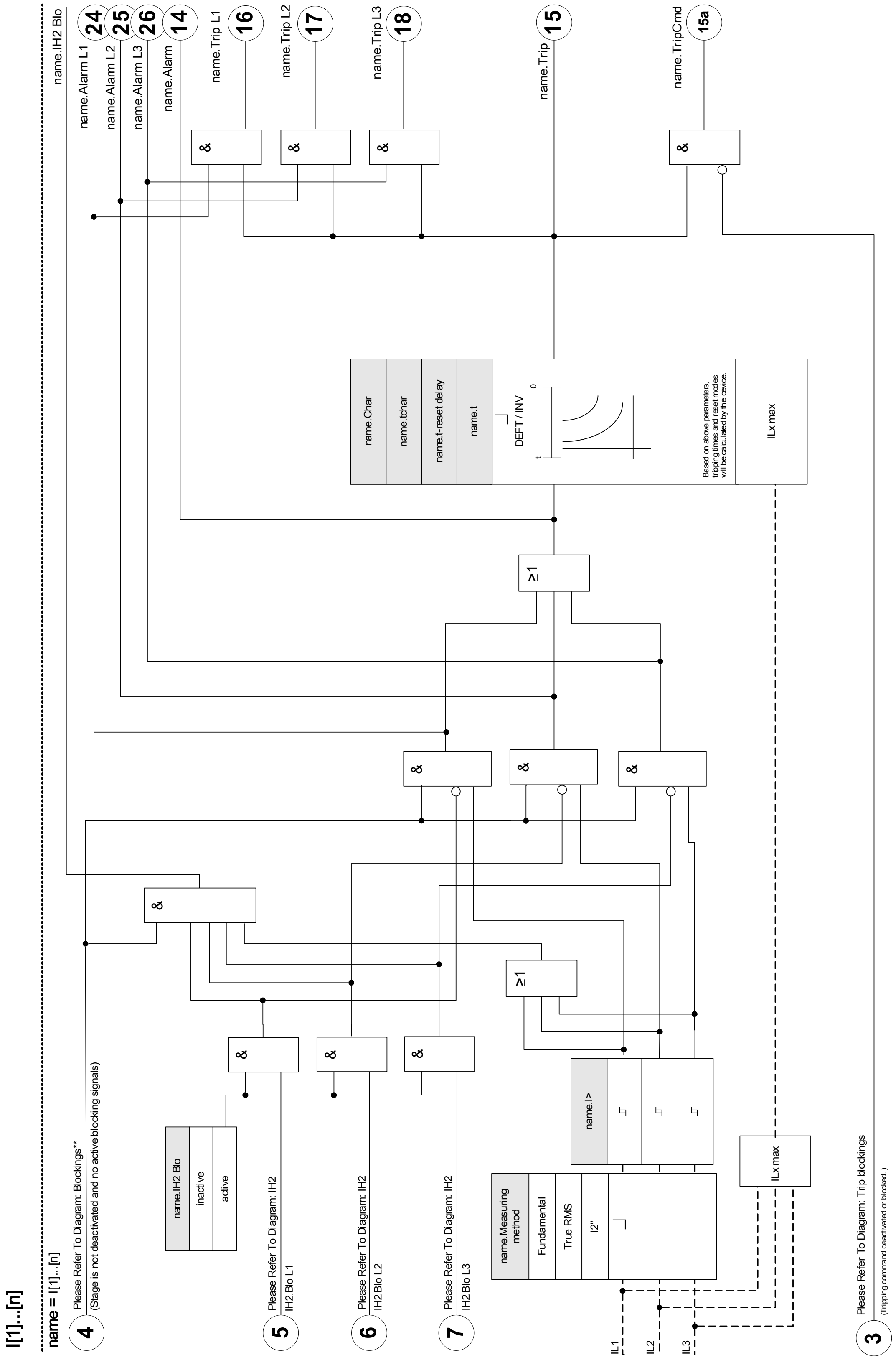
$$t = \frac{5 \cdot 3^4}{\left(\frac{I}{In}\right)^4} \cdot tchar$$

If: $1 < \frac{I}{In}$

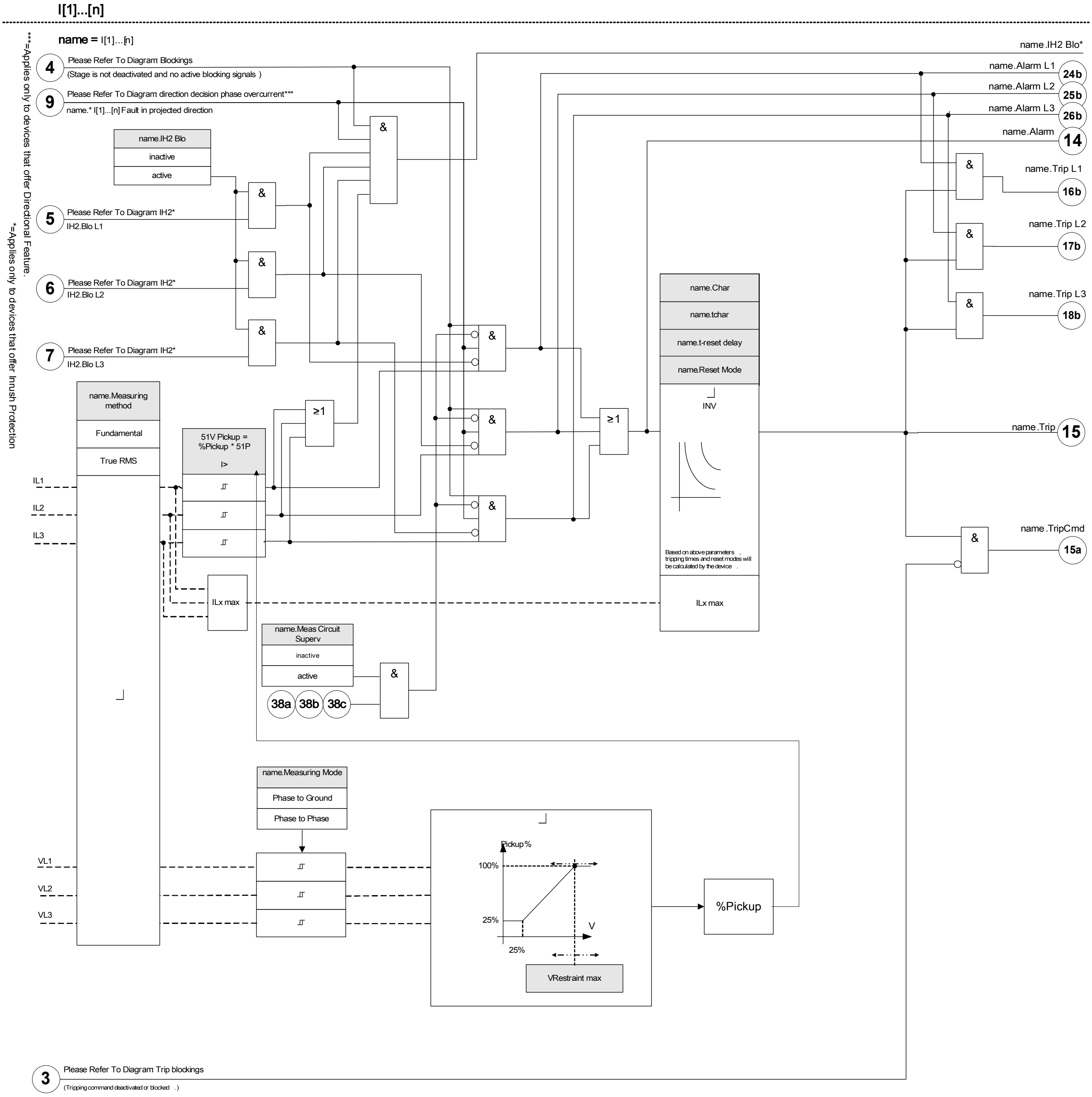


Pdoc_Z11

The following block diagram applies to devices without voltage measurement (without 51V)



The following block diagram applies to devices that offer a voltage measurement card (with 51V)



Device Planning Parameters of the I Module

Parameter	*Description*	*Options*	*Default*	*Menu path*
Mode	Mode	do not use, non directional	I[1]: non directional I[2]: non directional I[3]: do not use I[4]: do not use I[5]: do not use I[6]: do not use	[Device planning]

Global Protection Parameters of the I Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ExBlo1	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /I-Prot /I[1]]
ExBlo2	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /I-Prot /I[1]]
ExBlo dur. Mot.Strt	External blocking of the module, if the state of the assigned signal is true. This way it is possible to block the module during the motor start phase.	1..n, Trip Cmds	I[1]: MStart.Blo-IOCStart I[2]: MStart.Blo-IOCStart I[3]: -.- I[4]: -.- I[5]: -.- I[6]: -.-	[Protection Para /Global Prot Para /I-Prot /I[1]]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ExBlo TripCmd	External blocking of the Trip Command of the module/the stage, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /I-Prot /I[1]]
Ex rev Interl	External blocking of the module by external reverse interlocking, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /I-Prot /I[1]]
AdaptSet 1	Assignment Adaptive Parameter 1	AdaptSet	-.-	[Protection Para /Global Prot Para /I-Prot /I[1]]
AdaptSet 2	Assignment Adaptive Parameter 2	AdaptSet	-.-	[Protection Para /Global Prot Para /I-Prot /I[1]]
AdaptSet 3	Assignment Adaptive Parameter 3	AdaptSet	-.-	[Protection Para /Global Prot Para /I-Prot /I[1]]
AdaptSet 4	Assignment Adaptive Parameter 4	AdaptSet	-.-	[Protection Para /Global Prot Para /I-Prot /I[1]]

Setting Group Parameters of the I Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	I[1]: active I[2]: active I[3]: inactive I[4]: inactive I[5]: inactive I[6]: inactive	[Protection Para /<1..4> /I-Prot /I[1]]
ExBlo Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /I-Prot /I[1]]
Ex rev Interl Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "Ex rev Interl Fc = active".	inactive, active	inactive	[Protection Para /<1..4> /I-Prot /I[1]]
Blo TripCmd	Permanent blocking of the Trip Command of the module/stage.	inactive, active	inactive	[Protection Para /<1..4> /I-Prot /I[1]]
ExBlo TripCmd Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo TripCmd Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /I-Prot /I[1]]
Measuring method	Measuring method: fundamental or rms or 3rd harmonic (only generator protection relays)	Fundamental, True RMS, I2	Fundamental	[Protection Para /<1..4> /I-Prot /I[1]]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
I>	If the pickup value is exceeded, the module/element starts to time out to trip. Only available if: Characteristic = DEFT Or Characteristic = INV Minimum of the setting range If: VRestraint = active Minimum of the setting range If: VRestraint = inactive	0.02 - 40.00In	I[1]: 2.0In I[2]: 5.0In I[3]: 1.00In I[4]: 1.00In I[5]: 1.00In I[6]: 1.00In	[Protection Para /<1..4> /I-Prot /I[1]]
Char	Characteristic	DEFT, IEC NINV, IEC VINV, IEC EINV, IEC LINV, RINV, ANSI MINV, ANSI VINV, ANSI EINV, Therm Flat, IT, I2T, I4T	DEFT	[Protection Para /<1..4> /I-Prot /I[1]]
t	Tripping delay Only available if: Characteristic = DEFT	0.00 - 300.00s	I[1]: 0.5s I[2]: 0.5s I[3]: 1.00s I[4]: 1.00s I[5]: 1.00s I[6]: 1.00s	[Protection Para /<1..4> /I-Prot /I[1]]
tchar	Time multiplier/tripping characteristic factor. The setting range depends on the selected tripping curve. Only available if: Characteristic = INV Or Characteristic = Therm Flat Or Characteristic = IT Or Characteristic = I2T Or Characteristic = I4T	0.02 - 20.00	1	[Protection Para /<1..4> /I-Prot /I[1]]
Reset Mode	Reset Mode Only available if: Characteristic = INV Or Characteristic = Therm Flat Or Characteristic = IT Or Characteristic = I2T Or Characteristic = I4T	instantaneous, delayed, calculated	instantaneous	[Protection Para /<1..4> /I-Prot /I[1]]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
t-reset delay	Reset delay for intermittent phase failures (INV characteristics only) Available if:Reset Mode = delayed	0.00 - 60.00s	0s	[Protection Para /<1..4> /I-Prot /I[1]]

I Module Input States

Name	*Description*	*Assignment via*
ExBlo1-I	Module input state: External blocking1	[Protection Para /Global Prot Para /I-Prot /I[1]]
ExBlo2-I	Module input state: External blocking2	[Protection Para /Global Prot Para /I-Prot /I[1]]
ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command	[Protection Para /Global Prot Para /I-Prot /I[1]]
Ex rev Interl-I	Module input state: External reverse interlocking	[Protection Para /Global Prot Para /I-Prot /I[1]]
AdaptSet1-I	Module input state: Adaptive Parameter1	[Protection Para /Global Prot Para /I-Prot /I[1]]
AdaptSet2-I	Module input state: Adaptive Parameter2	[Protection Para /Global Prot Para /I-Prot /I[1]]
AdaptSet3-I	Module input state: Adaptive Parameter3	[Protection Para /Global Prot Para /I-Prot /I[1]]

Name	*Description*	*Assignment via*
AdaptSet4-I	Module input state: Adaptive Parameter4	[Protection Para /Global Prot Para /I-Prot /I[1]]

I Module Signals (Output States)

Signal	*Description*
active	Signal: active
ExBlo	Signal: External Blocking
Ex rev Interl	Signal: External reverse Interlocking
Blo TripCmd	Signal: Trip Command blocked
ExBlo TripCmd	Signal: External Blocking of the Trip Command
Alarm L1	Signal: Alarm L1
Alarm L2	Signal: Alarm L2
Alarm L3	Signal: Alarm L3
Alarm	Signal: Alarm
Trip L1	Signal: General Trip Phase L1
Trip L2	Signal: General Trip Phase L2
Trip L3	Signal: General Trip Phase L3
Trip	Signal: Trip
TripCmd	Signal: Trip Command
Active AdaptSet	Active Adaptive Parameter
DefaultSet	Signal: Default Parameter Set
AdaptSet 1	Signal: Adaptive Parameter 1
AdaptSet 2	Signal: Adaptive Parameter 2
AdaptSet 3	Signal: Adaptive Parameter 3
AdaptSet 4	Signal: Adaptive Parameter 4

Counter Values of the I Module

Value	*Description*	*Default*	*Size*	*Menu path*
NumberOfAlarms	Number of alarms since last reset.	0	0 - 9999999999	[Operation /History /AlarmCr]
NumberOfTripCmds	Number of trip commands since last reset	0	0 - 9999999999	[Operation /History /TripCmdCr]

Commissioning: Overcurrent Protection, non-directional [50, 51]

Object to be tested

- Signals to be measured for each current protection element, the threshold values, total tripping time (recommended), or alternatively tripping delays and the fallback ratios; each time 3 x single-phase and 1 x three-phase.

NOTICE

Especially in Holmgreen connections, wiring errors can easily happen, and these are then detected safely. Measuring the total tripping time can ensure that the secondary wiring is o.k. (from the terminal on, up to the trip coil of the CB).

NOTICE

It is recommended to measure the total tripping time instead of the tripping delay. The tripping delay should be specified by the customer. The total tripping time is measured at the position signalling contact of the CB (not at the relay output!).

Total tripping time = tripping delay (please refer to the tolerances of the protection stages) + CB operating time (about 50 ms)

Please take the CB operating times from the technical data specified in the relevant documentation provided by the CB manufacturer.

Necessary means

- Current source
- May be: ampere meters
- Timer

Procedure

Testing the threshold values (3 x single-phase and 1 x three-phase)
Each time feed a current which is about 3-5% above the threshold value for activation/tripping. Then check the threshold values.

Testing the total tripping delay (recommendation)
Measure the total tripping times at the auxiliary contacts of the CB (CB tripping).

Testing the tripping delay (measuring at the relay output)
Measure the tripping times at the relay output.

Testing the fallback ratio
Reduce the current to 97% below the trip value and check the fallback ratio.

Successful test result

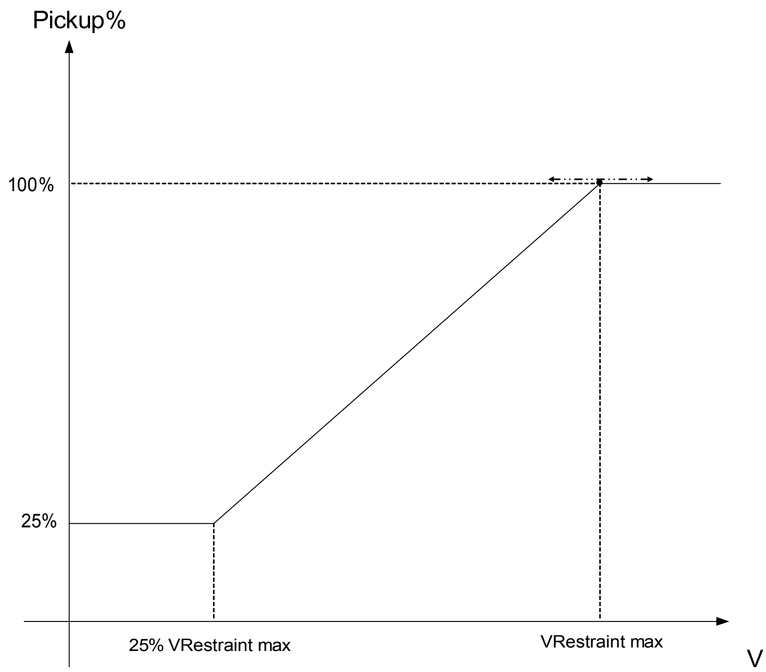
The measured total tripping delays or individual tripping delays, threshold values and fallback ratios correspond with those values, specified in the adjustment list. Permissible deviations/tolerances can be found under Technical Data.

51V - Voltage Restraint Overcurrent*

*=available only for devices that offer voltage measurement.

For activating this function, the parameter »*VRestraint*« has to be set to *active* in the parameter set of the corresponding overcurrent element I[x].The *51V* protection function restrains operation which reduces pickup levels. This allows the User to lower the pickup value of the *51V* protection function with the corresponding phase input voltage (phase-to-phase or phase-to-ground, depending on the setting of »*Measuring Channel*« within the current protection module). When the minimum fault phase current is close to the load current, it may make the phase time overcurrent protection coordination difficult. In this case, an undervoltage function may be used to alleviate this situation. When the voltage is low, the phase time overcurrent pickup threshold may be set low accordingly, so that the phase time overcurrent protection may achieve adequate sensitivity and better coordination. The device uses a simple linear model to determine the effective pickup by characterizing the relationship between the voltage and the phase time overcurrent pickup threshold.

Once the voltage restraint protection function is activated, the effective phase time overcurrent pickup threshold will be the calculated Pickup% times the phase time overcurrent pickup setting. The effective pickup threshold must be within the setting range allowed and, if it is less, the minimum pickup value will be used.



That means:
Vmin = 0.25*Vmax;
•Pickup%min = 25%;
•Pickup% = 25%, if V <= Vmin;
•Pickup% = 1/Vmax*(V - Vmin) + 25%, if Vmin < V < Vmax;
•Pickup% = 100%, if V >= Vmax;

The tripping curves (characteristic) will not be influenced by the voltage restraint function.
If the voltage transformer supervision is activated, the voltage restraint overcurrent protection element is blocked in case of m.c.b. trip to avoid false trippings.

NOTICE

Definition of Vn:
Vn is dependent on the *»Measuring Channel«* setting in the current protection modules.

In case that this parameter is set to "Phase to Phase":

$$Vn = Main\,VT\,sec$$

In case that this parameter is set to "Phase to Neutral":

$$Vn = \frac{Main\,VT\,sec}{\sqrt{3}}$$

If the parameter *»VT con«* within the field parameters is set to *»Phase to Phase«* the setting *»Phase to Neutral«* in the current modules is effectless.

Commissioning: Overcurrent Protection, Non-directional [ANSI 51V]*

**=available only for devices that offer voltage measurement.*

Object to be tested:

Signals to be measured for Voltage Restraint protection function: the threshold values, total tripping time (recommended), or alternatively tripping delays and the dropout ratios; each time 3 x single-phase and 1 x three-phase.

NOTICE

It is recommended to measure the total tripping time instead of the tripping time. The tripping delay should be specified by the customer. The total tripping time is measured at the position signaling contacts of the CBs (not at the relay output!).

Total tripping time: = tripping delay (please refer to the tolerances of the protection stages) + CB operating time (about 50 ms)

Please take the CB switching times from the technical data, specified in the relevant documentation, provided by the CB manufacturer.

Necessary means:

- Current source;
- Voltage Source;
- Current and Voltage meters; and
- Timer.

Procedure:

Testing the threshold values (3 x single-phase and 1 x three-phase)
Feed %Pickup voltage. For each test performed, feed a current that is about 3-5% above the threshold value for activation/tripping. Then check if the pickup values are %Pickup of the value according to the standard overcurrent protection.

Testing the total tripping delay (recommendation)
Measure the total tripping times at the auxiliary contacts of the breakers (breaker tripping).

Testing the tripping delay (measuring at the relay output contact)
Measure the tripping times at the relay output contact.

Testing the dropout ratio
Reduce the current to 97% below the trip value and check the dropout ratio.

Successful test result
The measured total tripping delays or individual tripping delays, threshold values, and dropout ratios correspond with those values specified in the adjustment list. Permissible deviations/tolerances can be found under Technical Data.

I2> - Negative-Sequence Overcurrent [51Q]

For activating this function, the parameter *»Measuring Mode«* has to be set to *»I2«* in the parameter set of the corresponding overcurrent element I[x].

The negative-sequence overcurrent protection function (*I2>*) is to be seen as an equivalent to the phase overcurrent protection with the exception that it uses negative-sequence current (I2>) as measured quantities instead of the three phase currents used by phase overcurrent protection function. The negative-sequence current used by *I2>* is derived from the following well-known symmetrical component transformation:

$$I_2 = \frac{1}{3}(I_{L1} + a^2 I_{L2} + a I_{L3})$$

The pickup set value of a *I2>* protection function should be set in accordance of the negative-sequence current occurrence in the protected object.

Besides that, the negative-sequence overcurrent protection function (*I2>*) uses the same setting parameters as the phase overcurrent protection function, like trip and reset characteristics from both IEC/ANSI standards, time multiplier, etc.

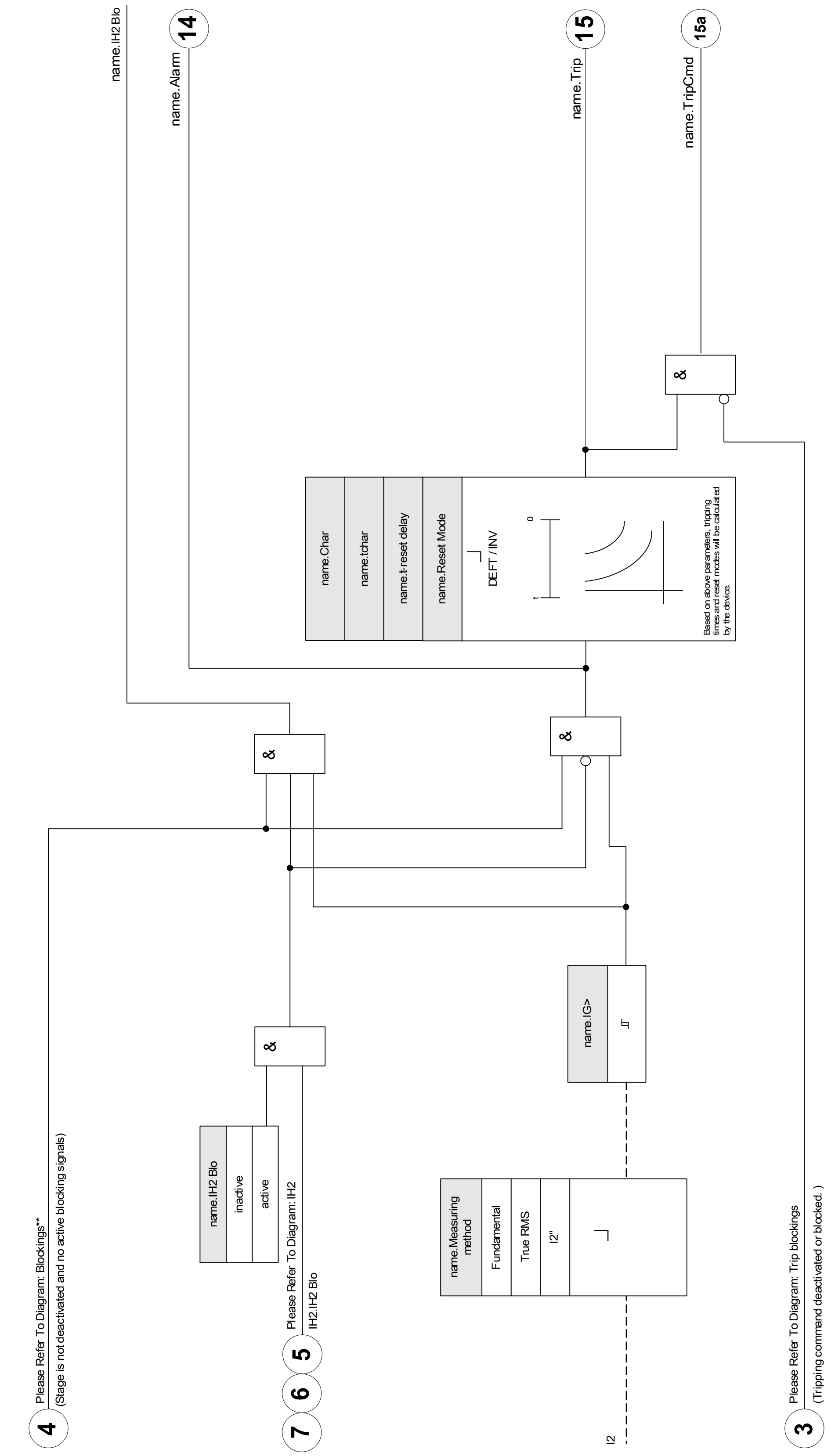
The negative-sequence overcurrent protection function (*I2>*) can be used for line, generator, transformer and motor protection to protect the system from unbalanced faults. Because the *I2>* protection function operates on the negative-sequence current component which is normally absent during load conditions, the *I2>* can, therefore, be set more sensitive than the phase overcurrent protection functions. On the other hand, coordination of negative-sequence overcurrent protection function in a radial system does not mean automatically very long fault clearing time for the furthest upstream protection devices, because the tripping time of concerned negative-sequence overcurrent protection function needs only be coordinate with the next downstream device with the negative-sequence overcurrent protection function. This makes the *I2>* in many cases as an advantageous protection concept in addition to the phase overcurrent protection function.

WARNING **If you are using inrush blockings, the tripping delay of the current protection functions must be at least 30 ms or more in order to prevent faulty trippings.**

NOTICE **At the moment of breaker closure, negative-sequence current might be the result of transients.**

I[1]...[n]: Measuring method = (I2>)

name = I[1]...[n]



Commissioning: Negative Sequence Overcurrent

Object to be tested

Signals to be measured for each current protection function: the threshold values, total tripping time (recommended), or alternatively tripping delays and the dropout ratios.

NOTICE

It is recommended to measure the total tripping time instead of the tripping time. The tripping delay should be specified by the customer. The total tripping time is measured at the position signalling contacts of the CBs (not at the relay output!).

Total tripping time: = tripping delay (please refer to the tolerances of the protection stages) + CB operating time (about 50 ms)

Please take the CB switching times from the technical data, specified in the relevant documentation, provided by the CB manufacturer.

Necessary means:
- Current source
- Current meters
- Timer

Procedure:

Testing the threshold values

In order to get a negative-sequence current, please change the phase sequence at the terminals of the current source (in case of ABC sequence to ACB – in case of a ACB sequence to ABC).

For each test performed, feed a current that is about 3-5% above the threshold value for activation/tripping. Then check the threshold values.

Testing the total tripping delay (recommendation)
Measure the total tripping times at the auxiliary contacts of the breakers (breaker tripping).

Testing the tripping delay (measuring at the relay output contact)
Measure the tripping times at the relay output contact.

Testing the dropout ratio
Reduce the current to 97% below the trip value and check the dropout ratio.

Successful test result
The measured total tripping delays or individual tripping delays, threshold values, and dropout ratios correspond with those values specified in the adjustment list. Permissible deviations/tolerances can be found under Technical Data.

Voltage Controlled Overcurrent Protection [51C]*

*=available only for devices that offer voltage measurement.

When a sort circuit is near the generator, the voltage might drop down. By means of ***Adaptive Parameters*** (Please refer to chapter Parameter) the tripping times or tripping characteristics can be modified by the output signal of a voltage element (depending on a threshold). The device might change a load curve to a fault curve (taking influence on tripping time, trip curves and reset modes).

Please proceed as follows:

- Read and understand the section „Adaptive Parameters“ within the chapter Parameter.
- Do the device planning and set all required parameters for the Undervoltage element.
- Do the device planning and set all required parameters for the Overcurrent element.
- Set the ***Adaptive Parameters*** within the Overcurrent element in the relevant parameter sets (e.g. Curve multiplier, curve type...).
- Assign the Undervoltage alarm (pickup) within the ***Global Parameters*** as an activation signal for the corresponding ***Adaptive Parameter set*** of the overcurrent element that should be modified.
- Check the functionality by a commissioning test.

Special Notes on Earth Fault Current Transformers

Elements:
Earth Fault Protection

Functional Description

Earth current measurement is usually been done with a summation current transformer (core-balance transformer). This CT has a large primary window through which all three-phase conductors can pass.

Note that the earth fault current settings are based on the earth CT rated **primary current (In),** not on FLA or the phase CT ratio. For example, a pick-up setting of 0.10 gives a trip or alarm for an actual earth leakage current of 5 A on the primary side of the sensor with a 50:5 CT.

This function is only useful for an earthed power system. The earth return is normally made from the neutral of the secondary wire winding of the supply power transformer. Resistance earthing is acceptable as long as the resulting fault current is at a level the protective device can be set to detect.

The earth CT, which provides sensitive protection for high-resistance earth faults, may saturate for a robust heavy-current earth fault in a solid-earthed system. Minimize the saturation problem by minimizing the burden. Use the shortest and heaviest leads possible between the earth CT and the relay. The relay itself has very low burden, usually much lower than the connecting wiring.

A residual connection – the wired summation of the phase CT circuits through the earth CT input – requires a much higher earth fault time setting to avoid false tripping. Thus sensitivity is not nearly as good as with a separate flux-canceling CT.

If the relay is installed where a residual connection is used, XCT should be set to the same value as CT Pri. The User must then set the earth fault trip level at a high value to avoid nuisance tripping from CT ratio errors, third harmonic and certain higher harmonics or other measurement errors producing false residual currents. Monitor the metered earth current during various loading conditions to ensure a good margin between these error currents and the earth fault trip current setting 50R [x]. Also watch out for phase CTs that saturate during motor starting. The saturation produces a large residual current and an earth fault trip.

IG> - Earth Fault [50N/G, 51N/G]

Available elements:
IG[1] ,IG[2] ,IG[3] ,IG[4]

WARNING **If you are using inrush blockings the tripping delay of the earth current protection functions must be at least 30 ms or more in order to prevent faulty trippings.**

NOTICE **All earth current elements are identically structured.**

NOTICE **This module offers Adaptive Parameter Sets.**
Parameters can be modified within parameter sets dynamically by means of Adaptive Parameter Sets.
Please refer to chapter Parameter / Adaptive Parameter Sets.

The following table shows the application options of the earth overcurrent protection element

Applications of the IE-Protection Module	Setting in	Option
ANSI 50N/G – Earth overcurrent protection, non directional	Device Planning menu Setting: non directional	Measuring Mode: Fundamental/TrueRMS
ANSI 51N/G – Earth short circuit protection, non directional	Device Planning menu Setting: non directional	Measuring Mode: Fundamental/TrueRMS

Measuring Mode
For all protection elements it can be determined, whether the measurement is done on basis of the »*Fundamental*« or if »*TrueRMS*« measurement is used.

For each element the following characteristics are available:

- DEFT (UMZ) – *Definite Time-Overcurrent*
- NINV (IEC/AMZ) – *IEC Normal Inverse*
- VINV (IEC/AMZ) – *IEC Very Inverse*
- LINV (IEC/AMZ) – *IEC Long Time Inverse*
- EINV (IEC/AMZ) – *IEC Extremely Inverse*
- MINV (ANSI/AMZ) – *ANSI Moderately Inverse*
- VINV (ANSI/AMZ) – *ANSI Very Inverse*
- EINV (ANSI/AMZ) – *ANSI Extremely Inverse*
- RINV – *R Inverse*
- RXIDG
- Thermal Flat
- IT
- I2T
- I4T
-

Explanation:

t = Tripping delay

t-char = Time multiplier/tripping characteristic factor. The setting range depends on the selected tripping curve.
IG = Fault current

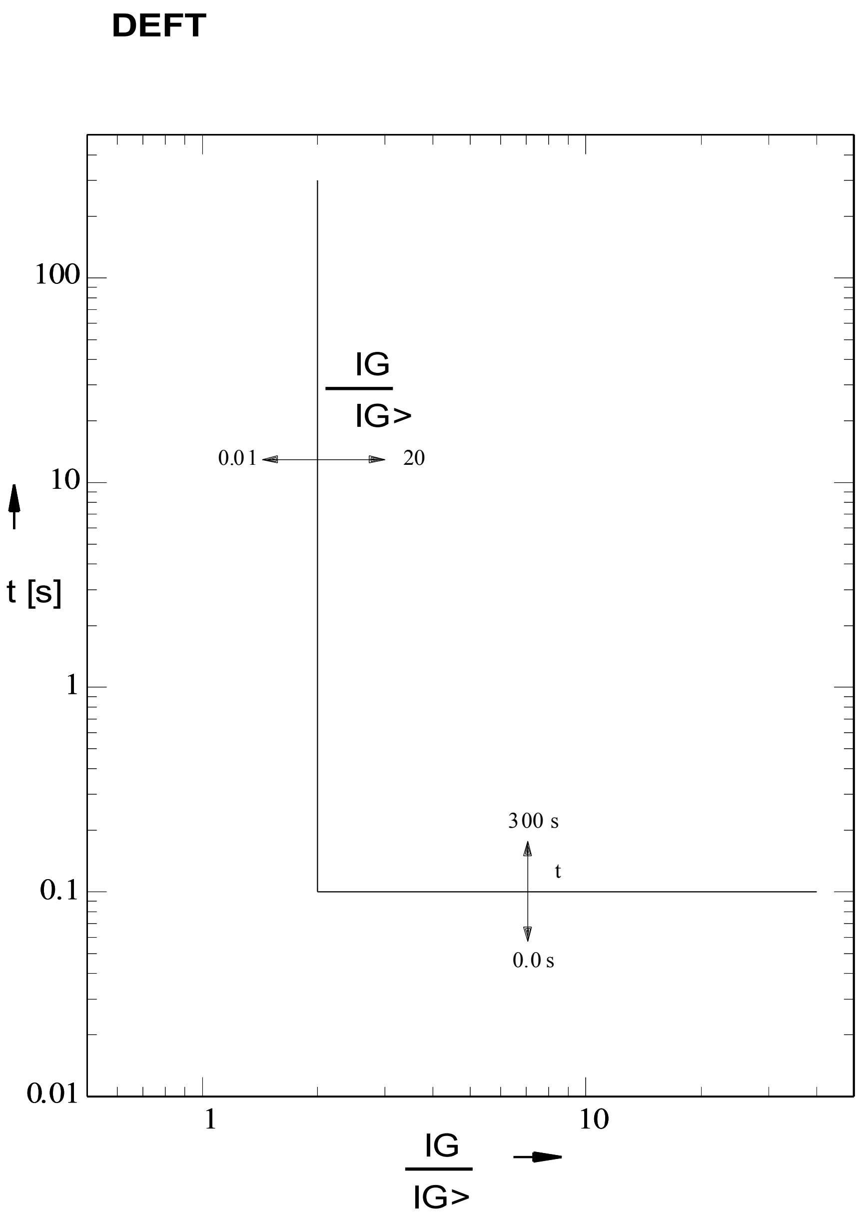
IG> = If the pickup value is exceeded, the module/element starts to time out to trip .

The directional decision depends on the layout of the mains star-point or the angle between residual voltage and ground current. The residual voltage can be measured via suitable transformers (da-dn winding – formerly: e-n) or can be calculated, provided the VTs are in star-connection.

The earth current can be measured either directly via a cable-type transformer or detected by a Holmgreen connection. The earth current can alternatively be calculated from the phase currents; but this is only possible if the phase currents are not ascertained by a V-connection.

The device can optionally be procured with a sensitive earth current measuring input (in preparation).

DEFT – *Definite Time-Overcurrent*



IEC Normal Inverse

NOTICE

Various reset modes are available:
Resetting via characteristic, delayed and instantaneous.

Remark: For $I_G > 20 \cdot I_{G>}$, the curve stops decreasing, the t-values are kept constant at the value for $I_G = 20 \cdot I_{G>}$.

»*Char*« = IEC NINV

Reset

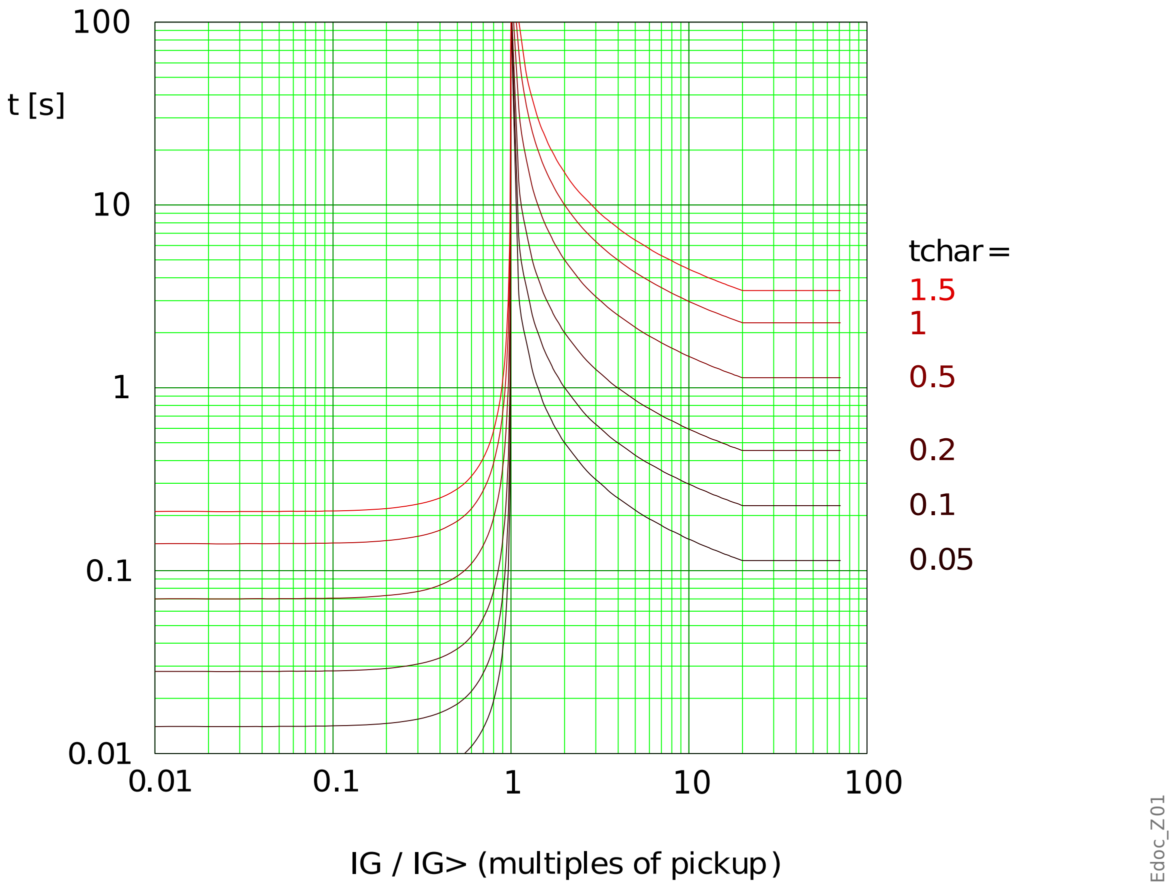
$$t = \frac{0.14}{1 - \left(\frac{IG}{IG>} \right)^2} \cdot tchar$$

If: $\frac{IG}{IG>} < 1$

Trip

$$t = \frac{0.14}{\left(\frac{IG}{IG>} \right)^{0.02} - 1} \cdot tchar$$

If: $1 < \frac{IG}{IG>} \leq 20$



IEC Very Inverse

NOTICE **Various reset modes are available:**
Resetting via characteristic, delayed and instantaneous.

Remark: For $I_G > 20 \cdot I_{G>}$, the curve stops decreasing, the t-values are kept constant at the value for $I_G = 20 \cdot I_{G>}$.

»Char« = IEC VINV

Reset

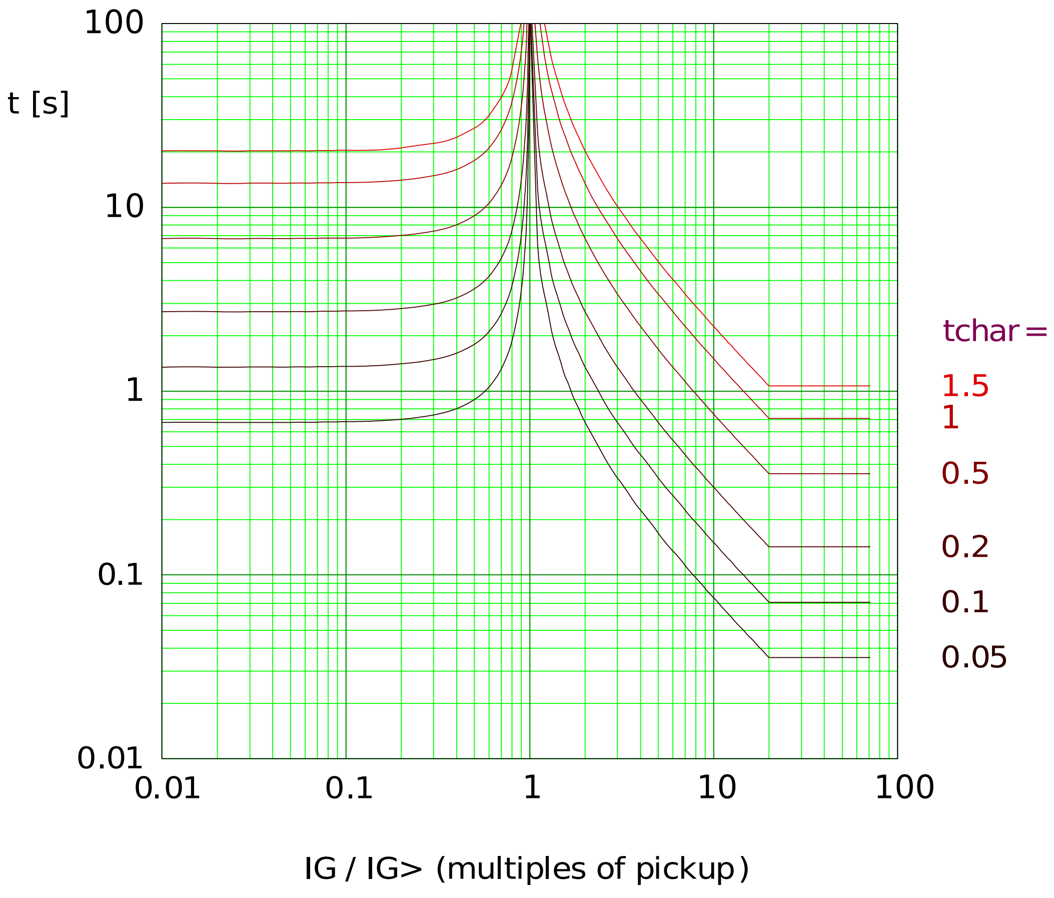
$$t = \frac{13.5}{1-\left(\frac{IG}{IG>}\right)^2} \cdot tchar$$

If: $\frac{IG}{IG>} < 1$

Trip

$$t = \frac{13.5}{\frac{IG}{IG>} - 1} \cdot tchar$$

If: $1 < \frac{IG}{IG>} \leq 20$



IEC Extremely Inverse

NOTICE **Various reset modes are available: Resetting via characteristic, delayed and instantaneous.**

Remark: For $I_G > 20 \cdot I_{G>}$, the curve stops decreasing, the t-values are kept constant at the value for $I_G = 20 \cdot I_{G>}$.

»Char« = IEC EINV

Reset

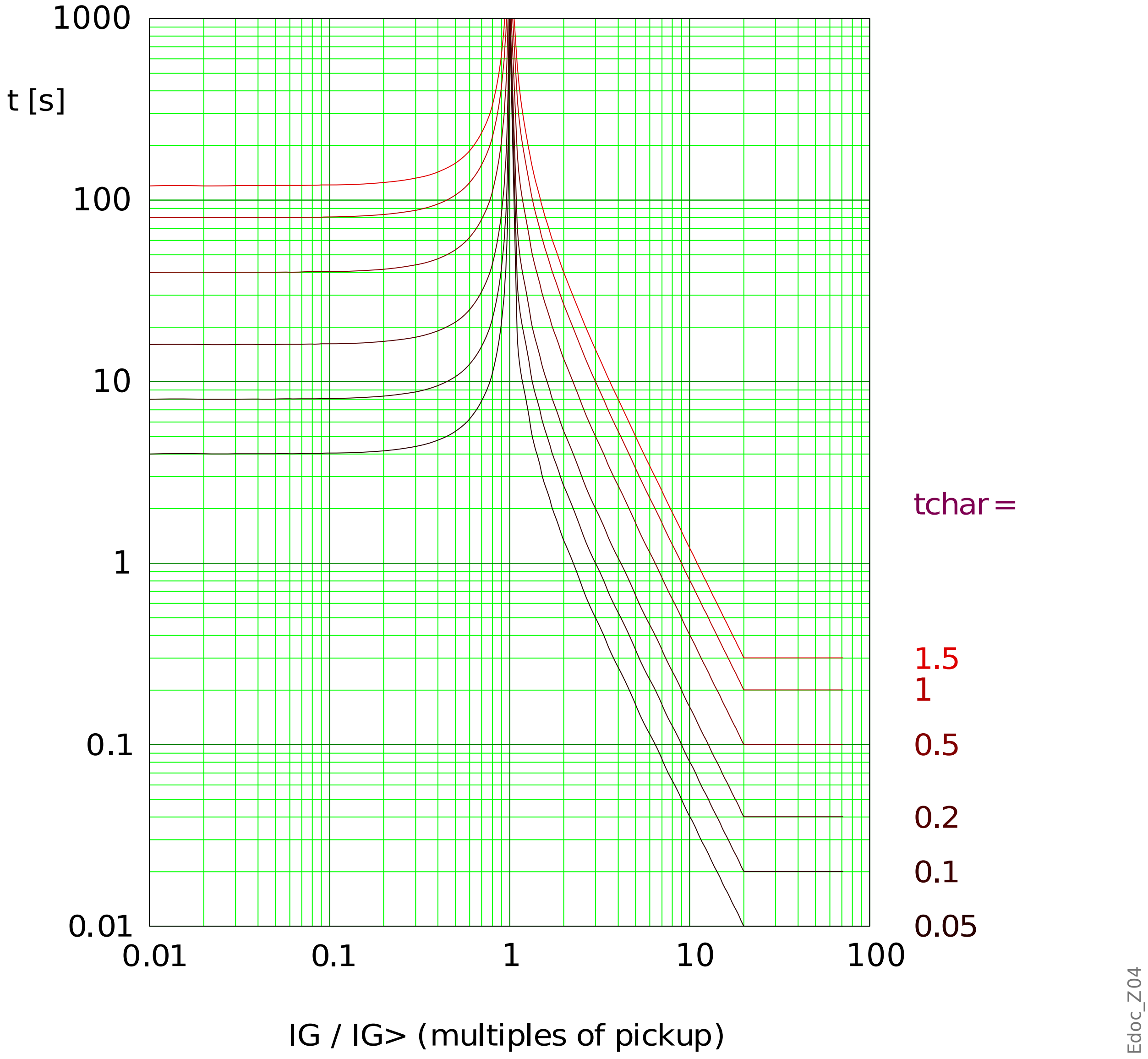
$$t = \frac{80}{1 - \left(\frac{IG}{IG>}\right)^2} \cdot tchar$$

If: $\frac{IG}{IG>} < 1$

Trip

$$t = \frac{80}{\left(\frac{IG}{IG>}\right)^2 - 1} \cdot tchar$$

If: $1 < \frac{IG}{IG>} \leq 20$



IEC Long Time Inverse

NOTICE **Various reset modes are available:**
Resetting via characteristic, delayed and instantaneous.

Remark: For $I_G > 20 \cdot I_{G>}$, the curve stops decreasing, the t-values are kept constant at the value for $I_G = 20 \cdot I_{G>}$.

»Char« = IEC LINV

Reset

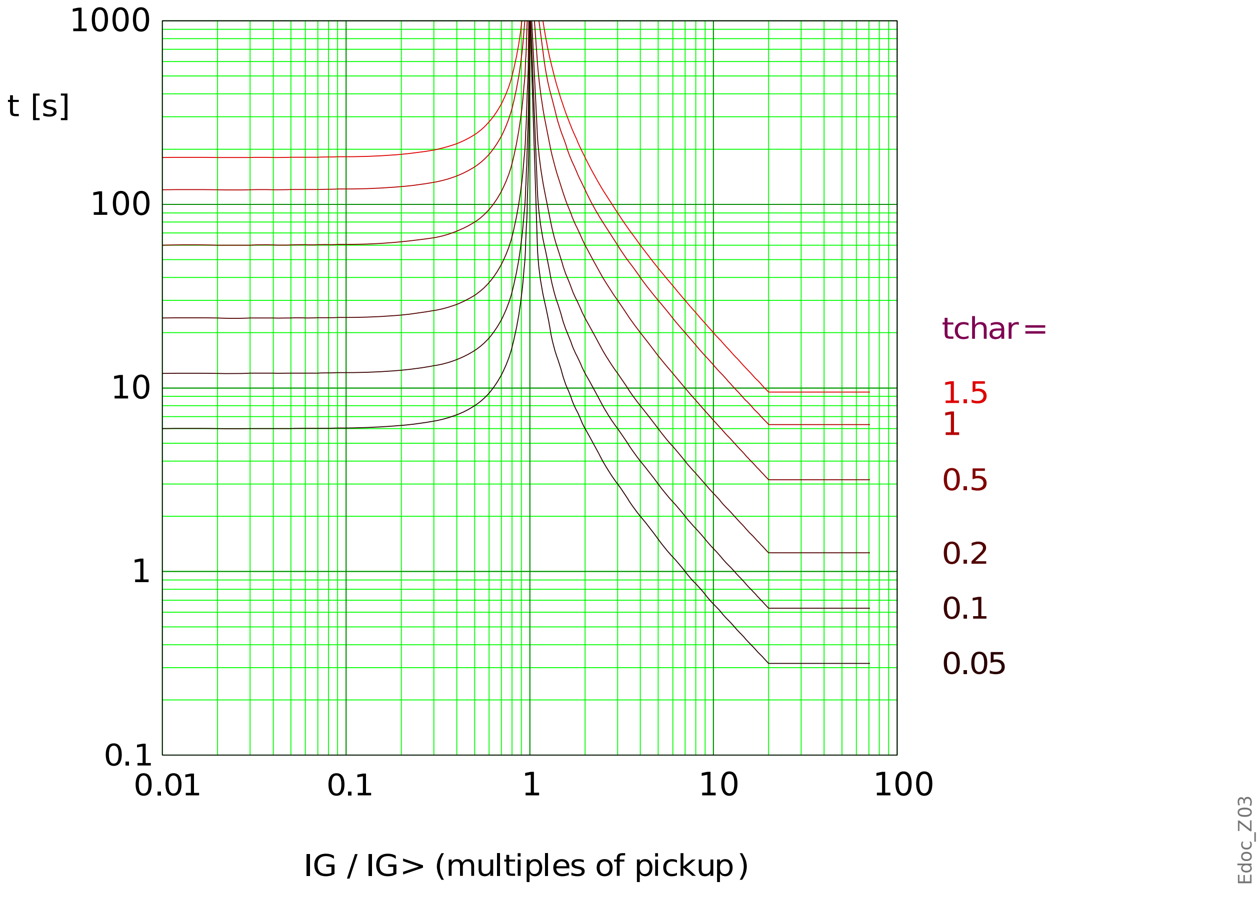
$$t = \frac{120}{1-\left(\frac{IG}{IG>}\right)^2} \cdot tchar$$

If: $$\frac{IG}{IG>} < 1$$

Trip

$$t = \frac{120}{\frac{IG}{IG>} - 1} \cdot tchar$$

If: $$1 < \frac{IG}{IG>} \leq 20$$



ANSI Moderately Inverse

NOTICE **Various reset modes are available: Resetting via characteristic, delayed and instantaneous.**

Remark: For $I_G > 20 \cdot I_{G>}$, the curve stops decreasing, the t-values are kept constant at the value for $I_G = 20 \cdot I_{G>}$.

»Char« = ANSI MINV

Reset

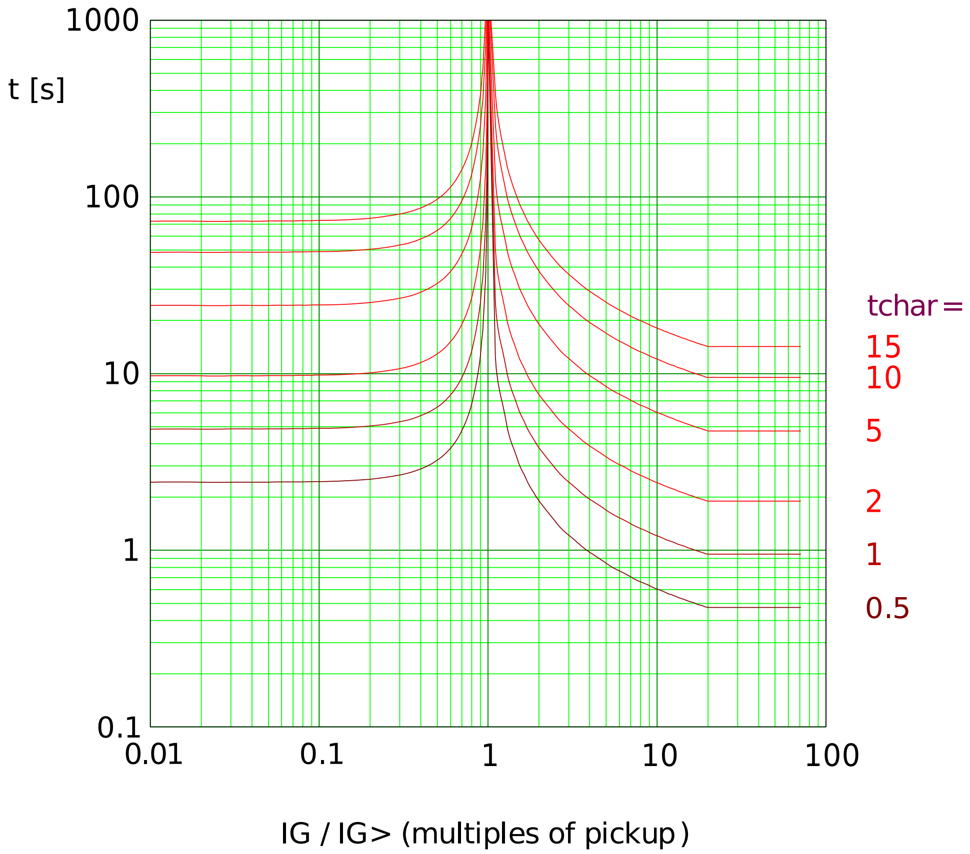
$$t = \frac{4.85}{1-\left(\frac{IG}{IG>}\right)^2} \cdot tchar$$

If: $\frac{IG}{IG>} < 1$

Trip

$$t = \left(\frac{0.0515}{\left(\frac{IG}{IG>}\right)^{0.02} - 1} + 0.1140\right) \cdot tchar$$

If: $1 < \frac{IG}{IG>} \leq 20$



Edoc_Z05

ANSI Very Inverse

NOTICE **Various reset modes are available:**
Resetting via characteristic, delayed and instantaneous.

Remark: For $I_G > 20 \cdot I_{G>}$, the curve stops decreasing, the t-values are kept constant at the value for $I_G = 20 \cdot I_{G>}$.

»Char« = ANSI VINV

Reset

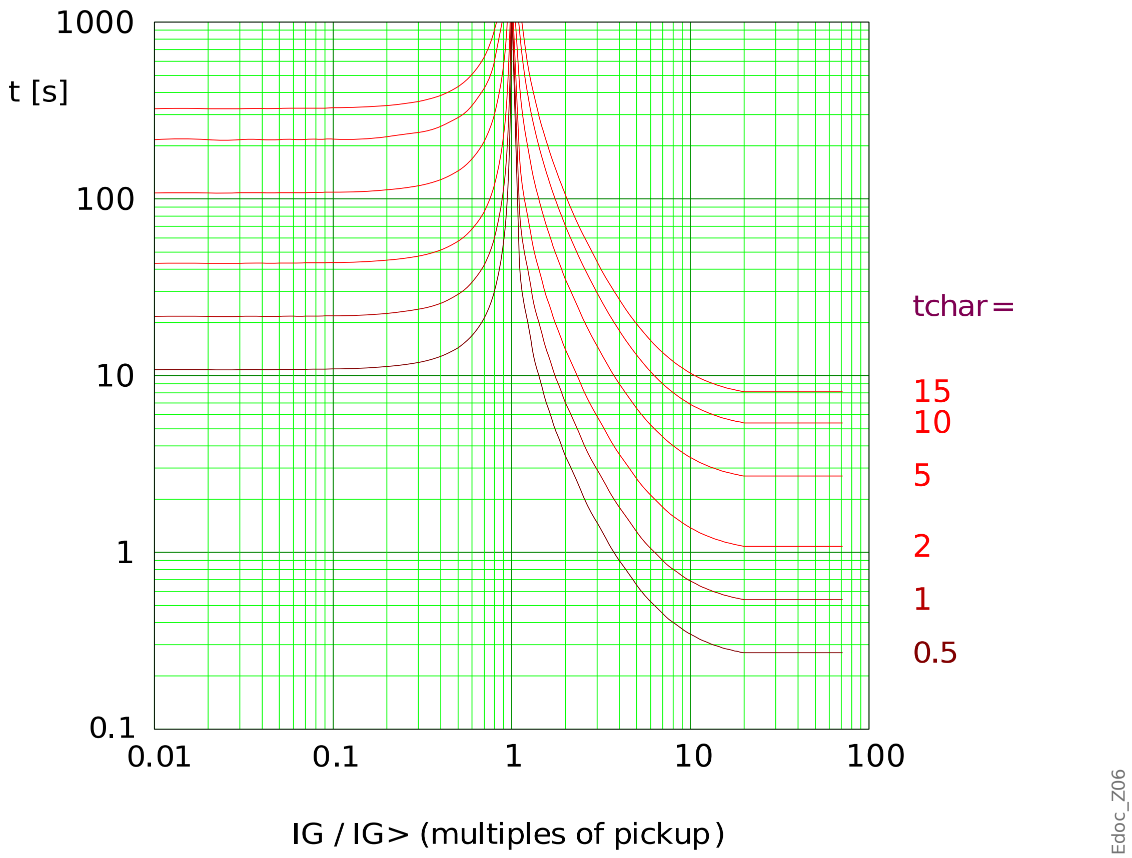
$$t = \frac{21.6}{1 - \left(\frac{IG}{IG>}\right)^2} \cdot tchar$$

If: $$\frac{IG}{IG>} < 1$$

Trip

$$t = \left(\frac{19.61}{\left(\frac{IG}{IG>}\right)^2 - 1} + 0.491 \right) \cdot tchar$$

If: $$1 < \frac{IG}{IG>} \leq 20$$



ANSI Extremely Inverse

NOTICE **Various reset modes are available:**
Resetting via characteristic, delayed and instantaneous.

Remark: For $I_G > 20 \cdot I_{G>}$, the curve stops decreasing, the t-values are kept constant at the value for $I_G = 20 \cdot I_{G>}$.

»Char« = ANSI EINV

Reset

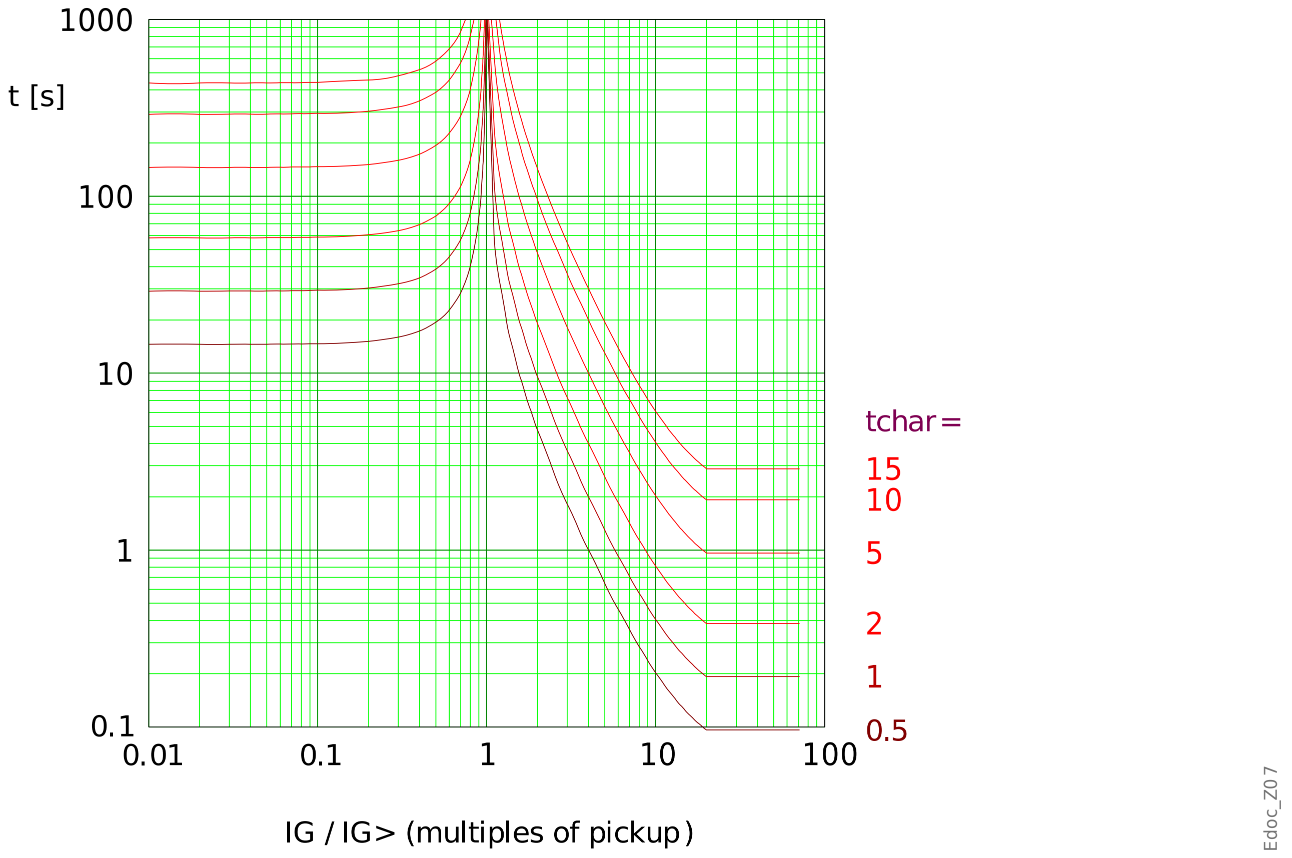
$$t = \frac{29.1}{1-\left(\frac{IG}{IG>}\right)^2} \cdot tchar$$

If: $\frac{IG}{IG>} < 1$

Trip

$$t = \left(\frac{28.2}{\left(\frac{IG}{IG>}\right)^2 - 1} + 0.1217\right) \cdot tchar$$

If: $1 < \frac{IG}{IG>} \leq 20$



R Inverse

NOTICE

Various reset modes are available:
Resetting via characteristic, delayed and instantaneous.

Remark: For $I_G > 20 \cdot I_{G>}$, the curve stops decreasing, the t-values are kept constant at the value for $I_G = 20 \cdot I_{G>}$.

***»Char«* = RINV**

Reset

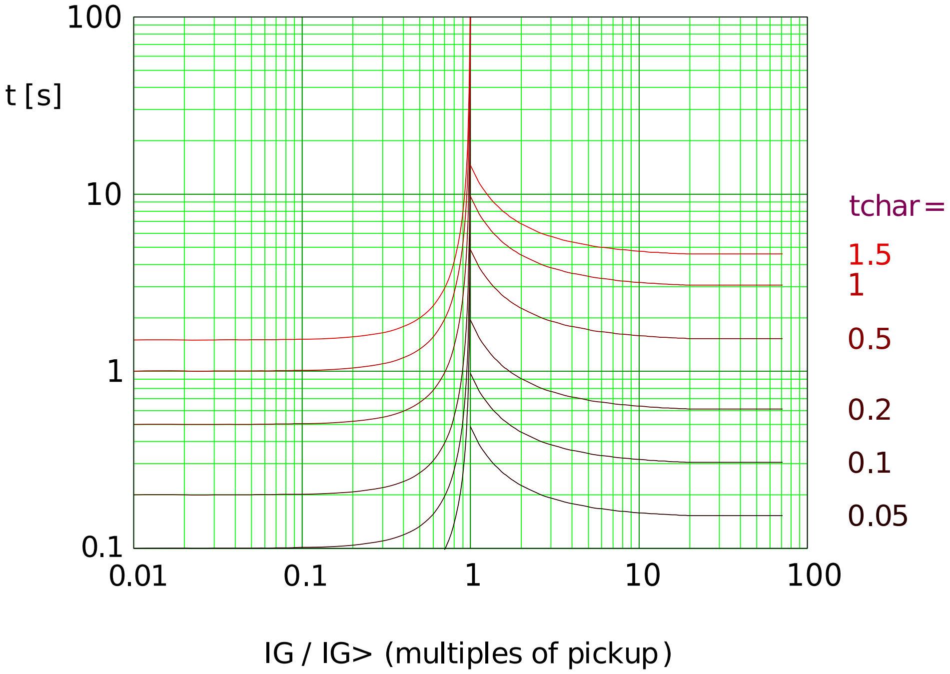
$$t = \frac{1.0}{1-\left(\frac{IG}{IG>}\right)^2} \cdot tchar$$

If: $\frac{IG}{IG>} < 1$

Trip

$$t = \frac{1.0}{0.339-0.236 \cdot \left(\frac{IG}{IG>}\right)^{-1}} \cdot tchar$$

If: $1 < \frac{IG}{IG>} \leq 20$



RXIDG

NOTICE **Various reset modes are available:**
Resetting via characteristic, delayed and instantaneous.

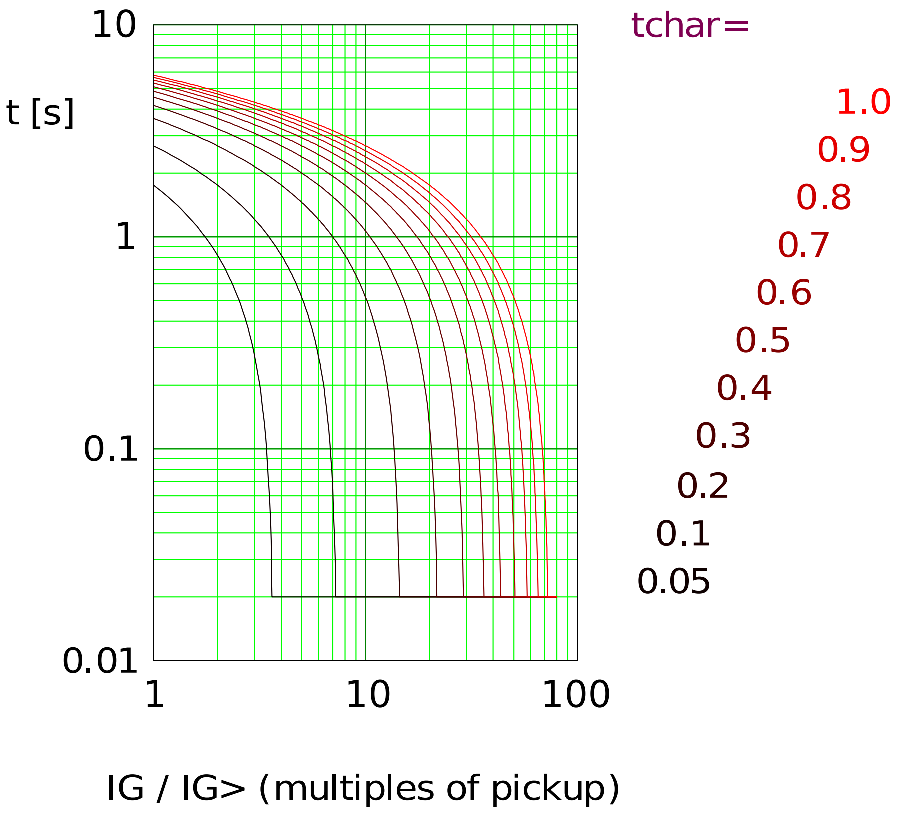
Remark: The curve stops decreasing at t = 0.02 s and is kept constant for higher I_G *values*.

»*Char*« = RXIDG

Trip

$$t = 5.8 - 1.35 \cdot \ln\left(\frac{IG}{IG> \cdot tchar}\right)$$

If: $$1 < \frac{IG}{IG>} \qquad \text{AND} \quad t \geq 0.02\ \text{s}$$



Edoc_Z13

Thermal Flat Curve

NOTICE Various reset modes are available:
Resetting via characteristic, delayed and instantaneous.

***»Char«* = Therm Flat**

Reset

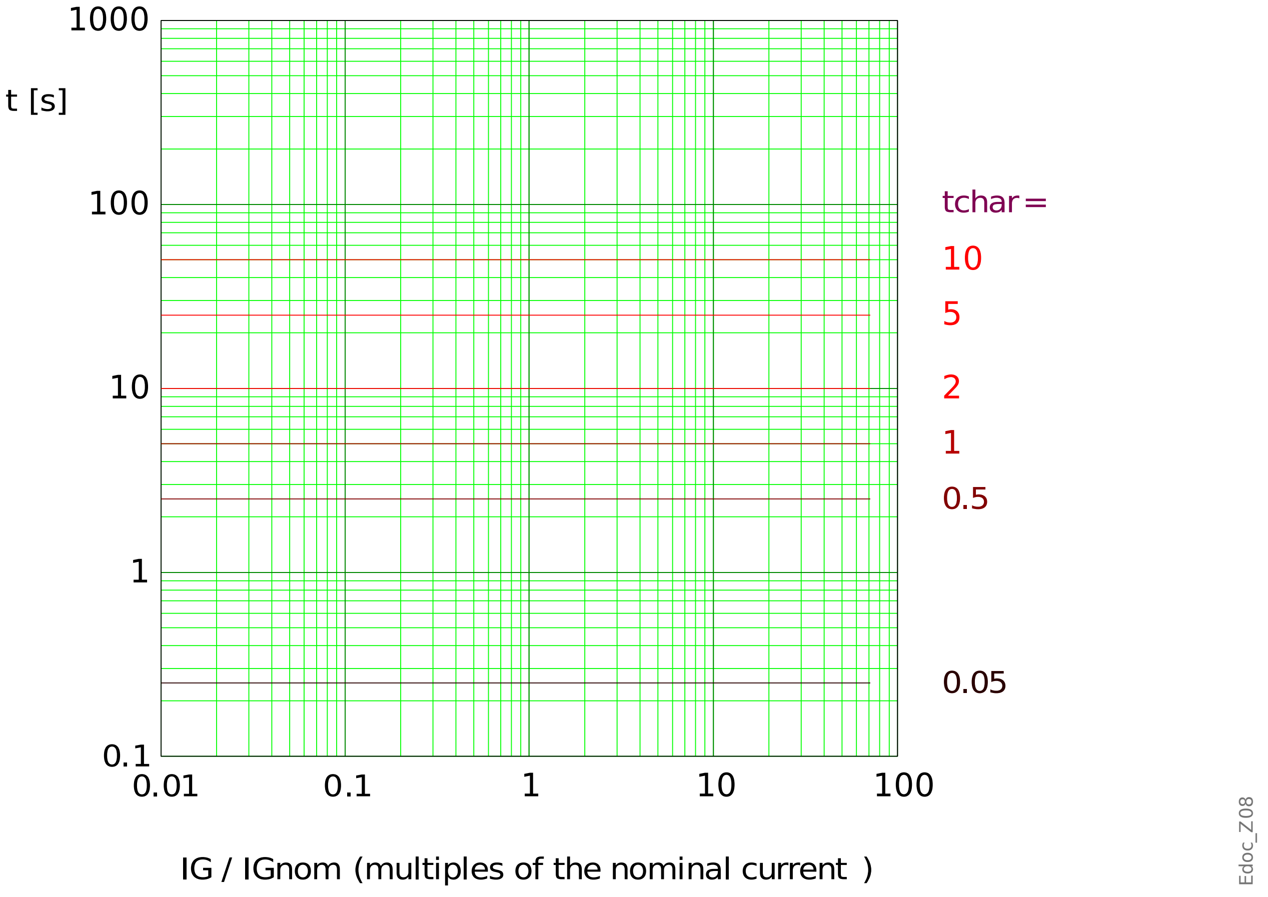
$$t = (5 \cdot 1^2) \cdot tchar$$

If: $\frac{IG}{IGnom} < 1$

Trip

$$t = (5 \cdot 1^0) \cdot tchar$$

If: $1 < \frac{IG}{IGnom}$



Thermal Curve IT

NOTICE Various reset modes are available:
Resetting via characteristic, delayed and instantaneous.

***»Char«* = IT**

Reset

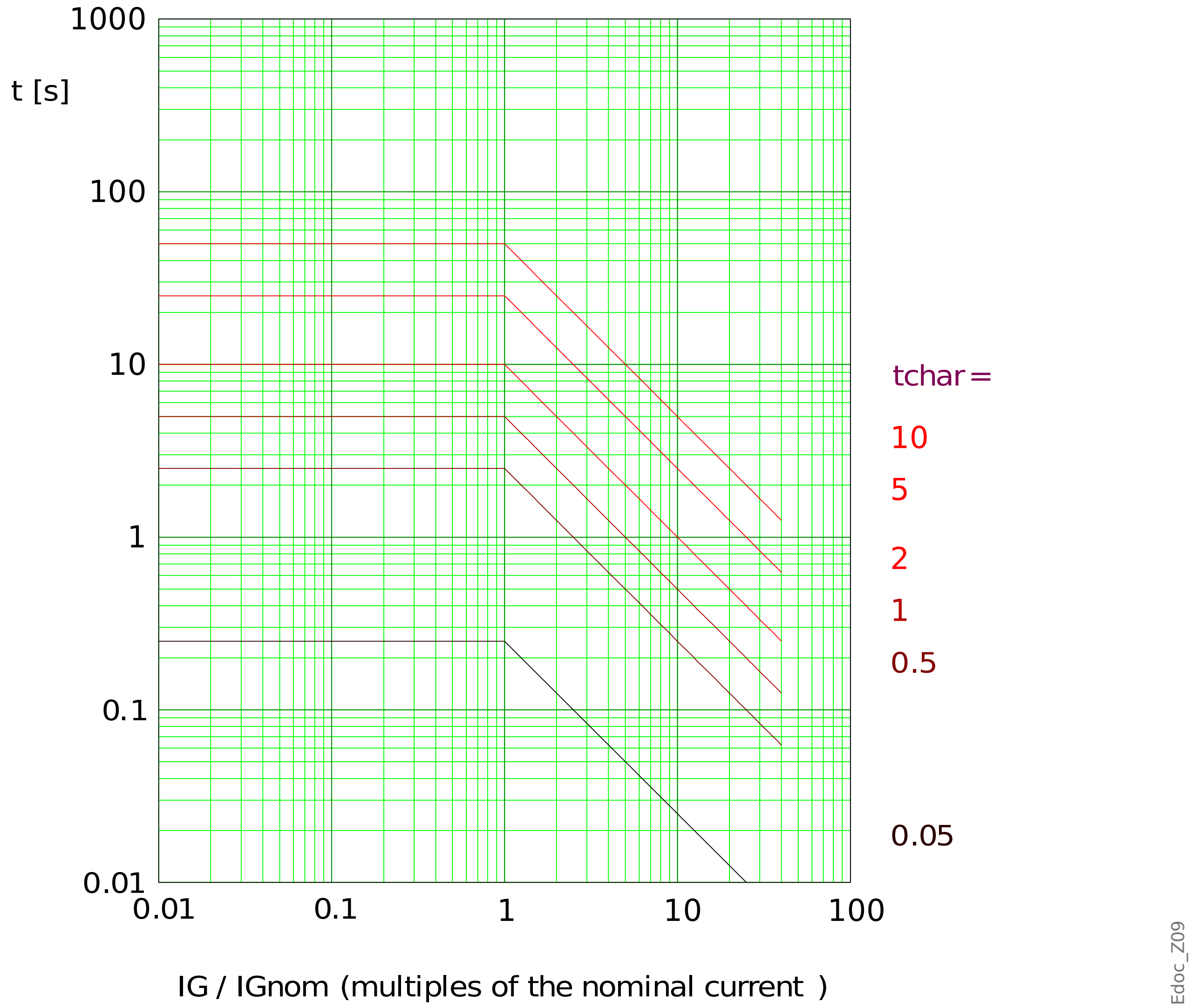
$$t = (5 \cdot 1^2) \cdot tchar$$

If: $\frac{IG}{IGnom} < 1$

Trip

$$t = \frac{5 \cdot 1^1}{\left(\frac{IG}{IGnom}\right)^1} \cdot tchar$$

If: $1 < \frac{IG}{IGnom}$



Thermal Curve I2T

NOTICE Various reset modes are available:
Resetting via characteristic, delayed and instantaneous.

***»Char«* = I2T**

Reset

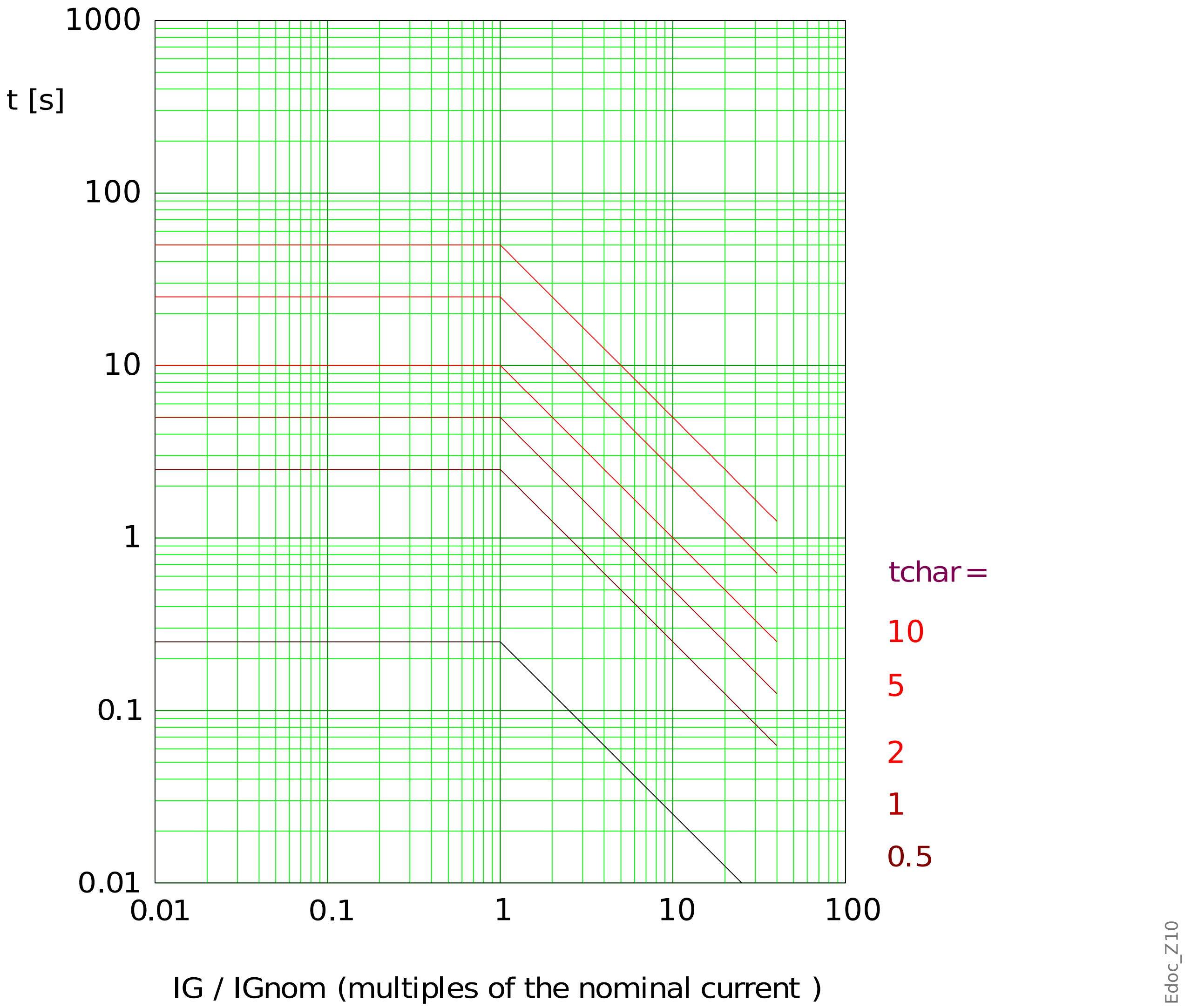
$$t = (5 \cdot 1^2) \cdot tchar$$

If: $\frac{IG}{IGnom} < 1$

Trip

$$t = \frac{5 \cdot 1^2}{\left(\frac{IG}{IGnom}\right)^2} \cdot tchar$$

If: $1 < \frac{IG}{IGnom}$



Thermal Curve I4T

NOTICE Various reset modes are available:
Resetting via characteristic, delayed and instantaneous.

***»Char«* = I4T**

Reset

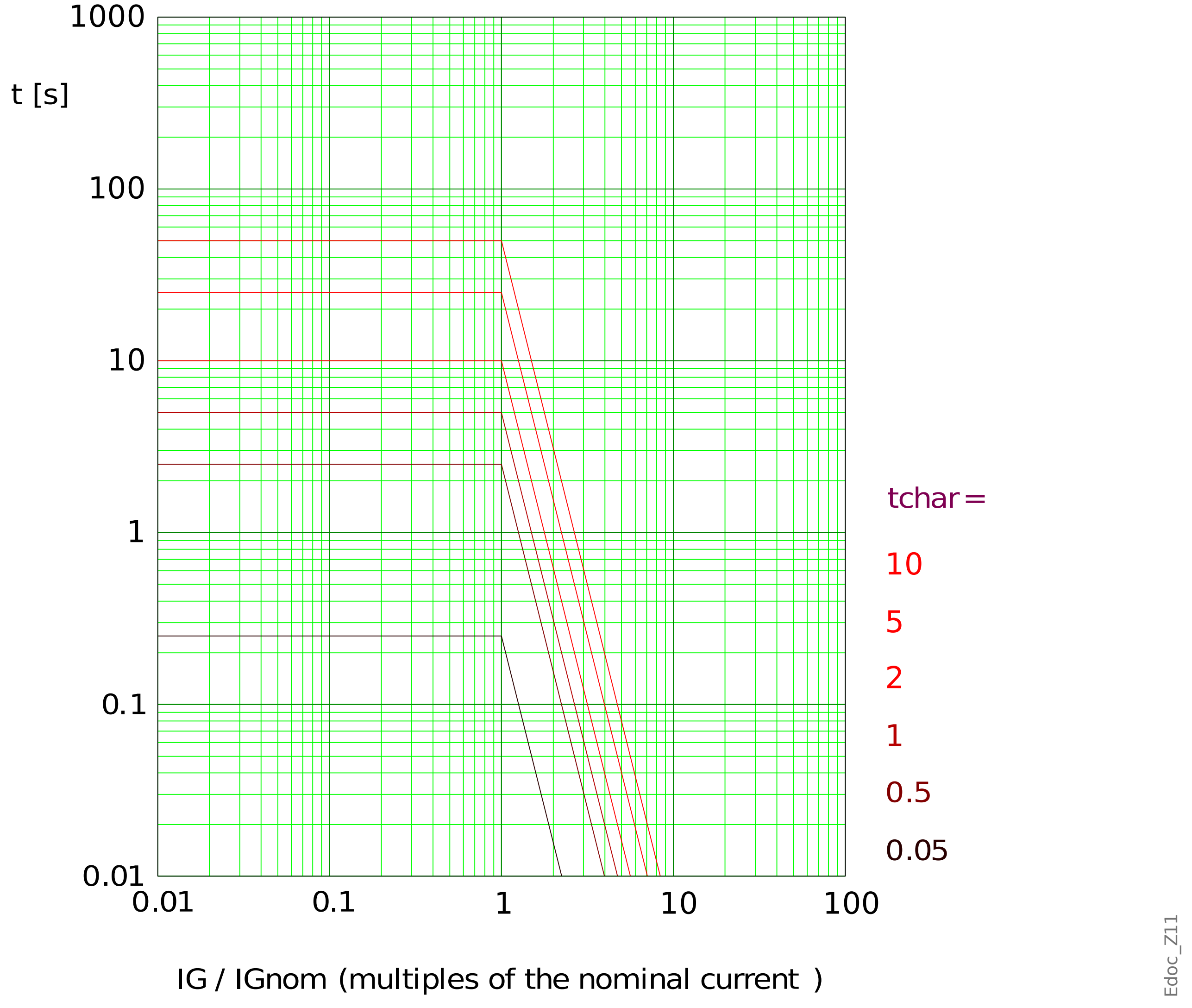
$$t = (5 \cdot 1^2) \cdot tchar$$

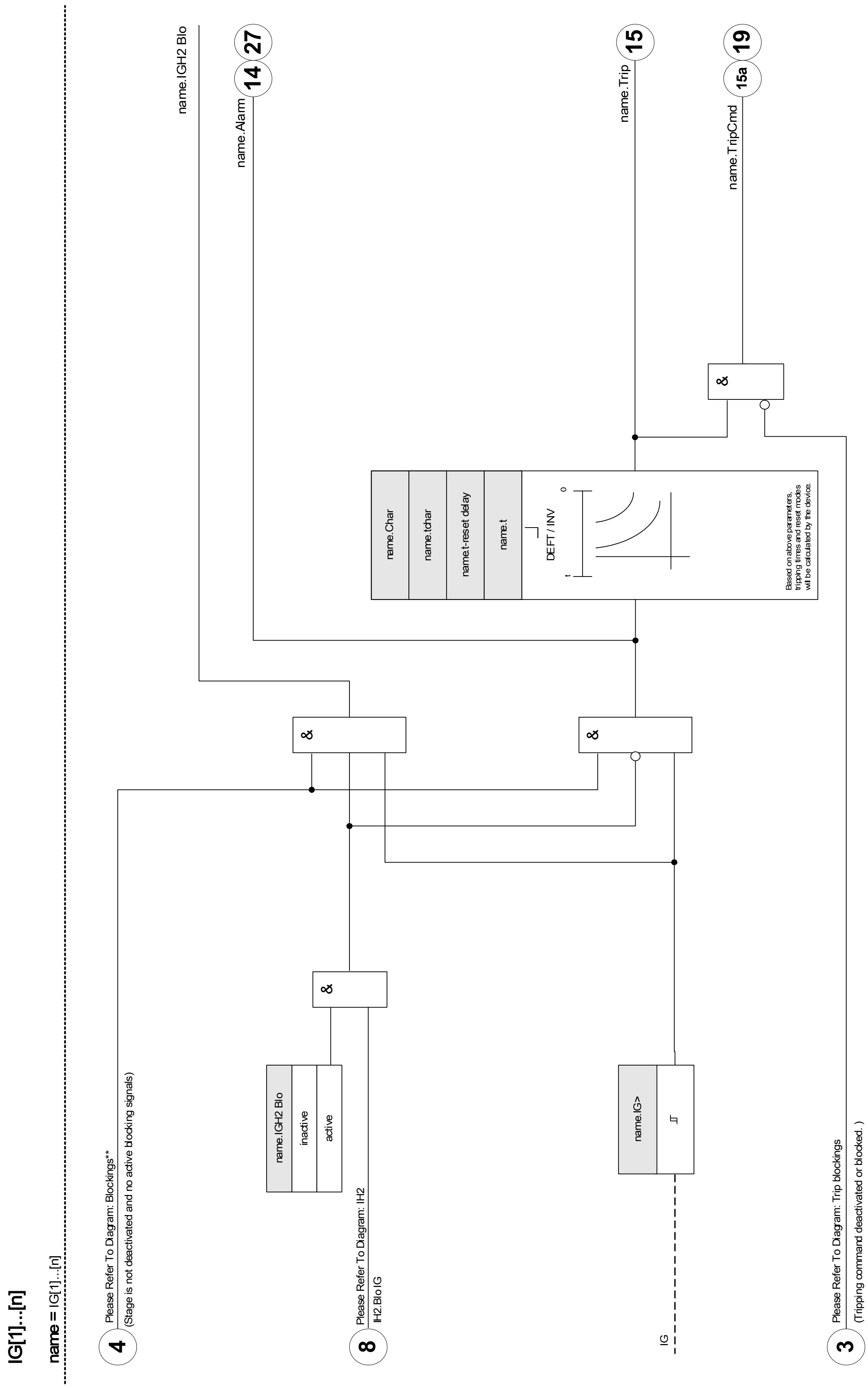
If: $\frac{IG}{IGnom} < 1$

Trip

$$t = \frac{5 \cdot 1^4}{\left(\frac{IG}{IGnom}\right)^4} \cdot tchar$$

If: $1 < \frac{IG}{IGnom}$




IG[1]..[n]
name = IG[1]...[n]
4
Please Refer To Diagram: Blockings**
(Stage is not deactivated and no active blocking signals)
8
Please Refer To Diagram: IH2
IH2.Blo IG
name.IGH2 Blo
inactive
active
&
&
&
&
IG
name.IG>
3
Please Refer To Diagram: Trip blockings
(Tripping command deactivated or blocked.)
name.Char
name.tchar
name.t-reset delay
name.t
DEFT / INV
Based on above parameters, tripping times and reset modes will be calculated by the device.
name.IGH2 Blo
name.Alarm
14
27
name.Trip
15
name.TripCmd
15a
19

Device Planning Parameters of the Ground Fault Protection

Parameter	*Description*	*Options*	*Default*	*Menu path*
Mode	Mode	do not use, non directional	do not use	[Device planning]

Global Protection Parameters of the Ground Fault Protection

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ExBlo1	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /I-Prot /IG[1]]
ExBlo2	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /I-Prot /IG[1]]
ExBlo dur. Mot.Strt	External blocking of the module, if the state of the assigned signal is true. This way it is possible to block the module during the motor start phase.	1..n, Trip Cmds	-.-	[Protection Para /Global Prot Para /I-Prot /IG[1]]
ExBlo TripCmd	External blocking of the Trip Command of the module/the stage, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /I-Prot /IG[1]]
Ex rev Interl	External blocking of the module by external reverse interlocking, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /I-Prot /IG[1]]

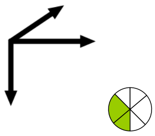
Parameter	Description	Setting range	Default	Menu path
AdaptSet 1	Assignment Adaptive Parameter 1	AdaptSet	-.-	[Protection Para /Global Prot Para /I-Prot /IG[1]]
AdaptSet 2	Assignment Adaptive Parameter 2	AdaptSet	-.-	[Protection Para /Global Prot Para /I-Prot /IG[1]]
AdaptSet 3	Assignment Adaptive Parameter 3	AdaptSet	-.-	[Protection Para /Global Prot Para /I-Prot /IG[1]]
AdaptSet 4	Assignment Adaptive Parameter 4	AdaptSet	-.-	[Protection Para /Global Prot Para /I-Prot /IG[1]]

Setting Group Parameters of the Ground Fault Protection

Parameter	Description	Setting range	Default	Menu path
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[Protection Para /<1..4> /I-Prot /IG[1]]
ExBlo Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /I-Prot /IG[1]]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Ex rev Interl Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "Ex rev Interl Fc = active".	inactive, active	inactive	[Protection Para /<1..4> /I-Prot /IG[1]]
Blo TripCmd	Permanent blocking of the Trip Command of the module/stage.	inactive, active	inactive	[Protection Para /<1..4> /I-Prot /IG[1]]
ExBlo TripCmd Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo TripCmd Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /I-Prot /IG[1]]
IG Source	Selection if measured or calculated ground current should be used.	sensitive measurement, measured, calculated	calculated	[Protection Para /<1..4> /I-Prot /IG[1]]
Measuring method	Measuring method: fundamental or rms or 3rd harmonic (only generator protection relays)	Fundamental, True RMS	Fundamental	[Protection Para /<1..4> /I-Prot /IG[1]]
Meas Circuit Superv	Activates the use of the measuring circuit supervision. In this case the module will be blocked if a measuring circuit supervision module (e.g. LOP, VTS) signals a disturbed measuring circuit (e.g. caused by a fuse failure). Only available if "VX Source" ist set to "calculated".	inactive	inactive	[Protection Para /<1..4> /I-Prot /IG[1]]
IG>	If the pickup value is exceeded, the module/stage will be started.	0.02 - 20.00In	0.02In	[Protection Para /<1..4> /I-Prot /IG[1]]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
IGs>	If the pickup value is exceeded, the module/stage will be started.	0.002 - 2.000In	0.02In	[Protection Para /<1..4> /I-Prot /IG[1]]
Char	Characteristic	DEFT, IEC NINV, IEC VINV, IEC EINV, IEC LINV, RINV, ANSI MINV, ANSI VINV, ANSI EINV, Therm Flat, IT, I2T, I4T, RXIDG	DEFT	[Protection Para /<1..4> /I-Prot /IG[1]]
t	Tripping delay Only available if: Characteristic = DEFT	0.00 - 300.00s	0.00s	[Protection Para /<1..4> /I-Prot /IG[1]]
tchar	Time multiplier/tripping characteristic factor. The setting range depends on the selected tripping curve. Only available if: Characteristic = INV Or Characteristic = Therm Flat Or Characteristic = IT Or Characteristic = I2T Or Characteristic = I4TOr Characteristic = RXIDG	0.02 - 20.00	1	[Protection Para /<1..4> /I-Prot /IG[1]]
Reset Mode	Reset Mode Only available if: Characteristic = INV Or Characteristic = Therm Flat Or Characteristic = IT Or Characteristic = I2T Or Characteristic = I4TOr Characteristic = RXIDG	instantaneous, delayed, calculated	instantaneous	[Protection Para /<1..4> /I-Prot /IG[1]]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
t-reset delay 	Reset delay for intermittent phase failures (INV characteristics only) Only available if: Characteristic = INV Or Characteristic = Therm Flat Or Characteristic = IT Or Characteristic = I2T Or Characteristic = I4TOr Characteristic = RXIDG Only available if:Reset Mode = delayed	0.00 - 60.00s	0.00s	[Protection Para /<1..4> /I-Prot /IG[1]]

Ground Fault Protection Input States

Name	*Description*	*Assignment via*
ExBlo1-I	Module input state: External blocking1	[Protection Para /Global Prot Para /I-Prot /IG[1]]
ExBlo2-I	Module input state: External blocking2	[Protection Para /Global Prot Para /I-Prot /IG[1]]
ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command	[Protection Para /Global Prot Para /I-Prot /IG[1]]
Ex rev Interl-I	Module input state: External reverse interlocking	[Protection Para /Global Prot Para /I-Prot /IG[1]]
AdaptSet1-I	Module input state: Adaptive Parameter1	[Protection Para /Global Prot Para /I-Prot /IG[1]]
AdaptSet2-I	Module input state: Adaptive Parameter2	[Protection Para /Global Prot Para /I-Prot /IG[1]]
AdaptSet3-I	Module input state: Adaptive Parameter3	[Protection Para /Global Prot Para /I-Prot /IG[1]]

Name	*Description*	*Assignment via*
AdaptSet4-I	Module input state: Adaptive Parameter4	[Protection Para /Global Prot Para /I-Prot /IG[1]]

Ground Fault Protection Signals (Output States)

Signal	*Description*
active	Signal: active
ExBlo	Signal: External Blocking
Ex rev Interl	Signal: External reverse Interlocking
Blo TripCmd	Signal: Trip Command blocked
ExBlo TripCmd	Signal: External Blocking of the Trip Command
Alarm	Signal: Alarm IG
Trip	Signal: Trip
TripCmd	Signal: Trip Command
Active AdaptSet	Active Adaptive Parameter
DefaultSet	Signal: Default Parameter Set
AdaptSet 1	Signal: Adaptive Parameter 1
AdaptSet 2	Signal: Adaptive Parameter 2
AdaptSet 3	Signal: Adaptive Parameter 3
AdaptSet 4	Signal: Adaptive Parameter 4

Ground Fault Protection Counter Values

Value	*Description*	*Default*	*Size*	*Menu path*
NumberOfAlarms	Number of alarms since last reset.	0	0 - 9999999999	[Operation /History /AlarmCr]
NumberOfTripCmds	Number of trip commands since last reset	0	0 - 9999999999	[Operation /History /TripCmdCr]

Commissioning: Ground Fault Protection – non-directional [50N/G, 51N/G]

Please test the non-directional earth overcurrent analog to the nondirectional phase overcurrent protection.

I2> and %I2/I1> – Unbalanced Load [46]

Elements:
I2>[1] ,I2>[2]

The *I2>* Current Unbalance module works similar to the *V 012* Voltage Unbalance module. The positive and negative sequence currents are calculated from the 3-phase currents. The threshold setting (either »*I2>*« or *»I2/FLA«*) defines a minimum operating current magnitude of I2 for the 46 function to operate, which insures that the relay has a solid basis for initiating a current unbalance trip. The »*%(I2/I1)«* (option) setting is the unbalance trip pickup setting. It is defined by the ratio of negative sequence current to positive sequence current »*%(I2/I1)«.*

NOTICE **All I2> Current Unbalance modules are identically structured.**

The condition for a trip of this module is that the negative sequence current I2 is above the set threshold ***and*** – if configured – the percentage current unbalance is above the setting »*%(I2/I1)«*. The module initiates a trip if this condition is fulfilled for a specific tripping delay time.

For this tripping delay time, there are two characteristics available as configuring options, a definite time characteristic (DEFT, where the tripping delay is a setting value) and an inverse characteristic (INV, where the tripping delay is calculated).

The setting of »CurrentBase*«* decides about whether »*I2>«* or *»I2/FLA«* is used as the threshold value. This rating value – »*I2>«* or *»I2/FLA«* – is the permitted continuous unbalanced load current, and it is specified in units of either I_n (for *»CurrentBase« = "*Device Rating*"*) or I_b (for *»CurrentBase« = "*Protected Object Rating*"*).

The principle of the definite time characteristic (DEFT) is as follows:

- The module trips if for the tripping delay time (which is set as the Setting Group parameter *»t«*) the negative sequence current I2 is above the set threshold ***and*** (if configured) the percentage current unbalance is above the setting »*%(I2/I1)«*.

The principle of the inverse time characteristic (INV) is as follows:

- The protective device permanently calculates the heat (thermal) energy θ of the object to be protected. This happens all the time, independent of any alarm or tripping decisions.
  The module trips if for the tripping delay time t_{trip} – which is dependent on θ – the following conditions are all fulfilled:

  1. The negative sequence current *I2* is above the set threshold (»*I2>«* or *»I2/FLA«*) ***and***
  2. the percentage current unbalance is above the setting »*%(I2/I1)«* (if »*%(I2/I1)«* is set to *active*) **and**
  3. the calculated thermal energy θ exceeds a maximum value θ_{max},, which is calculated based on the setting *K* for the thermal load capability.

- For $\theta = 0$ the tripping delay time is calculated as follows:

for *»CurrentBase« = "*Device Rating*"*	for *»CurrentBase« = "*Protected Object Rating*"*
$t_A = \frac{K \cdot I_n^2}{I_2^2 - I_{2>}^2}$	$t_A = \frac{K \cdot I_b^2}{I_2^2 - I_{2/FLA}^2}$

where

t_{trip} = tripping delay in seconds,

K = thermal load capability of the object while running with 100% unbalanced load current. This is an intrinsic property of the object that is to be protected, and therefore it must be specified as a setting value (Setting Group parameter »*K*«).

I_n = nominal current, in case of *»CurrentBase« = "*Device Rating*",*
I_b = nominal current of the protected object, in case of *»CurrentBase« = "*Protected Object Rating*".*

I_2 = unbalanced load current *I2* (calculated from measured current values),

$I_{2>}$ = Setting value »*I2>*«, in case of *»CurrentBase« = "*Device Rating*",*
$I_{2/FLA}$ = Setting value »*I2/FLA*«, in case of *»CurrentBase« = "*Protected Object Rating*".*

- In case of a still present residual heat, $\theta > 0$, the tripping delay t_{trip} is reduced accordingly, so that an earlier tripping occurs.
- As long as the unbalanced load current *I2* is ***greater*** than the threshold »*I2>*« it is assumed that the object is *heating up*. During this phase, the heat (thermal) energy is calculated by an integration of the current value *I2*:

$$\theta(t)=\theta_{0,cool}+f\cdot\int\left|\vec{I}_2\right|^2 dt$$

$\theta(t)$ = actual value of the thermal energy,

$\theta_{0,cool}$ = initial value at the beginning of the heating phase, i. e. the thermal energy at the end of the last cooling-down phase (or = 0, if the last cooling-down phase has ended, see below, or if there has not been any cooling-down phase yet),

f = scaling factor.

- As long as the unbalanced load current *I2* is ***less*** than the threshold (»*I2>*« or *»I2/FLA«*) it is assumed that the object is *cooling down*. During this phase, the heat (thermal) energy is calculated based on a cooling-down constant. This constant is another intrinsic property of the object that is to be protected, and therefore it must be specified as a setting value (Setting Group parameter »*τ-cool*«):

$$\theta(t)=\theta_{0,heat}\cdot e^{-\frac{t}{\tau_{cool}}}$$

$\theta(t)$ = actual value of the thermal energy,

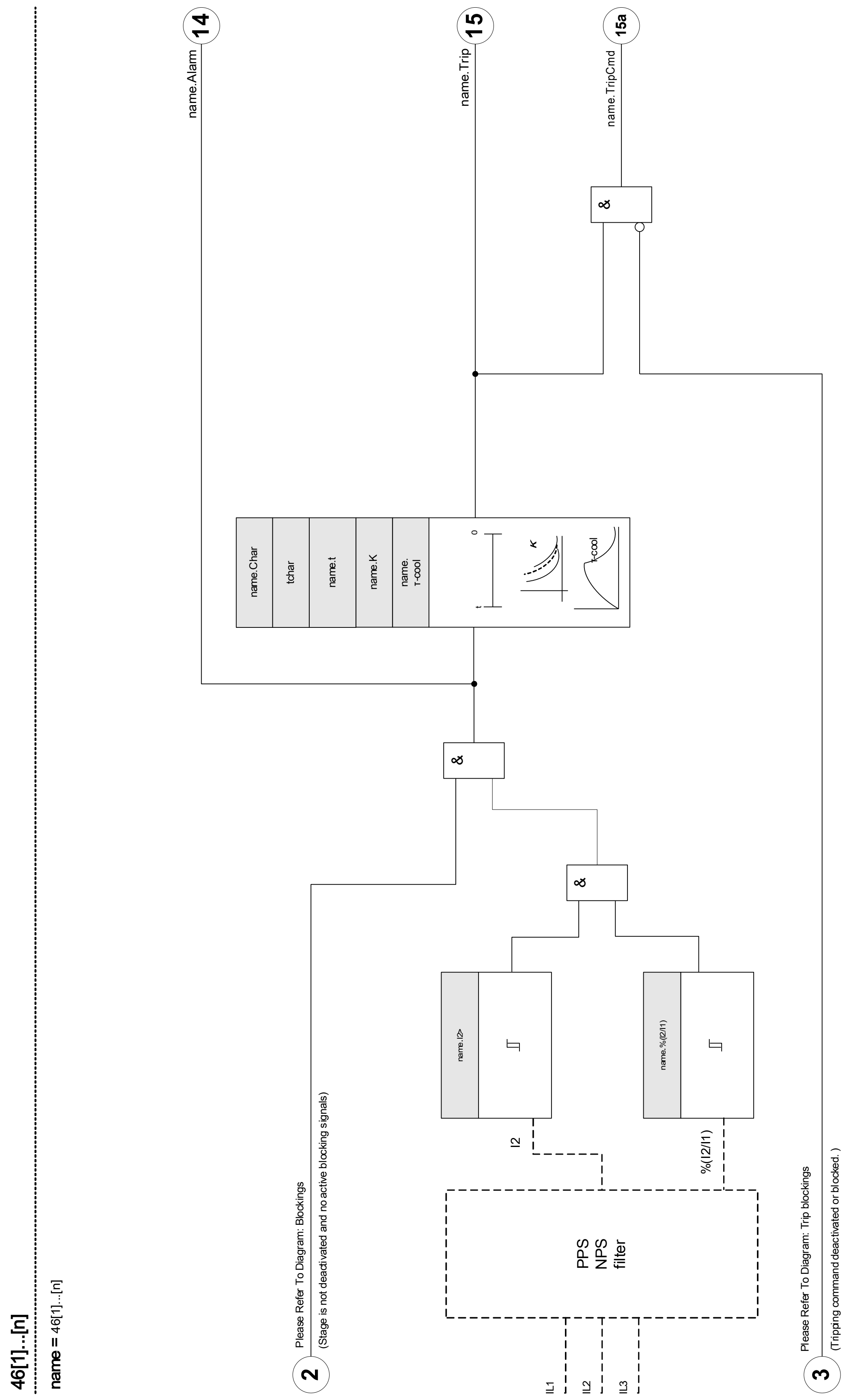
$\theta_{0,heat}$ = initial value at the beginning of the cooling-down phase, i. e. the thermal energy at the end of the last heating-up phase

τ_{cool} = object property, setting value »*τ-cool*«.

- The cooling-down phase always continues as long as I2 is below the threshold, i. e. $\theta(t)$ is calculated continuously. (Only after $\theta(t)$ has dropped below $0.01\cdot\theta_{max}$ the calculation ends and θ gets reset to *0*, i. e. a subsequent heating-up phase will start with initial value $\theta_{0,cool} = 0$.)

NOTICE

The heat (thermal) energy is an auxiliary value that is calculated and maintained internally, i. e. it can neither be displayed at the HMI nor be retrieved via any communication protocol.



46[1]...[n]
name = 46[1]...[n]
2
Please Refer To Diagram: Blockings
(Stage is not deactivated and no active blocking signals)
IL1
IL2
IL3
PPS
NPS
filter
I2
%(I2/I1)
name.I2>
name.%(I2/I1)
&
&
name.Char
tchar
name.t
name.K
name.
τ-cool
K
τ-cool
name.Alarm
14
name.Trip
15
&
name.TripCmd
15a
3
Please Refer To Diagram: Trip blockings
(Tripping command deactivated or blocked.)

Device Planning Parameters of the Current Unbalance Module

Parameter	*Description*	*Options*	*Default*	*Menu path*
Mode	Mode	do not use, use	I2>[1]: use I2>[2]: do not use	[Device planning]

Global Protection Parameters of the Current Unbalance Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ExBlo1	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /I-Prot /I2>[1]]
ExBlo2	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /I-Prot /I2>[1]]
ExBlo dur. Mot.Strt	External blocking of the module, if the state of the assigned signal is true. This way it is possible to block the module during the motor start phase.	1..n, Trip Cmds	I2>[1]: MStart.Blo-I2>Start I2>[2]: -.-	[Protection Para /Global Prot Para /I-Prot /I2>[1]]
ExBlo TripCmd	External blocking of the Trip Command of the module/the stage, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /I-Prot /I2>[1]]

Setting Group Parameters of the Current Unbalance Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[Protection Para /<1..4> /I-Prot /I2>[1]]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ExBlo Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /I-Prot /I2>[1]]
Blo TripCmd	Permanent blocking of the Trip Command of the module/stage.	inactive, active	inactive	[Protection Para /<1..4> /I-Prot /I2>[1]]
ExBlo TripCmd Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo TripCmd Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /I-Prot /I2>[1]]
I2>	The Threshold setting defines a minimum operating current magnitude of I2 for the 46 function to operate, which ensures that the relay has a solid basis for initiating a current unbalance trip. This is a supervisory function and not a trip level. Only available if: I2>.CurrentBase = Device Rating	0.01 - 4.00In	I2>[1]: 0.08In I2>[2]: 0.01In	[Protection Para /<1..4> /I-Prot /I2>[1]]
%(I2/I1)	The %(I2/I1) setting is the unbalance trip pickup setting. It is defined by the ratio of negative sequence current to positive sequence current (% Unbalance=I2/I1). Phase sequence will be taken into account automatically.	inactive, active	inactive	[Protection Para /<1..4> /I-Prot /I2>[1]]
%(I2/I1)	The %(I2/I1) setting is the unbalance trip pickup setting. It is defined by the ratio of negative sequence current to positive sequence current (% Unbalance=I2/I1). Phase sequence will be taken into account automatically. Only available if: %(I2/I1) = use	2 - 40%	20%	[Protection Para /<1..4> /I-Prot /I2>[1]]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Char	Characteristic	DEFT, INV	DEFT	[Protection Para /<1..4> /I-Prot /I2>[1]]
t	Tripping delay Only available if: Characteristic = DEFT	0.00 - 300.00s	0.00s	[Protection Para /<1..4> /I-Prot /I2>[1]]
K	This setting is the negative sequence capability constant. This value is normally provided by the generator manufacturer. Only available if: Characteristic = INV	1.00 - 200.00s	10.0s	[Protection Para /<1..4> /I-Prot /I2>[1]]
τ-cool	If the unbalanced load current falls below the pickup value, the cooling-off time is taken into account. If the unbalanced load exceeds the pickup value again, than the saved heat within the electrical equipment will lead to an accelerated trip. Only available if: Characteristic = INV	0.0 - 60000.0s	0.0s	[Protection Para /<1..4> /I-Prot /I2>[1]]

Current Unbalance Module Input States

Name	*Description*	*Assignment via*
ExBlo1-I	Module input state: External blocking1	[Protection Para /Global Prot Para /I-Prot /I2>[1]]
ExBlo2-I	Module input state: External blocking2	[Protection Para /Global Prot Para /I-Prot /I2>[1]]
ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command	[Protection Para /Global Prot Para /I-Prot /I2>[1]]

Current Unbalance Module Signals (Output States)

Signal	*Description*
active	Signal: active
ExBlo	Signal: External Blocking
Blo TripCmd	Signal: Trip Command blocked
ExBlo TripCmd	Signal: External Blocking of the Trip Command
Alarm	Signal: Alarm Negative Sequence
Trip	Signal: Trip
TripCmd	Signal: Trip Command

Current Unbalance Module Counter Values

Value	*Description*	*Default*	*Size*	*Menu path*
NumberOfAlarms	Number of alarms since last reset.	0	0 - 9999999999	[Operation /History /AlarmCr]
NumberOfTripCmds	Number of trip commands since last reset	0	0 - 9999999999	[Operation /History /TripCmdCr]

Commissioning: Current Unbalance Module

Object to be tested:
Test of the unbalanced load protection function.

Necessary means:
- Three-phase current source with adjustable current unbalance; and
- Timer.

Procedure:

Check the phase sequence:

- Ensure that the phase sequence is the same as that set in the field parameters.
- Feed-in a three-phase nominal current.
- Change to the »Measuring Values« menu.
- Check the measuring value for the unbalanced current *»I2«*. The measuring value displayed for »*I2*« should be zero (within the physical measuring accuracy).

NOTICE **If the displayed magnitude for I2 is the same as that for the symmetrical nominal currents fed to the relay, it implies that the phase sequence of the currents seen by the relay is reversed.**

- Now turn-off phase L1.
- Again check the measuring value of the unbalanced current »*I2*« in the »Measuring Values« menu. The measuring value of the asymmetrical current »*I2*« should now be 33%.
- Turn-on phase L1, but turn-off phase L2.
- Once again check the measuring value of the asymmetrical current I2 in the »Measuring Values« menu. The measuring value of the asymmetrical current »*I2*« should be again 33%.
- Turn-on phase L2, but turn-off phase L3.
- Again check the measuring value of asymmetrical current »*I2*« in the »Measuring Values« menu. The measuring value of the asymmetrical current »*I2*« should still be 33%.

Testing the trip delay:

- Apply a symmetrical three-phase current system (nominal currents).
- Switch off IL1 (the threshold value »*Threshold*« for »*I2*« must be below 33%).
- Measure the tripping time.

The present current unbalance »*I2*« corresponds with 1/3 of the existing phase current displayed.

Testing the threshold values

- Configure minimum »*%I2/I1*« setting (2%) and an arbitrary threshold value »*Threshold*« (I2).
- For testing the threshold value, a current has to be fed to phase A which is lower than three times the adjusted threshold value »*Threshold*« (I2).
- Feeding only phase A results in »*%I2/I1 = 100%*«, so the first condition »*%I2/I1 >= 2%*« is always fulfilled.
- Now increase the phase L1 current until the relay is activated.

Testing the dropout ratio of the threshold values

Having tripped the relay in the previous test, now decrease the phase A current. The dropout ratio must not be higher than 0.97 times the threshold value.

Testing %I2/I1

- Configure minimum threshold value »*Threshold*« (I2) (0.01 x In) and set »*%I2/I1*« greater or equal to 10%.
- Apply a symmetrical three-phase current system (nominal currents). The measuring value of »*%I2/I1*« should be 0%.
- Now increase the phase L1 current. With this configuration, the threshold value »*Threshold*« (I2) should be reached before the value »*%I2/I1*« reaches the set »*%I2/I1*« ratio threshold.
- Continue increasing the phase 1 current until the relay is activated.

Testing the dropout ratio of %I2/I1

Having tripped the relay in the previous test, now decrease the phase L1 current. The dropout of »*%I2/I1*« has to be 1% below the »*%I2/I1*«setting.

Successful test result:

The measured trip delays, threshold values, and dropout ratios are within the permitted deviations/tolerances, specified under Technical Data.

Theta - Thermal Model [49M, 49R]

Available Elements:
ThR

General – Principle Use

Thermal Protection and Alarm

This protective device provides a thermal model. The thermal model can work with or without the URTD. The RTD-based direct temperature trips and alarms are independent of the thermal model. Without the URTD, meaning the URTD is not connected to the protective device or it is connected but not configured for the thermal protection trips, the thermal model protection will be solely based on the following settings:

1.Ib Full Load Ampere (FLA);
2.Locked Rotor Current (LRC);
3.Maximum Allowable Stall Time (Tc);
4.k-Factor;
5.Thermal Model Trip Threshold if enabled;
6.Trip Delay;
7.Thermal Model Alarm Threshold if enabled; and
8.Alarm Delay.

The first four settings (1-4) dictate the maximum allowable thermal limit curve of the protected equipment, and the last four settings (5-8) define the thermal trip and alarm curves relative to the thermal limit curve.

Mathematically, the thermal limit curve can be expressed as the following:

$$Trip\,Time = \frac{I_{LR}^2 \cdot T_{LR}}{I_{ef}^2} \quad \text{when} \quad I_{ef} > k_{Factor} \cdot CT_{pri}$$

If the direct stator temperature measurements are available, the thermal replica model will be modified to include the heat loss between stator and rotor. As a result, the motor will be able to run longer under overload conditions. The heat loss serves as a cooling. At some point, the cooling effect will cancel the heat increment so that the thermal capacity used will reach some steady-state level that may be below the trip or alarm limit. This equivalently raises the »*k-factor*« and shifts the trip curve right.

If the thermal capacity used is held at a level that is below the trip threshold, the thermal model will not trip. To prevent the protected equipment from overheating, the direct temperature trip function must be enabled. Keep in mind that in order for the stator temperature to be effective in the thermal replica model, the following conditions must be met:

- Some RTD channels must be configured to measure the winding temperatures; and
- These RTD channels must be enabled for trip.

In addition, at least one of these winding temperatures must be valid.

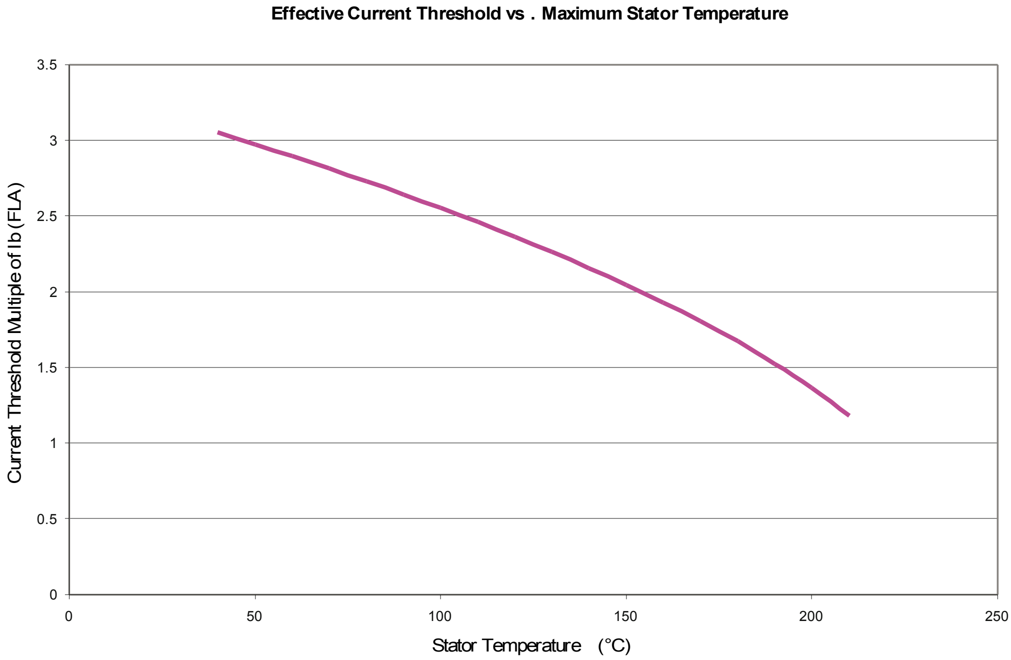
Knowing the maximum steady stator temperature Θ_S (°C), the thermal capacity used can be estimated by the following formula.

$$TC_{Used}\% = \left(\frac{\Theta_S}{240} + \frac{I_{ef}^2 \cdot 50}{I_{LR}^2 \cdot T_{LR}}\right) \quad \text{when} \quad I_{ef} > Ith \cdot FLA$$

Take for example, ILR = 6 · FLA, TLR = 15, and thermal trip level of 100%. The relationship between the effective current threshold and the stator temperature can be seen in the Stator Temperature Effect on Current Threshold Curve.

Stator Temperature Effect on Current Threshold Curve

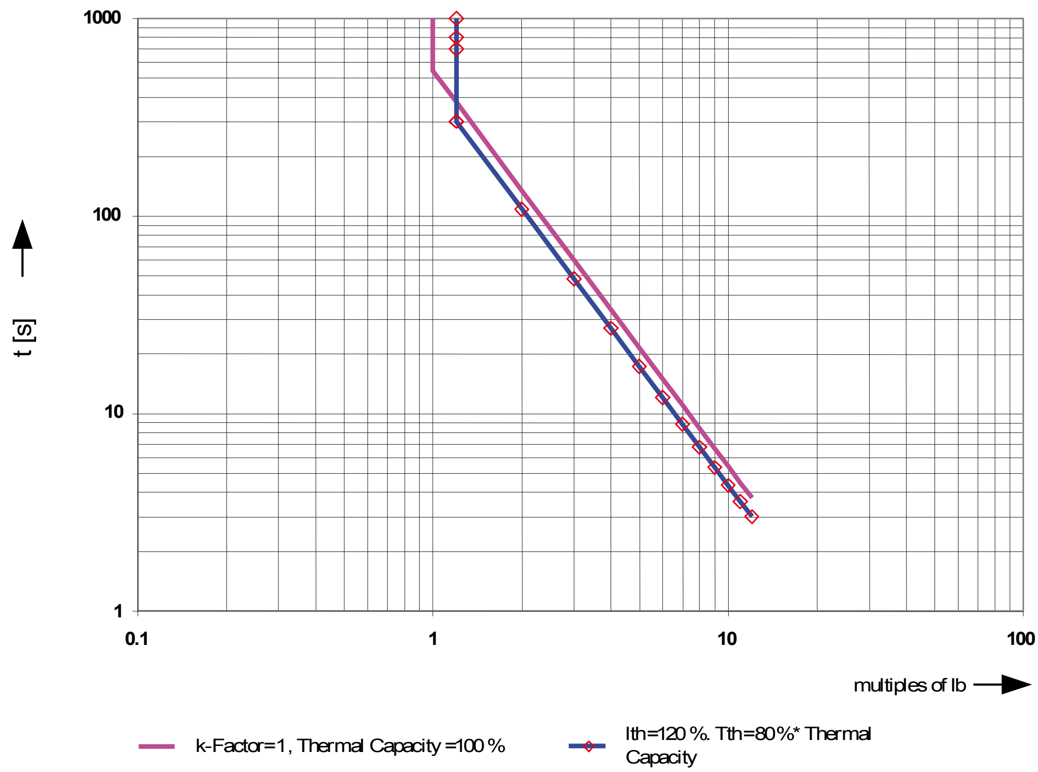
From the graph, it is seen that the lower the stator temperature, the higher the effective current threshold.

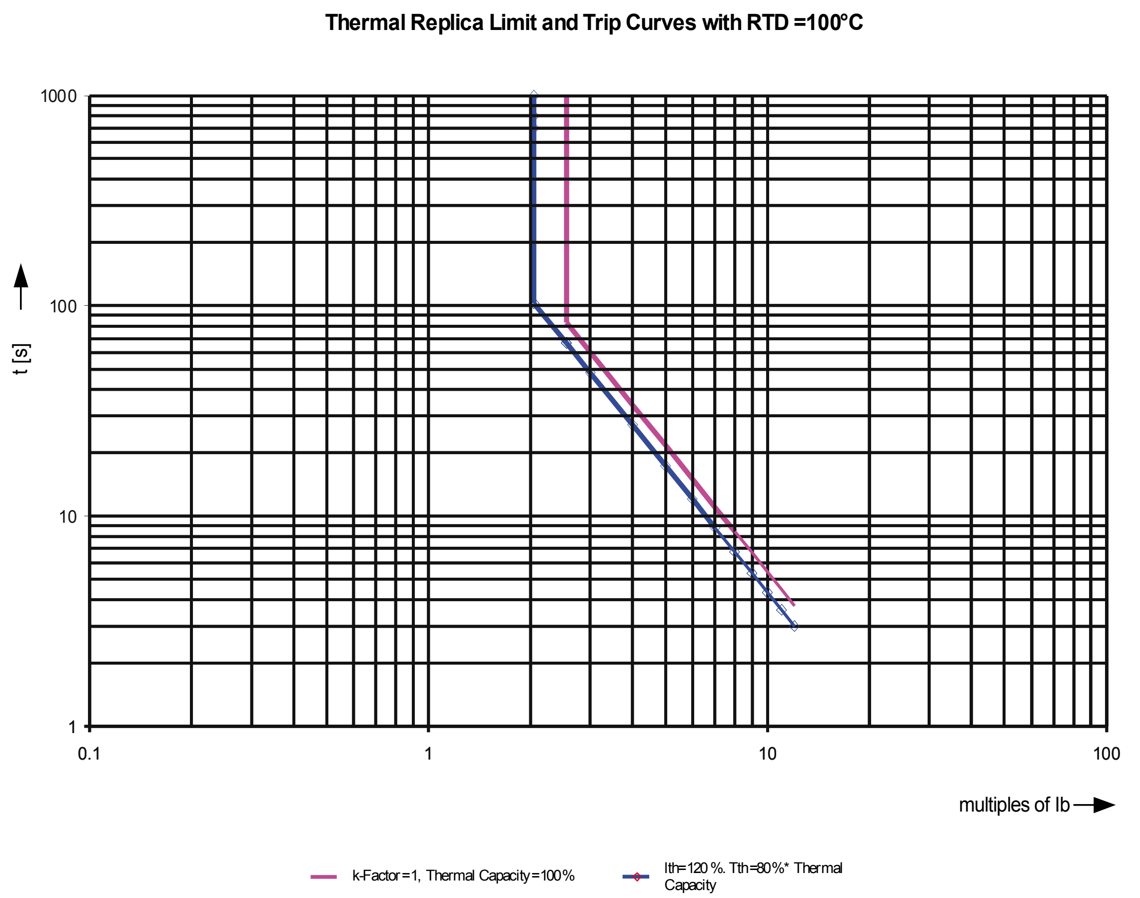


Without stator temperature, given the current threshold of 1.0 · Ib (FLA) and 2.0 · Ib (FLA) of the stator phase current, the thermal model will use the full thermal capacity in 139.54 seconds. However, if the stator temperature is known as 100°C (212°F), the effective ultimate trip current threshold is raised to 2.55 · Ib (FLA) and the thermal capacity used will reach a steady state of 77.5%. As a result, the thermal model will never trip under this condition. From this example, it can be seen that the stator RTD could keep the motor running under overload condition. In this case, the appropriate direct stator temperature trip function must be enabled.

In the Thermal Replica Model Trip Curves with and without RTD, the unmarked lines are the thermal limit curves and the marked lines are the trip curves. From the curve without RTD, it can be seen that one can change the thermal current threshold to shift the upper portion of the trip curve right to allow the motor to run at a higher overload condition than is specified with the service factor. From the curve with RTD, it can be seen that the stator RTD pushes the effective thermal current threshold to 2.55 · Ib (FLA) on the thermal limit curve (unmarked line). The marked line is the trip curve with 80% thermal capacity trip threshold, so actual effective thermal current threshold for the trip curve is about 2.05 · Ib (FLA). Although in this case, the thermal current threshold is set to 1.50 · Ib (FLA), it is effectively raised to a higher level with the stator RTD. Keep in mind that thermal limit and trip curves shown are based on the example above. They will vary with other sets of the settings.

Thermal Replica and Trip Curves without RTD





NOTICE The thermal model of the motor protection devices uses the hottest winding "WD" RTD value

Global Protection Parameters of the Thermal Model

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ExBlo1	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /I-Prot /ThR]
ExBlo2	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /I-Prot /ThR]
ExBlo TripCmd	External blocking of the Trip Command of the module/the stage, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /I-Prot /ThR]
Use RTD values	Take RTD values into account for the calculation of the Thermal Model.	inactive, active	inactive	[Protection Para /Global Prot Para /I-Prot /ThR]
K2	This value represents the negative sequence current weighting factor of the motor.	0.10 - 10.00	6.01	[Protection Para /Global Prot Para /I-Prot /ThR]
τ-cool	Cooling time constant	5 - 240s	60s	[Protection Para /Global Prot Para /I-Prot /ThR]

Setting Group Parameters of the Thermal Model

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	active	[Protection Para /<1..4> /I-Prot /ThR]
ExBlo Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /I-Prot /ThR]
Blo TripCmd	Permanent blocking of the Trip Command of the module/stage.	inactive, active	inactive	[Protection Para /<1..4> /I-Prot /ThR]
ExBlo TripCmd Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo TripCmd Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /I-Prot /ThR]
Trip Function	Turn on or off the trip function	inactive, active	active	[Protection Para /<1..4> /I-Prot /ThR]
Trip Threshold	Trip threshold at which the thermal model will trip, based on percentage of thermal capacity used. This value should typically always be set at 0.99 Only available if: Trip Function = active	0.60 - 0.99	0.99	[Protection Para /<1..4> /I-Prot /ThR]
t-Trip Delay	Thermal capacity used trip delay Only available if: Trip Function = active	0.0 - 3600.0s	0.0s	[Protection Para /<1..4> /I-Prot /ThR]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Alarm Function	Turn on or off the alarm function	inactive, active	active	[Protection Para /<1..4> /I-Prot /ThR]
Alarm Threshold	Alarm threshold at which the thermal model will trip, based on percentage of thermal capacity used Only available if: Alarm Function = active	0.60 - 0.99	0.70	[Protection Para /<1..4> /I-Prot /ThR]
t-Alarm Delay	Thermal capacity used alarm delay Only available if: Alarm Function = active	1 - 360min	1min	[Protection Para /<1..4> /I-Prot /ThR]

Thermal Model Module Input States

Name	*Description*	*Assignment via*
ExBlo1	Module input state: External blocking	[Protection Para /Global Prot Para /I-Prot /ThR]
ExBlo2	Module input state: External blocking	[Protection Para /Global Prot Para /I-Prot /ThR]
ExBlo TripCmd	Module input state: External Blocking of the Trip Command	[Protection Para /Global Prot Para /I-Prot /ThR]

Thermal Model Module Signals (Output States)

Signal	*Description*
Alarm Pickup	Signal: Alarm Pickup
Alarm Timeout	Signal: Alarm Timeout
RTD effective	This state becomes true if the following conditions are all fulfilled: - the state “Load above SF” is true, - RTD functionality is active, - for at least one temperature a valid value above 0°C is being displayed.
Load above SF	“Load above Service Factor”: If the current exceeds the set value of “UTC” (“Ultimate trip threshold”) then the used thermal capacity counts up and the state “Load above SF” is becoming true. If the current is below the “UTC” value this state is false.
active	Signal: active
ExBlo	Signal: External Blocking
Blo TripCmd	Signal: Trip Command blocked
ExBlo TripCmd	Signal: External Blocking of the Trip Command
Alarm	Signal: Alarm
Trip	Signal: Trip
TripCmd	Signal: Trip Command

Direct Commands of the Thermal Model Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Res I2T Used	Reset thermal capacity used.	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]

Thermal Model Module Counter Values

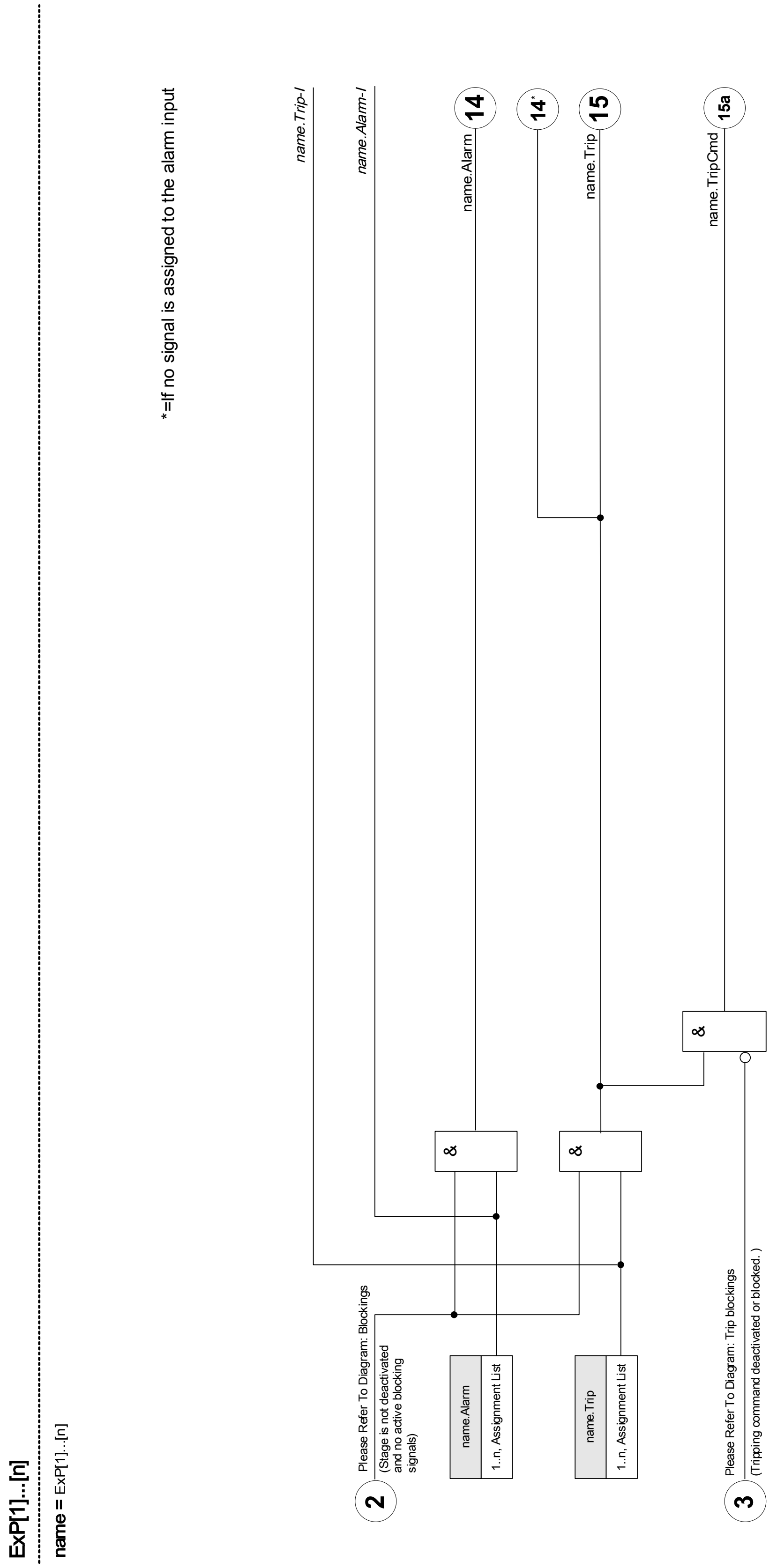
Value	*Description*	*Default*	*Size*	*Menu path*
I2T Used	Thermal capacity used.	0%	0 - 1000%	[Operation /Measured Values /ThR]
I2T Remained	Thermal capacity remained.	0%	0 - 1000%	[Operation /Measured Values /ThR]
NumberOfTripCmds	Number of trip commands since last reset	0	0 - 65535	[Operation /History /TripCmdCr]
nAlarms	nAlarms	0	0 - 65535	[Operation /History /AlarmCr]

ExP - External Protection

Available stages:
ExP[1] ,ExP[2] ,ExP[3] ,ExP[4]

NOTICE **All 4 stages of the external protection *ExP[1]...[4]* are identically structured.**

By using the module *External Protection* the following can be incorporated into the device function: trip commands, alarms and blockades of external protection facilities. Devices which are not provided with a communication interface can be connected to the control system as well.



ExP[1]...[n]
name = ExP[1]...[n]
*=If no signal is assigned to the alarm input
Please Refer To Diagram: Blockings
(Stage is not deactivated and no active blocking signals)
name.Alarm
1..n, Assignment List
name.Trip
1..n, Assignment List
Please Refer To Diagram: Trip blockings
(Tripping command deactivated or blocked.)
&
&
&
name.Trip-I
name.Alarm-I
name.Alarm
name.Trip
name.TripCmd
2
3
14
14*
15
15a

Device Planning Parameters of the Module External Protection

Parameter	*Description*	*Options*	*Default*	*Menu path*
Mode	Mode	do not use, use	do not use	[Device planning]

Global Protection Parameters of the Module External Protection

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ExBlo1	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /ExP /ExP[1]]
ExBlo2	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /ExP /ExP[1]]
ExBlo TripCmd	External blocking of the Trip Command of the module/the stage, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /ExP /ExP[1]]
Alarm	Assignment for External Alarm	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /ExP /ExP[1]]
Trip	External trip of the CB if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /ExP /ExP[1]]

Setting Group Parameters of the Module External Protection

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[Protection Para /<1..4> /ExP /ExP[1]]
ExBlo Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /ExP /ExP[1]]
Blo TripCmd	Permanent blocking of the Trip Command of the module/stage.	inactive, active	inactive	[Protection Para /<1..4> /ExP /ExP[1]]
ExBlo TripCmd Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo TripCmd Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /ExP /ExP[1]]

Module External Protection Input States

Name	*Description*	*Assignment via*
ExBlo1-I	Module input state: External blocking1	[Protection Para /Global Prot Para /ExP /ExP[1]]
ExBlo2-I	Module input state: External blocking2	[Protection Para /Global Prot Para /ExP /ExP[1]]
ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command	[Protection Para /Global Prot Para /ExP /ExP[1]]
Alarm-I	Module input state: Alarm	[Protection Para /Global Prot Para /ExP /ExP[1]]
Trip-I	Module input state: Trip	[Protection Para /Global Prot Para /ExP /ExP[1]]

Module External Protection Signals (Output States)

Signal	*Description*
active	Signal: active
ExBlo	Signal: External Blocking
Blo TripCmd	Signal: Trip Command blocked
ExBlo TripCmd	Signal: External Blocking of the Trip Command
Alarm	Signal: Alarm
Trip	Signal: Trip
TripCmd	Signal: Trip Command

Commissioning: External Protection

Object to be tested
Test of the module External Protection

Necessary means
- Depending on the application

Procedure
Simulate the functionality of the External Protection (Alarm, Trip, Blockings...) by (de-)energizing of the digital inputs.

Successful test result
All external alarms, external trips and external blockings are correctly recognized and processed by the device.

RTD Protection Module [26]

Elements:
RTD

General – Principle Use

NOTICE **The Resistance-based Temperature Detector (RTD) Protection Module uses temperature data that are provided by a Universal Resistance-based Temperature Detector (URTD) module (please refer to the URTD Module section).**

NOTICE **If voting trip is required, please map the output used for tripping purposes: "RTD. Voting Trip Grp 1" or "RTD. Voting Trip Grp 2".**

The protective device provides tripping and alarming functions based on the direct temperature measurements read from the URTD device that has 11 temperature sensor channels. Each channel will have one trip function without an intended delay and one alarm function with a delay.

•The "trip" function has only a threshold setting.

•Each individual »A*larm Function«* will have a threshold setting range, and can be individually enabled or disabled. Since the temperature cannot change instantaneously (which is a way that temperature differs from current), the "delay" is essentially built in to the function due to the fact that the temperature will take some time to increase from room temperature to the "trip threshold" level.

•The dropout ratio for both trip and alarm is 0.99.

•The temperature rise is limited by the RTD driver.

The entire function can be turned off or on, or individual channels can be turned off or on.

Voting

Additionally, RTD voting schemes are available and User programmable. The Voting feature must be activated and configured within the following menu, [Protection Para\Set[x]\Temp-Prot/ RTD\Vote[x]]. Here, the setting »*Function«* has to be set to »*Active«*.

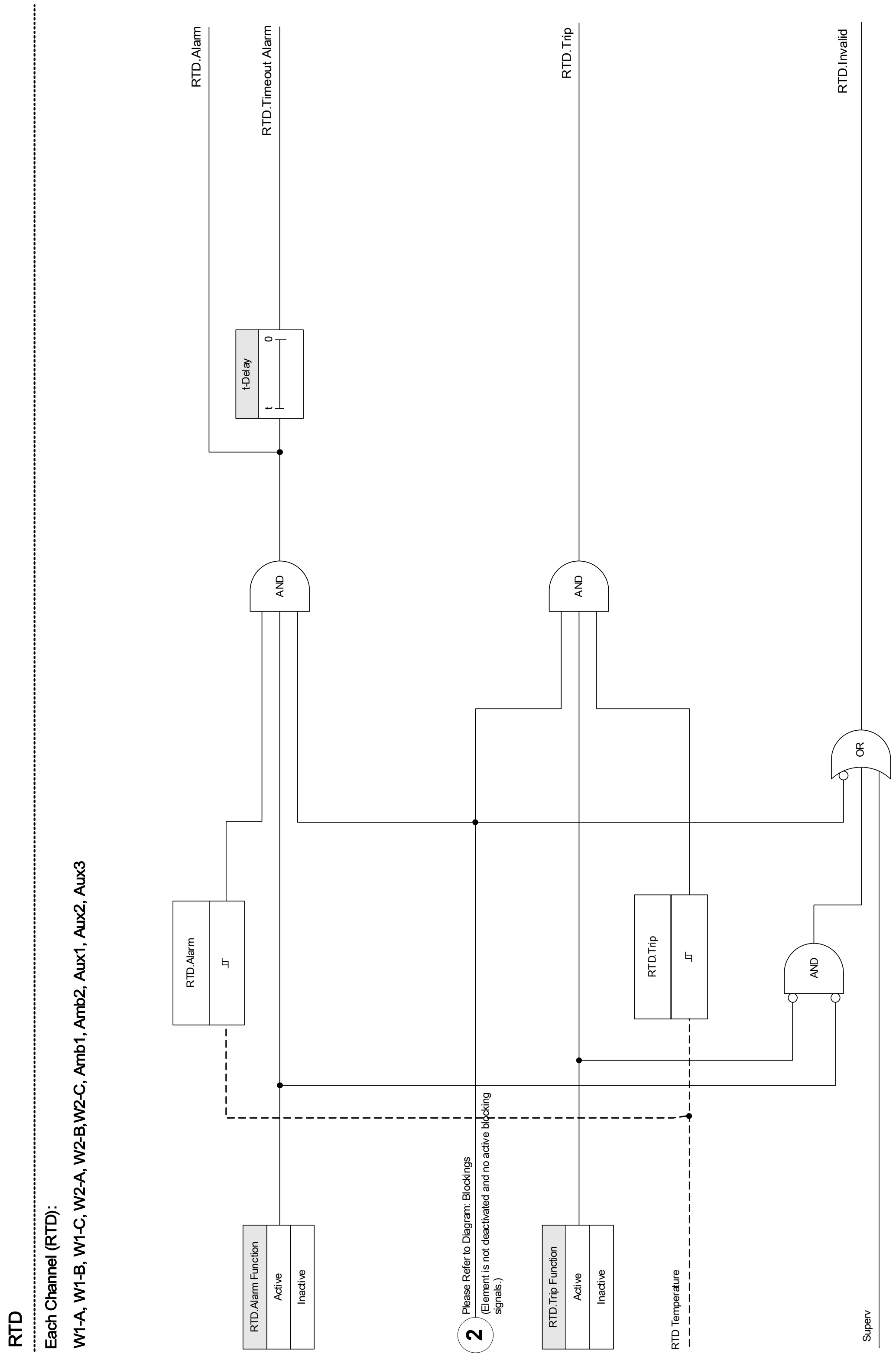
Once activated, the number of channels that will be used by the voting feature is selected. This is set by way of the parameter »*Voting[x]«*. This parameter defines how many of the selected channels must be over its threshold level in order to get a voting trip. Each individual channel must be selected or deselected by setting to either »*Yes«* or »*No«*. When selecting »*Yes«*, the channel will be used in the voting process. Note that in order to be selected, each channel must also be active and the RTD module itself has to be active.

If for example, Vote[x] is set to »*3«*, and all channels are set to »*Yes«*, and if any three of the selected channels exceed their individual threshold settings, a Vote trip will occur.

Please note that the voting trip will be issued as a RTD trip only, if the parameter »*TripCmd Selection«* is set to »*Voting trip«* within the Global Protection Parameters of the RTD module. The Trip has to be assigned then within the trip manager to the Breaker.

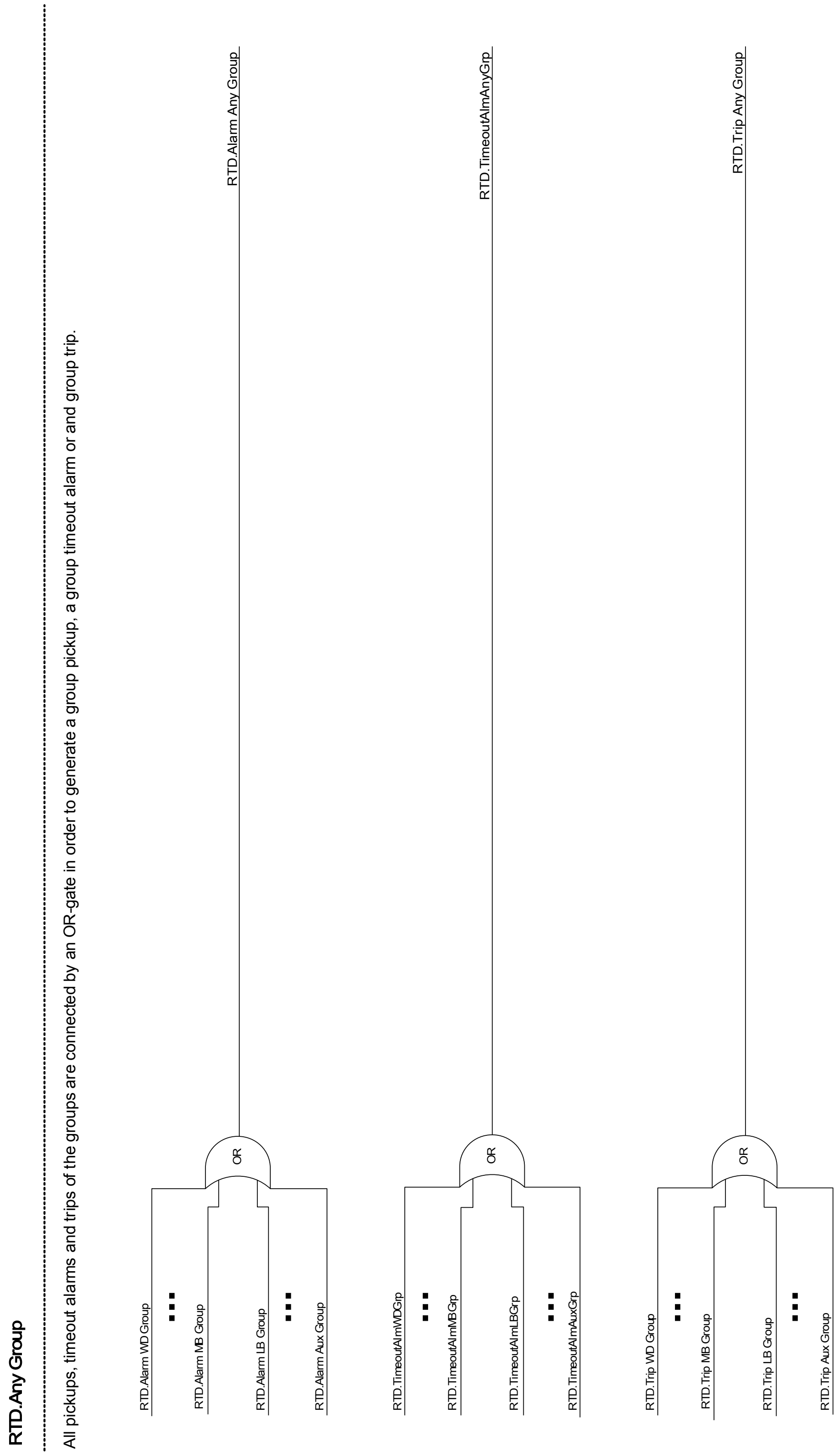
Alarm, Timeout Alarm and Trip Principle for each RTD Sensor

The following diagram shows the general working principle (delayed alarm, undelayed trip) of each of the RTD sensors.



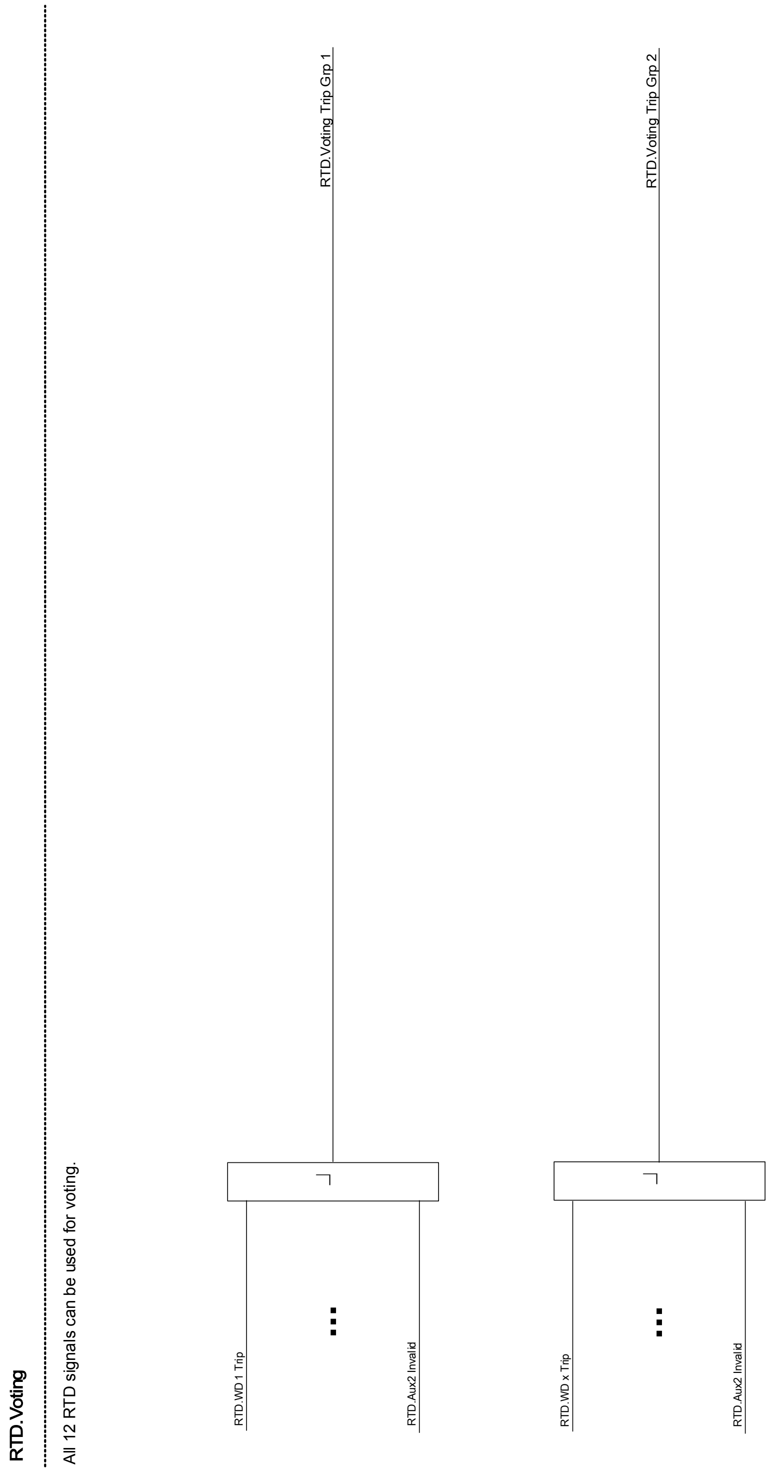
Collective Alarm, Timeout Alarm and Trip Signals

The RTD sensors are assigned to four groups (depending on the ordered device). These four groups are OR-connected to the ”AnyGroup“. The AnyGroup generates an alarm, an timeout alarm and a trip signal if any of the sensors mounted into this issues the corresponding signal.



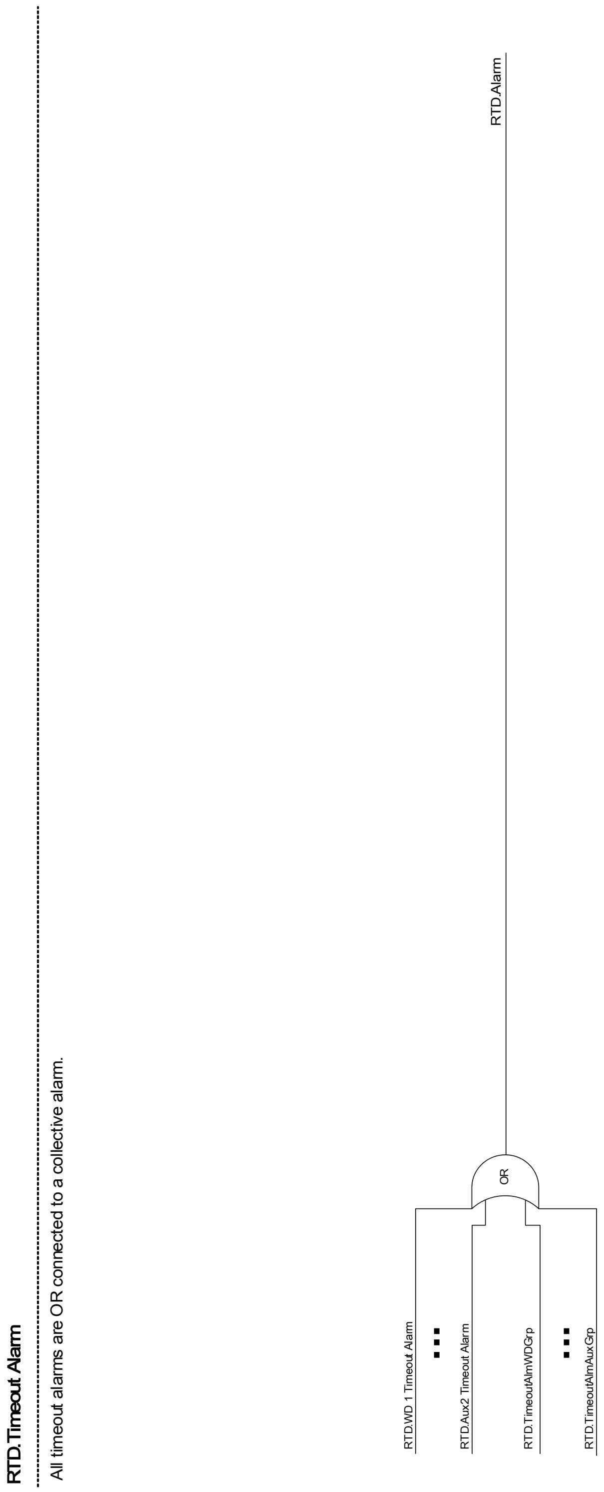
Trips of the Voting Groups

In order to use voting groups the user has to determine the sensors that should belong to a voting group and how many of them have to trip in order to generate a voting trip of the corresponding group.



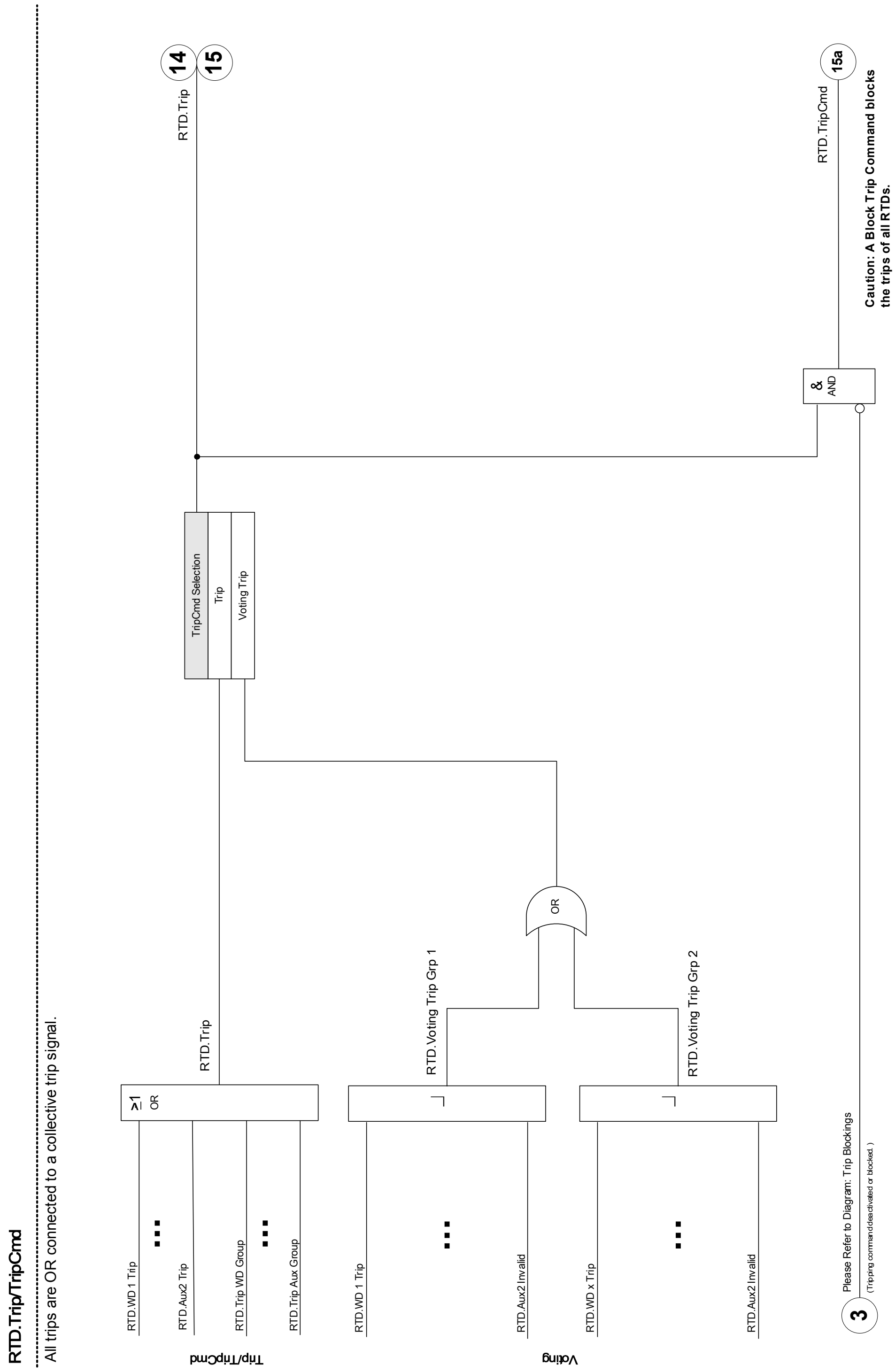
Collective Timeout Alarm Signal

All RTD sensor timeout alarms and all group timeouts are OR-connected.



Collective Trip Signal

By means of the trip command selection »*TripCmdSelection«* the user determines if the RTD element should use for the final trip signal the OR-connected default RTD trips or if the RTD element should use the OR-connected voting trips.



Device Planning Parameters of the RTD Temperature Protection Module

Parameter	*Description*	*Options*	*Default*	*Menu path*
Mode	Mode	do not use, use	do not use	[Device planning]

Global Protection Parameters of the RTD Temperature Protection Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ExBlo1	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /Temp-Prot /RTD]
ExBlo2	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /Temp-Prot /RTD]
ExBlo TripCmd	External blocking of the Trip Command of the module/the stage, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /Temp-Prot /RTD]
TripCmd Selection	This parameter determines if the final trip of the RTD module is issued by the default way or by the voting groups.	Trip, Voting Trip	Trip	[Protection Para /Global Prot Para /Temp-Prot /RTD]

Setting Group Parameters of the RTD Temperature Protection Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[Protection Para /<1..4> /Temp-Prot /RTD /General Settings]
ExBlo Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /Temp-Prot /RTD /General Settings]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Blo TripCmd	Permanent blocking of the Trip Command of the module/stage.	inactive, active	inactive	[Protection Para /<1..4> /Temp-Prot /RTD /General Settings]
ExBlo TripCmd Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo TripCmd Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /Temp-Prot /RTD /General Settings]
Windg 1 Alarm Function	Winding 1 Alarm Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 1]
Windg 1 Trip Function	Winding 1 Trip Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 1]
Windg 1 Alarm	Winding 1 Threshold for Temperature Alarm Only available if: Device planning: Alarm Function = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 1]
Windg 1 t-Delay	Winding 1 If this time is expired a Temperature Alarm will be generated. Only available if: Device planning: Alarm Function = use	0 - 360min	1min	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 1]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Windg 1 Trip	Winding 1 Threshold for Temperature Trip Only available if: Device planning: Trip Function = use	0 - 200°C	100°C	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 1]
Windg 2 Alarm Function	Winding 2 Alarm Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 2]
Windg 2 Trip Function	Winding 2 Trip Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 2]
Windg 2 Alarm	Winding 2 Threshold for Temperature Alarm Only available if: Device planning: Alarm Function = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 2]
Windg 2 t-Delay	Winding 2 If this time is expired a Temperature Alarm will be generated. Only available if: Device planning: Alarm Function = use	0 - 360min	1min	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 2]
Windg 2 Trip	Winding 2 Threshold for Temperature Trip Only available if: Device planning: Trip Function = use	0 - 200°C	100°C	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 2]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Windg 3 Alarm Function	Winding 3 Alarm Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 3]
Windg 3 Trip Function	Winding 3 Trip Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 3]
Windg 3 Alarm	Winding 3 Threshold for Temperature Alarm Only available if: Device planning: Alarm Function = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 3]
Windg 3 t-Delay	Winding 3 If this time is expired a Temperature Alarm will be generated. Only available if: Device planning: Alarm Function = use	0 - 360min	1min	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 3]
Windg 3 Trip	Winding 3 Threshold for Temperature Trip Only available if: Device planning: Trip Function = use	0 - 200°C	100°C	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 3]
Windg 4 Alarm Function	Winding 4 Alarm Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 4]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Windg 4 Trip Function	Winding 4 Trip Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 4]
Windg 4 Alarm	Winding 4 Threshold for Temperature Alarm Only available if: Device planning: Alarm Function = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 4]
Windg 4 t-Delay	Winding 4 If this time is expired a Temperature Alarm will be generated. Only available if: Device planning: Alarm Function = use	0 - 360min	1min	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 4]
Windg 4 Trip	Winding 4 Threshold for Temperature Trip Only available if: Device planning: Trip Function = use	0 - 200°C	100°C	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 4]
Windg 5 Alarm Function	Winding 5 Alarm Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 5]
Windg 5 Trip Function	Winding 5 Trip Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 5]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Windg 5 Alarm	Winding 5 Threshold for Temperature Alarm Only available if: Device planning: Alarm Function = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 5]
Windg 5 t-Delay	Winding 5 If this time is expired a Temperature Alarm will be generated. Only available if: Device planning: Alarm Function = use	0 - 360min	1min	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 5]
Windg 5 Trip	Winding 5 Threshold for Temperature Trip Only available if: Device planning: Trip Function = use	0 - 200°C	100°C	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 5]
Windg 6 Alarm Function	Winding 6 Alarm Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 6]
Windg 6 Trip Function	Winding 6 Trip Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 6]
Windg 6 Alarm	Winding 6 Threshold for Temperature Alarm Only available if: Device planning: Alarm Function = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 6]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Windg 6 t-Delay	Winding 6 If this time is expired a Temperature Alarm will be generated. Only available if: Device planning: Alarm Function = use	0 - 360min	1min	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 6]
Windg 6 Trip	Winding 6 Threshold for Temperature Trip Only available if: Device planning: Trip Function = use	0 - 200°C	100°C	[Protection Para /<1..4> /Temp-Prot /RTD /Windg 6]
MotBear 1 Alarm Function	Motor Bearing 1 Alarm Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /MotBear 1]
MotBear 1 Trip Function	Motor Bearing 1 Trip Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /MotBear 1]
MotBear 1 Alarm	Motor Bearing 1 Threshold for Temperature Alarm Only available if: Device planning: Alarm Function = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /MotBear 1]
MotBear 1 t-Delay	Motor Bearing 1 If this time is expired a Temperature Alarm will be generated. Only available if: Device planning: Alarm Function = use	0 - 360min	1min	[Protection Para /<1..4> /Temp-Prot /RTD /MotBear 1]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
MotBear 1 Trip	Motor Bearing 1 Threshold for Temperature Trip Only available if: Device planning: Trip Function = use	0 - 200°C	100°C	[Protection Para /<1..4> /Temp-Prot /RTD /MotBear 1]
MotBear 2 Alarm Function	Motor Bearing 2 Alarm Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /MotBear 2]
MotBear 2 Trip Function	Motor Bearing 2 Trip Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /MotBear 2]
MotBear 2 Alarm	Motor Bearing 2 Threshold for Temperature Alarm Only available if: Device planning: Alarm Function = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /MotBear 2]
MotBear 2 t-Delay	Motor Bearing 2 If this time is expired a Temperature Alarm will be generated. Only available if: Device planning: Alarm Function = use	0 - 360min	1min	[Protection Para /<1..4> /Temp-Prot /RTD /MotBear 2]
MotBear 2 Trip	Motor Bearing 2 Threshold for Temperature Trip Only available if: Device planning: Trip Function = use	0 - 200°C	100°C	[Protection Para /<1..4> /Temp-Prot /RTD /MotBear 2]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
LoadBear 1 Alarm Function	Load Bearing 1 Alarm Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /LoadBear 1]
LoadBear 1 Trip Function	Load Bearing 1 Trip Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /LoadBear 1]
LoadBear 1 Alarm	Load Bearing 1 Threshold for Temperature Alarm Only available if: Device planning: Alarm Function = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /LoadBear 1]
LoadBear 1 t-Delay	Load Bearing 1 If this time is expired a Temperature Alarm will be generated. Only available if: Device planning: Alarm Function = use	0 - 360min	1min	[Protection Para /<1..4> /Temp-Prot /RTD /LoadBear 1]
LoadBear 1 Trip	Load Bearing 1 Threshold for Temperature Trip Only available if: Device planning: Trip Function = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /LoadBear 1]
LoadBear 2 Alarm Function	Load Bearing 2 Alarm Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /LoadBear 2]

Parameter	Description	Setting range	Default	Menu path
LoadBear 2 Trip Function	Load Bearing 2 Trip Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /LoadBear 2]
LoadBear 2 Alarm	Load Bearing 2 Threshold for Temperature Alarm Only available if: Device planning: Alarm Function = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /LoadBear 2]
LoadBear 2 t-Delay	Load Bearing 2 If this time is expired a Temperature Alarm will be generated. Only available if: Device planning: Alarm Function = use	0 - 360min	1min	[Protection Para /<1..4> /Temp-Prot /RTD /LoadBear 2]
LoadBear 2 Trip	Load Bearing 2 Threshold for Temperature Trip Only available if: Device planning: Trip Function = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /LoadBear 2]
Aux1 Alarm Function	Auxiliary 1 Alarm Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /Aux 1]
Aux1 Trip Function	Auxiliary 1 Trip Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /Aux 1]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Aux1 Alarm	Auxiliary 1 Threshold for Temperature Alarm Only available if: Device planning: Alarm Function1 = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /Aux 1]
Aux1 t-Delay	Auxiliary 1 If this time is expired a Temperature Alarm will be generated. Only available if: Device planning: Alarm Function1 = use	0 - 360min	1min	[Protection Para /<1..4> /Temp-Prot /RTD /Aux 1]
Aux1 Trip	Auxiliary 1 Threshold for Temperature Trip Only available if: Device planning: Trip Function2 = use	0 - 200°C	100°C	[Protection Para /<1..4> /Temp-Prot /RTD /Aux 1]
Aux2 Alarm Function	Auxiliary 2 Alarm Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /Aux 2]
Aux2 Trip Function	Auxiliary 2 Trip Function	inactive, active	active	[Protection Para /<1..4> /Temp-Prot /RTD /Aux 2]
Aux2 Alarm	Auxiliary 2 Threshold for Temperature Alarm Only available if: Device planning: Alarm Function2 = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /Aux 2]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Aux2 t-Delay	Auxiliary 2 If this time is expired a Temperature Alarm will be generated. Only available if: Device planning: Alarm Function2 = use	0 - 360min	1min	[Protection Para /<1..4> /Temp-Prot /RTD /Aux 2]
Aux2 Trip	Auxiliary 2 Threshold for Temperature Trip Only available if: Device planning: Trip Function2 = use	0 - 200°C	100°C	[Protection Para /<1..4> /Temp-Prot /RTD /Aux 2]
Windg Alarm Function	Winding Alarm Function	inactive, active	inactive	[Protection Para /<1..4> /Temp-Prot /RTD /Windg Group]
Windg Trip Function	Winding Trip Function	inactive, active	inactive	[Protection Para /<1..4> /Temp-Prot /RTD /Windg Group]
Windg Alarm	Winding Threshold for Temperature Alarm Only available if: Device planning: Alarm Function = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /Windg Group]
Windg t-Delay	Winding If this time is expired a Temperature Alarm will be generated. Only available if: Device planning: Alarm Function = use	0 - 360min	1min	[Protection Para /<1..4> /Temp-Prot /RTD /Windg Group]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Windg Trip	Winding Threshold for Temperature Trip Only available if: Device planning: Trip Function = use	0 - 200°C	100°C	[Protection Para /<1..4> /Temp-Prot /RTD /Windg Group]
MotBear Alarm Function	Motor Bearing Alarm Function	inactive, active	inactive	[Protection Para /<1..4> /Temp-Prot /RTD /MotBear Group]
MotBear Trip Function	Motor Bearing Trip Function	inactive, active	inactive	[Protection Para /<1..4> /Temp-Prot /RTD /MotBear Group]
MotBear Alarm	Motor Bearing Threshold for Temperature Alarm Only available if: Device planning: Alarm Function = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /MotBear Group]
MotBear t-Delay	Motor Bearing If this time is expired a Temperature Alarm will be generated. Only available if: Device planning: Alarm Function = use	0 - 360min	1min	[Protection Para /<1..4> /Temp-Prot /RTD /MotBear Group]
MotBear Trip	Motor Bearing Threshold for Temperature Trip Only available if: Device planning: Trip Function = use	0 - 200°C	100°C	[Protection Para /<1..4> /Temp-Prot /RTD /MotBear Group]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
LoadBear Alarm Function	Load Bearing Alarm Function	inactive, active	inactive	[Protection Para /<1..4> /Temp-Prot /RTD /LoadBear Group]
LoadBear Trip Function	Load Bearing Trip Function	inactive, active	inactive	[Protection Para /<1..4> /Temp-Prot /RTD /LoadBear Group]
LoadBear Alarm	Load Bearing Threshold for Temperature Alarm Only available if: Device planning: Alarm Function = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /LoadBear Group]
LoadBear t-Delay	Load Bearing If this time is expired a Temperature Alarm will be generated. Only available if: Device planning: Alarm Function = use	0 - 360min	1min	[Protection Para /<1..4> /Temp-Prot /RTD /LoadBear Group]
LoadBear Trip	Load Bearing Threshold for Temperature Trip Only available if: Device planning: Trip Function = use	0 - 200°C	100°C	[Protection Para /<1..4> /Temp-Prot /RTD /LoadBear Group]
Aux Alarm Function	Auxiliary Alarm Function	inactive, active	inactive	[Protection Para /<1..4> /Temp-Prot /RTD /Aux Group]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Aux Trip Function	Auxiliary Trip Function	inactive, active	inactive	[Protection Para /<1..4> /Temp-Prot /RTD /Aux Group]
Aux Alarm	Auxiliary Threshold for Temperature Alarm Only available if: Device planning: Alarm Function = use	0 - 200°C	80°C	[Protection Para /<1..4> /Temp-Prot /RTD /Aux Group]
Aux t-Delay	Auxiliary If this time is expired a Temperature Alarm will be generated. Only available if: Device planning: Alarm Function = use	0 - 360min	1min	[Protection Para /<1..4> /Temp-Prot /RTD /Aux Group]
Aux Trip	Auxiliary Threshold for Temperature Trip Only available if: Device planning: Aux = use	0 - 200°C	100°C	[Protection Para /<1..4> /Temp-Prot /RTD /Aux Group]
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[Protection Para /<1..4> /Temp-Prot /RTD /Voting1]
Voting 1	Voting: This parameter defines how many of the selected channels must be over its threshold level for getting a voting trip	1 - 12	1	[Protection Para /<1..4> /Temp-Prot /RTD /Voting1]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Windg 1	Winding 1	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting1]
Windg 2	Winding 2	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting1]
Windg 3	Winding 3	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting1]
Windg 4	Winding 4	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting1]
Windg 5	Winding 5	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting1]
Windg 6	Winding 6	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting1]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
MotBear 1	Motor Bearing 1	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting1]
MotBear 2	Motor Bearing 2	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting1]
LoadBear 1	Load Bearing 1	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting1]
LoadBear 2	Load Bearing 2	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting1]
Aux1	Auxiliary1	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting1]
Aux2	Auxiliary2	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting1]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[Protection Para /<1..4> /Temp-Prot /RTD /Voting2]
Voting 2	Voting: This parameter defines how many of the selected channels must be over its threshold level for getting a voting trip	1 - 12	1	[Protection Para /<1..4> /Temp-Prot /RTD /Voting2]
Windg 1	Winding 1	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting2]
Windg 2	Winding 2	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting2]
Windg 3	Winding 3	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting2]
Windg 4	Winding 4	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting2]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Windg 5	Winding 5	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting2]
Windg 6	Winding 6	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting2]
MotBear 1	Motor Bearing 1	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting2]
MotBear 2	Motor Bearing 2	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting2]
LoadBear 1	Load Bearing 1	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting2]
LoadBear 2	Load Bearing 2	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting2]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Aux1	Auxiliary1	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting2]
Aux2	Auxiliary2	no, yes	no	[Protection Para /<1..4> /Temp-Prot /RTD /Voting2]

RTD Temperature Protection Module Input States

Name	*Description*	*Assignment via*
ExBlo1-I	Module input state: External blocking1	[Protection Para /Global Prot Para /Temp-Prot /RTD]
ExBlo2-I	Module input state: External blocking2	[Protection Para /Global Prot Para /Temp-Prot /RTD]
ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command	[Protection Para /Global Prot Para /Temp-Prot /RTD]

RTD Temperature Protection Module Signals (Output States)

Signal	*Description*
active	Signal: active
ExBlo	Signal: External Blocking
Blo TripCmd	Signal: Trip Command blocked
ExBlo TripCmd	Signal: External Blocking of the Trip Command
Alarm	Alarm RTD Temperature Protection
Trip	Signal: Trip
TripCmd	Signal: Trip Command
Windg 1 Trip	Winding 1 Signal: Trip

Signal	*Description*
Windg 1 Alarm	Winding 1 Alarm RTD Temperature Protection
Windg 1 Timeout Alarm	Winding 1 Timeout Alarm
Windg 1 Invalid	Winding 1 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
Windg 2 Trip	Winding 2 Signal: Trip
Windg 2 Alarm	Winding 2 Alarm RTD Temperature Protection
Windg 2 Timeout Alarm	Winding 2 Timeout Alarm
Windg 2 Invalid	Winding 2 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
Windg 3 Trip	Winding 3 Signal: Trip
Windg 3 Alarm	Winding 3 Alarm RTD Temperature Protection
Windg 3 Timeout Alarm	Winding 3 Timeout Alarm
Windg 3 Invalid	Winding 3 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
Windg 4 Trip	Winding 4 Signal: Trip
Windg 4 Alarm	Winding 4 Alarm RTD Temperature Protection
Windg 4 Timeout Alarm	Winding 4 Timeout Alarm
Windg 4 Invalid	Winding 4 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
Windg 5 Trip	Winding 5 Signal: Trip
Windg 5 Alarm	Winding 5 Alarm RTD Temperature Protection
Windg 5 Timeout Alarm	Winding 5 Timeout Alarm
Windg 5 Invalid	Winding 5 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
Windg 6 Trip	Winding 6 Signal: Trip
Windg 6 Alarm	Winding 6 Alarm RTD Temperature Protection
Windg 6 Timeout Alarm	Winding 6 Timeout Alarm
Windg 6 Invalid	Winding 6 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
MotBear 1 Trip	Motor Bearing 1 Signal: Trip
MotBear 1 Alarm	Motor Bearing 1 Alarm RTD Temperature Protection
MotBear 1 Timeout Alarm	Motor Bearing 1 Timeout Alarm
MotBear 1 Invalid	Motor Bearing 1 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
MotBear 2 Trip	Motor Bearing 2 Signal: Trip
MotBear 2 Alarm	Motor Bearing 2 Alarm RTD Temperature Protection
MotBear 2 Timeout Alarm	Motor Bearing 2 Timeout Alarm
MotBear 2 Invalid	Motor Bearing 2 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
LoadBear 1 Trip	Load Bearing 1 Signal: Trip
LoadBear 1 Alarm	Load Bearing 1 Alarm RTD Temperature Protection
LoadBear 1 Timeout Alarm	Load Bearing 1 Timeout Alarm

Signal	*Description*
LoadBear 1 Invalid	Load Bearing 1 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
LoadBear 2 Trip	Load Bearing 2 Signal: Trip
LoadBear 2 Alarm	Load Bearing 2 Alarm RTD Temperature Protection
LoadBear 2 Timeout Alarm	Load Bearing 2 Timeout Alarm
LoadBear 2 Invalid	Load Bearing 2 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
Aux1 Trip	Auxiliary 1 Signal: Trip
Aux1 Alarm	Auxiliary 1 Alarm RTD Temperature Protection
Aux1 Timeout Alarm	Auxiliary 1 Timeout Alarm
Aux1 Invalid	Auxiliary 1 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
Aux2 Trip	Auxiliary 2 Signal: Trip
Aux2 Alarm	Auxiliary 2 Alarm RTD Temperature Protection
Aux2 Timeout Alarm	Auxiliary 2 Timeout Alarm
Aux2 Invalid	Auxiliary 2 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
Trip WD Group	Trip all Windings
Alarm WD Group	Alarm all Windings
TimeoutAlmWDGrp	Timeout Alarm all Windings
Windg Group Invalid	Winding Group Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
Trip MB Group	Trip all Motor Bearings
Alarm MB Group	Alarm all Motor Bearings
TimeoutAlmMBGrp	Timeout Alarm all Motor Bearings
MotBear Group Invalid	Motor Bearing Group Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
Trip LB Group	Trip all Load Bearings
Alarm LB Group	Alarm all Load Bearings
TimeoutAlmLBGrp	Timeout Alarm all Load Bearings
LoadBear Group Invalid	Load Bearing Group Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
Trip Any Group	Trip Any Group
Alarm Any Group	Alarm Any Group
TimeoutAlmAnyGrp	Timeout Alarm Any Group
Trip Group 1	Trip Group 1
Trip Group 2	Trip Group 2
Timeout Alarm	Alarm timeout expired
Trip Aux Group	Trip Auxiliary Group
Alarm Aux Group	Alarm Auxiliary Group
TimeoutAlmAuxGrp	Timeout Alarm Auxiliary Group
AuxGrpInvalid	Invalid Auxiliary Group

RTD Temperature Protection Module Counter Values

Value	*Description*	*Default*	*Size*	*Menu path*
HottestWindingTemp	Hottest motor winding temperature in degrees C.	0°C	0 - 200°C	[Operation /Measured Values /URTD]
Hottest MotBearTemp	Hottest motor bearing temperature in degrees C.	0°C	0 - 200°C	[Operation /Measured Values /URTD]
Hottest LoadBearTemp	Hottest load bearing temperature in degrees C.	0°C	0 - 200°C	[Operation /Measured Values /URTD]
Hottest Aux Temp	Hottest Auxiliary temperature in degrees C.	0°C	0 - 200°C	[Operation /Measured Values /URTD]
HighestWdTemp	Highest motor winding temperature in degrees.	0°C	0 - 250°C	[Operation /History /OperationsCr]
HighestMbTemp	Highest motor bearing temperature in degrees.	0°C	0 - 250°C	[Operation /History /OperationsCr]
HighestLbTemp	Highest load bearing temperature in degrees.	0°C	0 - 250°C	[Operation /History /OperationsCr]
HighestAuxTemp	Highest Auxiliary temperature in degrees.	0°C	0 - 250°C	[Operation /History /OperationsCr]
nWdAlarms	Number of winding temperature alarms since last reset.	0	0 - 65535	[Operation /History /AlarmCr]
nMbAlarms	Number of motor bearing temperature alarms since last reset.	0	0 - 65535	[Operation /History /AlarmCr]
nLbAlarms	Number of load bearing temperature alarms since last reset.	0	0 - 65535	[Operation /History /AlarmCr]

Value	*Description*	*Default*	*Size*	*Menu path*
nAuxAlarms	Number of auxilary temperature alarms since last reset.	0	0 - 65535	[Operation /History /AlarmCr]
nWdTrips	Number of winding temperature trips since last reset.	0	0 - 65535	[Operation /History /TripCmdCr]
nMbTrips	Number of motor bearing temperature trips since last reset.	0	0 - 65535	[Operation /History /TripCmdCr]
nLbTrips	Number of load bearing temperature trips since last reset.	0	0 - 65535	[Operation /History /TripCmdCr]
nAuxTrips	Number of auxilary temperature trips since last reset.	0	0 - 65535	[Operation /History /TripCmdCr]
nChannelFails	Number of RTD channel failures.	0	0 - 65535	[Operation /History /AlarmCr]

URTDII Module Interface

URTD

Principle – General Use

The optional Universal Resistance-based Temperature Detector II (URTDII) Module provides temperature data to the protective device from up to 12 RTDs embedded in the motor, generator, transformer, or cable connector and driven equipment. The temperature data will be shown as measured values and statistics in the Operating Data menu. In addition, each channel will be monitored. The measured data provided by the URTDII Module can also be used for temperature protection (please refer to the Temperature Protection section).

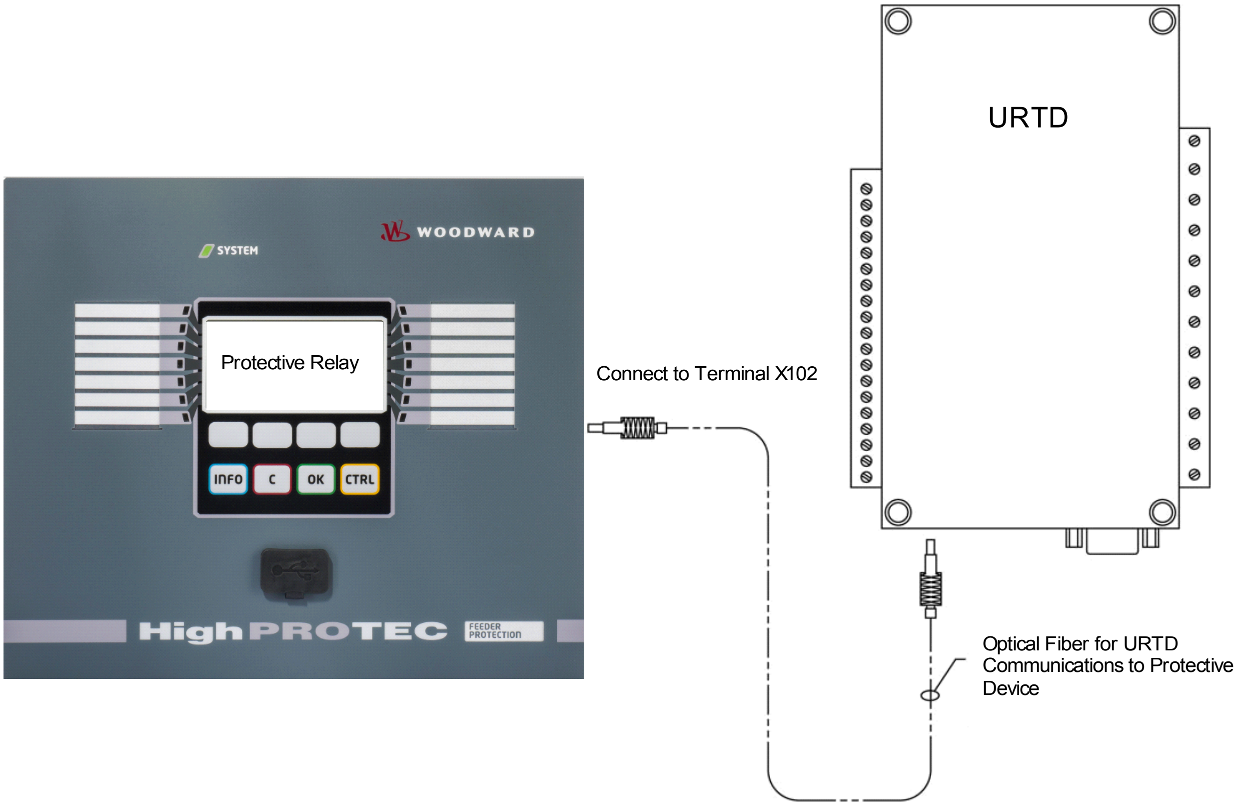
The URTDII conveys multiplexed temperature data back to the relay via a single optical fiber. The URTDII may be mounted remotely from the protective device. The fiber optic connector is located on the **X102** terminal of the protective device.

Consider the benefit of mounting the URTDII module away from the protective device and as close to the protected equipment as possible. The big bundle of RTD wires to the protected equipment becomes much shorter. The URTDII may be placed up to 400 ft (121.9 m) from the protective device with the optical fiber connection. Note that the URTDII will require a power supply connection at its remote location.

Connect a suitable source to the power terminals J10A-1 and J10A-2 on the URTDII module.

Style	Power Supply
URTDII-01	48-240 V AC 48-250 V DC
URTDII-02	24-48 V DC

URTDII Module Fiber Optic Connection to the Protective Device



The figure above shows the fiber optic connections between the URTDII Module and the protective device. The protective device supports the optical fiber connection.

Preassembled plastic optical fibers with connectors can be ordered from any distributor of optical fiber products. In addition, these same distributors offer long rolls of cable with connectors that can be installed in the field. Some distributors will make custom lengths to order.

NOTICE **Surplus length of a pre-cut fiber does not cause a problems. Simply coil and tie the excess fiber at a convenient point. Avoid high tie pressure. Bending radius of the fiber should be greater than 2 in. (50.8 mm).**

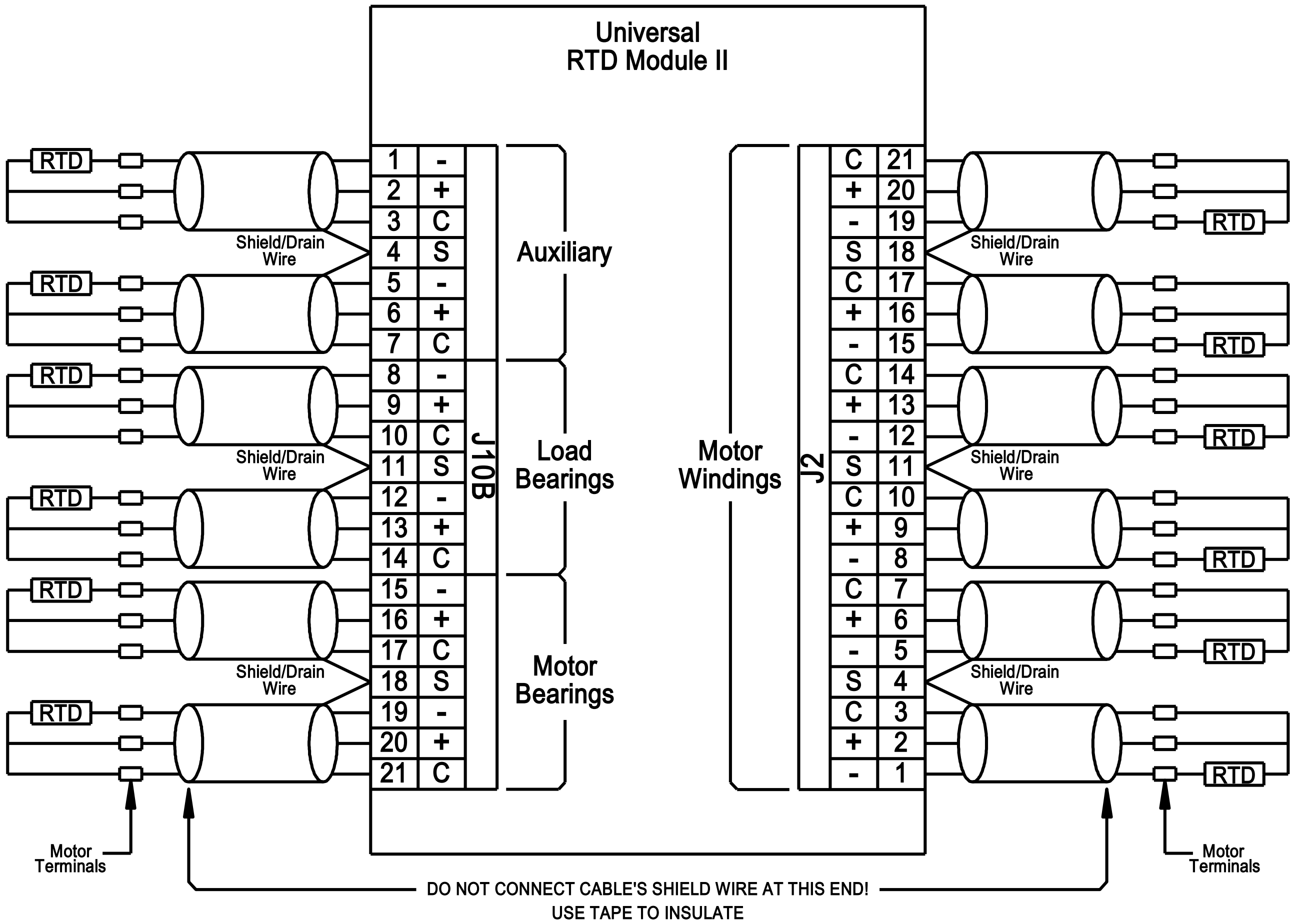
The fiber termination at the URTDII simply snaps into or out of the connector. To connect the fiber termination at the protective device, push the plug of the fiber optic onto the device interface then turn it until it “snaps”.

CAUTION **The protective device as well as the URTDII have various power supply options. Make certain that the power supply is acceptable for both units before connecting the same power supply to both devices.**

NOTICE **Consult the URTDII Module Instruction Leaflet for complete instructions.**

Three URTD terminals are provided for each RTD input.

The three terminals for any unused RTD input channel should be wired together. For example, if MW5 and MW6 are unused, MW5 terminals J2-15, J2-16, and J2-17 should be wired together and MW6 terminals J2-19, J2-20, J2-21 should be separately wired together.



See the figure above for wiring of RTDs to the URTD inputs. Use three-conductor shielded cable. Note the connection rules in the figure. When making connections to a two-lead RTD, connect two of the cable conductors to one of the RTD leads as shown. Make this connection as close to the protected object as possible. Connect the third cable conductor to the remaining RTD lead.

Connect the shield / drain wire to the Shield terminal as shown in the figure. The RTD cable shield should be connected only at the URTD end, and insulated at the RTD end. The RTD's themselves must not be grounded at the object to be protected.

Remember to set the URTDII module DIP switches according to the types of RTDs in each of the channels.

Direct Commands of the URTD Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[Service /Test (Prot inhibit) /URTD]
Force Windg1	Force Winding 1	0 - 392	0	[Service /Test (Prot inhibit) /URTD]
Force Windg2	Force Winding 2	0 - 392	0	[Service /Test (Prot inhibit) /URTD]
Force Windg3	Force Winding 3	0 - 392	0	[Service /Test (Prot inhibit) /URTD]
Force Windg4	Force Winding 4	0 - 392	0	[Service /Test (Prot inhibit) /URTD]
Force Windg5	Force Winding 5	0 - 392	0	[Service /Test (Prot inhibit) /URTD]
Force Windg6	Force Winding 6	0 - 392	0	[Service /Test (Prot inhibit) /URTD]
Force MotBear1	Force Motor Bearing 1	0 - 392	0	[Service /Test (Prot inhibit) /URTD]
Force MotBear2	Force Motor Bearing 2	0 - 392	0	[Service /Test (Prot inhibit) /URTD]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Force LoadBear1	Force Load Bearing 1	0 - 392	0	[Service /Test (Prot inhibit) /URTD]
Force LoadBear2	Force Load Bearing 2	0 - 392	0	[Service /Test (Prot inhibit) /URTD]
Force Aux1	Force Auxiliary1	0 - 392	0	[Service /Test (Prot inhibit) /URTD]
Force Aux2	Force Auxiliary2	0 - 392	0	[Service /Test (Prot inhibit) /URTD]

Global Protection Parameters of the URTD Module

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Force Mode	By means of this function the normal Output Relay States can be overwritten (forced) in case that the Relay is not in a disarmed state. The relays can be set from normal operation (relay works according to the assigned signals) to "force energized" or "force de-energized" state.	permanent, timeout	permanent	[Service /Test (Prot inhibit) /URTD]
t-Timeout Force	The Output State will be set by force for the duration of this time. That means for the duration of this time the Output Relay does not show the state of the signals that are assigned on it. Only available if: Mode = Timeout DISARM	0.00 - 300.00s	0.03s	[Service /Test (Prot inhibit) /URTD]
Temperature Unit	Temperature Unit	Celsius, Fahrenheit	Celsius	[Device Para /Measurem Display /General Settings]

URTD Signals (Output States)

Signal	*Description*
Windg1 Superv	Signal: Supervision Channel Windg1
Windg2 Superv	Signal: Supervision Channel Windg2
Windg3 Superv	Signal: Supervision Channel Windg3
Windg4 Superv	Signal: Supervision Channel Windg4
Windg5 Superv	Signal: Supervision Channel Windg5
Windg6 Superv	Signal: Supervision Channel Windg6
MotBear1 Superv	Signal: Supervision Channel MotBear1
MotBear2 Superv	Signal: Supervision Channel MotBear2
LoadBear1 Superv	Signal: Supervision Channel LoadBear1
LoadBear2 Superv	Signal: Supervision Channel LoadBear2
Aux1 Superv	Signal: Supervision Channel Aux1
Aux2 Superv	Signal: Supervision Channel Aux2
Superv	Signal: URTD Supervision Channel
active	Signal: URTD active
Outs forced	Signal: The State of at least one Relay Output has been set by force. That means that the state of at least one Relay is forced and hence does not show the state of the assigned signals.

URTD Module Statistics

Value	*Description*	*Menu path*
Windg1 max	Winding1 Maximum Value	[Operation /Statistics /Max /URTD]
Windg2 max	Winding2 Maximum Value	[Operation /Statistics /Max /URTD]
Windg3 max	Winding3 Maximum Value	[Operation /Statistics /Max /URTD]
Windg4 max	Winding4 Maximum Value	[Operation /Statistics /Max /URTD]
Windg5 max	Winding5 Maximum Value	[Operation /Statistics /Max /URTD]
Windg6 max	Winding6 Maximum Value	[Operation /Statistics /Max /URTD]
MotBear1 max	Motor Bearing1 Maximum Value	[Operation /Statistics /Max /URTD]
MotBear2 max	Motor Bearing2 Maximum Value	[Operation /Statistics /Max /URTD]
LoadBear1 max	Load Bearing1 Maximum Value	[Operation /Statistics /Max /URTD]

Value	*Description*	*Menu path*
LoadBear2 max	Load Bearing2 Maximum Value	[Operation /Statistics /Max /URTD]
Aux1 max	Auxiliary1 Maximum Value	[Operation /Statistics /Max /URTD]
Aux2 max	Auxiliary2 Maximum Value	[Operation /Statistics /Max /URTD]

URTD Measured Values

Value	*Description*	*Menu path*
Windg1	Winding 1	[Operation /Measured Values /URTD]
Windg2	Winding 2	[Operation /Measured Values /URTD]
Windg3	Winding 3	[Operation /Measured Values /URTD]
Windg4	Winding 4	[Operation /Measured Values /URTD]
Windg5	Winding 5	[Operation /Measured Values /URTD]
Windg6	Winding 6	[Operation /Measured Values /URTD]
MotBear1	Motor Bearing 1	[Operation /Measured Values /URTD]
MotBear2	Motor Bearing 2	[Operation /Measured Values /URTD]
LoadBear1	Load Bearing 1	[Operation /Measured Values /URTD]
LoadBear2	Load Bearing 2	[Operation /Measured Values /URTD]
Aux1	Auxiliary1	[Operation /Measured Values /URTD]
Aux2	Auxiliary2	[Operation /Measured Values /URTD]

Value	*Description*	*Menu path*
RTD Max	Maximum temperature of all channels.	[Operation /Measured Values /URTD]

Supervision

CBF- Circuit Breaker Failure [50BF*/62BF]

*=only available in protective relays that offer current measurement.

Available elements:
CBF

Principle – General Use

The breaker failure (BF) protection is used to provide backup protection in the event that a breaker fails to operate properly during fault clearing. This signal is to be used to trip the upstream breaker (e.g. infeed of a busbar) either via an output relay or via Communication (SCADA). Depending on the ordered device and type there are different/multiple schemes available to detect a breaker failure.

Start/Trigger of the CBF Timer
A supervision timer »*t-CBF«* will be started, once the *CBF* module is triggered. Even if the Trigger signal drops again, this timer will continue to run. If the timer runs down/elapses (is not stopped), the module will issue a trip afterwards. This trip signal is to be used to trip the upstream breaker (backup).

Stopping the CBF
The timer will be stopped if the opening of the breaker is detected. Depending on the supervision scheme the timer will be stopped if the current falls below the current threshold or if the position signals indicate the open position of the breaker or a combination of both. The *CBF* module will remain within the state rejected until the trigger signal drops (falls back).

Detecting a Breaker Failure
Depending on the supervision scheme, the Circuit Breaker Failure signal (Trip) will be set if either:

- the current doesn´t fall below the threshold or
- the position signals indicate that the breaker is in the closed position or
- both.

Reject state of the CBFmodule
The *CBF* module will switch into the rejected state if the circuit breaker failure triggers are still active while the open position of the breaker has been detected successfully.

Readiness for Operation
The *CBF* module will switch back into the Stand-by if the trigger signals drop (fall back).

Locking
A locking signal will be issued simultaneously with the *CBF*-Signal (Trip). The locking signal is permanent. This signal has to be acknowledged at the HMI.

NOTICE

Note on devices that offer Wide Frequency Range measurement:

The supervision scheme 50BF will be blocked as soon as the frequency differs more than 5% from the nominal frequency. As long as the frequency differs more than 5% from the nominal frequency the supervision scheme “50BF and CB Pos” will work according to the “CB Pos” scheme.

Supervision Schemes

Up to three supvervision schemes are available depending on the ordered device type and variant in order to detect a circuit breaker failure.

*50BF**
A supervision timer will be started as soon as the *CBF*module is triggered by a trip signal. A breaker failure will be detected and a signal will be issued if the measured current does not fall below a set threshold while this timer runs down.

This supervision scheme is available within protective relays that offer current measurement.

CB Pos
A supervision timer will be started as soon as the *CBF* module is triggered by a trip signal. A breaker failure will be detected and a signal will be issued if the evaluation of the position indicators of the circuit breaker does not indicate that the breaker has been switched off sucessfully while this timer runs down.

This supervision scheme is available within all protective relays. This scheme is recommended if breaker failures have to be detected while there is no or not much load flow (small currents). This might e.g. be the case if overvoltage or overfrequency is supervisioned for a Gen-Set that is running in Stand-by.

*50 BF and CB Pos**
A supervision timer will be started as soon as the *CBF* module is triggered by a trip signal. A breaker failure will be detected and a signal will be issued if the measured current does not fall below a set threshold and if simultaneously the evaluation of the position indicators of the circuit breaker does not indicate that the breaker has been switched off sucessfully while this timer runs down.

This scheme is recommended if breaker failures have to be double checked. This scheme will issue a trip command to the upstream breaker even if position indicators indicate misleadingly (faulty) that the breaker has been opened or if the current measurement indicates misleadingly (faulty) that the breaker is now in the open position.

*=only available in protective relays that offer current measurement.

Trigger Modes

There are three trigger modes for the *CBF* module available. In addition to that, there are three assignable trigger inputs available that might trigger the *CBF* module even if they are not assigned within the breaker manager onto the breaker that is to be monitored.

•*All Trips*: All trip signals that are assigned to this breaker (within the trip manager) will start the *CBF* module (please refer also to section „Trigger signals of the Circuit Breaker Failure“).

•*Current Trips*: All current trips that are assigned to this breaker (within the trip manager) will start the *CBF* module (please refer also to section „Trigger signals of the Circuit Breaker Failure“).

•*External Trips*: All external trips that are assigned to this breaker (within the trip manager) will start the *CBF* module (please refer also to section „Trigger signals of the Circuit Breaker Failure“).

•In addition, the User can also select *none* (e.g.: if the User intends to use one of the three additional assignable trigger inputs).

NOTICE

Those trips can exclusively start the breaker failures that are assigned within the trip manager to the breaker that is to be supervised. In contrast to that the additional three triggers 1-3 will trigger the *CBF*module even if they are not assigned onto the breaker within the corresponding breaker manager.

NOTICE

Select the winding side (Breaker, Winding) from which the measured currents should be taken in case this protective device provides more than one current measurement card.

NOTICE

This Notice applies to protective devices that offer control functionality only! This protective element requires, that a switchgear (circuit breaker) is assigned to it. It is allowed only to assign switchgears (circuit breaker) to this protective element, whose measuring transformers provide measuring data to the protective device.

Breaker Failure Lockout

The signal of the Circuit Breaker Failure is latched. This signal can be used to block the breaker against a switching on attempt.

Tabular Summary

	Supervision Schemes Where? Within [Protection Para\Global Prot Para\Supervision\CBF]		
	CB Pos[2)]	**50BF**[3)]	**CBPos und 50BF**[4)]
Which breaker is to be monitored? Where to select? Within [Protection Para\Global Prot Para\Supervision\CBF]	Selection of the breaker that is to be monitored. (In case that more than one breaker is available)	Selection of the breaker that is to be monitored. (In case that more than one breaker is available)	Selection ot the breaker that is to be monitored. (In case that more than one breaker is available)
Trigger Modi (Who starts the CBF-timer*?*) Where to set? Within [Protection Para\Global Prot Para\Supervision\CBF]	All Trips[5)] or All Current Trips[5)] or External Trips[5)] …and the breaker is in the closed position and the CBF module is within the stand-by state.	All Trips[5)] or All Current Trips[5)] or External Trips[5)] ...and the CBF module is within the stand-by state.	All Trips[5)] or All Current Trips[5)] or External Trips[5)] …and the breaker is in the closed position and the CBF module is within the stand-by state.
Who stops the CBF-Timer? Once the timer has been stopped the CBF module will switch into the state „Rejected“. The module will switch back into the state „Stand-by“ if the trigger signals are dropped.	Position indicators indicate that the switchgear (breaker) is in the open position.	Current is fallen below the I<-threshold[1)].	Position indicators indicate that the switchgear (breaker) is in the open position **and** current is fallen below the I<-threshold[1)].
A Breaker Failure will be detected ...and a trip signal to the upstream breaker will be issued?	When the CBF-Timer has run down (elapsed).	When the CBF-Timer has run down (elapsed).	When the CBF-Timer has run down (elapsed).
When does the trip signal to the upstream breaker drops (falls back)?	If the position indicators indicate that the switchgear (breaker) is in the open position **and** if the trigger signals are dropped (fallen back)	If the current is fallen below the I< **and** if the trigger signals are dropped (fallen back)	If the position indicators indicate that the switchgear (breaker) is in the open position **and** if the current is fallen below the I< **and** if the trigger signals are dropped (fallen back)

[1)] It is recommended to set the I< threshold to a value that is slightly below the fault current that is expectable. By means of that it is possible to shorten the CBF supervision timer and hence reduce thermal and mechanical damage of the electrical equipment in case of a breaker failure. The lower the threshold, the longer the time that is needed to detect, that the breaker is in the open position, especially if there are transients/harmonics.

Note: Tripping delay of the *CBF* module = Minimum delay time (tripping time) of the backup protection!

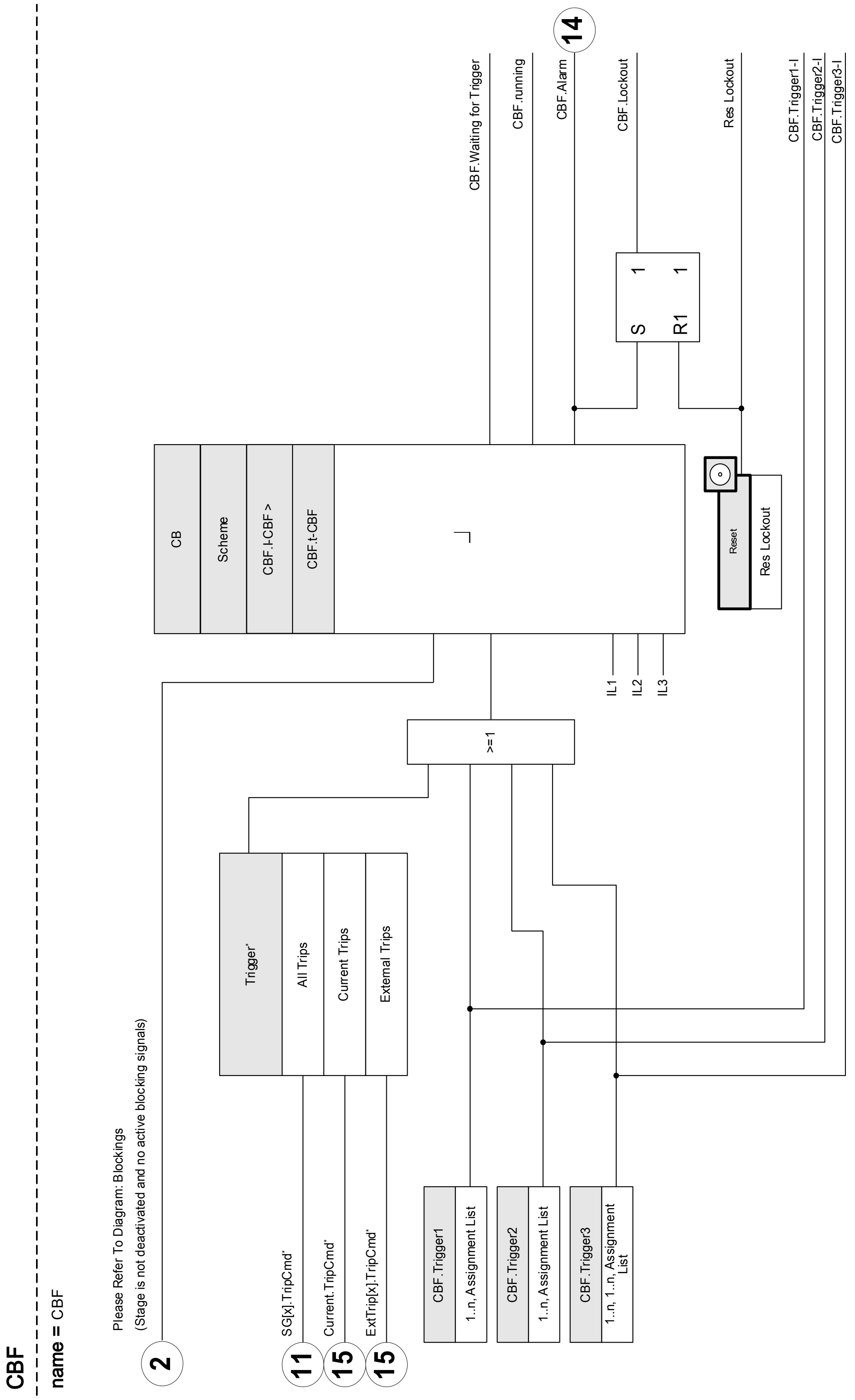
2), 3), 4)

Available in all devices with the corresponding software	Availalble in all devices that offer current measurement	Availalble in all devices that offer current measurement

5)

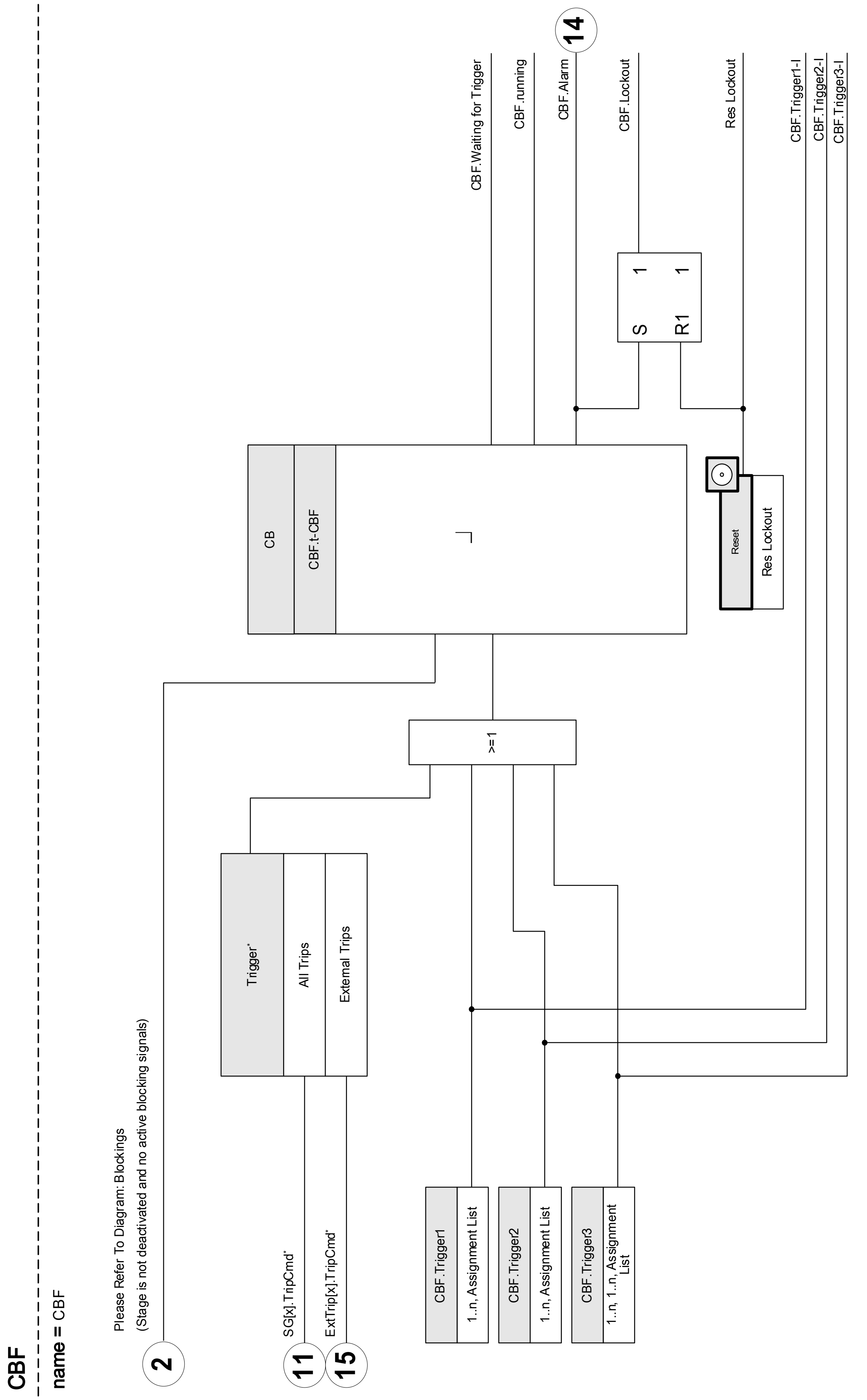
Only if the signals are assigned onto the breaker within the breaker manager.

Circuit Breaker Failure Protection for devices that offer current measurement



'The Breaker Failure will be triggered only by those trip signals that are assigned onto the the breaker within theTrip Manager.

Circuit Breaker Failure Protection for devices that offer voltage measurement only



*The Breaker Failure will be triggered only by those trip signals that are assigned onto the the breaker within theTrip Manager.

Device Planning Parameters of the CBF

Parameter	Description	Options	Default	Menu path
Mode	Mode	do not use, use	do not use	[Device planning]

Global Protection Parameters of the CBF

Parameter	Description	Setting range	Default	Menu path
Scheme	Scheme	50BF, CB Pos, 50BF and CB Pos	50BF	[Protection Para /Global Prot Para /Supervision /CBF]
ExBlo1	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /Supervision /CBF]
ExBlo2	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /Supervision /CBF]
Trigger	Determining the trigger mode for the Breaker Failure.	- . -, All Trips, External Trips, Current Trips	All Trips	[Protection Para /Global Prot Para /Supervision /CBF]
Trigger1	Trigger that will start the CBF	Trigger	-.-	[Protection Para /Global Prot Para /Supervision /CBF]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Trigger2	Trigger that will start the CBF	Trigger	-.-	[Protection Para /Global Prot Para /Supervision /CBF]
Trigger3	Trigger that will start the CBF	Trigger	-.-	[Protection Para /Global Prot Para /Supervision /CBF]

Direct Commands of the CBF

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Res Lockout	Reset Lockout	inactive, active	inactive	[Operation / Reset/Acknowledge /Reset]

Setting Group Parameters of the CBF

NOTICE

In order to prevent a faulty activation of the BF Module, the pickup (alarm) time must be greater than the sum of:

- **Operating time of the protective relay**
- **+The close-open time of the breaker (please refer to the technical data of the manufacturer of the breaker);**
- **+Drop off time (current- or position indicators)**
- **+Security margin.**

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[Protection Para /<1..4> /Supervision /CBF]
ExBlo Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /Supervision /CBF]
I-CBF >	Breaker Failure Alarm will be initiated if this threshold is still exceeded after the timer has expired (50 BF). Only available if: Scheme50BF = Or Scheme = 50BF and CB Pos	0.02 - 4.00In	0.02In	[Protection Para /<1..4> /Supervision /CBF]
t-CBF	If the delay time is expired, an CBF alarm is given out.	0.00 - 10.00s	0.20s	[Protection Para /<1..4> /Supervision /CBF]

CBF Input States

Name	*Description*	*Assignment via*
ExBlo1-I	Module input state: External blocking1	[Protection Para /Global Prot Para /Supervision /CBF]
ExBlo2-I	Module input state: External blocking2	[Protection Para /Global Prot Para /Supervision /CBF]
Trigger1-I	Module Input: Trigger that will start the CBF	[Protection Para /Global Prot Para /Supervision /CBF]
Trigger2-I	Module Input: Trigger that will start the CBF	[Protection Para /Global Prot Para /Supervision /CBF]
Trigger3-I	Module Input: Trigger that will start the CBF	[Protection Para /Global Prot Para /Supervision /CBF]

CBF Signals (Output States)

Signal	*Description*
active	Signal: active
ExBlo	Signal: External Blocking
Waiting for Trigger	Waiting for Trigger
running	Signal: CBF-Module started
Alarm	Signal: Circuit Breaker Failure
Lockout	Signal: Lockout
Res Lockout	Signal: Reset Lockout

Trigger signals of the Circuit Breaker Failure

*These trips will start the **CBF**module if »**All trips**« have been selected as the trigger event.*

Name	Description
-.-	No assignment
MStart.TripCmd	Signal: Trip Command
I[1].TripCmd	Signal: Trip Command
I[2].TripCmd	Signal: Trip Command
I[3].TripCmd	Signal: Trip Command
I[4].TripCmd	Signal: Trip Command
I[5].TripCmd	Signal: Trip Command
I[6].TripCmd	Signal: Trip Command
IG[1].TripCmd	Signal: Trip Command
IG[2].TripCmd	Signal: Trip Command
IG[3].TripCmd	Signal: Trip Command
IG[4].TripCmd	Signal: Trip Command
ThR.TripCmd	Signal: Trip Command
Jam[1].TripCmd	Signal: Trip Command
Jam[2].TripCmd	Signal: Trip Command
I<[1].TripCmd	Signal: Trip Command
I<[2].TripCmd	Signal: Trip Command
I<[3].TripCmd	Signal: Trip Command
I2>[1].TripCmd	Signal: Trip Command
I2>[2].TripCmd	Signal: Trip Command
ExP[1].TripCmd	Signal: Trip Command
ExP[2].TripCmd	Signal: Trip Command
ExP[3].TripCmd	Signal: Trip Command
ExP[4].TripCmd	Signal: Trip Command
RTD.TripCmd	Signal: Trip Command
DI Slot X1.DI 1	Signal: Digital Input
DI Slot X1.DI 2	Signal: Digital Input
DI Slot X1.DI 3	Signal: Digital Input
DI Slot X1.DI 4	Signal: Digital Input
DI Slot X1.DI 5	Signal: Digital Input
DI Slot X1.DI 6	Signal: Digital Input
DI Slot X1.DI 7	Signal: Digital Input
DI Slot X1.DI 8	Signal: Digital Input
DI Slot X1.DI 1	Signal: Digital Input
DI Slot X1.DI 2	Signal: Digital Input
DI Slot X1.DI 3	Signal: Digital Input

Name	*Description*
DI Slot X1.DI 4	Signal: Digital Input
Logics.LE1.Gate Out	Signal: Output of the logic gate
Logics.LE1.Timer Out	Signal: Timer Output
Logics.LE1.Out	Signal: Latched Output (Q)
Logics.LE1.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE2.Gate Out	Signal: Output of the logic gate
Logics.LE2.Timer Out	Signal: Timer Output
Logics.LE2.Out	Signal: Latched Output (Q)
Logics.LE2.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE3.Gate Out	Signal: Output of the logic gate
Logics.LE3.Timer Out	Signal: Timer Output
Logics.LE3.Out	Signal: Latched Output (Q)
Logics.LE3.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE4.Gate Out	Signal: Output of the logic gate
Logics.LE4.Timer Out	Signal: Timer Output
Logics.LE4.Out	Signal: Latched Output (Q)
Logics.LE4.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE5.Gate Out	Signal: Output of the logic gate
Logics.LE5.Timer Out	Signal: Timer Output
Logics.LE5.Out	Signal: Latched Output (Q)
Logics.LE5.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE6.Gate Out	Signal: Output of the logic gate
Logics.LE6.Timer Out	Signal: Timer Output
Logics.LE6.Out	Signal: Latched Output (Q)
Logics.LE6.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE7.Gate Out	Signal: Output of the logic gate
Logics.LE7.Timer Out	Signal: Timer Output
Logics.LE7.Out	Signal: Latched Output (Q)
Logics.LE7.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE8.Gate Out	Signal: Output of the logic gate
Logics.LE8.Timer Out	Signal: Timer Output
Logics.LE8.Out	Signal: Latched Output (Q)
Logics.LE8.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE9.Gate Out	Signal: Output of the logic gate
Logics.LE9.Timer Out	Signal: Timer Output
Logics.LE9.Out	Signal: Latched Output (Q)
Logics.LE9.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE10.Gate Out	Signal: Output of the logic gate
Logics.LE10.Timer Out	Signal: Timer Output
Logics.LE10.Out	Signal: Latched Output (Q)

Name	*Description*
Logics.LE10.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE11.Gate Out	Signal: Output of the logic gate
Logics.LE11.Timer Out	Signal: Timer Output
Logics.LE11.Out	Signal: Latched Output (Q)
Logics.LE11.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE12.Gate Out	Signal: Output of the logic gate
Logics.LE12.Timer Out	Signal: Timer Output
Logics.LE12.Out	Signal: Latched Output (Q)
Logics.LE12.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE13.Gate Out	Signal: Output of the logic gate
Logics.LE13.Timer Out	Signal: Timer Output
Logics.LE13.Out	Signal: Latched Output (Q)
Logics.LE13.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE14.Gate Out	Signal: Output of the logic gate
Logics.LE14.Timer Out	Signal: Timer Output
Logics.LE14.Out	Signal: Latched Output (Q)
Logics.LE14.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE15.Gate Out	Signal: Output of the logic gate
Logics.LE15.Timer Out	Signal: Timer Output
Logics.LE15.Out	Signal: Latched Output (Q)
Logics.LE15.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE16.Gate Out	Signal: Output of the logic gate
Logics.LE16.Timer Out	Signal: Timer Output
Logics.LE16.Out	Signal: Latched Output (Q)
Logics.LE16.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE17.Gate Out	Signal: Output of the logic gate
Logics.LE17.Timer Out	Signal: Timer Output
Logics.LE17.Out	Signal: Latched Output (Q)
Logics.LE17.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE18.Gate Out	Signal: Output of the logic gate
Logics.LE18.Timer Out	Signal: Timer Output
Logics.LE18.Out	Signal: Latched Output (Q)
Logics.LE18.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE19.Gate Out	Signal: Output of the logic gate
Logics.LE19.Timer Out	Signal: Timer Output
Logics.LE19.Out	Signal: Latched Output (Q)
Logics.LE19.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE20.Gate Out	Signal: Output of the logic gate
Logics.LE20.Timer Out	Signal: Timer Output
Logics.LE20.Out	Signal: Latched Output (Q)

Name	*Description*
Logics.LE20.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE21.Gate Out	Signal: Output of the logic gate
Logics.LE21.Timer Out	Signal: Timer Output
Logics.LE21.Out	Signal: Latched Output (Q)
Logics.LE21.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE22.Gate Out	Signal: Output of the logic gate
Logics.LE22.Timer Out	Signal: Timer Output
Logics.LE22.Out	Signal: Latched Output (Q)
Logics.LE22.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE23.Gate Out	Signal: Output of the logic gate
Logics.LE23.Timer Out	Signal: Timer Output
Logics.LE23.Out	Signal: Latched Output (Q)
Logics.LE23.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE24.Gate Out	Signal: Output of the logic gate
Logics.LE24.Timer Out	Signal: Timer Output
Logics.LE24.Out	Signal: Latched Output (Q)
Logics.LE24.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE25.Gate Out	Signal: Output of the logic gate
Logics.LE25.Timer Out	Signal: Timer Output
Logics.LE25.Out	Signal: Latched Output (Q)
Logics.LE25.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE26.Gate Out	Signal: Output of the logic gate
Logics.LE26.Timer Out	Signal: Timer Output
Logics.LE26.Out	Signal: Latched Output (Q)
Logics.LE26.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE27.Gate Out	Signal: Output of the logic gate
Logics.LE27.Timer Out	Signal: Timer Output
Logics.LE27.Out	Signal: Latched Output (Q)
Logics.LE27.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE28.Gate Out	Signal: Output of the logic gate
Logics.LE28.Timer Out	Signal: Timer Output
Logics.LE28.Out	Signal: Latched Output (Q)
Logics.LE28.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE29.Gate Out	Signal: Output of the logic gate
Logics.LE29.Timer Out	Signal: Timer Output
Logics.LE29.Out	Signal: Latched Output (Q)
Logics.LE29.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE30.Gate Out	Signal: Output of the logic gate
Logics.LE30.Timer Out	Signal: Timer Output
Logics.LE30.Out	Signal: Latched Output (Q)

Name	*Description*
Logics.LE30.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE31.Gate Out	Signal: Output of the logic gate
Logics.LE31.Timer Out	Signal: Timer Output
Logics.LE31.Out	Signal: Latched Output (Q)
Logics.LE31.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE32.Gate Out	Signal: Output of the logic gate
Logics.LE32.Timer Out	Signal: Timer Output
Logics.LE32.Out	Signal: Latched Output (Q)
Logics.LE32.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE33.Gate Out	Signal: Output of the logic gate
Logics.LE33.Timer Out	Signal: Timer Output
Logics.LE33.Out	Signal: Latched Output (Q)
Logics.LE33.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE34.Gate Out	Signal: Output of the logic gate
Logics.LE34.Timer Out	Signal: Timer Output
Logics.LE34.Out	Signal: Latched Output (Q)
Logics.LE34.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE35.Gate Out	Signal: Output of the logic gate
Logics.LE35.Timer Out	Signal: Timer Output
Logics.LE35.Out	Signal: Latched Output (Q)
Logics.LE35.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE36.Gate Out	Signal: Output of the logic gate
Logics.LE36.Timer Out	Signal: Timer Output
Logics.LE36.Out	Signal: Latched Output (Q)
Logics.LE36.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE37.Gate Out	Signal: Output of the logic gate
Logics.LE37.Timer Out	Signal: Timer Output
Logics.LE37.Out	Signal: Latched Output (Q)
Logics.LE37.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE38.Gate Out	Signal: Output of the logic gate
Logics.LE38.Timer Out	Signal: Timer Output
Logics.LE38.Out	Signal: Latched Output (Q)
Logics.LE38.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE39.Gate Out	Signal: Output of the logic gate
Logics.LE39.Timer Out	Signal: Timer Output
Logics.LE39.Out	Signal: Latched Output (Q)
Logics.LE39.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE40.Gate Out	Signal: Output of the logic gate
Logics.LE40.Timer Out	Signal: Timer Output
Logics.LE40.Out	Signal: Latched Output (Q)

Name	*Description*
Logics.LE40.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE41.Gate Out	Signal: Output of the logic gate
Logics.LE41.Timer Out	Signal: Timer Output
Logics.LE41.Out	Signal: Latched Output (Q)
Logics.LE41.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE42.Gate Out	Signal: Output of the logic gate
Logics.LE42.Timer Out	Signal: Timer Output
Logics.LE42.Out	Signal: Latched Output (Q)
Logics.LE42.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE43.Gate Out	Signal: Output of the logic gate
Logics.LE43.Timer Out	Signal: Timer Output
Logics.LE43.Out	Signal: Latched Output (Q)
Logics.LE43.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE44.Gate Out	Signal: Output of the logic gate
Logics.LE44.Timer Out	Signal: Timer Output
Logics.LE44.Out	Signal: Latched Output (Q)
Logics.LE44.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE45.Gate Out	Signal: Output of the logic gate
Logics.LE45.Timer Out	Signal: Timer Output
Logics.LE45.Out	Signal: Latched Output (Q)
Logics.LE45.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE46.Gate Out	Signal: Output of the logic gate
Logics.LE46.Timer Out	Signal: Timer Output
Logics.LE46.Out	Signal: Latched Output (Q)
Logics.LE46.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE47.Gate Out	Signal: Output of the logic gate
Logics.LE47.Timer Out	Signal: Timer Output
Logics.LE47.Out	Signal: Latched Output (Q)
Logics.LE47.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE48.Gate Out	Signal: Output of the logic gate
Logics.LE48.Timer Out	Signal: Timer Output
Logics.LE48.Out	Signal: Latched Output (Q)
Logics.LE48.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE49.Gate Out	Signal: Output of the logic gate
Logics.LE49.Timer Out	Signal: Timer Output
Logics.LE49.Out	Signal: Latched Output (Q)
Logics.LE49.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE50.Gate Out	Signal: Output of the logic gate
Logics.LE50.Timer Out	Signal: Timer Output
Logics.LE50.Out	Signal: Latched Output (Q)

Name	*Description*
Logics.LE50.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE51.Gate Out	Signal: Output of the logic gate
Logics.LE51.Timer Out	Signal: Timer Output
Logics.LE51.Out	Signal: Latched Output (Q)
Logics.LE51.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE52.Gate Out	Signal: Output of the logic gate
Logics.LE52.Timer Out	Signal: Timer Output
Logics.LE52.Out	Signal: Latched Output (Q)
Logics.LE52.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE53.Gate Out	Signal: Output of the logic gate
Logics.LE53.Timer Out	Signal: Timer Output
Logics.LE53.Out	Signal: Latched Output (Q)
Logics.LE53.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE54.Gate Out	Signal: Output of the logic gate
Logics.LE54.Timer Out	Signal: Timer Output
Logics.LE54.Out	Signal: Latched Output (Q)
Logics.LE54.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE55.Gate Out	Signal: Output of the logic gate
Logics.LE55.Timer Out	Signal: Timer Output
Logics.LE55.Out	Signal: Latched Output (Q)
Logics.LE55.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE56.Gate Out	Signal: Output of the logic gate
Logics.LE56.Timer Out	Signal: Timer Output
Logics.LE56.Out	Signal: Latched Output (Q)
Logics.LE56.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE57.Gate Out	Signal: Output of the logic gate
Logics.LE57.Timer Out	Signal: Timer Output
Logics.LE57.Out	Signal: Latched Output (Q)
Logics.LE57.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE58.Gate Out	Signal: Output of the logic gate
Logics.LE58.Timer Out	Signal: Timer Output
Logics.LE58.Out	Signal: Latched Output (Q)
Logics.LE58.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE59.Gate Out	Signal: Output of the logic gate
Logics.LE59.Timer Out	Signal: Timer Output
Logics.LE59.Out	Signal: Latched Output (Q)
Logics.LE59.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE60.Gate Out	Signal: Output of the logic gate
Logics.LE60.Timer Out	Signal: Timer Output
Logics.LE60.Out	Signal: Latched Output (Q)

Name	*Description*
Logics.LE60.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE61.Gate Out	Signal: Output of the logic gate
Logics.LE61.Timer Out	Signal: Timer Output
Logics.LE61.Out	Signal: Latched Output (Q)
Logics.LE61.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE62.Gate Out	Signal: Output of the logic gate
Logics.LE62.Timer Out	Signal: Timer Output
Logics.LE62.Out	Signal: Latched Output (Q)
Logics.LE62.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE63.Gate Out	Signal: Output of the logic gate
Logics.LE63.Timer Out	Signal: Timer Output
Logics.LE63.Out	Signal: Latched Output (Q)
Logics.LE63.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE64.Gate Out	Signal: Output of the logic gate
Logics.LE64.Timer Out	Signal: Timer Output
Logics.LE64.Out	Signal: Latched Output (Q)
Logics.LE64.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE65.Gate Out	Signal: Output of the logic gate
Logics.LE65.Timer Out	Signal: Timer Output
Logics.LE65.Out	Signal: Latched Output (Q)
Logics.LE65.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE66.Gate Out	Signal: Output of the logic gate
Logics.LE66.Timer Out	Signal: Timer Output
Logics.LE66.Out	Signal: Latched Output (Q)
Logics.LE66.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE67.Gate Out	Signal: Output of the logic gate
Logics.LE67.Timer Out	Signal: Timer Output
Logics.LE67.Out	Signal: Latched Output (Q)
Logics.LE67.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE68.Gate Out	Signal: Output of the logic gate
Logics.LE68.Timer Out	Signal: Timer Output
Logics.LE68.Out	Signal: Latched Output (Q)
Logics.LE68.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE69.Gate Out	Signal: Output of the logic gate
Logics.LE69.Timer Out	Signal: Timer Output
Logics.LE69.Out	Signal: Latched Output (Q)
Logics.LE69.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE70.Gate Out	Signal: Output of the logic gate
Logics.LE70.Timer Out	Signal: Timer Output
Logics.LE70.Out	Signal: Latched Output (Q)

Name	*Description*
Logics.LE70.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE71.Gate Out	Signal: Output of the logic gate
Logics.LE71.Timer Out	Signal: Timer Output
Logics.LE71.Out	Signal: Latched Output (Q)
Logics.LE71.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE72.Gate Out	Signal: Output of the logic gate
Logics.LE72.Timer Out	Signal: Timer Output
Logics.LE72.Out	Signal: Latched Output (Q)
Logics.LE72.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE73.Gate Out	Signal: Output of the logic gate
Logics.LE73.Timer Out	Signal: Timer Output
Logics.LE73.Out	Signal: Latched Output (Q)
Logics.LE73.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE74.Gate Out	Signal: Output of the logic gate
Logics.LE74.Timer Out	Signal: Timer Output
Logics.LE74.Out	Signal: Latched Output (Q)
Logics.LE74.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE75.Gate Out	Signal: Output of the logic gate
Logics.LE75.Timer Out	Signal: Timer Output
Logics.LE75.Out	Signal: Latched Output (Q)
Logics.LE75.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE76.Gate Out	Signal: Output of the logic gate
Logics.LE76.Timer Out	Signal: Timer Output
Logics.LE76.Out	Signal: Latched Output (Q)
Logics.LE76.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE77.Gate Out	Signal: Output of the logic gate
Logics.LE77.Timer Out	Signal: Timer Output
Logics.LE77.Out	Signal: Latched Output (Q)
Logics.LE77.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE78.Gate Out	Signal: Output of the logic gate
Logics.LE78.Timer Out	Signal: Timer Output
Logics.LE78.Out	Signal: Latched Output (Q)
Logics.LE78.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE79.Gate Out	Signal: Output of the logic gate
Logics.LE79.Timer Out	Signal: Timer Output
Logics.LE79.Out	Signal: Latched Output (Q)
Logics.LE79.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE80.Gate Out	Signal: Output of the logic gate
Logics.LE80.Timer Out	Signal: Timer Output
Logics.LE80.Out	Signal: Latched Output (Q)

Name	Description
Logics.LE80.Out inverted	Signal: Negated Latched Output (Q NOT)

These trips will start the BF module if »All current« functions have been selected as the trigger event.

Name	Description
-.-	No assignment
I[1].TripCmd	Signal: Trip Command
I[2].TripCmd	Signal: Trip Command
I[3].TripCmd	Signal: Trip Command
I[4].TripCmd	Signal: Trip Command
I[5].TripCmd	Signal: Trip Command
I[6].TripCmd	Signal: Trip Command
IG[1].TripCmd	Signal: Trip Command
IG[2].TripCmd	Signal: Trip Command
IG[3].TripCmd	Signal: Trip Command
IG[4].TripCmd	Signal: Trip Command
ThR.TripCmd	Signal: Trip Command
Jam[1].TripCmd	Signal: Trip Command
Jam[2].TripCmd	Signal: Trip Command
I<[1].TripCmd	Signal: Trip Command
I<[2].TripCmd	Signal: Trip Command
I<[3].TripCmd	Signal: Trip Command
I2>[1].TripCmd	Signal: Trip Command
I2>[2].TripCmd	Signal: Trip Command

These trips will start the BF module if »External trips« have been selected as the trigger event.

Name	*Description*
-.-	No assignment
ExP[1].TripCmd	Signal: Trip Command
ExP[2].TripCmd	Signal: Trip Command
ExP[3].TripCmd	Signal: Trip Command
ExP[4].TripCmd	Signal: Trip Command

Commissioning Example: Supervision Scheme 50BF

Object to Be Tested:

Test of the breaker failure protection (Supervision Scheme 50BF).

Necessary Means:
- Current source;
- Ammeter; and
- Timer.

NOTICE **When testing, the applied test current must always be higher than the tripping threshold *»I-CBF«*. If the test current falls below the threshold while the breaker is in the "Off" position, no pickup will be generated.**

Procedure (Single-Phase):
For testing the tripping time of the CBF protection, a test current has to be higher than the threshold value of one of the current protection modules that are assigned to trigger the CBF protection. The CBF trip delay can be measured from the time when one of the triggering inputs becomes active to the time when the CBF protection trip is asserted.

To avoid wiring errors, checked to make sure the breaker in the upstream system switches off.

The time, measured by the timer, should be in line with the specified tolerances.

Successful Test Result:
The actual times measured comply with the setpoint times. The breaker in the higher-level section switches off.

WARNING **Re-connect the control cable to the breaker!**

TCS - Trip Circuit Supervision [74TC]

Available elements:
TCS

The trip circuit monitoring is used for monitoring if the trip circuit is ready for operations. The monitoring can be fulfilled in two ways. The first assumes only »*Aux On (52a)«* is used in the trip circuit. The second assumes that, in addition to »*Aux On (52a)*, »*Aux Off(52b)«* is also used for the circuit monitoring.

With »*Aux On (52a)*, only in the trip circuit, the monitoring is only effective when the breaker is closed while if both »*Aux On (52a)*, and »*Aux Off(52b)«* are used, the trip circuit will be monitored all time as long as the control power is on.

Note that the digital inputs used for this purpose must be configured properly based on the trip circuit control voltage. If the trip circuit is detected broken, an alarm will be issued with a specified delay, which must be longer than the time when a trip contact is closed to the time when the breaker status is clearly recognized by the relay.

NOTICE **In Slot 1 has 2 digital inputs, each of which has a separate root (contact separation) for the trip circuit supervision.**

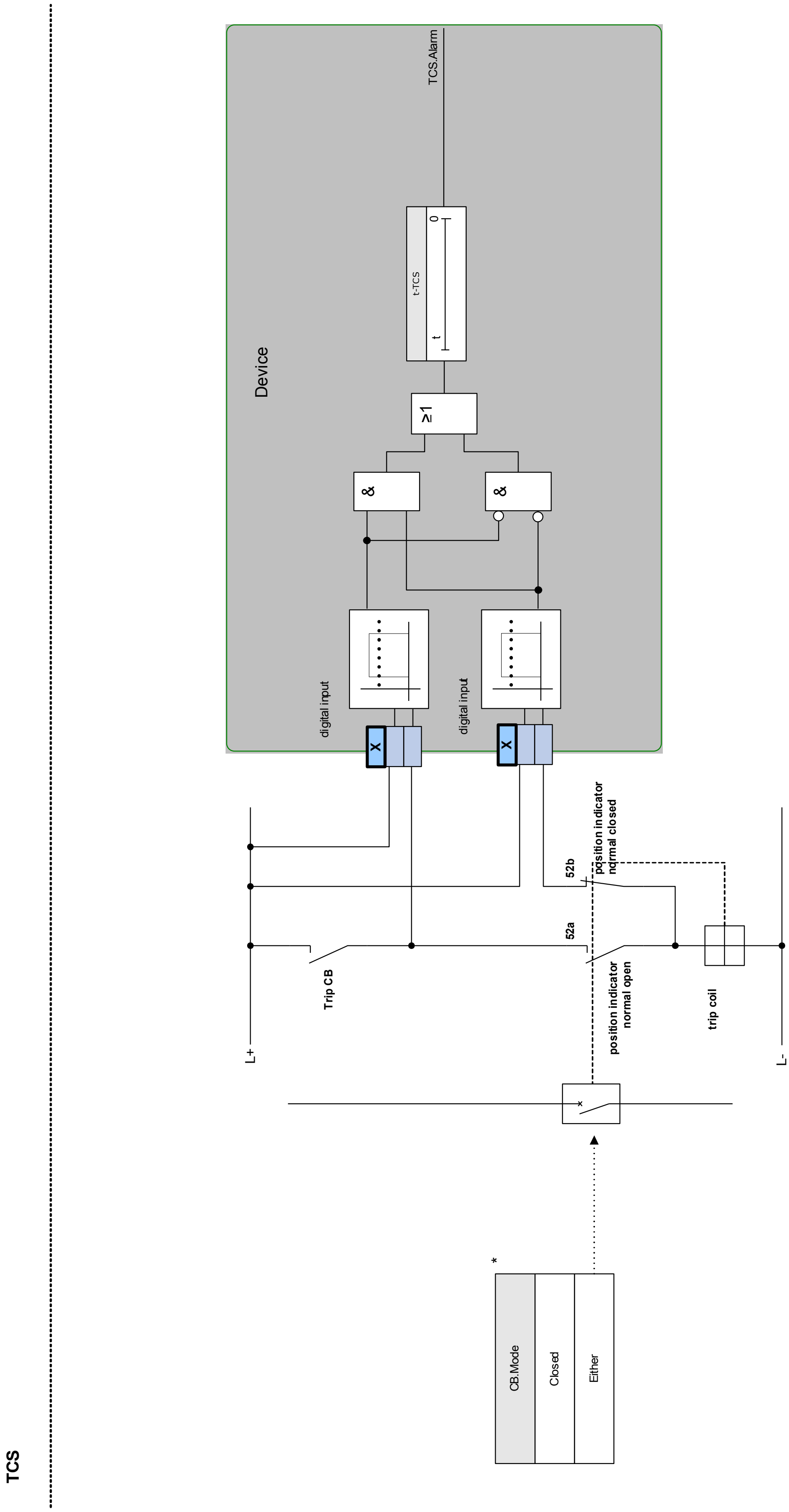
NOTICE **This Notice applies to protective devices that offer control functionality only! This protective element requires, that a switchgear (circuit breaker is assigned to it.**

In this case, the trip circuit supply voltage serves also as supply voltage for the digital inputs and so the supply voltage failure of a trip circuit can be detected directly.

In order to identify a conductor failure in the trip circuit on the supply line or in the trip coil, the off-coil has to be looped-in to the supervision circuit.

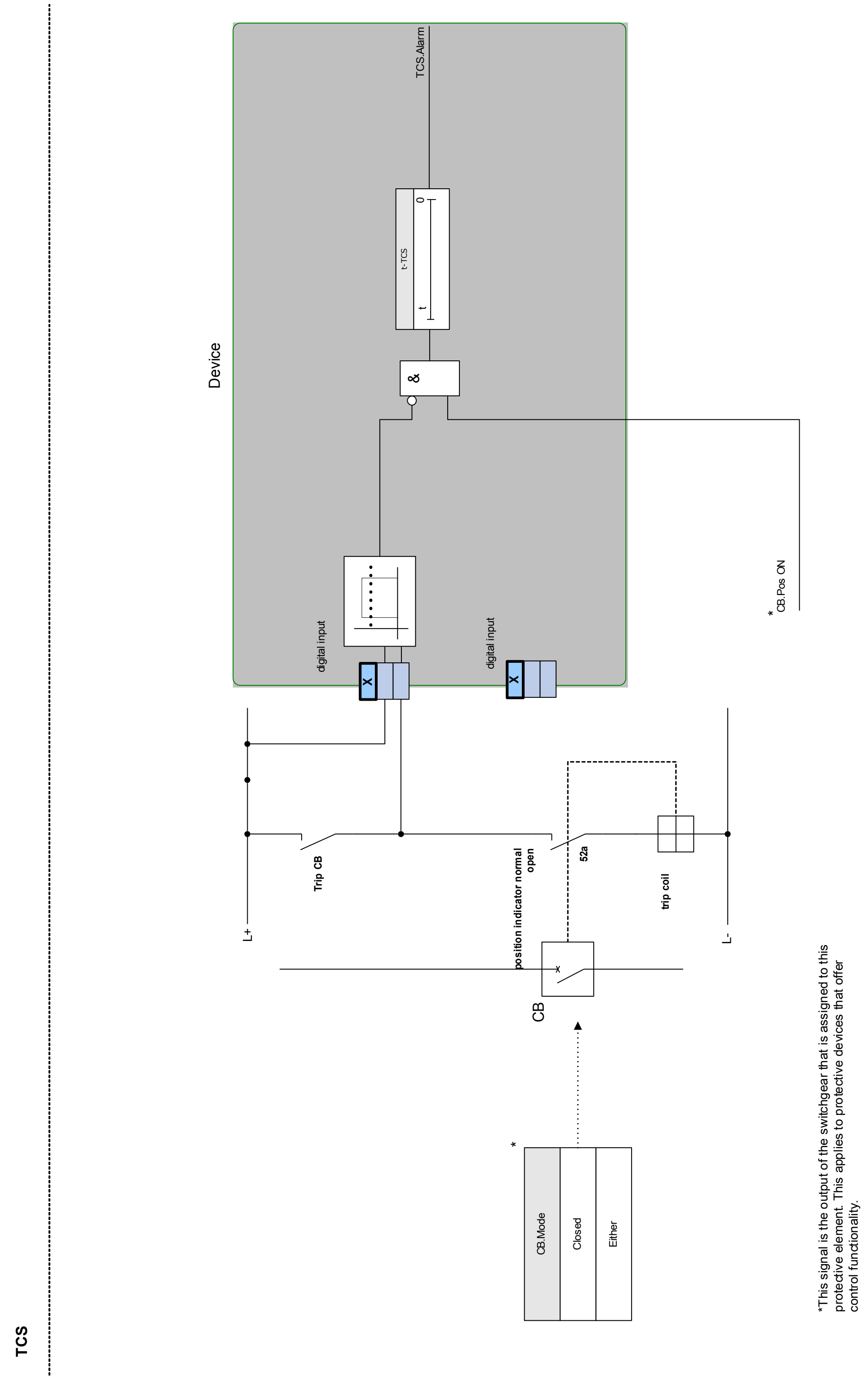
The time delay is to be set in a way that switching actions cannot cause false trips in this module.

Connection example: Trip circuit supervision with two CB auxiliary contacts.



*This signal is the output of the switchgear that is assigned to this protective element. This applies to protective devices that offer control functionality.

Connection example: Trip circuit supervision with one CB auxiliary contact (Aux On (52a)) only.



Device Planning Parameters of the Trip Circuit Supervision

Parameter	*Description*	*Options*	*Default*	*Menu path*
Mode	Mode	do not use, use	do not use	[Device planning]

Global Protection Parameters of the Trip Circuit Supervision

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Mode	Select if trip circuit is going to be monitored when the breaker is closed or when the breaker is either open or close.	Closed, Either	Closed	[Protection Para /Global Prot Para /Supervision /TCS]
Input 1	Select the input configured to monitor the trip coil when the breaker is closed.	1..n, Dig Inputs	-.-	[Protection Para /Global Prot Para /Supervision /TCS]
Input 2	Select the input configured to monitor the trip coil when the breaker is open. Only available if Mode set to “Either”. Only available if: Mode = Either	1..n, Dig Inputs	-.-	[Protection Para /Global Prot Para /Supervision /TCS]
ExBlo1	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /Supervision /TCS]
ExBlo2	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /Supervision /TCS]

Setting Group Parameters of the Trip Circuit Supervision

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[Protection Para /<1..4> /Supervision /TCS]
ExBlo Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /Supervision /TCS]
t-TCS	Tripping delay time of the Trip Circuit Supervision	0.10 - 10.00s	0.2s	[Protection Para /<1..4> /Supervision /TCS]

Trip Circuit Supervision Input States

Name	*Description*	*Assignment via*
Aux ON-I	Module Input State: Position indicator/check-back signal of the CB (52a)	[Protection Para /Global Prot Para /Supervision /TCS]
Aux OFF-I	Module input state: Position indicator/check-back signal of the CB (52b)	[Protection Para /Global Prot Para /Supervision /TCS]
ExBlo1-I	Module input state: External blocking1	[Protection Para /Global Prot Para /Supervision /TCS]
ExBlo2-I	Module input state: External blocking2	[Protection Para /Global Prot Para /Supervision /TCS]

Trip Circuit Supervision Signals (Output States)

Signal	*Description*
active	Signal: active
ExBlo	Signal: External Blocking
Alarm	Signal: Alarm Trip Circuit Supervision
Not Possible	Not possible because no state indicator assigned to the breaker.

Commissioning: Trip Circuit Supervision [74TC]

NOTICE **For CBs that trip by means of little energy (e.g. via an optocoupler), it has to be ensured that the current applied by the digital inputs will not cause false tripping of the CB.**

Object to be tested
Test of the trip circuit supervision.

Procedure, part 1
Simulate failure of the control voltage in the power circuits.

Successful test result, part 1
After expiry of *»t-TCS«* the trip circuit supervision *TCS* of the device should signal an alarm.

Procedure, part 2
Simulate a broken cable in the CB control circuit.

Successful test result, part 2
After expiry of *»t-TCS«* the trip circuit supervision *TCS* of the device should signal an alarm.

CTS - Current Transformer Supervision [60L]

Available elements:
CTS

Wire breaks and failures within measuring circuits cause current transformer failures.
The module *»CTS«* can detect a failure of the CT if the calculated earth current does not match the measured one. If an adjustable threshold value (Difference of measured and calculated earth current) is exceeded, a CT failure can be assumed. This is signaled through a message/alarm.
The precondition is that the conductor currents are measured by the device and the earth current, for instance, by a ring core type current transformer.

The measuring principles of the circuit supervision are based on comparing the measured and the calculated residual currents:
In an ideal case these are:

$$(\vec{IL1}+\vec{IL2}+\vec{IL3})+KI*\vec{IG}=3*I_0+KI*\vec{IG}=0$$

KI represents a correction factor which takes the different transformation ratio of the phase- and earth current transformers into account. The device automatically calculates this factor from the rated field parameters, i.e. the relation between the rated primary and secondary current values of the phase- and earth current transformers.

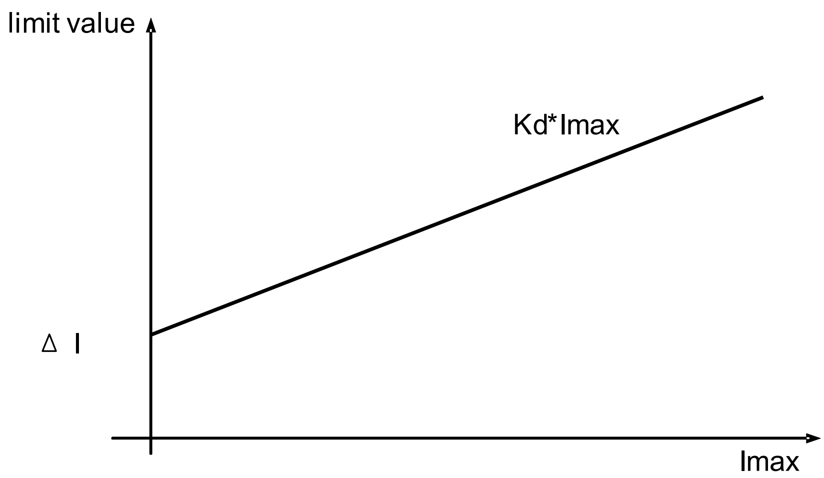
For compensating the current proportional ratio error of the measuring circuits, the dynamic correction factor Kd can be used. As a function of the measured max. current this factor is considering the linear rising measuring error.
The limiting value of the CT supervision is calculated as follows:

ΔI = deviation I (rated value)
Kd = correction factor
Imax = current maximum
Limiting value = ΔI + Kd x Imax

Precondition for identifying an error

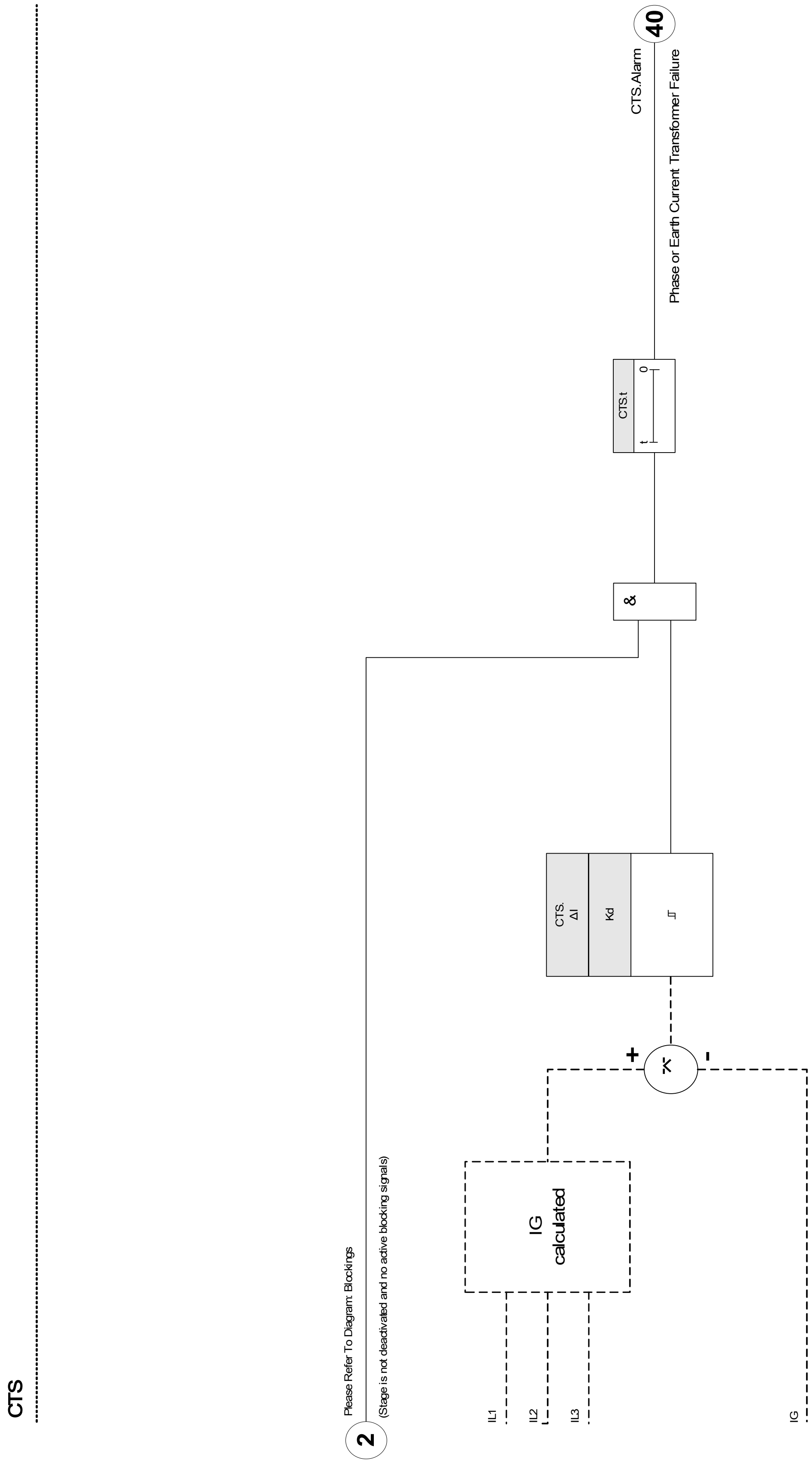
$$3*\vec{I}_0+KI*\vec{IG}\geqslant Delta\ I+Kd*Imax$$

The evaluation method of the circuit supervision by using factor Kd can be graphically represented as follows:



CAUTION

If the current is measured in two phases only (for instant only IL1/IL3) or if there is no separate earth current measuring (e.g. normally via a cable-type CT), the supervision function should be deactivated.



Device Planning Parameters of the Current Transformer Supervision

Parameter	*Description*	*Options*	*Default*	*Menu path*
Mode	Mode	do not use, use	do not use	[Device planning]

Global Protection Parameter of the Current Transformer Supervision

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
ExBlo1	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /Supervision /CTS]
ExBlo2	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.	1..n, Assignment List	-.-	[Protection Para /Global Prot Para /Supervision /CTS]

Setting Group Parameters of the Current Transformer Supervision

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Function	Permanent activation or deactivation of module/stage.	inactive, active	inactive	[Protection Para /<1..4> /Supervision /CTS]
ExBlo Fc	Activate (allow) or inactivate (disallow) blocking of the module/stage. This parameter is only effective if a signal is assigned to the corresponding global protection parameter. If the signal becomes true, those modules/stages are blocked that are parameterized "ExBlo Fc=active".	inactive, active	inactive	[Protection Para /<1..4> /Supervision /CTS]
ΔI	In order to prevent faulty tripping of phase selective protection functions that use the current as tripping criterion. If the difference of the measured earth current and the calculated value I0 is higher than the pick up value ΔI, an alarm event is generated after expiring of the excitation time. In such a case, a fuse failure, a broken wire or a faulty measuring circuit can be assumed.	0.10 - 1.00In	0.50In	[Protection Para /<1..4> /Supervision /CTS]
Alarm delay	Alarm delay	0.0 - 9999.0s	1.0s	[Protection Para /<1..4> /Supervision /CTS]
Kd	Dynamic correction factor for the evaluation of the difference between calculated and measured earth current. This correction factor allows transformer faults, caused by higher currents, to be compensated.	0.00 - 0.99	0.00	[Protection Para /<1..4> /Supervision /CTS]

Current Transformer Supervision Input States

Name	*Description*	*Assignment via*
ExBlo1-I	Module input state: External blocking1	[Protection Para /Global Prot Para /Supervision /CTS]
ExBlo2-I	Module input state: External blocking2	[Protection Para /Global Prot Para /Supervision /CTS]

Current Transformer Supervision Signals (Outputs States)

Signal	*Description*
active	Signal: active
ExBlo	Signal: External Blocking
Alarm	Signal: Alarm Current Transformer Measuring Circuit Supervision

Commissioning: Current Transformer Failure Supervision

NOTICE

Precondition:

1. Measurement of all three phase currents (are applied to the measuring inputs of the device).
2. The earth current is detected via a cable-type transformer (not in Holmgreen connection).

Object to be tested

Check of the CT supervision (by comparing the calculated with the measured earth current).

Necessary means

- Three-phase current source

Procedure, part 1

- Set the limiting value of the CTS to *»delta I=0.1*In«*.
- Feed a three-phase, symmetrical current system (approx. nominal current) to the secondary side.
- Disconnect the current of one phase from one of the measuring inputs (the symmetrical feeding at secondary side has to be maintained).
- Make sure that the signal »CTS.ALARM« is generated now.

Successful test result, part 1

- The signal »CTS.ALARM« is generated.

Procedure, part 2

- Feed a three-phase, symmetrical current system (approx. nominal current) to the secondary side.
- Feed a current that is higher than the threshold value for the measuring circuit supervision to the earth current measuring input.
- Ascertain that the signal »CTS.ALARM« is generated now.

Successful test result, part 2

The signal »CTS.ALARM« is generated.

Phase Sequence Supervision

The device calculates the phase sequence at each CT and VT (based on positive-sequence and negative-sequence components). The calculated phase sequence (i. e. „ACB“ or „ABC“) is permanently compared with the setting that has been made at [Field Para/General Settings] *»Phase Sequence«*.

The menu [Operation/Status Display/Supervision/Phase Sequence] contains a specific (warning) signal for each CT and VT. If the check of a CT / VT finds that the actual phase sequence is different from the setting under [Field Para] then the respective signal becomes true (active).

The phase sequence supervision is especially useful during commissioning of the device because it helps making sure that the *»Phase Sequence«* setting under [Field Para] is correct

WARNING **The supervision requires minimum values for the current (in case of a CT), or for the voltage (in case of a VT, respectively), otherwise the phase sequence cannot be reliably determined.**

- **For a VT: The minimum voltage is $0.1 \cdot V_n$.**
- **For a CT: The minimum current is $0.1 \cdot I_n$.**

Self Supervision

SSV

The protection devices are supervised by various check routines during normal operation and during the start-up phase on faulty operation.

The protection devices are carrying out various self supervision tests.

Self Supervision within the devices		
Supervision of...	Supervised by...	Action on detected issue...
Start phase	The duration (permitted time) of the boot phase is monitored.	The device will be rebooted. => The device will be taken out of service after three unsuccessful start attempts.
Supervision of the duration of a protection cycle (Software cycle)	The maximum permitted time for a protection cycle is monitored by a timing analysis.	The self-supervision contact will be deenergized if the permitted time for a protection cycle is exceeded (first threshold). The protection device will be rebooted, if the protection cycle exceeds the second threshold.
Monitoring of the communication between Main and Digital Signal Processor (DSP)	The cyclic measured value processing of the DSP is monitored by the main processor.	The device will be rebooted, if a failure is detected. The self-supervision contact will be deenergized.
Analog-Digital-Converter	The DSP does a plausibility check on the digitalized data.	Protection will be blocked, if a failure is detected, in order to prevent faulty tripping.
Supervision of data consistency after an outage of the power supply. (e.g. outage of the power supply while changing the parameter settings).	An internal logic detects fragmentary saved data after an outage of the power supply.	If the new data is incomplete or corrupt, it will be deleted during the reboot phase of the device. The device will continue to work with the last valid data set.
Data consistency in general	Generation of check-sums.	The device will be taken out of service in case that inconsistent data is detected that is not caused by an outage of the power supply. (fatal internal error).

Self Supervision within the devices		
Parameter Setting (Device)	Protecting the parameter setting by plausibility checks.	Implausibilities within the parameter configuration can be detected by means of plausibility checks. Detected implausibilities are highlighted by a question mark symbol. Please refer to chapter parameter setting for detailed information.
Quality of the power supply	A hardware circuit ensures that the device can only be used, if the power supply is in the range specified by the technical data.	If the supply voltage is too low, the device will not start up or it will be set out of service respectively.
Sags of the supply voltage	Short-term sags of the supply voltage are detected and can be bridged in most of the cases by means of the integrated buffer within the power supply hardware. This buffer also allows the termination of ongoing data writing procedures.	The module for the supervision of the system utilization will detect repetitive short-term sags of the supply voltage.
Internal data of the device (memory load, internal resources, ...)	An internal module monitors the system utilization.	The module for the supervision of the system utilization initiates in case of a fatal error a reboot of the device. In case of minor faults the System LED will flash alternating red and green (please refer to the *Troubleshooting Guide*). The issue will be recorded as a system message.
Battery	The battery is monitored continuously. Notice: The battery serves as buffering of the clock (real time clock). There's no impact on the functionality of the device if the battery breaks down, except for the buffering of the clock while the unit is in de-energized condition.	If the battery is low the System LED will flash alternating red and green (please refer to the *Troubleshooting Guide*).
Status of the device communication (SCADA)	The projected and activated SCADA module supervises its connection to the master communication system.	You can check if there is active communication with the master system within menu <Operation/ Status display/ Communication>. In order to monitor this state you can assign this status onto an LED and/or an output relay. For details on the status of the GOOSE communication please refer to chapter IEC61850.

Device Start (Reboot)

The device starts up if:

- it is connected to the supply voltage,
- the User initiates (intentionally) a restart of the device,
- the device is set back to factory defaults,
- the internal self-supervision of the device detects a fatal error.

The reason for a device start/reboot is shown numerically within menu <Operation/ Status display/ Sys/ Restart> (please refer to the table below). The reason will also be logged within the event recorder (Event: Sys.Restart).

The table below explains the numbers indicating the reason of the restart.

Device Start-up Codes	
1.	**Normal Start-up** Start-up after clean disconnection of the supply voltage.
2.	**Reboot by the Operator** Device reboot triggered by the operator via HMI or Smart view.
3.	**Reboot by means of Super Reset** Automatic reboot when setting the device back to factory defaults.
4.	-- (outdated)
5.	-- (outdated)
6.	**Unknown Error Source** Reboot due to unknown error source.
7.	**Forced Reboot (initiated by the main processor)** The main processor identified invalid conditions or data.
8.	**Exceeded Time Limit of the Protection Cycle** Unexpected interruption of the Protection Cycle.
9.	**Forced Reboot (initiated by the digital signal processor)** The digital signal processor identified invalid conditions or data.
10.	**Exceeded Time Limit of the Measured Value Processing** Unexpected interruption of the cyclic measured value processing.
11.	**Sags of the Supply Voltage** Reboot after short-term sag or outage of the supply voltage.
12.	**Illegal Memory Access** Reboot after illegal memory access.

Internal Messages

The menu [Operation / Self Supervision / Messages] gives access to the list of internal messages. In particular, it is recommended to check these in case of some problem directly related to the device.

All messages that can potentially appear here are described in detail in a separate document, the “HighPROTEC Troubleshooting Guide” (`DOK-HB-TS`).

Device taken out of Service "Device Stopped"

The protection device will be taken out of service, if there is an undefined state that cannot be escaped after three reboots.
In this state the system LED will be illuminated red or red flashing. The display will show the message „Device Stopped" followed by a 6-digit error code, e.g. E01487.

In addition to the recorders, messages and display information that can be accessed by the user, there may exist additional error information accessible by the Service Staff. These offer further failure analysis and diagnosis opportunities to the Service Staff.

NOTICE

In such a case please contact the Woodward Service Staff and provide them the error code.

For further information on trouble shooting please refer to the separately provided "HighPROTEC Trouble Shooting Guide".

Direct Commands of the Self Supvervision

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Ack System LED	Acknowledge System LED (red/green flashing LED)	False, True	False	[Operation / Reset/Acknowledge /Acknowledge]

Signals (Output States) of the Self Supvervision

Signal	*Description*
System Error	Signal: Device Failure
SelfSuperVision Contact	Signal: SelfSuperVision Contact

Counter Values of the Self Supvervision

Value	*Description*	*Menu path*
Cr No of free sockets	Counter for network diagnosis. Number of free sockets.	[Operation /Self Supervision /System State]

Programmable Logic

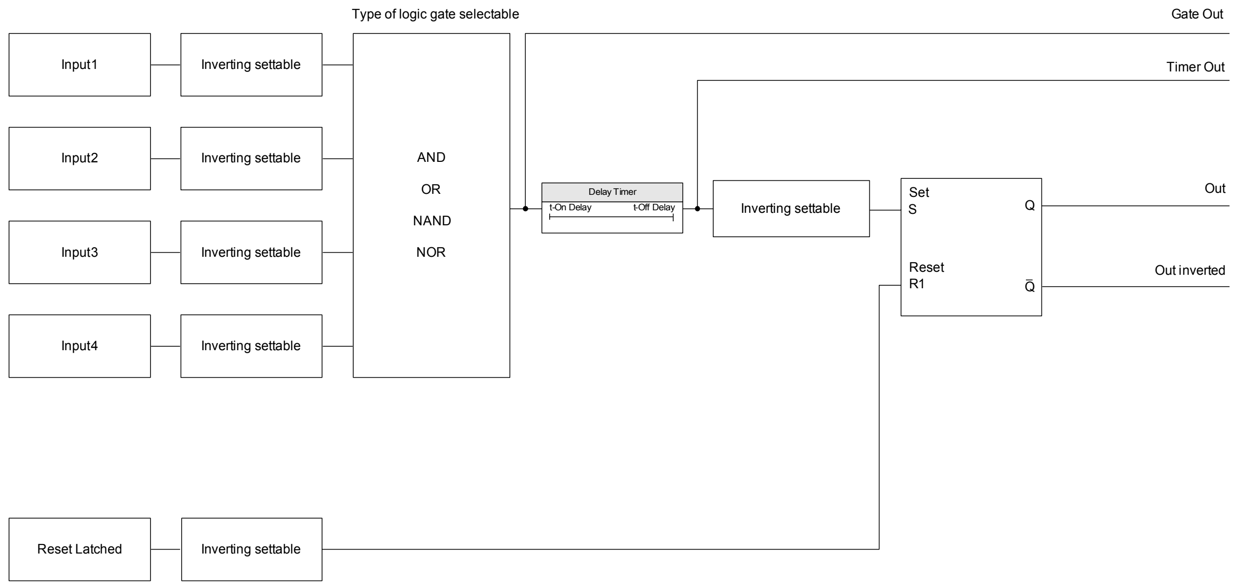
Available Elements (Equations):
Logics

General Description

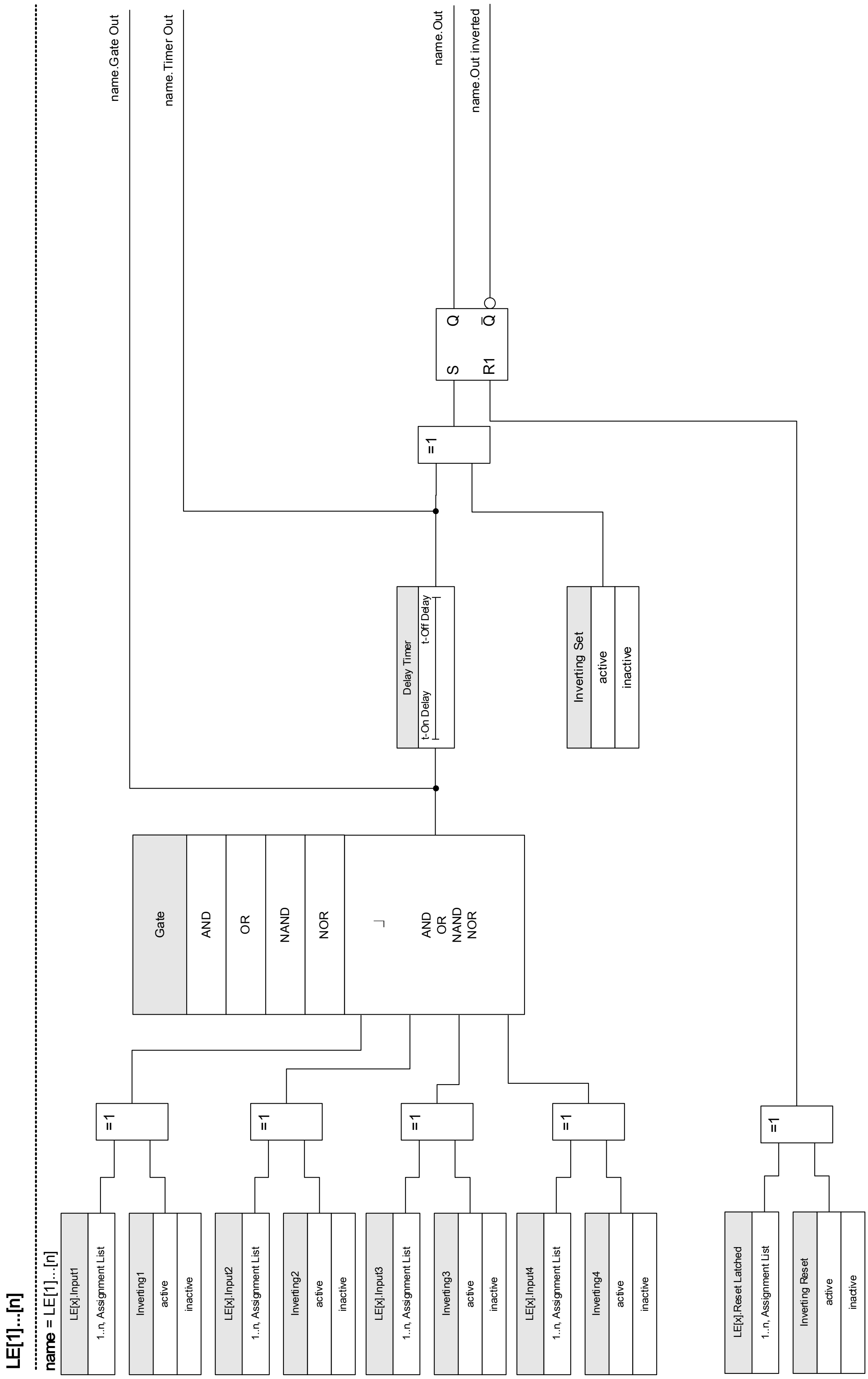
The Protective Relay includes programmable Logic Equations for programming output relays, blocking of protective functions and custom logic functions in the relay.

The logic provides control of the output relays based on the state of the inputs that can be choosen from the assignment list (protective function pickups, protective function states, breaker states, system alarms, and module inputs). The user can use the outputs signals of a Logic Equation as inputs in higher equations (e.g. the output signal of Logic Equation 10 might be used as an input of Logic Equation 11).

Principle Overview



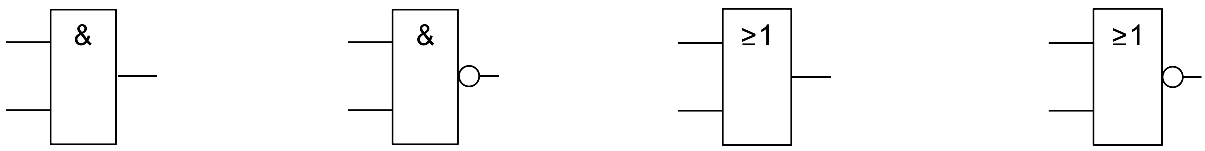
Detailed Overview – Overall Logic diagram



Available Gates (Operators)

Within the Logic Equation, the following Gates can be used:

Gate



AND NAND OR NOR

Input Signals

The user can assign up to 4 Input signals (from the assignment list) to the inputs of the gate.

As an option, each of the 4 input signals can be inverted (negated)

Timer Gate (On Delay and Off Delay)

The output of the gate can be delayed. The user has the option to set an On and an Off delay.

Latching

The logic equations issues two signals. An unlatched and a latched signal. The latched output is also available as an inverted output.
In order to reset the latched signal the user has to assign a reset signal from the assignment list. The reset signal can also optionally be inverted. The latching works based on reset priority. That means, the reset input is dominant.

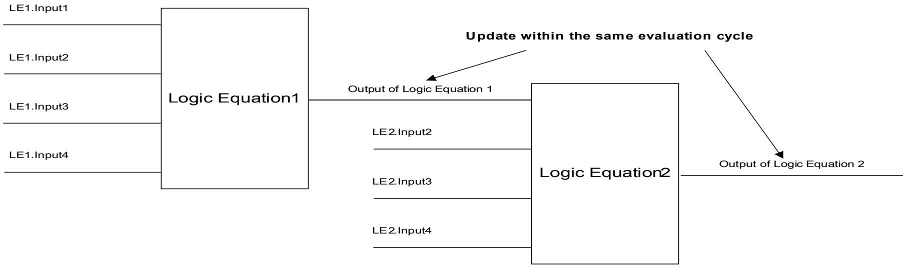
Cascading Logical Outputs

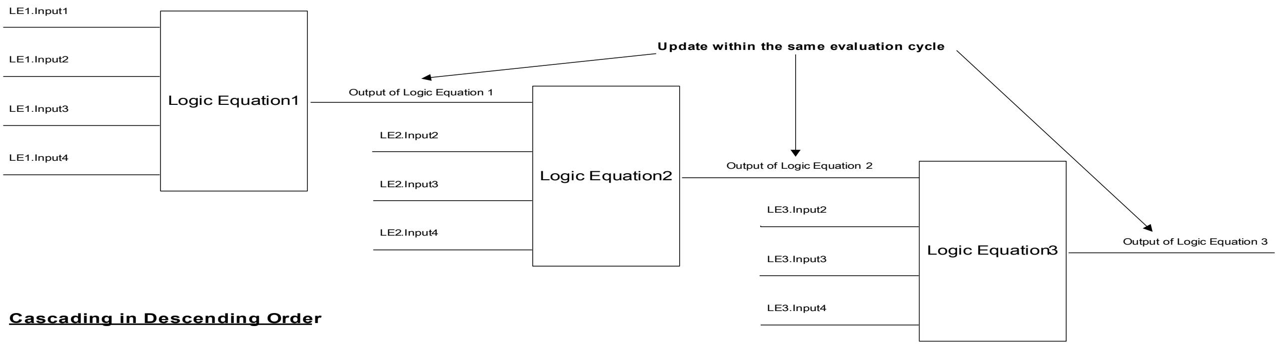
The device will evaluate output states of the Logic Equations starting from Logic Equation 1 up to the Logic Equation with the highest number. This evaluation (device) cycle will be continuously repeated.

Cascading Logic Equations in an ascending sequence
Cascading in an ascending sequence means that the user uses the output signal of “Logic Equation **n**” as input of “Logic Equation **n+1**”. If the state of “Logic Equation **n**” changes, the state of the output of “Logic Equation **n+1**” will be updated within the same cycle.

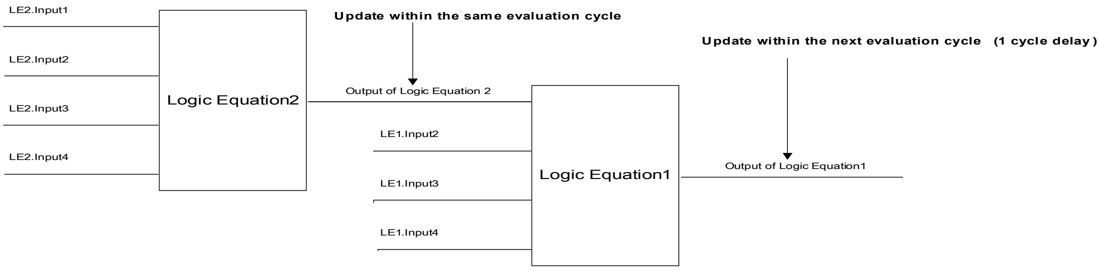
Cascading Logic Equations in a descending sequence
Cascading in a descending sequence means that the user uses the output signal of “Logic Equation **n+1**” as input of “Logic Equation **n**”. If the output of “Logic Equation **n+1**” changes, this change of the feed back signal at the input of “Logic Equation **n**” will be delayed for one cycle.

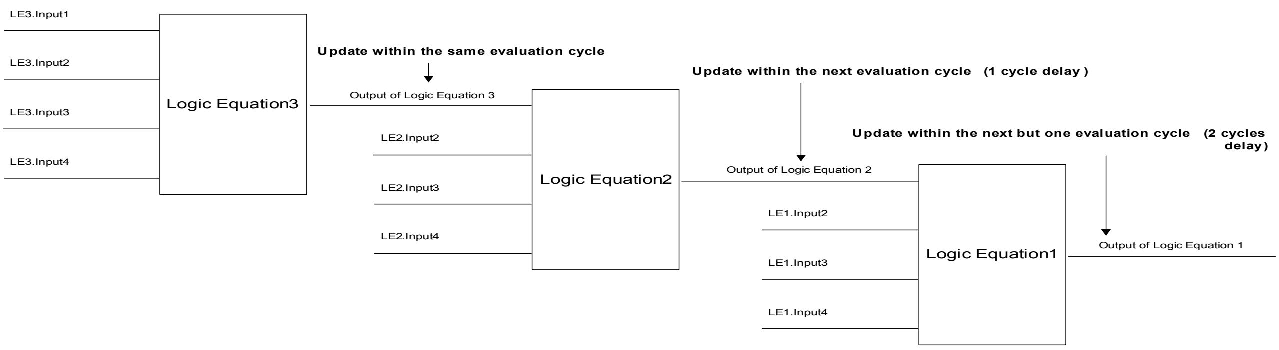
Cascading in Ascending Order





Cascading in Descending Order





Programmable Logic at the Panel

WARNING

WARNING improper use of Logic Equations might result in personal injury or damage the electrical equipment.

Don´t use Logic Equations unless that you can ensure the safe functionality.

How to configure a Logic Equation?

- Call up menu [Logics/LE [x]]:
- Set the Input Signals (where necessary, invert them).
- If required, configure the timer (»*On delay*« and »*Off delay*«).
- If the latched output signal is used assign a reset signal to the reset input.
- Within the »status display«, the user can check the status of the logical inputs and outputs of the Logic Equation.

In case that Logic Equations should be cascaded the user has to be aware of timing delays (cycles) in case of descending sequences (Please refer to section: Cascading Logical Outputs).

By means the Status Display [Operation/Status Display] the logical states can be verified.]

Device Planning Parameters of the Programmable Logic

Parameter	*Description*	*Options*	*Default*	*Menu path*
No of Equations:	Number of required Logic Equations:	0, 5, 10, 20, 40, 80	20	[Device planning]

Global Protection Parameter of the Programmable Logic

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
LE1.Gate	Logic gate	AND, OR, NAND, NOR	AND	[Logics /LE 1]
LE1.Input1	Assignment of the Input Signal	1..n, Assignment List	-.-	[Logics /LE 1]
LE1.Inverting1	Inverting the input signals. Only available if an input signal has been assigned.	inactive, active	inactive	[Logics /LE 1]
LE1.Input2	Assignment of the Input Signal	1..n, Assignment List	-.-	[Logics /LE 1]
LE1.Inverting2	Inverting the input signals. Only available if an input signal has been assigned.	inactive, active	inactive	[Logics /LE 1]
LE1.Input3	Assignment of the Input Signal	1..n, Assignment List	-.-	[Logics /LE 1]
LE1.Inverting3	Inverting the input signals. Only available if an input signal has been assigned.	inactive, active	inactive	[Logics /LE 1]
LE1.Input4	Assignment of the Input Signal	1..n, Assignment List	-.-	[Logics /LE 1]
LE1.Inverting4	Inverting the input signals. Only available if an input signal has been assigned.	inactive, active	inactive	[Logics /LE 1]
LE1.t-On Delay	Switch On Delay	0.00 - 36000.00s	0.00s	[Logics /LE 1]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
LE1.t-Off Delay	Switch Off Delay	0.00 - 36000.00s	0.00s	[Logics /LE 1]
LE1.Reset Latched	Reset Signal for the Latching	1..n, Assignment List	-.-	[Logics /LE 1]
LE1.Inverting Reset	Inverting Reset Signal for the Latching	inactive, active	inactive	[Logics /LE 1]
LE1.Inverting Set	Inverting the Setting Signal for the Latching	inactive, active	inactive	[Logics /LE 1]

Programmable Logic Inputs

Name	*Description*	*Assignment via*
LE1.Gate In1-I	State of the module input: Assignment of the Input Signal	[Logics /LE 1]
LE1.Gate In2-I	State of the module input: Assignment of the Input Signal	[Logics /LE 1]
LE1.Gate In3-I	State of the module input: Assignment of the Input Signal	[Logics /LE 1]
LE1.Gate In4-I	State of the module input: Assignment of the Input Signal	[Logics /LE 1]
LE1.Reset Latch-I	State of the module input: Reset Signal for the Latching	[Logics /LE 1]

Programmable Logic Outputs

Signal	*Description*
LE1.Gate Out	Signal: Output of the logic gate
LE1.Timer Out	Signal: Timer Output
LE1.Out	Signal: Latched Output (Q)
LE1.Out inverted	Signal: Negated Latched Output (Q NOT)

Commissioning

Before starting work on an opened switchboard it is imperative that the complete switchboard is dead and the following 5 safety regulations are always met: ,

DANGER

Safety precautions:

- Disconnect from the power supply
- Secure against reconnection
- Verify if the equipment is dead
- Connect to ground and short-circuit all phases
- Cover or safeguard all live adjacent parts

DANGER

The secondary circuit of a current transformer must never be opened during operation. The prevailing high voltages are dangerous to life.

WARNING

Even when the auxiliary voltage is switched off, it is likely that there are still hazardous voltages at the component connections.
All locally applicable national and international installation and safety regulations for working at electrical power installations must always to be followed (e.g. VDE, EN, DIN, IEC).

WARNING

Prior to the initial voltage connection, the following must be guaranteed:

- Correct grounding of the device
- That all signal circuits are tested
- That all control circuits are tested
- Transformer wiring is checked
- Correct rating of the CTs
- Correct burden of the CTs
- That the operational conditions are in line with the Technical Data
- Correct rating of the transformer protection
- Function of the transformer fuses
- Correct wiring of all digital inputs
- Polarity and capacity of the supply voltage
- Correct wiring of the analogue inputs and outputs
- *For line differential protection:* Correct fiber optics connection for a reliable Protection Communication

NOTICE

The permissible deviations of measuring values and device adjustment are dependent on the technical data/tolerances.

Commissioning/Protection Test

WARNING Putting into operation/Protection test must be carried out by authorized and qualified personnel. Before the device is put into operation the related documentation has to be read and understood.

WARNING With any test of the protection functions the following has to be checked:

- Is activation/tripping saved in the event recorder?
- Is tripping saved in the fault recorder?
- Is tripping saved in the disturbance recorder?
- Are all signals/messages correctly generated?
- Do all general parameterized blocking functions work properly?
- Do all temporary parameterized (via DI) blocking functions work properly?
- To enable checks on all LEDs and relay functions, these have to be provided with the relevant alarm and tripping functions of the respective protection functions/elements. This has to be tested in practical operation.

WARNING Check of all temporary blockings (via digital inputs):

- In order to avoid malfunctions, all blockings related to tripping/non-tripping of protection function have to be tested. The test can be very complex and should therefore be performed by the same people who set up the protection concept.

CAUTION Check of all general trip blockings:

- All general trip blockings have to be tested.

NOTICE Prior to the initial operation of the protection device all tripping times and values shown in the adjustment list have to be confirmed by a secondary test

NOTICE Any description of functions, parameters, inputs or outputs that does not match the device in hand, can be ignored.

Putting out of Operation – Plug out the Relay

WARNING

Warning! Dismounting the relay will lead to a loss of the protection functionality. Ensure that there is a back-up protection. If you are not aware of the consequences of dismounting the device – stop! Don´t start.

WARNING

Inform SCADA before you start.

Switch-off the power supply.

Ensure, that the cabinet is dead and that there are no voltages that could lead to personal injury.

Plug-out the terminals at the rear-side of the device. Do not pull any cable – pull on the plugs! If it is stuck use for example a screw driver.

Fasten the cables and terminals in the cabinet by means of cable clips to ensure that no accidental electrical connections are caused.

Hold the device at the front-side while opening the mounting nuts.

Remove the device carefully out of the cabinet.

In case no other device is to be mounted or replaced cover/close the cut-out in the front-door.

Close the cabinet.

Service and Commissioning Support

Within the service menu various functions support maintenance and commissioning of the device.

General

Within the menu [Service/General], the user can initiate a reboot of the device.

Phase Sequence

Within the menu [Operation/Status Display/Supervision/Phase Sequence], there are signals showing whether the phase sequence calculated by the device is different from the setting under [Field Para/General Settings] *»Phase Sequence«*. See Chapter “Phase Sequence Supervision” for details.

Forcing the Relay Output Contacts

NOTICE **The parameters, their defaults and setting ranges have to be taken from Relay Output Contacts section.**

Principle – General Use

DANGER **The User MUST ENSURE that the relay output contacts operate normally after the maintenance is completed. If the relay output contacts do not operate normally, the protective device WILL NOT provide protection.**

For commissioning purposes or for maintenance, relay output contacts can be set by force.

Within this mode [Service/Test Mode/Force OR/BO Slot X(2/5)], relay output contacts can be set by force:

- Permanent; or
- Via timeout.

If they are set with a timeout, they will only keep their “Force Position” as long as this timer runs. If the timer expires, the relay will operate normally. If they are set as Permanent, they will keep the “Force Position” continuously.

There are two options available:

- Forcing a single relay »*Force ORx«;* and
- Forcing an entire group of relay output contacts »*Force all Outs«*.

Forcing an entire group takes precedence over forcing a single relay output contact!

NOTICE **A relay output contact <u>will NOT follow a force command</u> as long as it is disarmed at the same time.**

NOTICE **A relay output contact <u>will follow a force command:</u>**

- **If it is not disarmed; and**
- **If the Direct Command is applied to the relay(s).**

Keep in mind, that the forcing of all relay output contacts (of the same assembly group) takes precedence over the force command of a single relay output contact.

Disarming the Relay Output Contacts

NOTICE **The parameters, their defaults, and setting ranges have to be taken from the Relay Output Contacts section.**

Principle – General Use

Within this mode [Service/Test Mode/DISARMED], entire groups of relay output contacts can be disabled. By means of this test mode, contact outputs switching actions of the relay output contacts are prevented. If the relay output contacts are disarmed, maintenance actions can be carried out without the risk of taking entire processes off-line.

DANGER **The User MUST ENSURE that the relay output contacts are ARMED AGAIN after the maintenance is complete. If they are not armed, the protective device WILL NOT provide protection.**

NOTICE **Zone Interlocking Output and the Supervision Contact cannot be disarmed.**

Within this mode [Service/Test Mode/DISARMED] entire groups of relay output contacts can be disarmed:

- Permanent; or
- Via timeout.

If they are set with a timeout, they will only keep their “Disarm Position” as long as this timer runs. If the timer expires, the relay output contacts will operate normally. If they are set Permanent, they will keep the “Disarm State” continuously.

NOTICE **A relay output contact will NOT be disarmed as long as:**

- **It´s latched (and not yet reset).**
- **As long as a running t-OFF-delay timer is not yet expired (hold time of a relay output contact).**
- **The Disarm Control is not set to active.**
- **The Direct Command is not applied.**

NOTICE

A relay output contact will be disarmed if it´s not latched and

- **There is no running t-OFF-delay timer (hold time of a relay output contact) and**
- **The DISARM Control is set to active and**
- **The Direct Command Disarm is applied.**

Forcing RTDs*

* = Availability depends on ordered device.

NOTICE **The parameters, their defaults, and setting ranges have to be taken from RTD/UTRD section.**

Principle – General Use

DANGER **The User MUST ENSURE that the RTDs operate normally after the maintenance is completed. If the RTDs do not operate normally, the protective device WILL NOT provide protection.**

For commissioning purposes or for maintenance, RTD temperatures can be set by force.

Within this mode [Service/Test Mode/URTD], RTD temperatures can be set by force:

- Permanent; or
- Via timeout.

If they are set with a timeout, they will keep their "Forced Temperature" only as long as this timer runs. If the timer expires, the RTD will operate normally. If they are set as »*Permanent*«, they will keep the "Forced Temperature" continuously. This menu will show the measured values of the RTDs until the User activates the force mode by calling up the »*Function*«. As soon as the force mode is activated, the shown values will be frozen as long as this mode is active. Now the User can force RTD values. As soon as the force mode is deactivated, measured values will be shown again.

Forcing Analog Outputs*

* = Availability depends on ordered device.

NOTICE **The parameters, their defaults, and setting ranges have to be taken from Analog Output section.**

Principle – General Use

DANGER **The User MUST ENSURE that the Analog Outputs operate normally after maintenance is completed. Do not use this mode if forced Analog Outputs cause issues in external processes.**

For commissioning purposes or for maintenance, Analog Outputs can be set by force.

Within this mode [Service/Test Mode/Analog Output(x)], Analog Outputs can be set by force:

- Permanent; or
- Via timeout.

If they are set with a timeout, they will only keep their "Forced Value" as long as this timer runs. If the timer expires, the Analog Output will operate normally. If they are set as »*Permanent*«, they will keep the "Forced Value" continuously. This menu will show the current value that is assigned onto the Analog Output until the User activates the force mode by calling up the »*Function*«. As soon as the force mode is activated, the shown values will be frozen as long as this mode is active. Now the User can force Analog Output values. As soon as the force mode is deactivated, measured values will be shown again.

Forcing Analog Inputs*

* = Availability depends on ordered device.

NOTICE **The parameters, their defaults, and setting ranges have to be taken from Analog Inputs section.**

Principle – General Use

DANGER **The User MUST ENSURE that the Analog Inputs operate normally after maintenance is completed.**

For commissioning purposes or for maintenance, Analog Inputs can be set by force.

Within this mode [Service/Test Mode (Prot inhibit)/WARNING! Cont?/Analog Inputs], Analog Inputs can be set by force:

- Permanent; or
- Via timeout.

If they are set with a timeout, they will only keep their “Forced Value” as long as this timer runs. If the timer expires, the Analog Input will operate normally. If they are set as »*Permanent*«, they will keep the “Forced Value” continuously. This menu will show the current value that is fed to the Analog Input until the User activates the force mode by calling up the »*Function*«. As soon as the force mode is activated, the shown value will be frozen as long as this mode is active. Now the User can force the Analog Input value. As soon as the force mode is deactivated, measured value will be shown again.

Fault Simulator (Sequencer)*

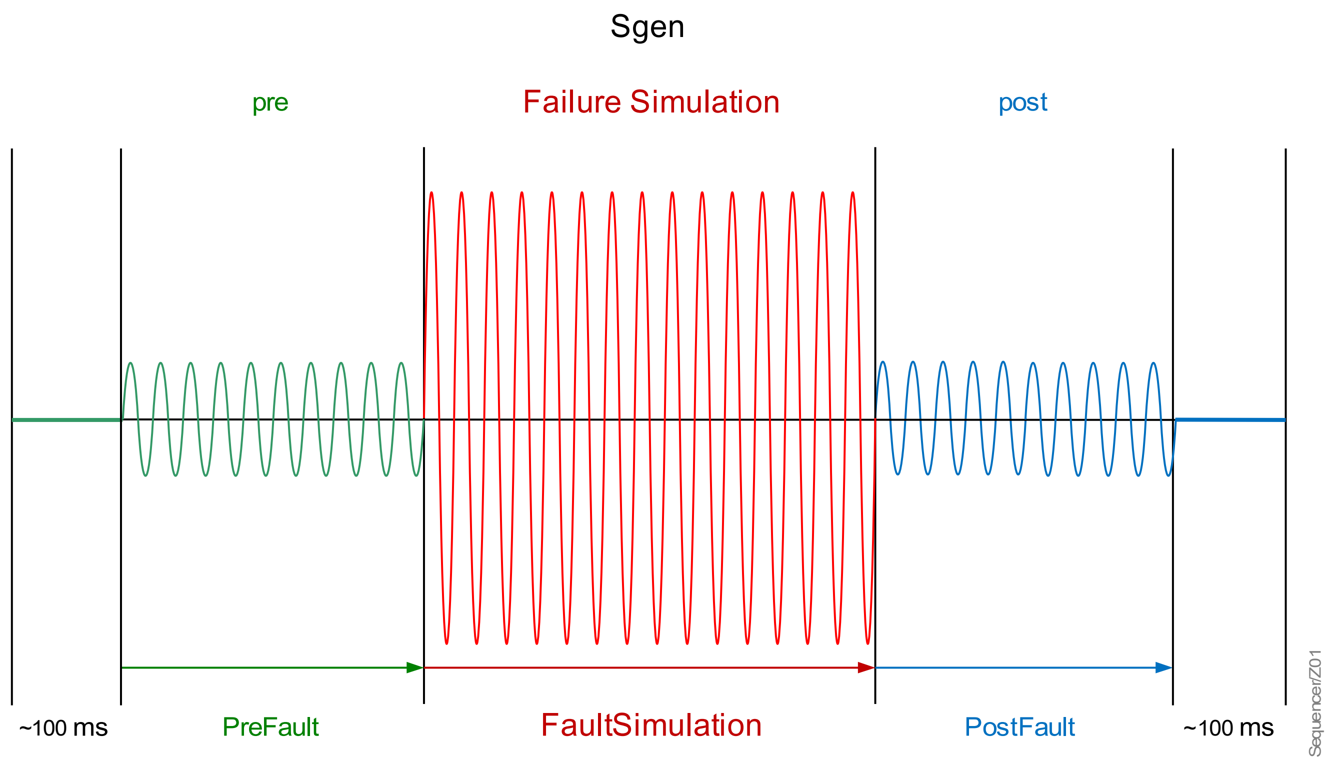
Available Elements:
Sgen

* = Availability depends on ordered device.

For commissioning support and in order to analyze failures, the protective device offers the option to simulate measuring quantities. The simulation menu can be found within the [Service/Test Mode/Sgen] menu.
The simulation cycle consists of three states:

1. Pre-fault;
2. Failure;
3. Post-fault State (Phase).

In addition to these three states, there is a short "reset stage" of about 100 ms immediately before the Pre-failure state, and another one after the Post-failure state, where all protection functions are deactivated. This is necessary to re-initialize all protection modules and related filters and set them to a healthy new state.



The states are recorded by the Event and Disturbance Recorders as follows:

- **0** Normal operation (i. e. without fault simulation)
- **1** Pre-fault
- **2** Fault
- **3** Post-fault
- **4** Reset / initialization phase

Within the [Service/Test Mode (Prot inhibit) / Sgen / Configuration / Times] sub-menu, the duration of each phase can be set. In addition; the measuring quantities to be simulated can be determined (e. g.: voltages, currents, and the corresponding angles) for each phase (and ground). The simulation will be terminated, if a phase current exceeds 0.1 · In. A simulation can be restarted, five seconds after the current has fallen below 0.1 · In.

Moreover, within the [Service / Test Mode (Prot inhibit) / Sgen / Process] sub-menu there are two blocking parameters *ExBlo1*, *ExBlo2*. Signals that are assigned to any of these block the Fault Simulator. For example, it can be recommended for security considerations to have the Fault Simulator blocked if the circuit breaker is in closed position.

Furthermore, there is the possibility to assign a signal to the parameter *Ex ForcePost*. Then this signal interrupts the actual state of the Fault Simulator (Pre-fault or Failure) and leads to an immediate transition into the Post-fault state. The typical application for this is a test whether the protective device correctly generates a trip decision, so that it is not necessary to always wait until the regular end of the Failure state. It is possible to assign the trip signal to *Ex ForcePost*. so that the Failure state is ended immediately after the trip signal has been correctly generated.

DANGER **Setting the device into the simulation mode means taking the protective device out of operation for the duration of the simulation. Do not use this feature during operation of the device if the User cannot guarantee that there is a running and properly working backup protection.**

NOTICE **The energy counters are stopped while the failure simulator is running.**

NOTICE **The simulation voltages are always phase to neutral voltages, irrespectively of the mains voltage transformers' connection method (Phase-to-phase / Wye / Open Delta).**

NOTICE **Due to internal dependencies, the frequency of the simulation module is 0.16% greater than the rated one.**

Application Options of the Fault Simulator

Stop Options	**Cold Simulation (Option 1)**	**Hot Simulation (Option 2)**
Manual start, no stop Run complete: Pre Failure, Failure, Post Failure. 1. Call up [Service / Test Mode / Sgen / Process] 2. *Ex Force Post* = no assignment 3. Press/Call up *Start Simulation*.	**Simulation without tripping the circuit breaker:** The TripCmd of all protection functions will be blocked. The protection function will possibly trip but not generate a TripCmd. 1. Call up [Service / Test Mode / Sgen / Process] 2. *TripCmd Mode* = No TripCmd	**Simulation is authorized to trip the breaker:** 1. Call up [Service / Test Mode / Sgen / Process] 2. *TripCmd Mode* = With TripCmd
Manual start, stop by external signal Force Post: As soon as this signal becomes true, the Fault Simulation will be forced to switch into the Post Failure mode. 1. Call up [Service / Test Mode / Sgen / Process] 2. *Ex Force Post* = Assigned Signal		
Manual start, manual stop As soon as this signal becomes true, the Fault Simulation will be terminated and the device changes back to normal operation. 1. Call up [Service / Test Mode / Sgen / Process] **2.** Press/Call up ***Stop Simulation***.		
Start by external signal The start of the Fault Simulator is triggered by the assigned external signal (unless a phase current exceeds 0.1 · In or the Fault Simulator is blocked, see also description above). 1. Call up [Service / Test Mode / Sgen / Process] **2.** *Ex Start Simulation* = Assigned Signal		

Device Planning Parameters of the Failure Simulator

Parameter	*Description*	*Options*	*Default*	*Menu path*
Mode	Mode	do not use, use	use	[Device planning]

Global Protection Parameter of the Failure Simulator

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
PreFault	Pre Fault Duration	0.00 - 300.00s	0.0s	[Service /Test (Prot inhibit) /Sgen /Configuration /Times]
FaultSimulation	Duration of Fault Simulation	0.00 - 10800.00s	0.0s	[Service /Test (Prot inhibit) /Sgen /Configuration /Times]
PostFault	PostFault	0.00 - 300.00s	0.0s	[Service /Test (Prot inhibit) /Sgen /Configuration /Times]
TripCmd Mode	Trip Command Mode	No TripCmd, With TripCmd	No TripCmd	[Service /Test (Prot inhibit) /Sgen /Process]
Ex Start Simulation	External Start of Fault Simulation (Using the test parameters)	1..n, Assignment List	-.-	[Service /Test (Prot inhibit) /Sgen /Process]

Parameter	Description	Setting range	Default	Menu path
ExBlo1	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.1	1..n, Assignment List	SG[1].Pos ON	[Service /Test (Prot inhibit) /Sgen /Process]
ExBlo2	External blocking of the module, if blocking is activated (allowed) within a parameter set and if the state of the assigned signal is true.2	1..n, Assignment List	-.-	[Service /Test (Prot inhibit) /Sgen /Process]
Ex ForcePost	Force Post state. Abort simulation.	1..n, Assignment List	-.-	[Service /Test (Prot inhibit) /Sgen /Process]

Current Parameter of the Failure Simulator

Parameter	Description	Setting range	Default	Menu path
IL1	Current Fundamental Magnitude in Pre State: phase L1	0.00 - 40.00In	0.0In	[Service /Test (Prot inhibit) /Sgen /Configuration /PreFault /CT]
IL2	Current Fundamental Magnitude in Pre State: phase L2	0.00 - 40.00In	0.0In	[Service /Test (Prot inhibit) /Sgen /Configuration /PreFault /CT]
IL3	Current Fundamental Magnitude in Pre State: phase L3	0.00 - 40.00In	0.0In	[Service /Test (Prot inhibit) /Sgen /Configuration /PreFault /CT]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
IG meas	Current Fundamental Magnitude in Pre State: IG	0.00 - 25.00In	0.0In	[Service /Test (Prot inhibit) /Sgen /Configuration /PreFault /CT]
phi IL1	Start Position respectively Start Angle of the Current Phasor during Pre-Phase:phase L1	-360 - 360°	0°	[Service /Test (Prot inhibit) /Sgen /Configuration /PreFault /CT]
phi IL2	Start Position respectively Start Angle of the Current Phasor during Pre-Phase:phase L2	-360 - 360°	240°	[Service /Test (Prot inhibit) /Sgen /Configuration /PreFault /CT]
phi IL3	Start Position respectively Start Angle of the Current Phasor during Pre-Phase:phase L3	-360 - 360°	120°	[Service /Test (Prot inhibit) /Sgen /Configuration /PreFault /CT]
phi IG meas	Start Position respectively Start Angle of the Current Phasor during Pre-Phase: IG	-360 - 360°	0°	[Service /Test (Prot inhibit) /Sgen /Configuration /PreFault /CT]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
IL1	Current Fundamental Magnitude in Fault State: phase L1	0.00 - 40.00In	0.0In	[Service /Test (Prot inhibit) /Sgen /Configuration / FaultSimulation /CT]
IL2	Current Fundamental Magnitude in Fault State: phase L2	0.00 - 40.00In	0.0In	[Service /Test (Prot inhibit) /Sgen /Configuration / FaultSimulation /CT]
IL3	Current Fundamental Magnitude in Fault State: phase L3	0.00 - 40.00In	0.0In	[Service /Test (Prot inhibit) /Sgen /Configuration / FaultSimulation /CT]
IG meas	Current Fundamental Magnitude in Fault State: IG	0.00 - 25.00In	0.0In	[Service /Test (Prot inhibit) /Sgen /Configuration / FaultSimulation /CT]
phi IL1	Start Position respectively Start Angle of the Current Phasor during Fault-Phase:phase L1	-360 - 360°	0°	[Service /Test (Prot inhibit) /Sgen /Configuration / FaultSimulation /CT]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
phi IL2	Start Position respectively Start Angle of the Current Phasor during Fault-Phase:phase L2	-360 - 360°	240°	[Service /Test (Prot inhibit) /Sgen /Configuration / FaultSimulation /CT]
phi IL3	Start Position respectively Start Angle of the Current Phasor during Fault-Phase:phase L3	-360 - 360°	120°	[Service /Test (Prot inhibit) /Sgen /Configuration / FaultSimulation /CT]
phi IG meas	Start Position respectively Start Angle of the Current Phasor during Fault-Phase: IG	-360 - 360°	0°	[Service /Test (Prot inhibit) /Sgen /Configuration / FaultSimulation /CT]
IL1	Current Fundamental Magnitude during Post phase: phase L1	0.00 - 40.00In	0.0In	[Service /Test (Prot inhibit) /Sgen /Configuration /PostFault /CT]
IL2	Current Fundamental Magnitude during Post phase: phase L2	0.00 - 40.00In	0.0In	[Service /Test (Prot inhibit) /Sgen /Configuration /PostFault /CT]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
IL3	Current Fundamental Magnitude during Post phase: phase L3	0.00 - 40.00In	0.0In	[Service /Test (Prot inhibit) /Sgen /Configuration /PostFault /CT]
IG meas	Current Fundamental Magnitude during Post phase: IG	0.00 - 25.00In	0.0In	[Service /Test (Prot inhibit) /Sgen /Configuration /PostFault /CT]
phi IL1	Start Position respectively Start Angle of the Current Phasor during Post phase: phase L1	-360 - 360°	0°	[Service /Test (Prot inhibit) /Sgen /Configuration /PostFault /CT]
phi IL2	Start Position respectively Start Angle of the Current Phasor during Post phase: phase L2	-360 - 360°	240°	[Service /Test (Prot inhibit) /Sgen /Configuration /PostFault /CT]
phi IL3	Start Position respectively Start Angle of the Current Phasor during Post phase: phase L3	-360 - 360°	120°	[Service /Test (Prot inhibit) /Sgen /Configuration /PostFault /CT]

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
phi IG meas	Start Position respectively Start Angle of the Current Phasor during Post phase: IG	-360 - 360°	0°	[Service /Test (Prot inhibit) /Sgen /Configuration /PostFault /CT]

States of the Inputs of the Failure Simulator

Name	*Description*	*Assignment via*
Ex Start Simulation-I	State of the module input:External Start of Fault Simulation (Using the test parameters)	[Service /Test (Prot inhibit) /Sgen /Process]
ExBlo1-I	Module input state: External blocking1	[Service /Test (Prot inhibit) /Sgen /Process]
ExBlo2-I	Module input state: External blocking2	[Service /Test (Prot inhibit) /Sgen /Process]
Ex ForcePost-I	State of the module input:Force Post state. Abort simulation.	[Service /Test (Prot inhibit) /Sgen /Process]

Signals of the Failure Simulator (States of the Outputs)

Signal	*Description*
Manual Start	Fault Simulation has been started manually.
Manual Stop	Fault Simulation has been stopped manually.
Running	Signal; Measuring value simulation is running
Started	Fault Simulation has been started
Stopped	Fault Simulation has been stopped
State	Signal: Wave generation states: 0=Off, 1=PreFault, 2=Fault, 3=PostFault, 4=InitReset

Direct Commands of the Failure Simulator

Parameter	*Description*	*Setting range*	*Default*	*Menu path*
Start Simulation	Start Fault Simulation (Using the test parameters)	inactive, active	inactive	[Service /Test (Prot inhibit) /Sgen /Process]
Stop Simulation	Stopp Fault Simulation (Using the test parameters)	inactive, active	inactive	[Service /Test (Prot inhibit) /Sgen /Process]

Failure Simulator Values

Value	*Description*	*Default*	*Size*	*Menu path*
State	Wave generation states: 0=Off, 1=PreFault, 2=Fault, 3=PostFault, 4=InitReset	Off	Off, PreFault, FaultSimulation, PostFault, Init Res	[Service /Test (Prot inhibit) /Sgen /State]

Technical Data

NOTICE **Use Copper conductors only, 75°C.
Conductor size AWG 14 [2.5 mm²].**

Climatic Environmental Conditions

Storage Temperature:	Operating Temperature:
-30°C up to +70°C (-22°F to 158°F)	-20°C up to +60°C (-4°F to 140°F)

Permissible Humidity at Ann. Average:	<75% rel. (on 56d up to 95% rel.)
Permissible Installation Altitude:	<2000 m (6561.67 ft) above sea level If 4000 m (13123.35 ft) altitude apply a changed classification of the operating and test voltages may be necessary.

Degree of Protection EN 60529

HMI front panel with seal	IP54
HMI front panel without seal	IP50
Rear side terminals	IP20

Routine Test

Insulation test acc. to IEC60255-5:	All tests to be carried out against earth and other input- and output circuits
Aux. voltage supply, digital inputs, current measuring inputs, signal relay outputs:	2.5 kV (eff) / 50 Hz
Voltage measuring inputs:	3.0 kV (eff) / 50 Hz
All wire-bound communication interfaces:	1.5 kV DC

Housing

Housing B1: height/-width (7 Pushbottons/Door Mounting)	173 mm (6.811”)/ 141.5 mm (5.570”)
Housing B1: height/-width (8 Pushbottons/Door Mounting)	183 mm (7.205”)/ 141.5 mm (5.570”)
Housing B1: height/-width (7 and 8 Pushbottons/19”)	173 mm (6.811” / 4U)/ 141.5 mm (5.570” / 28 HP)
Housing depth (incl. terminals):	208 mm (8.189”)
Material, housing:	Aluminum extruded section
Material, front panel:	Aluminum/Foil front
Mounting position:	Horizontal (±45° around the X-axis are allowed)
Weight:	Approx. 2.4 kg

Current and Earth Current Measurement

Plug-in Connectors with Integrated Short-Circuiter

(Conventional Current Inputs)

Nominal currents:	1 A / 5 A	
Max. measuring range:	up to 40 x In (phase currents) up to 25 x In (earth current standard)	up to 2.5 x In (earth current sensitive)[1)]
Continuous loading capacity:	Phase current/Earth current 4 x In/continuously	Earth current sensitive[1)] 2 x In/continuously
Overcurrent proof:	Phase current/Earth current 30 x In/10 s 100 x In/1 s 250 x In/10 ms (1 half-wave)	Earth current sensitive[1)] 10 x In/10 s 25 x In/1 s 100 x In/10 ms (1 half-wave)
Power consumption:	Phase current inputs: at In = 1 A S = 25 mVA at In = 5 A S = 90 mVA	
	Earth current input: at In = 1 A S = 25 mVA at In = 5 A S = 90 mVA	Sensitive earth[1)] current input: at 0,1 A (1A) S = 7 mVA (550 mVA) at 0,5 A (5A) S = 10 mVA (870 mVA)
Frequency range:	50 Hz / 60 Hz ±10%	
Terminals:	Screw-type terminals with integrated short-circuiters (contacts)	
Screws:	M4, captive type acc. to VDEW	
Connection Cross Sections:	1 x or 2 x 2.5 mm² (2 x AWG 14) with wire end ferrule 1 x or 2 x 4.0 mm² (2 x AWG 12) with ring cable sleeve or cable sleeve 1 x or 2 x 6 mm² (2 x AWG 10) with ring cable sleeve or cable sleeve Only The current measuring board´s terminal blocks may be used as with 2 (double) conductors AWG 10,12,14 otherwise with single conductors only.	

[1)] only in completion with sensitive earth measuring (see ordering information)

Voltage Supply

Aux. Voltage:	24V - 270 V DC/48 - 230 V AC (-20/+10%) ≂
Buffer time in case of supply failure:	>= 50 ms at minimal aux. voltage. The device will shut down if the buffer time is expired Note: communication could be interrupted
Max. permissible making current:	18 A peak value for ↥0.25 ms 12 A peak value for ↥1 ms

The voltage supply must be protected by a fuse of:

- 2,5 A time-lag miniature fuse 5x20 mm (approx. 1/5” x 0.8”) according to IEC 60127
- 3,5 A time-lag miniature fuse 6,3x32 mm (approx. 1/4” x 1 1/4”) according to UL 248-14

Power Consumption

Power supply range:	Power consumption in idle mode	Max. power consumption
24-270 V DC:	7 W	10 W
48-230 V AC (for frequencies of 50-60 Hz):	7 W / 13 VA	10 W / 17 VA

Display

Display type:	LCD with LED background illumination
Resolution graphics display:	128 x 64 pixel
LED-Type:	Two colored: red/green
Number of LEDs, Housing B1:	8

Front Interface USB

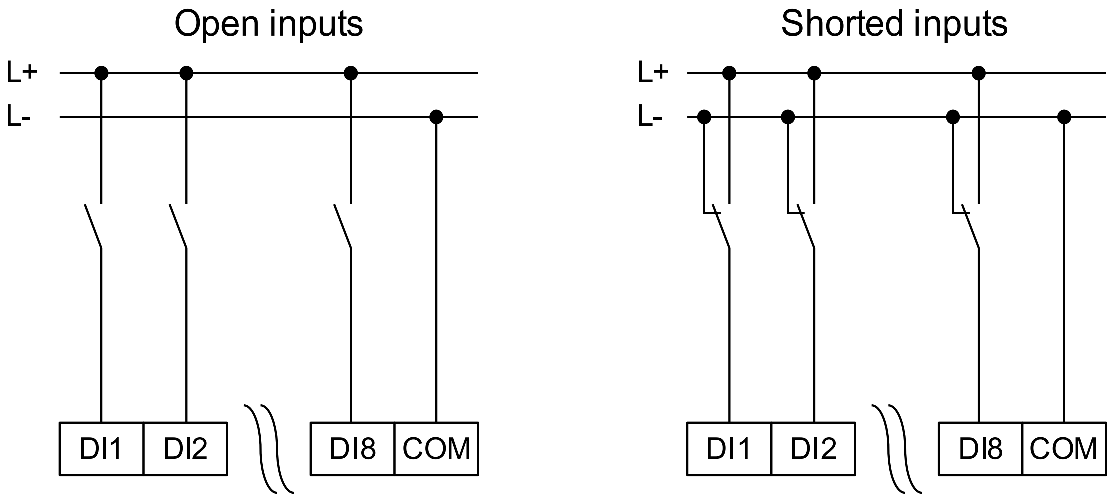
Type:	Mini B

Real Time Clock

Running reserve of the real time clock:	1 year min.

Digital Inputs

Max. input voltage:	300 V DC/259 V AC
Input current:	DC <4 mA AC <16 mA
Reaction time:	<20 ms
Fallback Time:	
Shorted inputs	<30 ms
Open inputs	<90 ms



(Safe state of the digital inputs)

4 Switching thresholds:	Un = 24 V DC, 48 V DC, 60 V DC, 110 V AC/DC, 230 V AC/DC
Un = 24 V DC:	
Switching threshold 1 ON:	min. 19.2 V DC
Switching threshold 1 OFF:	max. 9.6 V DC
Un = 48 V/60V DC:	
Switching threshold 2 ON:	Min. 42.6 V DC
Switching threshold 2 OFF:	max. 21.3 V DC
Un = 110 V AC/DC:	
Switching threshold 3 ON:	min. 88.0 V DC/88.0 V AC
Switching threshold 3 OFF:	max. 44.0 V DC/44.0 V AC
Un = 230 V AC/DC:	
Switching threshold 4 ON:	min. 184 V DC/184 V AC
Switching threshold 4 OFF	max. 92 V DC/92 V AC
Terminals:	Screw-type terminals

Binary Output Relays

Continuous current:	5 A AC/DC
Max. Switch-on current:	25 A AC/DC for 4 s
	48W (VA) at L/R = 40ms
	30 A / 230 Vac according to ANSI IEEE Std C37.90-2005
	30 A / 250 Vdc according to ANSI IEEE Std C37.90-2005
Max. breaking current:	5 A AC up to 240 V AC
	4 A AC at 230V and cos ϕ = 0,4
	5 A DC up to 30 V (resistive)
	0.3 A DC at 250 V (resistive)
	0,1 A DC at 220 V and L/R = 40ms
Max. switching voltage:	250 V AC/250 V DC
Switching capacity:	3000 VA
Operating time: (*)	typ. 7 ms
Reset time: (*)	typ. 3 ms
Contact type:	1 changeover contact or normally open or normally closed
Terminals:	Screw-type terminals

(*) The operating and reset times are the pure hardware-related switching times (coil – making/breaking contact), i. e. without the time that it takes the software to calculate the decisions.

Time Synchronization IRIG

Nominal input voltage:	5 V
Connection:	Screw-type terminals (twisted pair)

RS485*

Connection:	9-pole D-Sub socket (external terminating resistors/in D-Sub) or 6 screw-clamping terminals RM 3.5 mm (138 MIL) (terminating resistors internal)

*availability depends on device

CAUTION **In case that the RS485 interface is realised via terminals, the communication cable has to be shielded.**

Fiber Optic Module with ST connector*

Connector:	ST Port
Compatible Fiber:	50/125 µm, 62,5/125 µm, 100/140 µm and 200 µm HCS
Wavelength	820 nm
Minimum Optical Input Power:	−24,0 dBm
Minimum Optical Output Power:	−19.8 dBm with 50/125 µm fiber −16,0 dBm with 62,5/125 µm fiber −12,5 dBm with 100/145 µm fiber −8,5 dBm with 200 µm HCS fiber
Maximum Link Length:	approx. 2.7 km (depending on link attenuation)

*availability depends on device

Please note: The transmission speed of the optical interfaces is limited to 3 MBaud for Profibus.

Fiber Optic Module with LC Connector for Long-distance Protection Communication**

Connector:	LC Port
Compatible Fiber:	9 µm single mode
Wavelength:	1310 nm
Minimum Optical Input Power:	−31.0 dBm
Minimum Optical Output Power:	−15.0 dBm
Maximum Link Length:	approx. 20 km (depending on link attenuation)

** only for Line Differential Protection (MCDLV4)

Optical Ethernet Module with LC connector*

Connector:	LC-Port
Compatible Fiber:	50/125 µm and 62,5/125 µm
Wavelength:	1300 nm
Minimum Optical Input Power:	−30,0 dBm
Minimum Optical Output Power:	−22.5 dBm with 50/125 µm fiber −19,0 dBm with 62,5/125 µm fiber
Maximum Link Length:	approx. 2 km (depending on link attenuation)

*availability depends on device

URTD-Interface*

Connector:	Versatile Link
Compatible Fiber:	1 mm
Wavelength:	660 nm
Minimum Optical Input Power:	−39,0 dBm

*availability depends on device

Boot phase

After switching on the power supply the protection will be available in approximately 6 seconds. After approximately 37 seconds the boot phase is completed (HMI and Communication initialized).

Servicing and Maintenance

Within the scope of servicing and maintenance following checks of the unit hardware have to be conducted:

Component	*Step*	*Interval/How often?*
Output Relays	Please check the Output Relays via Test menu Force/Disarm (please see chapter Service)	Every 1–4 years, depending on ambient conditions.
Digital Inputs	Please supply a voltage to the Digital Inputs and control if the appropriate status signal appears.	Every 1–4 years, depending on ambient conditions.
Current plugs and Current measurements	Please supply testing current to the Current measurement inputs and control the displayed measure values from the unit.	Every 1–4 years, depending on ambient conditions.
Voltage plugs and Voltage measurements	Please supply testing current to the Voltage measurement inputs and control the displayed measure values from the unit.	Every 1–4 years, depending on ambient conditions.
Analog Inputs	Please feed analog signals into the measurement inputs and check if the displayed measure values match.	Every 1–4 years, depending on ambient conditions.
Analog Outputs	Please check the Analog Outputs via Test menu Force/Disarm (please see chapter Service)	Every 1–4 years, depending on ambient conditions.
Battery	The device checks the battery as part of its Self-Supervision, therefore no dedicated testing activities are required. If the battery is low, the System LED flashes red/green, and an error code is generated (see *Troubleshooting Guide*).	In general the battery lasts more than 10 years. Exchange by manufacturer. Notice: The battery serves as buffering of the clock (real time clock). There's no impact on the functionality of the device if the battery breaks down, except for the buffering of the clock while the unit is in de-energized condition.
Self-monitoring contact	Switch of the auxiliary supply of the unit. The Self-monitoring contact has to dropout now. Please switch on the auxiliary supply again.	Every 1–4 years, depending on ambient conditions.
Mechanical mounting of the unit of the cabinet door	Check the torque related to the specification of the Installation chapter.	With each maintenance or yearly.
Torque of all cable connections	Check the torque related to the specification of the Installation chapter which describes the hardware modules.	With each maintenance or yearly.

We recommend to execute an protection test after each 4 years period. This period can be extended to 6 years if a function test is executed at least every 3 years.

Standards

Approvals

- UL- File No.: E217753
- CSA File No.: 251990**
- CEI 0-16* (Tested by EuroTest Laboratori S.r.l, Italy)*
- BDEW Certified (FGW TR3/ FGW TR8/ Q-U-Schutz)**
- KEMA***
- EAC

* = applies to MRU4

** = applies to MCA4

*** = applies to (MRDT4, MCA4, MRA4, MRI4, MRU4)

Design Standards

Generic standard	EN 61000-6-2 , 2005 EN 61000-6-3 , 2006
Product standard	IEC 60255-1; 2009 IEC 60255-27, 2013 EN 50178, 1998 UL 508 (Industrial Control Equipment), 2005 CSA C22.2 No. 14-95 (Industrial Control Equipment),1995 ANSI C37.90, 2005

High Voltage Tests

High frequency interference test

IEC 60255-22-1 IEEE C37.90.1 IEC 61000-4-18	Within one circuit	1 kV , 2 s
	Circuit to earth	2.5 kV , 2 s
class 3	Circuit to circuit	2.5 kV , 2 s

Insulation voltage test

IEC 60255-27 (10.5.3.2) IEC 60255-5 EN 50178	All circuits to other circuits and exposed conductive parts	2.5 kV (eff.)/50Hz , 1 min.
	Except interfaces	1,5 kV DC , 1 min.
	and Voltage measuring input	3 kV (eff.)/50 Hz , 1 min.

Impulse voltage test

IEC 60255-27 (10.5.3.1) IEC 60255-5		5 kV/0.5J, 1.2/50 µs

Insulation resistance test

IEC 60255-27 (10.5.3.3) EN 50178	Within one circuit	500V DC , 5s
	Circuit to circuit	500V DC , 5s

EMC Immunity Tests

Fast transient disturbance immunity test (Burst)

IEC 60255-22-4 IEC 61000-4-4 class 4	Power supply, mains inputs	±4 kV, 2.5 kHz
	Other in- and outputs	±2 kV, 5 kHz

Surge immunity test (Surge)

IEC 60255-22-5 IEC 61000-4-5 class 4	Within one circuit	2 kV
	Circuit to earth	4 kV
class 3	Communication cables to earth	2 kV

Electrical discharge immunity test (ESD)

IEC 60255-22-2 IEC 61000-4-2 class 3	Air discharge	8 kV
	Contact discharge	6 kV

Radiated radio-frequency electromagnetic field immunity test

IEC 60255-22-3	26 MHz – 80 MHz	10 V/m
IEC 61000-4-3	80 MHz – 1 GHz	35 V/m
	1 GHz – 3 GHz	10 V/m

Immunity to conducted disturbances induced by radio frequency fields

IEC 61000-4-6 class 3	150kHz - 80MHz	10 V

Power frequency magnetic field immunity test

IEC 61000-4-8 class 4	continues	30 A/m
	3 sec	300 A/m

EMC Emission Tests

Radio interference suppression test

IEC/CISPR22	150kHz - 30MHz	Limit value class B
IEC60255-26		
DIN EN 55022		

Radio interference radiation test

IEC/CISPR22	30MHz - 1GHz	Limit value class B
IEC60255-25		
DIN EN 55022		

Environmental Tests

Classification:		
IEC 60068-1	Climatic classification	20/060/56
IEC 60721-3-1	Classification of ambient conditions (Storage)	1K5/1B1/1C1L/1S1/1M2 but min. -30°C
IEC 60721-3-2	Classification of ambient conditions (Transportation)	2K2/2B1/2C1/2S1/2M2 but min. -30°C
IEC 60721-3-3	Classification of ambient conditions (Stationary use at weather protected locations)	3K6/3B1/3C1/3S1/3M2 but min. -20°C/max +60°C

Test Ad: Cold		
IEC 60068-2-1	Temperature	-20°C
	test duration	16 h

Test Bd: Dry Heat		
IEC 60068-2-2	Temperature	60°C
	Relative humidity	<50%
	test duration	72 h

Test Db: Damp Heat (cyclic)		
IEC 60068-2-30	Temperature	60°C
	Relative humidity	95%
	Cycles (12 + 12-hour)	2

Environmental Tests

Test Cab: Damp Heat (permanent)

IEC 60255 (6.12.3.6)	Temperature	60°C
IEC 60068-2-78	Relative humidity	95%
	test duration	56 days

Test Nb:Temperature Change

IEC 60255 (6.12.3.5)	Temperature	60°C/-20°C
IEC 60068-2-14	cycle	5
	test duration	1°C/5min

Test BD: Dry Heat Transport and storage test

IEC 60255 (6.12.3.3)	Temperature	70°C
IEC 60068-2-2	test duration	16 h

Test AB: Cold Transport and storage test

IEC 60255-1 (6.12.3.4)	Temperature	-30°C
IEC 60068-2-1	test duration	16 h

Mechanical Tests

Test Fc: Vibration response test

IEC 60068-2-6 IEC 60255-21-1 class 1	(10 Hz – 59 Hz) Displacement	0.035 mm
	(59Hz – 150Hz) Acceleration	0,5 gn
	Number of cycles in each axis	1

Test Fc: Vibration endurance test

IEC 60068-2-6 IEC 60255-21-1 class 1	(10 Hz – 150 Hz) Acceleration	1.0 gn
	Number of cycles in each axis	20

Test Ea: Shock tests

IEC 60068-2-27 IEC 60255-21-2 class 1	Shock response test	5 gn, 11 ms, 3 impulses in each direction
	Shock resistance test	15 gn, 11 ms, 3 impulses in each direction

Test Eb: Shockendurance test

IEC 60068-2-29 IEC 60255-21-2 class 1	Shock endurance test	10 gn, 16 ms, 1000 impulses in each direction

Test Fe: Earthquake test

IEC 60068-3-3 IEC 60255-21-3	Single axis earthquake vibration test	1 – 9 Hz horizontal: 7.5 mm, 1 – 9 Hz vertical :3.5 mm, 1 sweep per axis
class 2		9 – 35 Hz horizontal: 2 gn, 9 – 35 Hz vertical : 1 gn, 1 sweep per axis

General Lists

Assignment List

The »ASSIGNMENT LIST« below summarizes all module outputs (signals) and inputs (e.g. states of the assignments).

Name	*Description*
-.-	No assignment
Prot.available	Signal: Protection is available
Prot.active	Signal: active
Prot.ExBlo	Signal: External Blocking
Prot.Blo TripCmd	Signal: Trip Command blocked
Prot.ExBlo TripCmd	Signal: External Blocking of the Trip Command
Prot.Alarm L1	Signal: General-Alarm L1
Prot.Alarm L2	Signal: General-Alarm L2
Prot.Alarm L3	Signal: General-Alarm L3
Prot.Alarm G	Signal: General-Alarm - Earth fault
Prot.Alarm	Signal: General Alarm
Prot.Trip L1	Signal: General Trip L1
Prot.Trip L2	Signal: General Trip L2
Prot.Trip L3	Signal: General Trip L3
Prot.Trip G	Signal: General Trip Ground fault
Prot.Trip	Signal: General Trip
Prot.Res FaultNo a GridFaultNo	Signal: Resetting of fault number and grid fault number.
Prot.ExBlo1-I	Module input state: External blocking1
Prot.ExBlo2-I	Module input state: External blocking2
Prot.ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
CT.Phase seq. wrong	Signal that the device has detected a phase sequence (L1-L2-L3 / L1-L3-L2) that is different from the one that had been set at [Field settings / General Settings] »Phase Sequence«.
Ctrl.Local	Switching Authority: Local
Ctrl.Remote	Switching Authority: Remote
Ctrl.NonInterl	Non-Interlocking is active
Ctrl.SG Indeterm	Minimum one Switchgear is moving (Position cannot be determined).
Ctrl.SG Disturb	Minimum one Switchgear is disturbed.
Ctrl.NonInterl-I	Non-Interlocking
SG[1].SI SingleContactInd	Signal: The Position of the Switchgear is detected by one auxiliary contact (pole) only. Thus indeterminate and disturbed Positions cannot be detected.
SG[1].Pos not ON	Signal: Pos not ON
SG[1].Pos ON	Signal: Circuit Breaker is in ON-Position
SG[1].Pos OFF	Signal: Circuit Breaker is in OFF-Position

Name	*Description*
SG[1].Pos Indeterm	Signal: Circuit Breaker is in Indeterminate Position
SG[1].Pos Disturb	Signal: Circuit Breaker Disturbed - Undefined Breaker Position. The Position Indicators contradict themselves. After expiring of a supervision timer this signal becomes true.
SG[1].Ready	Signal: Circuit breaker is ready for operation.
SG[1].t-Dwell	Signal: Dwell time
SG[1].Removed	Signal: The withdrawable circuit breaker is Removed
SG[1].Interl ON	Signal: One or more IL_On inputs are active.
SG[1].Interl OFF	Signal: One or more IL_Off inputs are active.
SG[1].CES succesf	Signal: Command Execution Supervision: Switching command executed successfully.
SG[1].CES Disturbed	Signal: Command Execution Supervision: Switching Command unsuccessful. Switchgear in disturbed position.
SG[1].CES Fail TripCmd	Signal: Command Execution Supervision: Command execution failed because trip command is pending.
SG[1].CES SwitchDir	Signal: Command Execution Supervision respectively Switching Direction Control: This signal becomes true, if a switch command is issued even though the switchgear is already in the requested position. Example: A switchgear that is already OFF should be switched OFF again (doubly). The same applies to CLOSE commands.
SG[1].CES ON d OFF	Signal: Command Execution Supervision: On Command during a pending OFF Command.
SG[1].CES SG not ready	Signal: Command Execution Supervision: Switchgear not ready
SG[1].CES Fiel Interl	Signal: Command Execution Supervision: Switching Command not executed because of field interlocking.
SG[1].CES SG removed	Signal: Command Execution Supervision: Switching Command unsuccessful, Switchgear removed.
SG[1].TripCmd	Signal: Trip Command
SG[1].Ack TripCmd	Signal: Acknowledge Trip Command
SG[1].OFF incl TripCmd	Signal: The OFF Command includes the OFF Command issued by the Protection module.
SG[1].Position Ind manipul	Signal: Position Indicators faked
SG[1].SGwear Slow SG	Signal: Alarm, the circuit breaker (load-break switch) becomes slower
SG[1].Res SGwear Sl SG	Signal: Resetting the slow Switchgear Alarm
SG[1].ON Cmd	Signal: ON Command issued to the switchgear. Depending on the setting the signal may include the ON command of the Prot module.
SG[1].OFF Cmd	Signal: OFF Command issued to the switchgear. Depending on the setting the signal may include the OFF command of the Prot module.
SG[1].ON Cmd manual	Signal: ON Cmd manual
SG[1].OFF Cmd manual	Signal: OFF Cmd manual
SG[1].Aux ON-I	Module Input State: Position indicator/check-back signal of the CB (52a)
SG[1].Aux OFF-I	Module input state: Position indicator/check-back signal of the CB (52b)
SG[1].Ready-I	Module input state: CB ready
SG[1].Removed-I	State of the module input: The withdrawable circuit breaker is Removed
SG[1].Ack TripCmd-I	State of the module input: Acknowledgement Signal (only for automatic acknowledgement) Module input signal

Name	*Description*
SG[1].Interl ON1-I	State of the module input: Interlocking of the ON command
SG[1].Interl ON2-I	State of the module input: Interlocking of the ON command
SG[1].Interl ON3-I	State of the module input: Interlocking of the ON command
SG[1].Interl OFF1-I	State of the module input: Interlocking of the OFF command
SG[1].Interl OFF2-I	State of the module input: Interlocking of the OFF command
SG[1].Interl OFF3-I	State of the module input: Interlocking of the OFF command
SG[1].SCmd ON-I	State of the module input: Switching ON Command, e.g. the state of the Logics or the state of the digital input
SG[1].SCmd OFF-I	State of the module input: Switching OFF Command, e.g. the state of the Logics or the state of the digital input
SG[1].Operations Alarm	Signal: Service Alarm, too many Operations
SG[1].Isum Intr trip: IL1	Signal: Maximum permissible Summation of the interrupting (tripping) currents exceeded: IL1
SG[1].Isum Intr trip: IL2	Signal: Maximum permissible Summation of the interrupting (tripping) currents exceeded: IL2
SG[1].Isum Intr trip: IL3	Signal: Maximum permissible Summation of the interrupting (tripping) currents exceeded: IL3
SG[1].Isum Intr trip	Signal: Maximum permissible Summation of the interrupting (tripping) currents exceeded in at least one phase.
SG[1].Res TripCmd Cr	Signal: Resetting of the Counter: total number of trip commands
SG[1].Res Sum trip	Signal: Reset summation of the tripping currents
SG[1].WearLevel Alarm	Signal: Threshold for the Alarm
SG[1].WearLevel Lockout	Signal: Threshold for the Lockout Level
SG[1].Res CB OPEN capacity	Signal: Reset of the wear maintenance curve (i. e. of the counter for the Circuit Breaker OPEN capacity.
SG[1].Isum Intr ph Alm	Signal: Alarm, the per hour Sum (Limit) of interrupting currents has been exceeded.
SG[1].Res Isum Intr ph Alm	Signal: Reset of the Alarm, "the per hour Sum (Limit) of interrupting currents has been exceeded".
MStart.active	Signal: active
MStart.Blo TripCmd	Signal: Trip Command blocked
MStart.Trip	Signal: Trip
MStart.TripCmd	Signal: Trip Command
MStart.Start	Signal: Motor is in start mode
MStart.Run	Signal: Motor is in run mode
MStart.Stop	Signal: Motor is in stop mode
MStart.Blo	Signal: Motor is blocked for starting or transition to Run mode
MStart.NOCSBlocked	Signal: Motor is prohibited to start due to number of cold start limits
MStart.SPHBlocked	Signal: Motor is prohibited to start due to starts per hour limits
MStart.SPHBlockAlarm	Signal: Motor is prohibited to start due to starts per hour limits, would come active in the next stop
MStart.TBSBlocked	Signal: Motor is prohibited to start due to time between starts limits
MStart.ThermalBlo	Signal: Thermal block

Name	*Description*
MStart.RemBlockStart	Signal: Motor is prohibited to start due to external blocking through digital input DI
MStart.TransitionTrip	Signal: Start transition fail trip
MStart.ZSSTrip	Signal: Zero speed trip (possible locked rotor)
MStart.INSQSP2STFailI	Signal: Fail to transit from stop to start based on reported back time
MStart.INSQSt2RunFail	Signal: Fail to transit from start to run based on reported back time
MStart.LATBlock	Signal: Long acceleration timer enforced
MStart.ColdStartSeq	Signal: Motor cold start sequence flag
MStart.ForcedStart	Signal: Motor being forced to start
MStart.TripPhaseRevers e	Signal: Relay tripped because of phase reverse detection
MStart.EmergOverrideDI	Signal: Emergency override start blocking through digital input DI
MStart.EmergOverrideUI	Signal: Emergency override start blocking through front panel
MStart.ABSActive	Signal: Anti-backspin is active. For certain applications, such as pumping a fluid up a pipe, the motor may be driven backward for a period of time after it stops. The anti-backspin timer prevents starting the motor while it is spinning in the reverse direction.
MStart.Blo-GOCStart	Signal: Ground Instantaneous Overcurrent Start Delay. GOC (Instantaneous Overcurrent) elements are blocked for the time programmed under this parameter
MStart.Blo-IOCStart	Signal: Phase Instantaneous Overcurrent Start Delay. IOC (Instantaneous Overcurrent) elements are blocked for the time programmed under this parameter
MStart.Blo-I<Start	Signal: Underload Start Delay. Underload(Instantaneous Overcurrent) elements are blocked for the time programmed under this parameter
MStart.Blo-JamStart	Signal: JAM Start Delay. JAM(Instantaneous Overcurrent) elements are blocked for the time programmed under this parameter
MStart.Blo-I2>Start	Signal: Motor start block current unbalance signal
MStart.Blo-Generic1	Generic Start Delay. This value can be used to block any protective element.1
MStart.Blo-Generic2	Generic Start Delay. This value can be used to block any protective element.2
MStart.Blo-Generic3	Generic Start Delay. This value can be used to block any protective element.3
MStart.Blo-Generic4	Generic Start Delay. This value can be used to block any protective element.4
MStart.Blo-Generic5	Generic Start Delay. This value can be used to block any protective element.5
MStart.I_Transit	Signal: Current transition signal
MStart.T_Transit	Signal: Time transition signal
MStart.MotorStopBlo	Signal: Motor stop block other protection functions
MStart.Rotating forward	Signal: Rotation Direction forward
MStart.Rotating backward	Signal: Rotation Direction reverse
MStart.ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
MStart.RemStartBlock-I	State of the module input: Remote Motor Start Blocking
MStart.EmgOvr-I	State of the module input: Emergency Override. Signal has to be active in order to release the thermal capacity of the motor. Please notice that by doing this you run the risk of damaging the motor. “EMGOVR” has to be set to “DI” or “DI or UI” for this input to take effect
MStart.INSQ-I	State of the module input: INcomplete SeQuence
MStart.ZSS-I	State of the module input: Zero Speed Switch

Name	*Description*
MStart.STPC Blo-I	State of the module input: With this setting a Digital Input keeps the Motor in the RUN mode, even when the motor current drops below STPC (motor stop current).
I[1].active	Signal: active
I[1].ExBlo	Signal: External Blocking
I[1].Ex rev Interl	Signal: External reverse Interlocking
I[1].Blo TripCmd	Signal: Trip Command blocked
I[1].ExBlo TripCmd	Signal: External Blocking of the Trip Command
I[1].Alarm L1	Signal: Alarm L1
I[1].Alarm L2	Signal: Alarm L2
I[1].Alarm L3	Signal: Alarm L3
I[1].Alarm	Signal: Alarm
I[1].Trip L1	Signal: General Trip Phase L1
I[1].Trip L2	Signal: General Trip Phase L2
I[1].Trip L3	Signal: General Trip Phase L3
I[1].Trip	Signal: Trip
I[1].TripCmd	Signal: Trip Command
I[1].DefaultSet	Signal: Default Parameter Set
I[1].AdaptSet 1	Signal: Adaptive Parameter 1
I[1].AdaptSet 2	Signal: Adaptive Parameter 2
I[1].AdaptSet 3	Signal: Adaptive Parameter 3
I[1].AdaptSet 4	Signal: Adaptive Parameter 4
I[1].ExBlo1-I	Module input state: External blocking1
I[1].ExBlo2-I	Module input state: External blocking2
I[1].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
I[1].Ex rev Interl-I	Module input state: External reverse interlocking
I[1].AdaptSet1-I	Module input state: Adaptive Parameter1
I[1].AdaptSet2-I	Module input state: Adaptive Parameter2
I[1].AdaptSet3-I	Module input state: Adaptive Parameter3
I[1].AdaptSet4-I	Module input state: Adaptive Parameter4
I[2].active	Signal: active
I[2].ExBlo	Signal: External Blocking
I[2].Ex rev Interl	Signal: External reverse Interlocking
I[2].Blo TripCmd	Signal: Trip Command blocked
I[2].ExBlo TripCmd	Signal: External Blocking of the Trip Command
I[2].Alarm L1	Signal: Alarm L1
I[2].Alarm L2	Signal: Alarm L2
I[2].Alarm L3	Signal: Alarm L3
I[2].Alarm	Signal: Alarm
I[2].Trip L1	Signal: General Trip Phase L1
I[2].Trip L2	Signal: General Trip Phase L2

Name	*Description*
I[2].Trip L3	Signal: General Trip Phase L3
I[2].Trip	Signal: Trip
I[2].TripCmd	Signal: Trip Command
I[2].DefaultSet	Signal: Default Parameter Set
I[2].AdaptSet 1	Signal: Adaptive Parameter 1
I[2].AdaptSet 2	Signal: Adaptive Parameter 2
I[2].AdaptSet 3	Signal: Adaptive Parameter 3
I[2].AdaptSet 4	Signal: Adaptive Parameter 4
I[2].ExBlo1-I	Module input state: External blocking1
I[2].ExBlo2-I	Module input state: External blocking2
I[2].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
I[2].Ex rev Interl-I	Module input state: External reverse interlocking
I[2].AdaptSet1-I	Module input state: Adaptive Parameter1
I[2].AdaptSet2-I	Module input state: Adaptive Parameter2
I[2].AdaptSet3-I	Module input state: Adaptive Parameter3
I[2].AdaptSet4-I	Module input state: Adaptive Parameter4
I[3].active	Signal: active
I[3].ExBlo	Signal: External Blocking
I[3].Ex rev Interl	Signal: External reverse Interlocking
I[3].Blo TripCmd	Signal: Trip Command blocked
I[3].ExBlo TripCmd	Signal: External Blocking of the Trip Command
I[3].Alarm L1	Signal: Alarm L1
I[3].Alarm L2	Signal: Alarm L2
I[3].Alarm L3	Signal: Alarm L3
I[3].Alarm	Signal: Alarm
I[3].Trip L1	Signal: General Trip Phase L1
I[3].Trip L2	Signal: General Trip Phase L2
I[3].Trip L3	Signal: General Trip Phase L3
I[3].Trip	Signal: Trip
I[3].TripCmd	Signal: Trip Command
I[3].DefaultSet	Signal: Default Parameter Set
I[3].AdaptSet 1	Signal: Adaptive Parameter 1
I[3].AdaptSet 2	Signal: Adaptive Parameter 2
I[3].AdaptSet 3	Signal: Adaptive Parameter 3
I[3].AdaptSet 4	Signal: Adaptive Parameter 4
I[3].ExBlo1-I	Module input state: External blocking1
I[3].ExBlo2-I	Module input state: External blocking2
I[3].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
I[3].Ex rev Interl-I	Module input state: External reverse interlocking
I[3].AdaptSet1-I	Module input state: Adaptive Parameter1

Name	*Description*
I[3].AdaptSet2-I	Module input state: Adaptive Parameter2
I[3].AdaptSet3-I	Module input state: Adaptive Parameter3
I[3].AdaptSet4-I	Module input state: Adaptive Parameter4
I[4].active	Signal: active
I[4].ExBlo	Signal: External Blocking
I[4].Ex rev Interl	Signal: External reverse Interlocking
I[4].Blo TripCmd	Signal: Trip Command blocked
I[4].ExBlo TripCmd	Signal: External Blocking of the Trip Command
I[4].Alarm L1	Signal: Alarm L1
I[4].Alarm L2	Signal: Alarm L2
I[4].Alarm L3	Signal: Alarm L3
I[4].Alarm	Signal: Alarm
I[4].Trip L1	Signal: General Trip Phase L1
I[4].Trip L2	Signal: General Trip Phase L2
I[4].Trip L3	Signal: General Trip Phase L3
I[4].Trip	Signal: Trip
I[4].TripCmd	Signal: Trip Command
I[4].DefaultSet	Signal: Default Parameter Set
I[4].AdaptSet 1	Signal: Adaptive Parameter 1
I[4].AdaptSet 2	Signal: Adaptive Parameter 2
I[4].AdaptSet 3	Signal: Adaptive Parameter 3
I[4].AdaptSet 4	Signal: Adaptive Parameter 4
I[4].ExBlo1-I	Module input state: External blocking1
I[4].ExBlo2-I	Module input state: External blocking2
I[4].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
I[4].Ex rev Interl-I	Module input state: External reverse interlocking
I[4].AdaptSet1-I	Module input state: Adaptive Parameter1
I[4].AdaptSet2-I	Module input state: Adaptive Parameter2
I[4].AdaptSet3-I	Module input state: Adaptive Parameter3
I[4].AdaptSet4-I	Module input state: Adaptive Parameter4
I[5].active	Signal: active
I[5].ExBlo	Signal: External Blocking
I[5].Ex rev Interl	Signal: External reverse Interlocking
I[5].Blo TripCmd	Signal: Trip Command blocked
I[5].ExBlo TripCmd	Signal: External Blocking of the Trip Command
I[5].Alarm L1	Signal: Alarm L1
I[5].Alarm L2	Signal: Alarm L2
I[5].Alarm L3	Signal: Alarm L3
I[5].Alarm	Signal: Alarm
I[5].Trip L1	Signal: General Trip Phase L1

Name	*Description*
I[5].Trip L2	Signal: General Trip Phase L2
I[5].Trip L3	Signal: General Trip Phase L3
I[5].Trip	Signal: Trip
I[5].TripCmd	Signal: Trip Command
I[5].DefaultSet	Signal: Default Parameter Set
I[5].AdaptSet 1	Signal: Adaptive Parameter 1
I[5].AdaptSet 2	Signal: Adaptive Parameter 2
I[5].AdaptSet 3	Signal: Adaptive Parameter 3
I[5].AdaptSet 4	Signal: Adaptive Parameter 4
I[5].ExBlo1-I	Module input state: External blocking1
I[5].ExBlo2-I	Module input state: External blocking2
I[5].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
I[5].Ex rev Interl-I	Module input state: External reverse interlocking
I[5].AdaptSet1-I	Module input state: Adaptive Parameter1
I[5].AdaptSet2-I	Module input state: Adaptive Parameter2
I[5].AdaptSet3-I	Module input state: Adaptive Parameter3
I[5].AdaptSet4-I	Module input state: Adaptive Parameter4
I[6].active	Signal: active
I[6].ExBlo	Signal: External Blocking
I[6].Ex rev Interl	Signal: External reverse Interlocking
I[6].Blo TripCmd	Signal: Trip Command blocked
I[6].ExBlo TripCmd	Signal: External Blocking of the Trip Command
I[6].Alarm L1	Signal: Alarm L1
I[6].Alarm L2	Signal: Alarm L2
I[6].Alarm L3	Signal: Alarm L3
I[6].Alarm	Signal: Alarm
I[6].Trip L1	Signal: General Trip Phase L1
I[6].Trip L2	Signal: General Trip Phase L2
I[6].Trip L3	Signal: General Trip Phase L3
I[6].Trip	Signal: Trip
I[6].TripCmd	Signal: Trip Command
I[6].DefaultSet	Signal: Default Parameter Set
I[6].AdaptSet 1	Signal: Adaptive Parameter 1
I[6].AdaptSet 2	Signal: Adaptive Parameter 2
I[6].AdaptSet 3	Signal: Adaptive Parameter 3
I[6].AdaptSet 4	Signal: Adaptive Parameter 4
I[6].ExBlo1-I	Module input state: External blocking1
I[6].ExBlo2-I	Module input state: External blocking2
I[6].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
I[6].Ex rev Interl-I	Module input state: External reverse interlocking

Name	*Description*
I[6].AdaptSet1-I	Module input state: Adaptive Parameter1
I[6].AdaptSet2-I	Module input state: Adaptive Parameter2
I[6].AdaptSet3-I	Module input state: Adaptive Parameter3
I[6].AdaptSet4-I	Module input state: Adaptive Parameter4
IG[1].active	Signal: active
IG[1].ExBlo	Signal: External Blocking
IG[1].Ex rev Interl	Signal: External reverse Interlocking
IG[1].Blo TripCmd	Signal: Trip Command blocked
IG[1].ExBlo TripCmd	Signal: External Blocking of the Trip Command
IG[1].Alarm	Signal: Alarm IG
IG[1].Trip	Signal: Trip
IG[1].TripCmd	Signal: Trip Command
IG[1].DefaultSet	Signal: Default Parameter Set
IG[1].AdaptSet 1	Signal: Adaptive Parameter 1
IG[1].AdaptSet 2	Signal: Adaptive Parameter 2
IG[1].AdaptSet 3	Signal: Adaptive Parameter 3
IG[1].AdaptSet 4	Signal: Adaptive Parameter 4
IG[1].ExBlo1-I	Module input state: External blocking1
IG[1].ExBlo2-I	Module input state: External blocking2
IG[1].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
IG[1].Ex rev Interl-I	Module input state: External reverse interlocking
IG[1].AdaptSet1-I	Module input state: Adaptive Parameter1
IG[1].AdaptSet2-I	Module input state: Adaptive Parameter2
IG[1].AdaptSet3-I	Module input state: Adaptive Parameter3
IG[1].AdaptSet4-I	Module input state: Adaptive Parameter4
IG[2].active	Signal: active
IG[2].ExBlo	Signal: External Blocking
IG[2].Ex rev Interl	Signal: External reverse Interlocking
IG[2].Blo TripCmd	Signal: Trip Command blocked
IG[2].ExBlo TripCmd	Signal: External Blocking of the Trip Command
IG[2].Alarm	Signal: Alarm IG
IG[2].Trip	Signal: Trip
IG[2].TripCmd	Signal: Trip Command
IG[2].DefaultSet	Signal: Default Parameter Set
IG[2].AdaptSet 1	Signal: Adaptive Parameter 1
IG[2].AdaptSet 2	Signal: Adaptive Parameter 2
IG[2].AdaptSet 3	Signal: Adaptive Parameter 3
IG[2].AdaptSet 4	Signal: Adaptive Parameter 4
IG[2].ExBlo1-I	Module input state: External blocking1
IG[2].ExBlo2-I	Module input state: External blocking2

Name	*Description*
IG[2].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
IG[2].Ex rev Interl-I	Module input state: External reverse interlocking
IG[2].AdaptSet1-I	Module input state: Adaptive Parameter1
IG[2].AdaptSet2-I	Module input state: Adaptive Parameter2
IG[2].AdaptSet3-I	Module input state: Adaptive Parameter3
IG[2].AdaptSet4-I	Module input state: Adaptive Parameter4
IG[3].active	Signal: active
IG[3].ExBlo	Signal: External Blocking
IG[3].Ex rev Interl	Signal: External reverse Interlocking
IG[3].Blo TripCmd	Signal: Trip Command blocked
IG[3].ExBlo TripCmd	Signal: External Blocking of the Trip Command
IG[3].Alarm	Signal: Alarm IG
IG[3].Trip	Signal: Trip
IG[3].TripCmd	Signal: Trip Command
IG[3].DefaultSet	Signal: Default Parameter Set
IG[3].AdaptSet 1	Signal: Adaptive Parameter 1
IG[3].AdaptSet 2	Signal: Adaptive Parameter 2
IG[3].AdaptSet 3	Signal: Adaptive Parameter 3
IG[3].AdaptSet 4	Signal: Adaptive Parameter 4
IG[3].ExBlo1-I	Module input state: External blocking1
IG[3].ExBlo2-I	Module input state: External blocking2
IG[3].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
IG[3].Ex rev Interl-I	Module input state: External reverse interlocking
IG[3].AdaptSet1-I	Module input state: Adaptive Parameter1
IG[3].AdaptSet2-I	Module input state: Adaptive Parameter2
IG[3].AdaptSet3-I	Module input state: Adaptive Parameter3
IG[3].AdaptSet4-I	Module input state: Adaptive Parameter4
IG[4].active	Signal: active
IG[4].ExBlo	Signal: External Blocking
IG[4].Ex rev Interl	Signal: External reverse Interlocking
IG[4].Blo TripCmd	Signal: Trip Command blocked
IG[4].ExBlo TripCmd	Signal: External Blocking of the Trip Command
IG[4].Alarm	Signal: Alarm IG
IG[4].Trip	Signal: Trip
IG[4].TripCmd	Signal: Trip Command
IG[4].DefaultSet	Signal: Default Parameter Set
IG[4].AdaptSet 1	Signal: Adaptive Parameter 1
IG[4].AdaptSet 2	Signal: Adaptive Parameter 2
IG[4].AdaptSet 3	Signal: Adaptive Parameter 3
IG[4].AdaptSet 4	Signal: Adaptive Parameter 4

Name	*Description*
IG[4].ExBlo1-I	Module input state: External blocking1
IG[4].ExBlo2-I	Module input state: External blocking2
IG[4].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
IG[4].Ex rev Interl-I	Module input state: External reverse interlocking
IG[4].AdaptSet1-I	Module input state: Adaptive Parameter1
IG[4].AdaptSet2-I	Module input state: Adaptive Parameter2
IG[4].AdaptSet3-I	Module input state: Adaptive Parameter3
IG[4].AdaptSet4-I	Module input state: Adaptive Parameter4
ThR.Alarm Pickup	Signal: Alarm Pickup
ThR.Alarm Timeout	Signal: Alarm Timeout
ThR.RTD effective	This state becomes true if the following conditions are all fulfilled: - the state “Load above SF” is true, - RTD functionality is active, - for at least one temperature a valid value above 0°C is being displayed.
ThR.Load above SF	“Load above Service Factor”: If the current exceeds the set value of “UTC” (“Ultimate trip threshold”) then the used thermal capacity counts up and the state “Load above SF” is becoming true. If the current is below the “UTC” value this state is false.
ThR.active	Signal: active
ThR.ExBlo	Signal: External Blocking
ThR.Blo TripCmd	Signal: Trip Command blocked
ThR.ExBlo TripCmd	Signal: External Blocking of the Trip Command
ThR.Alarm	Signal: Alarm
ThR.Trip	Signal: Trip
ThR.TripCmd	Signal: Trip Command
ThR.ExBlo1	Module input state: External blocking
ThR.ExBlo2	Module input state: External blocking
ThR.ExBlo TripCmd	Module input state: External Blocking of the Trip Command
Jam[1].active	Signal: active
Jam[1].ExBlo	Signal: External Blocking
Jam[1].Blo TripCmd	Signal: Trip Command blocked
Jam[1].ExBlo TripCmd	Signal: External Blocking of the Trip Command
Jam[1].Alarm	Signal: Alarm
Jam[1].Trip	Signal: Trip
Jam[1].TripCmd	Signal: Trip Command
Jam[1].ExBlo1-I	Module input state: External blocking1
Jam[1].ExBlo2-I	Module input state: External blocking2
Jam[1].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
Jam[2].active	Signal: active
Jam[2].ExBlo	Signal: External Blocking
Jam[2].Blo TripCmd	Signal: Trip Command blocked

Name	Description
Jam[2].ExBlo TripCmd	Signal: External Blocking of the Trip Command
Jam[2].Alarm	Signal: Alarm
Jam[2].Trip	Signal: Trip
Jam[2].TripCmd	Signal: Trip Command
Jam[2].ExBlo1-I	Module input state: External blocking1
Jam[2].ExBlo2-I	Module input state: External blocking2
Jam[2].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
I<[1].active	Signal: active
I<[1].ExBlo	Signal: External Blocking
I<[1].Blo TripCmd	Signal: Trip Command blocked
I<[1].ExBlo TripCmd	Signal: External Blocking of the Trip Command
I<[1].Alarm	Signal: Alarm
I<[1].Trip	Signal: Trip
I<[1].TripCmd	Signal: Trip Command
I<[1].ExBlo1-I	Module input state: External blocking1
I<[1].ExBlo2-I	Module input state: External blocking2
I<[1].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
I<[2].active	Signal: active
I<[2].ExBlo	Signal: External Blocking
I<[2].Blo TripCmd	Signal: Trip Command blocked
I<[2].ExBlo TripCmd	Signal: External Blocking of the Trip Command
I<[2].Alarm	Signal: Alarm
I<[2].Trip	Signal: Trip
I<[2].TripCmd	Signal: Trip Command
I<[2].ExBlo1-I	Module input state: External blocking1
I<[2].ExBlo2-I	Module input state: External blocking2
I<[2].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
I<[3].active	Signal: active
I<[3].ExBlo	Signal: External Blocking
I<[3].Blo TripCmd	Signal: Trip Command blocked
I<[3].ExBlo TripCmd	Signal: External Blocking of the Trip Command
I<[3].Alarm	Signal: Alarm
I<[3].Trip	Signal: Trip
I<[3].TripCmd	Signal: Trip Command
I<[3].ExBlo1-I	Module input state: External blocking1
I<[3].ExBlo2-I	Module input state: External blocking2
I<[3].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
MLS.active	Signal: active
MLS.ExBlo	Signal: External Blocking
MLS.Alarm	Signal: Alarm

Name	*Description*
MLS.Trip	Signal: Trip
MLS.ExBlo1-I	Module input state: External blocking1
MLS.ExBlo2-I	Module input state: External blocking2
I2>[1].active	Signal: active
I2>[1].ExBlo	Signal: External Blocking
I2>[1].Blo TripCmd	Signal: Trip Command blocked
I2>[1].ExBlo TripCmd	Signal: External Blocking of the Trip Command
I2>[1].Alarm	Signal: Alarm Negative Sequence
I2>[1].Trip	Signal: Trip
I2>[1].TripCmd	Signal: Trip Command
I2>[1].ExBlo1-I	Module input state: External blocking1
I2>[1].ExBlo2-I	Module input state: External blocking2
I2>[1].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
I2>[2].active	Signal: active
I2>[2].ExBlo	Signal: External Blocking
I2>[2].Blo TripCmd	Signal: Trip Command blocked
I2>[2].ExBlo TripCmd	Signal: External Blocking of the Trip Command
I2>[2].Alarm	Signal: Alarm Negative Sequence
I2>[2].Trip	Signal: Trip
I2>[2].TripCmd	Signal: Trip Command
I2>[2].ExBlo1-I	Module input state: External blocking1
I2>[2].ExBlo2-I	Module input state: External blocking2
I2>[2].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
ExP[1].active	Signal: active
ExP[1].ExBlo	Signal: External Blocking
ExP[1].Blo TripCmd	Signal: Trip Command blocked
ExP[1].ExBlo TripCmd	Signal: External Blocking of the Trip Command
ExP[1].Alarm	Signal: Alarm
ExP[1].Trip	Signal: Trip
ExP[1].TripCmd	Signal: Trip Command
ExP[1].ExBlo1-I	Module input state: External blocking1
ExP[1].ExBlo2-I	Module input state: External blocking2
ExP[1].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
ExP[1].Alarm-I	Module input state: Alarm
ExP[1].Trip-I	Module input state: Trip
ExP[2].active	Signal: active
ExP[2].ExBlo	Signal: External Blocking
ExP[2].Blo TripCmd	Signal: Trip Command blocked
ExP[2].ExBlo TripCmd	Signal: External Blocking of the Trip Command
ExP[2].Alarm	Signal: Alarm

Name	*Description*
ExP[2].Trip	Signal: Trip
ExP[2].TripCmd	Signal: Trip Command
ExP[2].ExBlo1-I	Module input state: External blocking1
ExP[2].ExBlo2-I	Module input state: External blocking2
ExP[2].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
ExP[2].Alarm-I	Module input state: Alarm
ExP[2].Trip-I	Module input state: Trip
ExP[3].active	Signal: active
ExP[3].ExBlo	Signal: External Blocking
ExP[3].Blo TripCmd	Signal: Trip Command blocked
ExP[3].ExBlo TripCmd	Signal: External Blocking of the Trip Command
ExP[3].Alarm	Signal: Alarm
ExP[3].Trip	Signal: Trip
ExP[3].TripCmd	Signal: Trip Command
ExP[3].ExBlo1-I	Module input state: External blocking1
ExP[3].ExBlo2-I	Module input state: External blocking2
ExP[3].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
ExP[3].Alarm-I	Module input state: Alarm
ExP[3].Trip-I	Module input state: Trip
ExP[4].active	Signal: active
ExP[4].ExBlo	Signal: External Blocking
ExP[4].Blo TripCmd	Signal: Trip Command blocked
ExP[4].ExBlo TripCmd	Signal: External Blocking of the Trip Command
ExP[4].Alarm	Signal: Alarm
ExP[4].Trip	Signal: Trip
ExP[4].TripCmd	Signal: Trip Command
ExP[4].ExBlo1-I	Module input state: External blocking1
ExP[4].ExBlo2-I	Module input state: External blocking2
ExP[4].ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
ExP[4].Alarm-I	Module input state: Alarm
ExP[4].Trip-I	Module input state: Trip
URTD.Windg1 Superv	Signal: Supervision Channel Windg1
URTD.Windg2 Superv	Signal: Supervision Channel Windg2
URTD.Windg3 Superv	Signal: Supervision Channel Windg3
URTD.Windg4 Superv	Signal: Supervision Channel Windg4
URTD.Windg5 Superv	Signal: Supervision Channel Windg5
URTD.Windg6 Superv	Signal: Supervision Channel Windg6
URTD.MotBear1 Superv	Signal: Supervision Channel MotBear1
URTD.MotBear2 Superv	Signal: Supervision Channel MotBear2
URTD.LoadBear1 Superv	Signal: Supervision Channel LoadBear1

Name	*Description*
URTD.LoadBear2 Superv	Signal: Supervision Channel LoadBear2
URTD.Aux1 Superv	Signal: Supervision Channel Aux1
URTD.Aux2 Superv	Signal: Supervision Channel Aux2
URTD.Superv	Signal: URTD Supervision Channel
URTD.active	Signal: URTD active
URTD.Outs forced	Signal: The State of at least one Relay Output has been set by force. That means that the state of at least one Relay is forced and hence does not show the state of the assigned signals.
RTD.active	Signal: active
RTD.ExBlo	Signal: External Blocking
RTD.Blo TripCmd	Signal: Trip Command blocked
RTD.ExBlo TripCmd	Signal: External Blocking of the Trip Command
RTD.Alarm	Alarm RTD Temperature Protection
RTD.Trip	Signal: Trip
RTD.TripCmd	Signal: Trip Command
RTD.Windg 1 Trip	Winding 1 Signal: Trip
RTD.Windg 1 Alarm	Winding 1 Alarm RTD Temperature Protection
RTD.Windg 1 Timeout Alarm	Winding 1 Timeout Alarm
RTD.Windg 1 Invalid	Winding 1 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
RTD.Windg 2 Trip	Winding 2 Signal: Trip
RTD.Windg 2 Alarm	Winding 2 Alarm RTD Temperature Protection
RTD.Windg 2 Timeout Alarm	Winding 2 Timeout Alarm
RTD.Windg 2 Invalid	Winding 2 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
RTD.Windg 3 Trip	Winding 3 Signal: Trip
RTD.Windg 3 Alarm	Winding 3 Alarm RTD Temperature Protection
RTD.Windg 3 Timeout Alarm	Winding 3 Timeout Alarm
RTD.Windg 3 Invalid	Winding 3 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
RTD.Windg 4 Trip	Winding 4 Signal: Trip
RTD.Windg 4 Alarm	Winding 4 Alarm RTD Temperature Protection
RTD.Windg 4 Timeout Alarm	Winding 4 Timeout Alarm
RTD.Windg 4 Invalid	Winding 4 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
RTD.Windg 5 Trip	Winding 5 Signal: Trip
RTD.Windg 5 Alarm	Winding 5 Alarm RTD Temperature Protection
RTD.Windg 5 Timeout Alarm	Winding 5 Timeout Alarm

Name	*Description*
RTD.Windg 5 Invalid	Winding 5 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
RTD.Windg 6 Trip	Winding 6 Signal: Trip
RTD.Windg 6 Alarm	Winding 6 Alarm RTD Temperature Protection
RTD.Windg 6 Timeout Alarm	Winding 6 Timeout Alarm
RTD.Windg 6 Invalid	Winding 6 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
RTD.MotBear 1 Trip	Motor Bearing 1 Signal: Trip
RTD.MotBear 1 Alarm	Motor Bearing 1 Alarm RTD Temperature Protection
RTD.MotBear 1 Timeout Alarm	Motor Bearing 1 Timeout Alarm
RTD.MotBear 1 Invalid	Motor Bearing 1 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
RTD.MotBear 2 Trip	Motor Bearing 2 Signal: Trip
RTD.MotBear 2 Alarm	Motor Bearing 2 Alarm RTD Temperature Protection
RTD.MotBear 2 Timeout Alarm	Motor Bearing 2 Timeout Alarm
RTD.MotBear 2 Invalid	Motor Bearing 2 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
RTD.LoadBear 1 Trip	Load Bearing 1 Signal: Trip
RTD.LoadBear 1 Alarm	Load Bearing 1 Alarm RTD Temperature Protection
RTD.LoadBear 1 Timeout Alarm	Load Bearing 1 Timeout Alarm
RTD.LoadBear 1 Invalid	Load Bearing 1 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
RTD.LoadBear 2 Trip	Load Bearing 2 Signal: Trip
RTD.LoadBear 2 Alarm	Load Bearing 2 Alarm RTD Temperature Protection
RTD.LoadBear 2 Timeout Alarm	Load Bearing 2 Timeout Alarm
RTD.LoadBear 2 Invalid	Load Bearing 2 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
RTD.Aux1 Trip	Auxiliary 1 Signal: Trip
RTD.Aux1 Alarm	Auxiliary 1 Alarm RTD Temperature Protection
RTD.Aux1 Timeout Alarm	Auxiliary 1 Timeout Alarm
RTD.Aux1 Invalid	Auxiliary 1 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
RTD.Aux2 Trip	Auxiliary 2 Signal: Trip
RTD.Aux2 Alarm	Auxiliary 2 Alarm RTD Temperature Protection
RTD.Aux2 Timeout Alarm	Auxiliary 2 Timeout Alarm
RTD.Aux2 Invalid	Auxiliary 2 Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
RTD.Trip WD Group	Trip all Windings

Name	*Description*
RTD.Alarm WD Group	Alarm all Windings
RTD.TimeoutAlmWDGrp	Timeout Alarm all Windings
RTD.Windg Group Invalid	Winding Group Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
RTD.Trip MB Group	Trip all Motor Bearings
RTD.Alarm MB Group	Alarm all Motor Bearings
RTD.TimeoutAlmMBGrp	Timeout Alarm all Motor Bearings
RTD.MotBear Group Invalid	Motor Bearing Group Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
RTD.Trip LB Group	Trip all Load Bearings
RTD.Alarm LB Group	Alarm all Load Bearings
RTD.TimeoutAlmLBGrp	Timeout Alarm all Load Bearings
RTD.LoadBear Group Invalid	Load Bearing Group Signal: Invalid Temperature Measurement Value (e.g caused by an defective or interrupted RTD Measurement)
RTD.Trip Any Group	Trip Any Group
RTD.Alarm Any Group	Alarm Any Group
RTD.TimeoutAlmAnyGrp	Timeout Alarm Any Group
RTD.Trip Group 1	Trip Group 1
RTD.Trip Group 2	Trip Group 2
RTD.Timeout Alarm	Alarm timeout expired
RTD.Trip Aux Group	Trip Auxiliary Group
RTD.Alarm Aux Group	Alarm Auxiliary Group
RTD.TimeoutAlmAuxGrp	Timeout Alarm Auxiliary Group
RTD.AuxGrpInvalid	Invalid Auxiliary Group
RTD.ExBlo1-I	Module input state: External blocking1
RTD.ExBlo2-I	Module input state: External blocking2
RTD.ExBlo TripCmd-I	Module input state: External Blocking of the Trip Command
CBF.active	Signal: active
CBF.ExBlo	Signal: External Blocking
CBF.Waiting for Trigger	Waiting for Trigger
CBF.running	Signal: CBF-Module started
CBF.Alarm	Signal: Circuit Breaker Failure
CBF.Lockout	Signal: Lockout
CBF.Res Lockout	Signal: Reset Lockout
CBF.ExBlo1-I	Module input state: External blocking1
CBF.ExBlo2-I	Module input state: External blocking2
CBF.Trigger1-I	Module Input: Trigger that will start the CBF
CBF.Trigger2-I	Module Input: Trigger that will start the CBF
CBF.Trigger3-I	Module Input: Trigger that will start the CBF
TCS.active	Signal: active
TCS.ExBlo	Signal: External Blocking

Name	*Description*
TCS.Alarm	Signal: Alarm Trip Circuit Supervision
TCS.Not Possible	Not possible because no state indicator assigned to the breaker.
TCS.Aux ON-I	Module Input State: Position indicator/check-back signal of the CB (52a)
TCS.Aux OFF-I	Module input state: Position indicator/check-back signal of the CB (52b)
TCS.ExBlo1-I	Module input state: External blocking1
TCS.ExBlo2-I	Module input state: External blocking2
CTS.active	Signal: active
CTS.ExBlo	Signal: External Blocking
CTS.Alarm	Signal: Alarm Current Transformer Measuring Circuit Supervision
CTS.ExBlo1-I	Module input state: External blocking1
CTS.ExBlo2-I	Module input state: External blocking2
SysA.active	Signal: active
SysA.ExBlo	Signal: External Blocking
SysA.Alm Current Demd	Signal: Alarm averaged demand current
SysA.Alarm I THD	Signal: Alarm Total Harmonic Distortion Current
SysA.Trip Current Demand	Signal: Trip averaged demand current
SysA.Trip I THD	Signal: Trip Total Harmonic Distortion Current
SysA.ExBlo-I	Module input state: External blocking
DI Slot X1.DI 1	Signal: Digital Input
DI Slot X1.DI 2	Signal: Digital Input
DI Slot X1.DI 3	Signal: Digital Input
DI Slot X1.DI 4	Signal: Digital Input
DI Slot X1.DI 5	Signal: Digital Input
DI Slot X1.DI 6	Signal: Digital Input
DI Slot X1.DI 7	Signal: Digital Input
DI Slot X1.DI 8	Signal: Digital Input
DI Slot X1.DI 1	Signal: Digital Input
DI Slot X1.DI 2	Signal: Digital Input
DI Slot X1.DI 3	Signal: Digital Input
DI Slot X1.DI 4	Signal: Digital Input
BO Slot X2.BO 1	Signal: Binary Output Relay
BO Slot X2.BO 2	Signal: Binary Output Relay
BO Slot X2.BO 3	Signal: Binary Output Relay
BO Slot X2.BO 4	Signal: Binary Output Relay
BO Slot X2.BO 5	Signal: Binary Output Relay
BO Slot X2.DISARMED!	Signal: CAUTION! RELAYS DISARMED in order to safely perform maintenance while eliminating the risk of taking an entire process off-line. (Note: The Self Supervision Contact cannot be disarmed). YOU MUST ENSURE that the relays are ARMED AGAIN after maintenance

Name	*Description*
BO Slot X2.Outs forced	Signal: The State of at least one Relay Output has been set by force. That means that the state of at least one Relay is forced and hence does not show the state of the assigned signals.
BO Slot X2.BO 1	Signal: Binary Output Relay
BO Slot X2.BO 2	Signal: Binary Output Relay
BO Slot X2.BO 3	Signal: Binary Output Relay
BO Slot X2.DISARMED!	Signal: CAUTION! RELAYS DISARMED in order to safely perform maintenance while eliminating the risk of taking an entire process off-line. (Note: The Self Supervision Contact cannot be disarmed). YOU MUST ENSURE that the relays are ARMED AGAIN after maintenance
BO Slot X2.Outs forced	Signal: The State of at least one Relay Output has been set by force. That means that the state of at least one Relay is forced and hence does not show the state of the assigned signals.
AnOut[1].Force Mode	For commissioning purposes or for maintenance, Analog Outputs can be set by force. By means of this function the normal Analog Outputs can be overwritten (forced).
Event rec.Res all records	Signal: All records deleted
Disturb rec.recording	Signal: Recording
Disturb rec.memory full	Signal: Memory full
Disturb rec.Clear fail	Signal: Clear failure in memory
Disturb rec.Res all records	Signal: All records deleted
Disturb rec.Res rec	Signal: Delete record
Disturb rec.Man Trigger	Signal: Manual Trigger
Disturb rec.Start1-I	State of the module input:: Trigger event / start recording if:
Disturb rec.Start2-I	State of the module input:: Trigger event / start recording if:
Disturb rec.Start3-I	State of the module input:: Trigger event / start recording if:
Disturb rec.Start4-I	State of the module input:: Trigger event / start recording if:
Disturb rec.Start5-I	State of the module input:: Trigger event / start recording if:
Disturb rec.Start6-I	State of the module input:: Trigger event / start recording if:
Disturb rec.Start7-I	State of the module input:: Trigger event / start recording if:
Disturb rec.Start8-I	State of the module input:: Trigger event / start recording if:
Fault rec.Res rec	Signal: Delete record
Trend rec.Hand Reset	Hand Reset
Start rec.Storing	Signal: Data are saved
SSV.System Error	Signal: Device Failure
SSV.SelfSuperVision Contact	Signal: SelfSuperVision Contact
Scada.SCADA connected	At least one SCADA System is connected to the device.
Scada.SCADA not connected	No SCADA System is connected to the device
DNP3.busy	This message is set if the protocol is started. It will be reset if the protocol is shut down.
DNP3.ready	The message will be set if the protocol is successfully started and ready for data exchange.

Name	*Description*
DNP3.active	The communication with the Master (SCADA) is active. Note that for TCP/UDP, this state is permanently “Low” unless »DataLink confirm« is set to “Always”.
DNP3.BinaryOutput0	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput1	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput2	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput3	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput4	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput5	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput6	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput7	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput8	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput9	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput10	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput11	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput12	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput13	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput14	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput15	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput16	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput17	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput18	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput19	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput20	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput21	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.

Name	*Description*
DNP3.BinaryOutput22	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput23	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput24	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput25	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput26	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput27	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput28	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput29	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput30	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput31	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryInput0-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput1-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput2-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput3-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput4-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput5-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput6-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput7-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput8-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput9-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput10-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput11-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput12-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.

Name	*Description*
DNP3.BinaryInput13-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput14-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput15-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput16-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput17-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput18-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput19-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput20-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput21-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput22-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput23-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput24-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput25-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput26-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput27-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput28-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput29-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput30-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput31-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput32-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput33-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput34-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput35-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.

Name	*Description*
DNP3.BinaryInput36-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput37-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput38-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput39-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput40-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput41-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput42-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput43-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput44-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput45-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput46-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput47-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput48-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput49-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput50-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput51-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput52-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput53-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput54-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput55-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput56-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput57-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput58-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.

Name	*Description*
DNP3.BinaryInput59-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput60-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput61-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput62-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
DNP3.BinaryInput63-I	Virtual Digital Input (DNP). This corresponds to a virtual binary output of the protective device.
Modbus.Transmission RTU	Signal: SCADA active
Modbus.Transmission TCP	Signal: SCADA active
Modbus.Scada Cmd 1	Scada Command
Modbus.Scada Cmd 2	Scada Command
Modbus.Scada Cmd 3	Scada Command
Modbus.Scada Cmd 4	Scada Command
Modbus.Scada Cmd 5	Scada Command
Modbus.Scada Cmd 6	Scada Command
Modbus.Scada Cmd 7	Scada Command
Modbus.Scada Cmd 8	Scada Command
Modbus.Scada Cmd 9	Scada Command
Modbus.Scada Cmd 10	Scada Command
Modbus.Scada Cmd 11	Scada Command
Modbus.Scada Cmd 12	Scada Command
Modbus.Scada Cmd 13	Scada Command
Modbus.Scada Cmd 14	Scada Command
Modbus.Scada Cmd 15	Scada Command
Modbus.Scada Cmd 16	Scada Command
Modbus.Config Bin Inp1-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp2-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp3-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp4-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp5-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp6-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp7-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp8-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp9-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp10-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp11-I	State of the module input: Config Bin Inp

Name	*Description*
Modbus.Config Bin Inp12-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp13-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp14-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp15-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp16-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp17-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp18-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp19-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp20-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp21-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp22-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp23-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp24-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp25-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp26-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp27-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp28-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp29-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp30-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp31-I	State of the module input: Config Bin Inp
Modbus.Config Bin Inp32-I	State of the module input: Config Bin Inp
IEC61850.MMS Client connected	At least one MMS client is connected to the device
IEC61850.All Goose Subscriber active	All Goose subscriber in the device are working
IEC61850.VirtInp1	Signal: Virtual Input (IEC61850 GGIO Ind)

Name	*Description*
IEC61850.VirtInp2	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp3	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp4	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp5	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp6	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp7	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp8	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp9	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp10	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp11	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp12	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp13	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp14	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp15	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp16	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp17	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp18	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp19	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp20	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp21	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp22	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp23	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp24	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp25	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp26	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp27	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp28	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp29	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp30	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp31	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.VirtInp32	Signal: Virtual Input (IEC61850 GGIO Ind)
IEC61850.Quality of GGIO In1	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In2	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In3	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In4	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In5	Self-Supervision of the GGIO Input

Name	*Description*
IEC61850.Quality of GGIO In6	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In7	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In8	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In9	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In10	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In11	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In12	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In13	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In14	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In15	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In16	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In17	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In18	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In19	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In20	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In21	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In22	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In23	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In24	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In25	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In26	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In27	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In28	Self-Supervision of the GGIO Input

Name	*Description*
IEC61850.Quality of GGIO In29	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In30	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In31	Self-Supervision of the GGIO Input
IEC61850.Quality of GGIO In32	Self-Supervision of the GGIO Input
IEC61850.SPCSO1	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO2	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO3	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO4	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO5	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO6	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO7	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO8	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO9	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO10	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO11	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO12	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO13	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO14	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO15	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO16	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO17	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO18	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO19	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).

Name	*Description*
IEC61850.SPCSO20	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO21	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO22	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO23	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO24	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO25	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO26	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO27	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO28	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO29	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO30	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO31	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.SPCSO32	Status bit that can be set by clients like e.g. SCADA (Single Point Controllable Status Output).
IEC61850.VirtOut1-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut2-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut3-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut4-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut5-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut6-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut7-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut8-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut9-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut10-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut11-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut12-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut13-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut14-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut15-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut16-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut17-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut18-I	Module input state: Binary state of the Virtual Output (GGIO)

Name	*Description*
IEC61850.VirtOut19-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut20-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut21-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut22-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut23-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut24-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut25-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut26-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut27-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut28-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut29-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut30-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut31-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC61850.VirtOut32-I	Module input state: Binary state of the Virtual Output (GGIO)
IEC 103.Scada Cmd 1	Scada Command
IEC 103.Scada Cmd 2	Scada Command
IEC 103.Scada Cmd 3	Scada Command
IEC 103.Scada Cmd 4	Scada Command
IEC 103.Scada Cmd 5	Scada Command
IEC 103.Scada Cmd 6	Scada Command
IEC 103.Scada Cmd 7	Scada Command
IEC 103.Scada Cmd 8	Scada Command
IEC 103.Scada Cmd 9	Scada Command
IEC 103.Scada Cmd 10	Scada Command
IEC 103.Transmission	Signal: SCADA active
IEC 103.Failure Event lost	Failure event lost
IEC 103.Test mode active	Signal: IEC103 communication has been switched over into Test Mode.
IEC 103.Block MD active	Signal: The blocking of IEC103 transmission in monitor direction has been activated.
IEC 103.Ex activate test mode-I	Module input state: Test Mode of the IEC103 communication.
IEC 103.Ex activate Block MD-I	Module input state: Activation of the blocking of IEC103 transmission in monitor direction.
Profibus.Data OK	Data within the Input field are OK (Yes=1)
Profibus.SubModul Err	Assignable Signal, Failure in Sub-Module, Communication Failure.
Profibus.Connection active	Connection active
Profibus.Scada Cmd 1	Scada Command
Profibus.Scada Cmd 2	Scada Command
Profibus.Scada Cmd 3	Scada Command

Name	*Description*
Profibus.Scada Cmd 4	Scada Command
Profibus.Scada Cmd 5	Scada Command
Profibus.Scada Cmd 6	Scada Command
Profibus.Scada Cmd 7	Scada Command
Profibus.Scada Cmd 8	Scada Command
Profibus.Scada Cmd 9	Scada Command
Profibus.Scada Cmd 10	Scada Command
Profibus.Scada Cmd 11	Scada Command
Profibus.Scada Cmd 12	Scada Command
Profibus.Scada Cmd 13	Scada Command
Profibus.Scada Cmd 14	Scada Command
Profibus.Scada Cmd 15	Scada Command
Profibus.Scada Cmd 16	Scada Command
IRIG-B.IRIG-B active	Signal: If there is no valid IRIG-B signal for 60 sec, IRIG-B is regarded as inactive.
IRIG-B.High-Low Invert	Signal: The High and Low signals of the IRIG-B are inverted. This does NOT mean that the wiring is faulty. If the wiring is faulty no IRIG-B signal will be detected.
IRIG-B.Control Signal1	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
IRIG-B.Control Signal2	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
IRIG-B.Control Signal3	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
IRIG-B.Control Signal4	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
IRIG-B.Control Signal5	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
IRIG-B.Control Signal6	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
IRIG-B.Control Signal7	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
IRIG-B.Control Signal8	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
IRIG-B.Control Signal9	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
IRIG-B.Control Signal10	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).

Name	*Description*
IRIG-B.Control Signal11	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
IRIG-B.Control Signal12	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
IRIG-B.Control Signal13	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
IRIG-B.Control Signal14	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
IRIG-B.Control Signal15	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
IRIG-B.Control Signal16	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
IRIG-B.Control Signal17	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
IRIG-B.Control Signal18	Signal: IRIG-B Control Signal. The external IRIG-B generator can set these signals. They can be used for further control procedures inside the device (e.g. logic funtions).
SNTP.SNTP active	Signal: If there is no valid SNTP signal for 120 sec, SNTP is regarded as inactive.
TimeSync.synchronized	Clock is synchronized.
Statistics.ResFc all	Signal: Resetting of all Statistic values (Current Demand, Power Demand, Min, Max)
Statistics.ResFc I Demand	Signal: Resetting of Statistics - Current Demand (avg, peak avg)
Statistics.ResFc Max	Signal: Resetting of all Maximum values
Statistics.ResFc Min	Signal: Resetting of all Minimum values
Statistics.StartFc I Demand-I	State of the module input: Start of the Statistics of the Current Demand
Logics.LE1.Gate Out	Signal: Output of the logic gate
Logics.LE1.Timer Out	Signal: Timer Output
Logics.LE1.Out	Signal: Latched Output (Q)
Logics.LE1.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE1.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE1.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE1.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE1.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE1.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE2.Gate Out	Signal: Output of the logic gate
Logics.LE2.Timer Out	Signal: Timer Output
Logics.LE2.Out	Signal: Latched Output (Q)

Name	Description
Logics.LE2.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE2.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE2.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE2.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE2.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE2.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE3.Gate Out	Signal: Output of the logic gate
Logics.LE3.Timer Out	Signal: Timer Output
Logics.LE3.Out	Signal: Latched Output (Q)
Logics.LE3.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE3.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE3.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE3.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE3.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE3.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE4.Gate Out	Signal: Output of the logic gate
Logics.LE4.Timer Out	Signal: Timer Output
Logics.LE4.Out	Signal: Latched Output (Q)
Logics.LE4.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE4.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE4.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE4.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE4.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE4.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE5.Gate Out	Signal: Output of the logic gate
Logics.LE5.Timer Out	Signal: Timer Output
Logics.LE5.Out	Signal: Latched Output (Q)
Logics.LE5.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE5.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE5.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE5.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE5.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE5.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE6.Gate Out	Signal: Output of the logic gate
Logics.LE6.Timer Out	Signal: Timer Output
Logics.LE6.Out	Signal: Latched Output (Q)
Logics.LE6.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE6.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE6.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE6.Gate In3-I	State of the module input: Assignment of the Input Signal

Name	*Description*
Logics.LE6.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE6.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE7.Gate Out	Signal: Output of the logic gate
Logics.LE7.Timer Out	Signal: Timer Output
Logics.LE7.Out	Signal: Latched Output (Q)
Logics.LE7.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE7.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE7.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE7.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE7.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE7.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE8.Gate Out	Signal: Output of the logic gate
Logics.LE8.Timer Out	Signal: Timer Output
Logics.LE8.Out	Signal: Latched Output (Q)
Logics.LE8.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE8.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE8.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE8.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE8.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE8.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE9.Gate Out	Signal: Output of the logic gate
Logics.LE9.Timer Out	Signal: Timer Output
Logics.LE9.Out	Signal: Latched Output (Q)
Logics.LE9.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE9.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE9.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE9.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE9.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE9.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE10.Gate Out	Signal: Output of the logic gate
Logics.LE10.Timer Out	Signal: Timer Output
Logics.LE10.Out	Signal: Latched Output (Q)
Logics.LE10.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE10.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE10.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE10.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE10.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE10.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE11.Gate Out	Signal: Output of the logic gate

Name	*Description*
Logics.LE11.Timer Out	Signal: Timer Output
Logics.LE11.Out	Signal: Latched Output (Q)
Logics.LE11.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE11.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE11.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE11.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE11.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE11.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE12.Gate Out	Signal: Output of the logic gate
Logics.LE12.Timer Out	Signal: Timer Output
Logics.LE12.Out	Signal: Latched Output (Q)
Logics.LE12.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE12.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE12.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE12.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE12.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE12.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE13.Gate Out	Signal: Output of the logic gate
Logics.LE13.Timer Out	Signal: Timer Output
Logics.LE13.Out	Signal: Latched Output (Q)
Logics.LE13.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE13.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE13.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE13.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE13.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE13.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE14.Gate Out	Signal: Output of the logic gate
Logics.LE14.Timer Out	Signal: Timer Output
Logics.LE14.Out	Signal: Latched Output (Q)
Logics.LE14.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE14.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE14.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE14.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE14.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE14.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE15.Gate Out	Signal: Output of the logic gate
Logics.LE15.Timer Out	Signal: Timer Output

Name	*Description*
Logics.LE15.Out	Signal: Latched Output (Q)
Logics.LE15.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE15.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE15.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE15.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE15.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE15.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE16.Gate Out	Signal: Output of the logic gate
Logics.LE16.Timer Out	Signal: Timer Output
Logics.LE16.Out	Signal: Latched Output (Q)
Logics.LE16.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE16.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE16.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE16.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE16.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE16.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE17.Gate Out	Signal: Output of the logic gate
Logics.LE17.Timer Out	Signal: Timer Output
Logics.LE17.Out	Signal: Latched Output (Q)
Logics.LE17.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE17.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE17.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE17.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE17.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE17.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE18.Gate Out	Signal: Output of the logic gate
Logics.LE18.Timer Out	Signal: Timer Output
Logics.LE18.Out	Signal: Latched Output (Q)
Logics.LE18.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE18.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE18.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE18.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE18.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE18.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE19.Gate Out	Signal: Output of the logic gate
Logics.LE19.Timer Out	Signal: Timer Output
Logics.LE19.Out	Signal: Latched Output (Q)

Name	*Description*
Logics.LE19.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE19.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE19.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE19.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE19.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE19.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE20.Gate Out	Signal: Output of the logic gate
Logics.LE20.Timer Out	Signal: Timer Output
Logics.LE20.Out	Signal: Latched Output (Q)
Logics.LE20.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE20.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE20.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE20.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE20.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE20.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE21.Gate Out	Signal: Output of the logic gate
Logics.LE21.Timer Out	Signal: Timer Output
Logics.LE21.Out	Signal: Latched Output (Q)
Logics.LE21.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE21.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE21.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE21.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE21.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE21.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE22.Gate Out	Signal: Output of the logic gate
Logics.LE22.Timer Out	Signal: Timer Output
Logics.LE22.Out	Signal: Latched Output (Q)
Logics.LE22.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE22.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE22.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE22.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE22.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE22.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE23.Gate Out	Signal: Output of the logic gate
Logics.LE23.Timer Out	Signal: Timer Output
Logics.LE23.Out	Signal: Latched Output (Q)
Logics.LE23.Out inverted	Signal: Negated Latched Output (Q NOT)

Name	*Description*
Logics.LE23.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE23.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE23.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE23.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE23.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE24.Gate Out	Signal: Output of the logic gate
Logics.LE24.Timer Out	Signal: Timer Output
Logics.LE24.Out	Signal: Latched Output (Q)
Logics.LE24.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE24.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE24.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE24.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE24.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE24.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE25.Gate Out	Signal: Output of the logic gate
Logics.LE25.Timer Out	Signal: Timer Output
Logics.LE25.Out	Signal: Latched Output (Q)
Logics.LE25.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE25.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE25.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE25.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE25.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE25.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE26.Gate Out	Signal: Output of the logic gate
Logics.LE26.Timer Out	Signal: Timer Output
Logics.LE26.Out	Signal: Latched Output (Q)
Logics.LE26.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE26.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE26.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE26.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE26.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE26.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE27.Gate Out	Signal: Output of the logic gate
Logics.LE27.Timer Out	Signal: Timer Output
Logics.LE27.Out	Signal: Latched Output (Q)
Logics.LE27.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE27.Gate In1-I	State of the module input: Assignment of the Input Signal

Name	*Description*
Logics.LE27.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE27.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE27.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE27.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE28.Gate Out	Signal: Output of the logic gate
Logics.LE28.Timer Out	Signal: Timer Output
Logics.LE28.Out	Signal: Latched Output (Q)
Logics.LE28.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE28.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE28.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE28.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE28.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE28.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE29.Gate Out	Signal: Output of the logic gate
Logics.LE29.Timer Out	Signal: Timer Output
Logics.LE29.Out	Signal: Latched Output (Q)
Logics.LE29.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE29.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE29.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE29.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE29.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE29.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE30.Gate Out	Signal: Output of the logic gate
Logics.LE30.Timer Out	Signal: Timer Output
Logics.LE30.Out	Signal: Latched Output (Q)
Logics.LE30.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE30.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE30.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE30.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE30.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE30.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE31.Gate Out	Signal: Output of the logic gate
Logics.LE31.Timer Out	Signal: Timer Output
Logics.LE31.Out	Signal: Latched Output (Q)
Logics.LE31.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE31.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE31.Gate In2-I	State of the module input: Assignment of the Input Signal

Name	*Description*
Logics.LE31.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE31.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE31.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE32.Gate Out	Signal: Output of the logic gate
Logics.LE32.Timer Out	Signal: Timer Output
Logics.LE32.Out	Signal: Latched Output (Q)
Logics.LE32.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE32.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE32.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE32.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE32.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE32.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE33.Gate Out	Signal: Output of the logic gate
Logics.LE33.Timer Out	Signal: Timer Output
Logics.LE33.Out	Signal: Latched Output (Q)
Logics.LE33.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE33.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE33.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE33.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE33.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE33.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE34.Gate Out	Signal: Output of the logic gate
Logics.LE34.Timer Out	Signal: Timer Output
Logics.LE34.Out	Signal: Latched Output (Q)
Logics.LE34.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE34.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE34.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE34.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE34.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE34.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE35.Gate Out	Signal: Output of the logic gate
Logics.LE35.Timer Out	Signal: Timer Output
Logics.LE35.Out	Signal: Latched Output (Q)
Logics.LE35.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE35.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE35.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE35.Gate In3-I	State of the module input: Assignment of the Input Signal

Name	Description
Logics.LE35.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE35.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE36.Gate Out	Signal: Output of the logic gate
Logics.LE36.Timer Out	Signal: Timer Output
Logics.LE36.Out	Signal: Latched Output (Q)
Logics.LE36.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE36.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE36.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE36.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE36.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE36.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE37.Gate Out	Signal: Output of the logic gate
Logics.LE37.Timer Out	Signal: Timer Output
Logics.LE37.Out	Signal: Latched Output (Q)
Logics.LE37.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE37.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE37.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE37.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE37.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE37.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE38.Gate Out	Signal: Output of the logic gate
Logics.LE38.Timer Out	Signal: Timer Output
Logics.LE38.Out	Signal: Latched Output (Q)
Logics.LE38.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE38.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE38.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE38.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE38.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE38.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE39.Gate Out	Signal: Output of the logic gate
Logics.LE39.Timer Out	Signal: Timer Output
Logics.LE39.Out	Signal: Latched Output (Q)
Logics.LE39.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE39.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE39.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE39.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE39.Gate In4-I	State of the module input: Assignment of the Input Signal

Name	*Description*
Logics.LE39.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE40.Gate Out	Signal: Output of the logic gate
Logics.LE40.Timer Out	Signal: Timer Output
Logics.LE40.Out	Signal: Latched Output (Q)
Logics.LE40.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE40.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE40.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE40.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE40.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE40.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE41.Gate Out	Signal: Output of the logic gate
Logics.LE41.Timer Out	Signal: Timer Output
Logics.LE41.Out	Signal: Latched Output (Q)
Logics.LE41.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE41.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE41.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE41.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE41.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE41.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE42.Gate Out	Signal: Output of the logic gate
Logics.LE42.Timer Out	Signal: Timer Output
Logics.LE42.Out	Signal: Latched Output (Q)
Logics.LE42.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE42.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE42.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE42.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE42.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE42.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE43.Gate Out	Signal: Output of the logic gate
Logics.LE43.Timer Out	Signal: Timer Output
Logics.LE43.Out	Signal: Latched Output (Q)
Logics.LE43.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE43.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE43.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE43.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE43.Gate In4-I	State of the module input: Assignment of the Input Signal

Name	*Description*
Logics.LE43.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE44.Gate Out	Signal: Output of the logic gate
Logics.LE44.Timer Out	Signal: Timer Output
Logics.LE44.Out	Signal: Latched Output (Q)
Logics.LE44.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE44.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE44.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE44.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE44.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE44.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE45.Gate Out	Signal: Output of the logic gate
Logics.LE45.Timer Out	Signal: Timer Output
Logics.LE45.Out	Signal: Latched Output (Q)
Logics.LE45.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE45.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE45.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE45.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE45.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE45.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE46.Gate Out	Signal: Output of the logic gate
Logics.LE46.Timer Out	Signal: Timer Output
Logics.LE46.Out	Signal: Latched Output (Q)
Logics.LE46.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE46.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE46.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE46.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE46.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE46.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE47.Gate Out	Signal: Output of the logic gate
Logics.LE47.Timer Out	Signal: Timer Output
Logics.LE47.Out	Signal: Latched Output (Q)
Logics.LE47.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE47.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE47.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE47.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE47.Gate In4-I	State of the module input: Assignment of the Input Signal

Name	*Description*
Logics.LE47.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE48.Gate Out	Signal: Output of the logic gate
Logics.LE48.Timer Out	Signal: Timer Output
Logics.LE48.Out	Signal: Latched Output (Q)
Logics.LE48.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE48.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE48.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE48.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE48.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE48.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE49.Gate Out	Signal: Output of the logic gate
Logics.LE49.Timer Out	Signal: Timer Output
Logics.LE49.Out	Signal: Latched Output (Q)
Logics.LE49.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE49.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE49.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE49.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE49.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE49.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE50.Gate Out	Signal: Output of the logic gate
Logics.LE50.Timer Out	Signal: Timer Output
Logics.LE50.Out	Signal: Latched Output (Q)
Logics.LE50.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE50.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE50.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE50.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE50.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE50.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE51.Gate Out	Signal: Output of the logic gate
Logics.LE51.Timer Out	Signal: Timer Output
Logics.LE51.Out	Signal: Latched Output (Q)
Logics.LE51.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE51.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE51.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE51.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE51.Gate In4-I	State of the module input: Assignment of the Input Signal

Name	*Description*
Logics.LE51.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE52.Gate Out	Signal: Output of the logic gate
Logics.LE52.Timer Out	Signal: Timer Output
Logics.LE52.Out	Signal: Latched Output (Q)
Logics.LE52.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE52.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE52.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE52.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE52.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE52.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE53.Gate Out	Signal: Output of the logic gate
Logics.LE53.Timer Out	Signal: Timer Output
Logics.LE53.Out	Signal: Latched Output (Q)
Logics.LE53.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE53.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE53.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE53.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE53.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE53.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE54.Gate Out	Signal: Output of the logic gate
Logics.LE54.Timer Out	Signal: Timer Output
Logics.LE54.Out	Signal: Latched Output (Q)
Logics.LE54.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE54.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE54.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE54.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE54.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE54.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE55.Gate Out	Signal: Output of the logic gate
Logics.LE55.Timer Out	Signal: Timer Output
Logics.LE55.Out	Signal: Latched Output (Q)
Logics.LE55.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE55.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE55.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE55.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE55.Gate In4-I	State of the module input: Assignment of the Input Signal

Name	*Description*
Logics.LE55.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE56.Gate Out	Signal: Output of the logic gate
Logics.LE56.Timer Out	Signal: Timer Output
Logics.LE56.Out	Signal: Latched Output (Q)
Logics.LE56.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE56.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE56.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE56.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE56.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE56.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE57.Gate Out	Signal: Output of the logic gate
Logics.LE57.Timer Out	Signal: Timer Output
Logics.LE57.Out	Signal: Latched Output (Q)
Logics.LE57.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE57.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE57.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE57.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE57.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE57.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE58.Gate Out	Signal: Output of the logic gate
Logics.LE58.Timer Out	Signal: Timer Output
Logics.LE58.Out	Signal: Latched Output (Q)
Logics.LE58.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE58.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE58.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE58.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE58.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE58.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE59.Gate Out	Signal: Output of the logic gate
Logics.LE59.Timer Out	Signal: Timer Output
Logics.LE59.Out	Signal: Latched Output (Q)
Logics.LE59.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE59.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE59.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE59.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE59.Gate In4-I	State of the module input: Assignment of the Input Signal

Name	*Description*
Logics.LE59.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE60.Gate Out	Signal: Output of the logic gate
Logics.LE60.Timer Out	Signal: Timer Output
Logics.LE60.Out	Signal: Latched Output (Q)
Logics.LE60.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE60.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE60.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE60.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE60.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE60.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE61.Gate Out	Signal: Output of the logic gate
Logics.LE61.Timer Out	Signal: Timer Output
Logics.LE61.Out	Signal: Latched Output (Q)
Logics.LE61.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE61.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE61.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE61.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE61.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE61.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE62.Gate Out	Signal: Output of the logic gate
Logics.LE62.Timer Out	Signal: Timer Output
Logics.LE62.Out	Signal: Latched Output (Q)
Logics.LE62.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE62.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE62.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE62.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE62.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE62.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE63.Gate Out	Signal: Output of the logic gate
Logics.LE63.Timer Out	Signal: Timer Output
Logics.LE63.Out	Signal: Latched Output (Q)
Logics.LE63.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE63.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE63.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE63.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE63.Gate In4-I	State of the module input: Assignment of the Input Signal

Name	*Description*
Logics.LE63.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE64.Gate Out	Signal: Output of the logic gate
Logics.LE64.Timer Out	Signal: Timer Output
Logics.LE64.Out	Signal: Latched Output (Q)
Logics.LE64.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE64.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE64.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE64.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE64.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE64.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE65.Gate Out	Signal: Output of the logic gate
Logics.LE65.Timer Out	Signal: Timer Output
Logics.LE65.Out	Signal: Latched Output (Q)
Logics.LE65.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE65.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE65.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE65.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE65.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE65.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE66.Gate Out	Signal: Output of the logic gate
Logics.LE66.Timer Out	Signal: Timer Output
Logics.LE66.Out	Signal: Latched Output (Q)
Logics.LE66.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE66.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE66.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE66.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE66.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE66.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE67.Gate Out	Signal: Output of the logic gate
Logics.LE67.Timer Out	Signal: Timer Output
Logics.LE67.Out	Signal: Latched Output (Q)
Logics.LE67.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE67.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE67.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE67.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE67.Gate In4-I	State of the module input: Assignment of the Input Signal

Name	Description
Logics.LE67.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE68.Gate Out	Signal: Output of the logic gate
Logics.LE68.Timer Out	Signal: Timer Output
Logics.LE68.Out	Signal: Latched Output (Q)
Logics.LE68.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE68.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE68.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE68.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE68.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE68.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE69.Gate Out	Signal: Output of the logic gate
Logics.LE69.Timer Out	Signal: Timer Output
Logics.LE69.Out	Signal: Latched Output (Q)
Logics.LE69.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE69.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE69.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE69.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE69.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE69.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE70.Gate Out	Signal: Output of the logic gate
Logics.LE70.Timer Out	Signal: Timer Output
Logics.LE70.Out	Signal: Latched Output (Q)
Logics.LE70.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE70.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE70.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE70.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE70.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE70.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE71.Gate Out	Signal: Output of the logic gate
Logics.LE71.Timer Out	Signal: Timer Output
Logics.LE71.Out	Signal: Latched Output (Q)
Logics.LE71.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE71.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE71.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE71.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE71.Gate In4-I	State of the module input: Assignment of the Input Signal

Name	*Description*
Logics.LE71.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE72.Gate Out	Signal: Output of the logic gate
Logics.LE72.Timer Out	Signal: Timer Output
Logics.LE72.Out	Signal: Latched Output (Q)
Logics.LE72.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE72.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE72.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE72.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE72.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE72.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE73.Gate Out	Signal: Output of the logic gate
Logics.LE73.Timer Out	Signal: Timer Output
Logics.LE73.Out	Signal: Latched Output (Q)
Logics.LE73.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE73.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE73.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE73.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE73.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE73.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE74.Gate Out	Signal: Output of the logic gate
Logics.LE74.Timer Out	Signal: Timer Output
Logics.LE74.Out	Signal: Latched Output (Q)
Logics.LE74.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE74.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE74.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE74.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE74.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE74.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE75.Gate Out	Signal: Output of the logic gate
Logics.LE75.Timer Out	Signal: Timer Output
Logics.LE75.Out	Signal: Latched Output (Q)
Logics.LE75.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE75.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE75.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE75.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE75.Gate In4-I	State of the module input: Assignment of the Input Signal

Name	*Description*
Logics.LE75.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE76.Gate Out	Signal: Output of the logic gate
Logics.LE76.Timer Out	Signal: Timer Output
Logics.LE76.Out	Signal: Latched Output (Q)
Logics.LE76.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE76.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE76.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE76.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE76.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE76.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE77.Gate Out	Signal: Output of the logic gate
Logics.LE77.Timer Out	Signal: Timer Output
Logics.LE77.Out	Signal: Latched Output (Q)
Logics.LE77.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE77.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE77.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE77.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE77.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE77.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE78.Gate Out	Signal: Output of the logic gate
Logics.LE78.Timer Out	Signal: Timer Output
Logics.LE78.Out	Signal: Latched Output (Q)
Logics.LE78.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE78.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE78.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE78.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE78.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE78.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE79.Gate Out	Signal: Output of the logic gate
Logics.LE79.Timer Out	Signal: Timer Output
Logics.LE79.Out	Signal: Latched Output (Q)
Logics.LE79.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE79.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE79.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE79.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE79.Gate In4-I	State of the module input: Assignment of the Input Signal

Name	*Description*
Logics.LE79.Reset Latch-I	State of the module input: Reset Signal for the Latching
Logics.LE80.Gate Out	Signal: Output of the logic gate
Logics.LE80.Timer Out	Signal: Timer Output
Logics.LE80.Out	Signal: Latched Output (Q)
Logics.LE80.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE80.Gate In1-I	State of the module input: Assignment of the Input Signal
Logics.LE80.Gate In2-I	State of the module input: Assignment of the Input Signal
Logics.LE80.Gate In3-I	State of the module input: Assignment of the Input Signal
Logics.LE80.Gate In4-I	State of the module input: Assignment of the Input Signal
Logics.LE80.Reset Latch-I	State of the module input: Reset Signal for the Latching
Sgen.Manual Start	Fault Simulation has been started manually.
Sgen.Manual Stop	Fault Simulation has been stopped manually.
Sgen.Running	Signal; Measuring value simulation is running
Sgen.Started	Fault Simulation has been started
Sgen.Stopped	Fault Simulation has been stopped
Sgen.Ex Start Simulation-I	State of the module input:External Start of Fault Simulation (Using the test parameters)
Sgen.ExBlo1-I	Module input state: External blocking1
Sgen.ExBlo2-I	Module input state: External blocking2
Sgen.Ex ForcePost-I	State of the module input:Force Post state. Abort simulation.
Sys.PS 1	Signal: Parameter Set 1
Sys.PS 2	Signal: Parameter Set 2
Sys.PS 3	Signal: Parameter Set 3
Sys.PS 4	Signal: Parameter Set 4
Sys.PSS manual	Signal: Manual Switch over of a Parameter Set
Sys.PSS via Scada	Signal: Parameter Set Switch via Scada. Write into this output byte the integer of the parameter set that should become active (e.g. 4 => Switch onto parameter set 4).
Sys.PSS via Inp fct	Signal: Parameter Set Switch via input function
Sys.min 1 param changed	Signal: At least one parameter has been changed
Sys.Setting Lock Bypass	Signal: Short-period unlock of the Setting Lock
Sys.Ack LED	Signal: LEDs acknowledgement
Sys.Ack BO	Signal: Acknowledgement of the Binary Outputs
Sys.Ack Scada	Signal: Acknowledge Scada
Sys.Ack TripCmd	Signal: Reset Trip Command
Sys.Ack LED-HMI	Signal: LEDs acknowledgement :HMI
Sys.Ack BO-HMI	Signal: Acknowledgement of the Binary Outputs :HMI
Sys.Ack Scada-HMI	Signal: Acknowledge Scada :HMI
Sys.Ack TripCmd-HMI	Signal: Reset Trip Command :HMI

Name	*Description*
Sys.Ack LED-Sca	Signal: LEDs acknowledgement :SCADA
Sys.Ack BO-Sca	Signal: Acknowledgement of the Binary Outputs :SCADA
Sys.Ack Counter-Sca	Signal: Reset of all Counters :SCADA
Sys.Ack Scada-Sca	Signal: Acknowledge Scada :SCADA
Sys.Ack TripCmd-Sca	Signal: Reset Trip Command :SCADA
Sys.Res OperationsCr	Signal:: Res OperationsCr
Sys.Res AlarmCr	Signal:: Res AlarmCr
Sys.Res TripCmdCr	Signal:: Res TripCmdCr
Sys.Res TotalCr	Signal:: Res TotalCr
Sys.Ack LED-I	Module input state: LEDs acknowledgement by digital input
Sys.Ack BO-I	Module input state: Acknowledgement of the binary Output Relays
Sys.Ack Scada-I	Module input state: Acknowledge Scada via digital input. The replica that SCADA has got from the device is to be reset.
Sys.PS1-I	State of the module input respectively of the signal, that should activate this Parameter Setting Group.
Sys.PS2-I	State of the module input respectively of the signal, that should activate this Parameter Setting Group.
Sys.PS3-I	State of the module input respectively of the signal, that should activate this Parameter Setting Group.
Sys.PS4-I	State of the module input respectively of the signal, that should activate this Parameter Setting Group.
Sys.Internal test state	Auxiliary state for testing purposes.

List of the Digital Inputs

The following list comprises all Digital Inputs. This list is used in various Protective Elements (e.g. TCS, Q->&V<...). The availability and the number of entries depends on the type of device.

Name	*Description*
-.-	No assignment
DI Slot X1.DI 1	Signal: Digital Input
DI Slot X1.DI 2	Signal: Digital Input
DI Slot X1.DI 3	Signal: Digital Input
DI Slot X1.DI 4	Signal: Digital Input
DI Slot X1.DI 5	Signal: Digital Input
DI Slot X1.DI 6	Signal: Digital Input
DI Slot X1.DI 7	Signal: Digital Input
DI Slot X1.DI 8	Signal: Digital Input
DI Slot X1.DI 1	Signal: Digital Input
DI Slot X1.DI 2	Signal: Digital Input
DI Slot X1.DI 3	Signal: Digital Input
DI Slot X1.DI 4	Signal: Digital Input

Signals of the Digital Inputs and Logic

The following list comprises the signals of the Digital Inputs and the Logic. This list is used in various protective elements.

Name	*Description*
-.-	No assignment
DI Slot X1.DI 1	Signal: Digital Input
DI Slot X1.DI 2	Signal: Digital Input
DI Slot X1.DI 3	Signal: Digital Input
DI Slot X1.DI 4	Signal: Digital Input
DI Slot X1.DI 5	Signal: Digital Input
DI Slot X1.DI 6	Signal: Digital Input
DI Slot X1.DI 7	Signal: Digital Input
DI Slot X1.DI 8	Signal: Digital Input
DI Slot X1.DI 1	Signal: Digital Input
DI Slot X1.DI 2	Signal: Digital Input
DI Slot X1.DI 3	Signal: Digital Input
DI Slot X1.DI 4	Signal: Digital Input
DNP3.BinaryOutput0	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput1	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput2	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput3	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput4	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput5	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput6	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput7	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput8	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput9	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput10	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput11	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput12	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput13	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.

Name	*Description*
DNP3.BinaryOutput14	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput15	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput16	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput17	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput18	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput19	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput20	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput21	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput22	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput23	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput24	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput25	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput26	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput27	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput28	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput29	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput30	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
DNP3.BinaryOutput31	Virtual Digital Output (DNP). This corresponds to a virtual binary input of the protective device.
Logics.LE1.Gate Out	Signal: Output of the logic gate
Logics.LE1.Timer Out	Signal: Timer Output
Logics.LE1.Out	Signal: Latched Output (Q)
Logics.LE1.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE2.Gate Out	Signal: Output of the logic gate
Logics.LE2.Timer Out	Signal: Timer Output
Logics.LE2.Out	Signal: Latched Output (Q)
Logics.LE2.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE3.Gate Out	Signal: Output of the logic gate

Name	Description
Logics.LE3.Timer Out	Signal: Timer Output
Logics.LE3.Out	Signal: Latched Output (Q)
Logics.LE3.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE4.Gate Out	Signal: Output of the logic gate
Logics.LE4.Timer Out	Signal: Timer Output
Logics.LE4.Out	Signal: Latched Output (Q)
Logics.LE4.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE5.Gate Out	Signal: Output of the logic gate
Logics.LE5.Timer Out	Signal: Timer Output
Logics.LE5.Out	Signal: Latched Output (Q)
Logics.LE5.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE6.Gate Out	Signal: Output of the logic gate
Logics.LE6.Timer Out	Signal: Timer Output
Logics.LE6.Out	Signal: Latched Output (Q)
Logics.LE6.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE7.Gate Out	Signal: Output of the logic gate
Logics.LE7.Timer Out	Signal: Timer Output
Logics.LE7.Out	Signal: Latched Output (Q)
Logics.LE7.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE8.Gate Out	Signal: Output of the logic gate
Logics.LE8.Timer Out	Signal: Timer Output
Logics.LE8.Out	Signal: Latched Output (Q)
Logics.LE8.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE9.Gate Out	Signal: Output of the logic gate
Logics.LE9.Timer Out	Signal: Timer Output
Logics.LE9.Out	Signal: Latched Output (Q)
Logics.LE9.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE10.Gate Out	Signal: Output of the logic gate
Logics.LE10.Timer Out	Signal: Timer Output
Logics.LE10.Out	Signal: Latched Output (Q)
Logics.LE10.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE11.Gate Out	Signal: Output of the logic gate
Logics.LE11.Timer Out	Signal: Timer Output
Logics.LE11.Out	Signal: Latched Output (Q)
Logics.LE11.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE12.Gate Out	Signal: Output of the logic gate
Logics.LE12.Timer Out	Signal: Timer Output
Logics.LE12.Out	Signal: Latched Output (Q)
Logics.LE12.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE13.Gate Out	Signal: Output of the logic gate

Name	*Description*
Logics.LE13.Timer Out	Signal: Timer Output
Logics.LE13.Out	Signal: Latched Output (Q)
Logics.LE13.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE14.Gate Out	Signal: Output of the logic gate
Logics.LE14.Timer Out	Signal: Timer Output
Logics.LE14.Out	Signal: Latched Output (Q)
Logics.LE14.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE15.Gate Out	Signal: Output of the logic gate
Logics.LE15.Timer Out	Signal: Timer Output
Logics.LE15.Out	Signal: Latched Output (Q)
Logics.LE15.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE16.Gate Out	Signal: Output of the logic gate
Logics.LE16.Timer Out	Signal: Timer Output
Logics.LE16.Out	Signal: Latched Output (Q)
Logics.LE16.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE17.Gate Out	Signal: Output of the logic gate
Logics.LE17.Timer Out	Signal: Timer Output
Logics.LE17.Out	Signal: Latched Output (Q)
Logics.LE17.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE18.Gate Out	Signal: Output of the logic gate
Logics.LE18.Timer Out	Signal: Timer Output
Logics.LE18.Out	Signal: Latched Output (Q)
Logics.LE18.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE19.Gate Out	Signal: Output of the logic gate
Logics.LE19.Timer Out	Signal: Timer Output
Logics.LE19.Out	Signal: Latched Output (Q)
Logics.LE19.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE20.Gate Out	Signal: Output of the logic gate
Logics.LE20.Timer Out	Signal: Timer Output
Logics.LE20.Out	Signal: Latched Output (Q)
Logics.LE20.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE21.Gate Out	Signal: Output of the logic gate
Logics.LE21.Timer Out	Signal: Timer Output
Logics.LE21.Out	Signal: Latched Output (Q)
Logics.LE21.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE22.Gate Out	Signal: Output of the logic gate
Logics.LE22.Timer Out	Signal: Timer Output
Logics.LE22.Out	Signal: Latched Output (Q)
Logics.LE22.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE23.Gate Out	Signal: Output of the logic gate

Name	*Description*
Logics.LE23.Timer Out	Signal: Timer Output
Logics.LE23.Out	Signal: Latched Output (Q)
Logics.LE23.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE24.Gate Out	Signal: Output of the logic gate
Logics.LE24.Timer Out	Signal: Timer Output
Logics.LE24.Out	Signal: Latched Output (Q)
Logics.LE24.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE25.Gate Out	Signal: Output of the logic gate
Logics.LE25.Timer Out	Signal: Timer Output
Logics.LE25.Out	Signal: Latched Output (Q)
Logics.LE25.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE26.Gate Out	Signal: Output of the logic gate
Logics.LE26.Timer Out	Signal: Timer Output
Logics.LE26.Out	Signal: Latched Output (Q)
Logics.LE26.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE27.Gate Out	Signal: Output of the logic gate
Logics.LE27.Timer Out	Signal: Timer Output
Logics.LE27.Out	Signal: Latched Output (Q)
Logics.LE27.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE28.Gate Out	Signal: Output of the logic gate
Logics.LE28.Timer Out	Signal: Timer Output
Logics.LE28.Out	Signal: Latched Output (Q)
Logics.LE28.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE29.Gate Out	Signal: Output of the logic gate
Logics.LE29.Timer Out	Signal: Timer Output
Logics.LE29.Out	Signal: Latched Output (Q)
Logics.LE29.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE30.Gate Out	Signal: Output of the logic gate
Logics.LE30.Timer Out	Signal: Timer Output
Logics.LE30.Out	Signal: Latched Output (Q)
Logics.LE30.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE31.Gate Out	Signal: Output of the logic gate
Logics.LE31.Timer Out	Signal: Timer Output
Logics.LE31.Out	Signal: Latched Output (Q)
Logics.LE31.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE32.Gate Out	Signal: Output of the logic gate
Logics.LE32.Timer Out	Signal: Timer Output
Logics.LE32.Out	Signal: Latched Output (Q)
Logics.LE32.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE33.Gate Out	Signal: Output of the logic gate

Name	*Description*
Logics.LE33.Timer Out	Signal: Timer Output
Logics.LE33.Out	Signal: Latched Output (Q)
Logics.LE33.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE34.Gate Out	Signal: Output of the logic gate
Logics.LE34.Timer Out	Signal: Timer Output
Logics.LE34.Out	Signal: Latched Output (Q)
Logics.LE34.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE35.Gate Out	Signal: Output of the logic gate
Logics.LE35.Timer Out	Signal: Timer Output
Logics.LE35.Out	Signal: Latched Output (Q)
Logics.LE35.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE36.Gate Out	Signal: Output of the logic gate
Logics.LE36.Timer Out	Signal: Timer Output
Logics.LE36.Out	Signal: Latched Output (Q)
Logics.LE36.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE37.Gate Out	Signal: Output of the logic gate
Logics.LE37.Timer Out	Signal: Timer Output
Logics.LE37.Out	Signal: Latched Output (Q)
Logics.LE37.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE38.Gate Out	Signal: Output of the logic gate
Logics.LE38.Timer Out	Signal: Timer Output
Logics.LE38.Out	Signal: Latched Output (Q)
Logics.LE38.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE39.Gate Out	Signal: Output of the logic gate
Logics.LE39.Timer Out	Signal: Timer Output
Logics.LE39.Out	Signal: Latched Output (Q)
Logics.LE39.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE40.Gate Out	Signal: Output of the logic gate
Logics.LE40.Timer Out	Signal: Timer Output
Logics.LE40.Out	Signal: Latched Output (Q)
Logics.LE40.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE41.Gate Out	Signal: Output of the logic gate
Logics.LE41.Timer Out	Signal: Timer Output
Logics.LE41.Out	Signal: Latched Output (Q)
Logics.LE41.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE42.Gate Out	Signal: Output of the logic gate
Logics.LE42.Timer Out	Signal: Timer Output
Logics.LE42.Out	Signal: Latched Output (Q)
Logics.LE42.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE43.Gate Out	Signal: Output of the logic gate

Name	*Description*
Logics.LE43.Timer Out	Signal: Timer Output
Logics.LE43.Out	Signal: Latched Output (Q)
Logics.LE43.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE44.Gate Out	Signal: Output of the logic gate
Logics.LE44.Timer Out	Signal: Timer Output
Logics.LE44.Out	Signal: Latched Output (Q)
Logics.LE44.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE45.Gate Out	Signal: Output of the logic gate
Logics.LE45.Timer Out	Signal: Timer Output
Logics.LE45.Out	Signal: Latched Output (Q)
Logics.LE45.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE46.Gate Out	Signal: Output of the logic gate
Logics.LE46.Timer Out	Signal: Timer Output
Logics.LE46.Out	Signal: Latched Output (Q)
Logics.LE46.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE47.Gate Out	Signal: Output of the logic gate
Logics.LE47.Timer Out	Signal: Timer Output
Logics.LE47.Out	Signal: Latched Output (Q)
Logics.LE47.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE48.Gate Out	Signal: Output of the logic gate
Logics.LE48.Timer Out	Signal: Timer Output
Logics.LE48.Out	Signal: Latched Output (Q)
Logics.LE48.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE49.Gate Out	Signal: Output of the logic gate
Logics.LE49.Timer Out	Signal: Timer Output
Logics.LE49.Out	Signal: Latched Output (Q)
Logics.LE49.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE50.Gate Out	Signal: Output of the logic gate
Logics.LE50.Timer Out	Signal: Timer Output
Logics.LE50.Out	Signal: Latched Output (Q)
Logics.LE50.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE51.Gate Out	Signal: Output of the logic gate
Logics.LE51.Timer Out	Signal: Timer Output
Logics.LE51.Out	Signal: Latched Output (Q)
Logics.LE51.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE52.Gate Out	Signal: Output of the logic gate
Logics.LE52.Timer Out	Signal: Timer Output
Logics.LE52.Out	Signal: Latched Output (Q)
Logics.LE52.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE53.Gate Out	Signal: Output of the logic gate

Name	*Description*
Logics.LE53.Timer Out	Signal: Timer Output
Logics.LE53.Out	Signal: Latched Output (Q)
Logics.LE53.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE54.Gate Out	Signal: Output of the logic gate
Logics.LE54.Timer Out	Signal: Timer Output
Logics.LE54.Out	Signal: Latched Output (Q)
Logics.LE54.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE55.Gate Out	Signal: Output of the logic gate
Logics.LE55.Timer Out	Signal: Timer Output
Logics.LE55.Out	Signal: Latched Output (Q)
Logics.LE55.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE56.Gate Out	Signal: Output of the logic gate
Logics.LE56.Timer Out	Signal: Timer Output
Logics.LE56.Out	Signal: Latched Output (Q)
Logics.LE56.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE57.Gate Out	Signal: Output of the logic gate
Logics.LE57.Timer Out	Signal: Timer Output
Logics.LE57.Out	Signal: Latched Output (Q)
Logics.LE57.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE58.Gate Out	Signal: Output of the logic gate
Logics.LE58.Timer Out	Signal: Timer Output
Logics.LE58.Out	Signal: Latched Output (Q)
Logics.LE58.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE59.Gate Out	Signal: Output of the logic gate
Logics.LE59.Timer Out	Signal: Timer Output
Logics.LE59.Out	Signal: Latched Output (Q)
Logics.LE59.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE60.Gate Out	Signal: Output of the logic gate
Logics.LE60.Timer Out	Signal: Timer Output
Logics.LE60.Out	Signal: Latched Output (Q)
Logics.LE60.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE61.Gate Out	Signal: Output of the logic gate
Logics.LE61.Timer Out	Signal: Timer Output
Logics.LE61.Out	Signal: Latched Output (Q)
Logics.LE61.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE62.Gate Out	Signal: Output of the logic gate
Logics.LE62.Timer Out	Signal: Timer Output
Logics.LE62.Out	Signal: Latched Output (Q)
Logics.LE62.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE63.Gate Out	Signal: Output of the logic gate

Name	*Description*
Logics.LE63.Timer Out	Signal: Timer Output
Logics.LE63.Out	Signal: Latched Output (Q)
Logics.LE63.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE64.Gate Out	Signal: Output of the logic gate
Logics.LE64.Timer Out	Signal: Timer Output
Logics.LE64.Out	Signal: Latched Output (Q)
Logics.LE64.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE65.Gate Out	Signal: Output of the logic gate
Logics.LE65.Timer Out	Signal: Timer Output
Logics.LE65.Out	Signal: Latched Output (Q)
Logics.LE65.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE66.Gate Out	Signal: Output of the logic gate
Logics.LE66.Timer Out	Signal: Timer Output
Logics.LE66.Out	Signal: Latched Output (Q)
Logics.LE66.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE67.Gate Out	Signal: Output of the logic gate
Logics.LE67.Timer Out	Signal: Timer Output
Logics.LE67.Out	Signal: Latched Output (Q)
Logics.LE67.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE68.Gate Out	Signal: Output of the logic gate
Logics.LE68.Timer Out	Signal: Timer Output
Logics.LE68.Out	Signal: Latched Output (Q)
Logics.LE68.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE69.Gate Out	Signal: Output of the logic gate
Logics.LE69.Timer Out	Signal: Timer Output
Logics.LE69.Out	Signal: Latched Output (Q)
Logics.LE69.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE70.Gate Out	Signal: Output of the logic gate
Logics.LE70.Timer Out	Signal: Timer Output
Logics.LE70.Out	Signal: Latched Output (Q)
Logics.LE70.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE71.Gate Out	Signal: Output of the logic gate
Logics.LE71.Timer Out	Signal: Timer Output
Logics.LE71.Out	Signal: Latched Output (Q)
Logics.LE71.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE72.Gate Out	Signal: Output of the logic gate
Logics.LE72.Timer Out	Signal: Timer Output
Logics.LE72.Out	Signal: Latched Output (Q)
Logics.LE72.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE73.Gate Out	Signal: Output of the logic gate

Name	*Description*
Logics.LE73.Timer Out	Signal: Timer Output
Logics.LE73.Out	Signal: Latched Output (Q)
Logics.LE73.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE74.Gate Out	Signal: Output of the logic gate
Logics.LE74.Timer Out	Signal: Timer Output
Logics.LE74.Out	Signal: Latched Output (Q)
Logics.LE74.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE75.Gate Out	Signal: Output of the logic gate
Logics.LE75.Timer Out	Signal: Timer Output
Logics.LE75.Out	Signal: Latched Output (Q)
Logics.LE75.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE76.Gate Out	Signal: Output of the logic gate
Logics.LE76.Timer Out	Signal: Timer Output
Logics.LE76.Out	Signal: Latched Output (Q)
Logics.LE76.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE77.Gate Out	Signal: Output of the logic gate
Logics.LE77.Timer Out	Signal: Timer Output
Logics.LE77.Out	Signal: Latched Output (Q)
Logics.LE77.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE78.Gate Out	Signal: Output of the logic gate
Logics.LE78.Timer Out	Signal: Timer Output
Logics.LE78.Out	Signal: Latched Output (Q)
Logics.LE78.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE79.Gate Out	Signal: Output of the logic gate
Logics.LE79.Timer Out	Signal: Timer Output
Logics.LE79.Out	Signal: Latched Output (Q)
Logics.LE79.Out inverted	Signal: Negated Latched Output (Q NOT)
Logics.LE80.Gate Out	Signal: Output of the logic gate
Logics.LE80.Timer Out	Signal: Timer Output
Logics.LE80.Out	Signal: Latched Output (Q)
Logics.LE80.Out inverted	Signal: Negated Latched Output (Q NOT)

Specifications

Specifications of the Real Time Clock

Resolution:	1 ms
Tolerance:	<1 minute / month (+20°C [68°F]) <±1ms if synchronized via IRIG-B

Time Synchronisation Tolerances

The different protocols for time synchronisation vary in their accuracy:

Used Protocol	***Time drift over one month***	***Deviation to time generator***
Without time synchronization	<1 min (+20°C)	Time drifts
IRIG-B	Dependent on the time drift of the time generator	<±1 ms
SNTP	Dependent on the time drift of the time generator	<±1 ms, if network connection is GOOD (see operation status of SNTP)
IEC60870-5-103	Dependent on the time drift of the time generator	<±1 ms
Modbus TCP	Dependent on the time drift of the time generator	Dependent on the network load
Modbus RTU	Dependent on the time drift of the time generator	<±1 ms
DNP3 TCP	Dependent on the time drift of the time generator	Dependent on the network load
DNP3 UDP	Dependent on the time drift of the time generator	Dependent on the network load
DNP3 RTU	Dependent on the time drift of the time generator	<±1 ms

Specifications of the Measured Value Acquisition

Phase and Ground Current Measuring

Frequency Range:	50 Hz / 60 Hz ± 10%
Accuracy:	Class 0.5
Amplitude Error if I < In:	±0.5% of the rated current *3)
Amplitude Error if I > In:	±0.5% of the measured current *3)
Amplitude Error if I > 2 In:	±1.0% of the measured current *3)
Harmonics:	Up to 20% 3rd harmonic ±2% Up to 20% 5th harmonic ±2%
Frequency Influence:	<±2% / Hz in the range of ±10% of the configured nominal frequency
Temperature Influence:	<±1% within the range of 0°C to +60°C (+32°F to +140°F)

*3) For earth current sensitive the precision does not depend on the nominal value but is referenced to 100 mA (with In =1 A) respectively. 500 mA (with In = 5 A)

Protection Elements Accuracy

NOTICE **The tripping delay relates to the time between alarm and trip.**
The accuracy of the operating time relates to the time between fault entry and the time when the protection element is picked-up.

Reference conditions for all Protection Elements: sine wave, at rated frequency, THD < 1%
Measuring method: Fundamental

Overcurrent Protection Elements: ***I[x]***	***Accuracy***
I>	±1.5% of the setting value or ±1% In
Dropout Ratio	97% or 0.5% In
t	DEFT ±1% or ±10 ms
Operating Time At testing current >= 2 times pickup value	<36ms
Disengaging Time	<55ms
t-char	±5% (according to selected curve)
t-reset (Reset Mode = t-delay)	±1% or ±10 ms

Overcurrent Protection Elements: ***I[x]*** ***with selected Measuring method = I2*** ***(Negative phase sequence current)***	***Accuracy***
I>	±2% of the setting value or ±1% In
Dropout Ratio	97% or 0.5% In
t	DEFT ±1% or ±10 ms
Operating Time At testing current >= 2 times pickup value	<60ms
Disengaging Time	<45ms

Ground Current Elements: ***IG[x]***	***Accuracy*** *3)
IG>	±1.5% of the setting value or ±1% In
Dropout Ratio	97% or 0.5% x In
t	DEFT ±1% or ±10 ms
Operating time Starting from IG higher than 1.2 x IG>	<45ms
Disengaging Time	<55ms
t-char	±5% (according to selected curve)
t-reset (Reset Mode = t-delay)	±1% or ±10 ms

*3) For earth current sensitive the precision does not depend on the nominal value but is referenced to 100 mA (with In =1 A) respectively 500 mA (with In = 5 A)

Motor Protection:	***Accuracy***
Stop Declaration Time period current must drop below STPC	<50 ms ±1.5% of the setting value or 1% In
Anti Backspin Blocking time to allow for back spin.	±1sec.
TBS Timer Time between repeated starts.	±1sec.
Reset Starts Per Hour Reset starts per hours timer from oldest start event.	±1 min.

Thermal Model: ***ThR***	***Accuracy***
Trip Threshold	±2%
Trip Delay	±1% or ±10 ms
Alarm Threshold	±2%
Alarm Delay	±1% or ±10 ms

Jam-Stall Protection: ***Jam[x]***	***Accuracy***
Pickup	±1.5% of the setting value or 1% In
Dropout Ratio	97% or 0.5% In
t	DEFT ±1% or ±10 ms
Operating Time Starting from I higher than 1.1 x I>	<35 ms
Disengaging Time	<45 ms

Under Load Protection: ***I<[x]***	***Accuracy***
Threshold	±1.5% of the setting value or 1% In
Dropout Ratio	103% or 0.5% x In
t	DEFT ±1% or ±10 ms
Operating Time Starting from I lower than 0.9 x setting value	<50ms
Disengaging Time	<50 ms

Mechanical Load Shedding: ***MLS***	***Accuracy***
Pickup Threshold	±1.5% of the setting value or 1% In
Pickup Delay	DEFT ±1% or ±10 ms
Dropout Threshold	±1.5% of the setting value or 1% In
Dropout Delay	DEFT ±1% or ±10 ms

Start Delay Timers	***Accuracy***
Start Delay (common timers)	±1% or ±10 ms
Operating Times	
for IOC, GOC, JAM	<35 ms
for Underload, Generic 1-5	<60 ms

RTD Protection: RTD/URTD	***Accuracy***
Trip Threshold	±1°C (1.8°F)
Alarm Threshold	±1°C (1.8°F)
t-delay Alarm	DEFT ±1% or ±10 ms
Reset Hysteresis	-2°C (-3.6°F) of threshold ±1°C (1.8°F)

Current unbalance: I2>[x]	***Accuracy*** *1)
I2>	±2% of the setting value or 1% In
Dropout Ratio	97% or 0.5% x In
%(I2/I1)	±1%
t	DEFT ±1% or ±10 ms
Operating Time	<70 ms
Disengaging Time	<50 ms
K	±5% INV
τ-cool	±5% INV

*1) Negative-sequence current I2 must be ≥ 0.01 x In, I1 must be ≥ 0.1 x In.

Circuit Breaker Failure Protection: CBF	***Accuracy***
I-CBF>	±1.5% of the setting value or1% In
t-CBF	±1% or ±10 ms
Operating Time Starting from I Higher than 1.3 x I-CBF>	<40 ms
Disengaging Time	<40 ms

Trip Circuit Supervision: TCS	***Accuracy***
t-TCS	±1% or ±10 ms

Current Transformer Supervision: CTS	***Accuracy***
ΔI	±2% of the setting value or 1.5% In
Dropout Ratio	94%
Alarm delay	±1% or ± 10 ms

Revision History

This chapter lists all changes since version 3.0. If you need a change history for the versions 2.x please contact Woodward Kempen GmbH.

NOTICE

All 3.x hardware and software versions are downwards compatible with each other. For special questions and more detailed information, please contact Woodward Kempen GmbH Support.

NOTICE

Up to date documentation?

Please check the web site of Woodward Kempen GmbH for the latest revision of this
Technical Manual and if there is an Errata Sheet with updated information.

Version: 3.4

- Date: 2017-October-01
- Revision: C

Hardware

- A metal protecting cap has been added to the LC connectors for the Ethernet / TCP/IP via fiber optics. Since the cap improves the EMC immunity it is recommended to always fasten it carefully after plugging in the LC connectors.
- There is a new communication type “T” available:
  RS485 (IEC 60870-5-103, MODBUS RTU, DNP3.0 RTU)
  + RJ45 Ethernet 100 Mbit/s (IEC 61850, Modbus TCP, DNP3.0 TCP/UDP)

Software

- The device firmware is also available in Romanian language now.
- If the MRM4 is connected to *Smart view as of* version 4.50 the synchronization of date and considers automatically that the timezone settings might be different on PC and MRM4.

Communication

The menu [Device Para / HMI / Security] now makes the following setting parameters available:

- *»Smart view via Eth«* activates or deactivates the access of Smart view via Ethernet.
- *»Smart view via USB«* activates or deactivates the access of Smart view via the USB interface.

IEC60870-5-103

This communication protocol now supports the blocking of the transmission in Monitor Direction and the test mode.

Modbus

The transmission of fault values via Modbus protocol has been added. For the last fault event, all fault values are accessible with addresses above 50000. For each fault value, the Modbus address corresponds to the address of the respective instantaneous value shifted by the offset 30000. (Example: The current value IE1 has the address 20100, therefore the corresponding fault value has the address 50100.) For a detailed list, please consult the SCADA documentation.

For devices with RS485 *and* Ethernet interfaces (communication types “I” or “T”), the project setting „Modbus RTU/TCP“ is available now (via parameter [Device Planning] *»Scada . Protocol«*).
This makes the device communicate via serial line (RTU) and Ethernet (TCP) in parallel. In particular, note that:

- All masters see the same set of states.
- All masters can reset latched states.
- All masters can control the same breaker, make resets and acknowledgments.

Device Para

The Reset dialog, that starts when the »C« key is pressed during a cold start, has been adapted to new security-related requests: Now there is a new setting parameter *»Reset Options«* that allows to remove options from the Reset dialog.

Overcurrent – I[n], IG[n]

All ANSI and IEC inverse time characteristics have a time limit now according to IEC 60255-151.

A new inverse time characteristic “RINV” has been added.

SelfSupervision

Device-internal messages (in particular error messages) are now accessible under the menu [Operation / Self Supervision / Messages].

All messages that can potentially appear here are described in a separate document, the “HighPROTEC Troubleshooting Guide” (`DOK-HB-TS`).

Supervision

The MRM4 supervises the phase sequence and compares it with the setting that has been made at [Field Para / General Settings] *»Phase Sequence«* (i. e. „ACB“ or „ABC“).

Under the menu [Operation / Status Display / Supervision / Phase Sequence], there is a specific signal for each CT and VT, which is set active if the check of the respective CT / VT finds that the actual phase sequence is different from the setting under [Field Para].

LEDs

There is a new automatic acknowledgment mode for all LEDs: The latching of all LEDs is acknowledged (reset) in case of an alarm (from any protection module).

The automatic acknowledgment must be activated by setting: [Device Para / LEDs / LEDs group A / LED 1...n] *»Latched«* = “active, ack. by alarm”

Manual Acknowledgment

It is possible to acknowledge LEDs, SCADA, binary output relays and / or a pending trip command by pressing the »C« key at the panel. After it has been configured which items shall be be assigned to the *»Ack via »C« key«*, these are acknowledged by simply pressing the »C« key (for ca. 1 second).
Notice: If there is the need to be able to acknowledge without entering any password set an empty password for the level »Prot-Lv1«.

Version: 3.1

NOTICE **This version has not been released!**

- Date: 2017-March-06

Hardware

No changes.

Software

Reconnection – ReCon[n]

The Reconnection module has been enhanced according to VDE-AR-N 4120.

- The release condition has been made selectable via ReCon . Reconnect. Release Cond (options: V Internal Release, V Ext Release PCC, Both).
- The measuring method has been made selectable via ReCon . Measuring method (options: Fundamental, True RMS, Vavg).

SCADA

Datapoints have been added for the second instance of the Reconnection module.

TCP

Bugfix:

- Some problem with the PPP/TCP communication has been fixed.

Version: 3.0.b

- Date: 2016-February-20
- Revision: B

Hardware

No changes.

Software

The self-monitoring has been improved.

Overcurrent – I[n]

Bugfix:

- An initialization issue has been fixed in the Overcurrent module. In case of MeasureMode I2 and DEFT characteristic, this issue could have caused a false pickup or trip after start-up.

Sys

Bugfix:

- Under special circumstances, an unintended warm restart had been possible.

SCADA / Modbus

Bugfix:

- The Modbus protocol did not read the system time correctly.

Self Supervision

Bugfix:

- Warnings related to the internal temperature monitoring did not work correctly.

Version: 3.0

- Date: 2015-October-01
- Revision: B

Hardware

- A new front plate in dark gray color replaces the blue housing that had been used for all **2.x** versions.
- The new front plate features a USB interface for the connection with the *Smart view* operating software. (This replaces the serial interface of the **2.x** versions.)
- There is a new communication type “I” available:
  RS485 (IEC 60870-5-103, MODBUS RTU, DNP3.0 RTU) + RJ45 Ethernet 100 Mbit/s (Modbus TCP, DNP3.0 TCP/UDP)
- “Conformal coating” is available now as an order option.
- The characters -2 in the typecode signify the major version upgrade from 2.x to 3.x.

Software

The device firmware is also available in Spanish language now.

Various small changes and restructuring have been made to the menu and the display.

Protection

Cause of trips are shown directly on the display.

Low Voltage Ride Through – LVRT

A second LVRT element has been added.

Loss of Potential – LOP

The Dead Bus Detection has been made configurable.

The breaker assignment is optional. (If no breaker has been assigned then the position is ignored.)

The general IOC blocking has been removed.

The load current threshold LOP . I< can be set with a range 0.5 to 4 In.

Q->&V< / ReCon

The reconnection part has been split off and has become an independent module.

The decoupling functions of the Reconnection module has been extended to all trip commands.

Temperature Protection Module – RTD

The trip command has been made selectable.

Switch Onto Fault - Module – SOTF

The SOTF function has been removed.

SCADA

The DNP3 has been made available (with RTU/TCP/UDP).

New fiber-optic interfaces for SCADA.

Setting procedure (menu structure, default settings) has been modified.

New “SCADA connection status” signal.

Ethernet “TCP Keep Alive” according to RFC 793.

Bugfix:

- After a hardware exception, the IP address might have been lost.

SCADA / IEC 61850

New support of Direct-Control.

Support for LN descriptions via DAI entry in the SCD file.

Handling of InGGIO Ind improved.

Speed of GOOSE messages improved. Potential problem with time-correlated GOOSE messages fixed.

New Logical Nodes for energy counters, LVRT, ExP, TCM, 47.

New LNClass for sensors and monitoring.

Updated reports if angles become zero, and if angles of phasors exceed deadband.

Deadband algorithm improved.

It is now possible to assign IEC 61850 alarm signals to the LEDs of the device.

Counter for the number of active client-server connections added.

Missing modes of directional power fixed.

SCADA / Modbus

“Fast Status Register” added.

Configurable registers added.

Read Fault Recorder and some device-specific information via Modbus.

Stability of Modbus TCP improved.

IEC 60870-5-103

Bugfix:

- Problem with reading disturbances fixed.

SNTP

Start the network after protection is active.

Bugfix:

- SNTP might not have worked correctly in case of an empty battery.
- Default daylight-saving changed to “Sunday”.

PC interface / Smart view connection

As of *Smart view* R4.30, it is possible to exchange the single-line for devices that support this.

The user interface supports the improved validation of IEC 61850 SCD files.

Characteristic curves can now be shown graphically.

There is now a Page Editor for creating single lines and device-pages.

Bugfix:

- After an interruption of communication, waveforms could no longer be received from the PC.
- After an interrupted download of the Device Model, file handling could be erroneous.

PC simulation

The LED status has been added to the simulation software.

Trend recorder

Bugfix:

- A memory leak has been fixed.

Analog Output – AnOut

Bugfix:

- After a restart of the device the output could peak to 100% for a short time.

When upgrading from a version 2.x device, the following must be noted with respect to the settings:

HINWEIS

- *All communication settings have to be re-defined. An automatic conversion is only partly possible.*
- *The VirtualOutput assignment of IEC 61850 communication has been restructured.*
- *All assignment settings need to be re-defined.*
- *The reconnection part of Q->&V< has been split off as a new module ReCon. An automatic conversion is not possible.*
- *The V-Prot mode V<(t) has been abandoned and replaced by the LVRT module.*

Abbreviations, and Acronyms

The following abbreviations and acronyms are used in this manual.

°C	Degrees Celsius
°F	Degrees Fahrenheit
A	Ampere(s), Amp(s)
AC	Alternating current
Ack.	Acknowledge
AND	Logical gate (The output becomes true if all Input signals are true.)
ANSI	American National Standards Institute
avg.	Average
AWG	American wire gauge
BF	Circuit breaker failure
Bkr	Breaker
Blo	Blocking(s)
BO	Binary output relay
BO1	1st binary output relay
BO2	2nd binary output relay
BO3	3rd binary output relay
calc	Calculated
CB	Circuit breaker
CBF	Module Circuit Breaker Failure protection
CD	Compact disk
Char	Curve shape
CLPU	Cold Load Pickup Module
Cmd.	Command
CMN	Common input
COM	Common input
Comm	Communication
Cr.	Counter(s)
CSA	Canadian Standards Association
CT	Control transformer
Ctrl.	Control
CTS	Current Transformer Supervision
CTS	Current transformer supervision
d	Day
D-Sub-Plug	Communication interface
DC	Direct current
DEFT	Definite time characteristic (Tripping time does not depend on the height of the current.)
delta phi	Vector surge
df/dt	Rate-of-frequency-change
DI	Digital Input
Diagn Cr	Diagnosis counter(s)
Diagn.	Diagnosis

DIN	Deutsche Industrie Norm
dir	Directional
EINV	Extremely inverse tripping characteristic
EMC	Electromagnetic compatibility
EN	Europäische Norm
err. / Err.	Error
EVTcon	Parameter determines if the residual voltage is measured or calculated.
Ex	External
Ex Oil Temp	External Oil Temperature
ExBlo	External blocking(s)
ExP	External Protection - Module
ExP	External protection
Ext Sudd Press	Sudden Pressure
Ext Temp Superv	External Temperature Supervision
f	Frequency Protection Module
Fc	Function (Enable or disable functionality = allow or disallow.)
FIFO	First in first out
FIFO Principal	First in first out
fund	Fundamental (ground wave)
gn	Acceleration of the earth in vertical direction (9.81 m/s2)
GND	Ground
h	Hour
HMI	Human machine interface (Front of the protective relay)
HTL	Manufacturer internal product designation
Hz	Hertz
I	Phase Overcurrent Stage
I	Fault current
I	Current
I-BF	Tripping threshold
I0	Zero current (symmetrical components)
I1	Positive sequence current (symmetrical components)
I2	Negative sequence current (symmetrical components)
I2>	Unbalanced Load-Stage
I2T	Thermal Characteristic
I4T	Thermal Characteristic
IA	Phase A current
IB	Phase B current
IC	Phase C current
IC's	Manufacturer internal product designation
Id	Differential Protection Module
IdG	Restricted Ground Fault Differential Protection Module
IdGH	Restricted Ground Fault Highset Protection Module
IdH	High-Set Differential Protection Module
IEC	International Electrotechnical Commission
IEC61850	IEC61850

IEEE	Institute of Electrical and Electronics Engineers
IG	Earth current protection - Stage
IG	Ground current
IG	Fault current
IGnom	Nominal ground current
IH1	1st harmonic
IH2	Module Inrush
IH2	2nd harmonic
in.	Inch
incl.	Include, including
InEn	Inadvertent Energization
Info.	Information
Interl.	Interlocking
Intertripping	Intertripping
INV	Inverse characteristic (The tripping time will be calculated depending on the height of the current)
IR	Calculated ground current
IRIG	Input for time synchronization (Clock)
IRIG-B	IRIG-B-Module
IT	Thermal Characteristic
IX	4th measuring input of the current measuring assembly group (either ground or neutral current)
J	Joule
kg	Kilogram
kHz	Kilohertz
kV	Kilovolt(s)
kVdc or kVDC	Kilovolt(s) direct current
I/In	Ratio of current to nominal current.
L1	Phase A
L2	Phase B
L3	Phase C
lb-in	Pound-inch
LED	Light emitting diode
LINV	Long time inverse tripping characteristic
LoE-Z1	Loss of Excitation
LoE-Z2	Loss of Excitation
Logics	Logic
LOP	Loss of Potential
LV	Low voltage
LVRT	Low Voltage Ride Through
m	Meter
mA	Milliampere(s), Milliamp(s)
man.	Manual
max.	Maximum
meas	Measured
min.	Minimum

min.	Minute
MINV	Moderately Inverse Tripping Characteristic
MK	Manufacturer Internal Product Designation Code
mm	Millimeter
MMU	Memory mapping unit
ms	Milli-second(s)
MV	Medium voltage
mVA	Milli volt amperes (Power)
N.C.	Not connected
N.O.	Normal open (Contact)
NINV	Normal inverse tripping characteristic
Nm	Newton-meter
No	Number
Nom.	Nominal
NT	Manufacturer internal product designation code
P	Reverse Active Power
Para.	Parameter
PC	Personal computer
PCB	Printed circuit board
PE	Protected Earth
p.u.	per unit
PF	Power Factor - Module
Ph	Phase
PQS	Power Protection - Module
pri	Primary
PROT or Prot	Protection Module (Master Module)
PS1	Parameter set 1
PS2	Parameter set 2
PS3	Parameter set 3
PS4	Parameter set 4
PSet	Parameter set
PSS	Parameter set switch (Switching from one parameter set to another)
Q	Reverse Reactive Power
Q->&V<	Undervoltage and Reactive Power Direction Protection
R	Reset
rec.	Record
rel	Relative
res	Reset
ResetFct	Reset function
RevData	Review data
RMS	Root mean square
Rst	Reset
RTD	Temperature Protection Module
s	Second
SC	Supervision Contact (Synonyms: Life-Contact, Watchdog, State of Health Contact)

Sca	SCADA
SCADA	Communication module
sec	Second(s)
sec	Secondary
Sgen	Sine wave generator
Sig.	Signal
SNTP	SNTP-Module
SOTF	Switch Onto Fault - Module
StartFct	Start function
Sum	Summation
SW	Software
Sync	Synchrocheck
Sys.	System
t	Tripping delay
t or t.	Time
Tcmd	Trip command
TCP/IP	Communication protocol
TCS	Trip circuit supervision
ThR	Thermal replica module
TI	Manufacturer internal product designation code
TripCmd	Trip command
txt	Text
UL	Underwriters Laboratories
UMZ	DEFT (definite time tripping characteristic)
USB	Universal serial bus
V	Voltage-stage
V	Volts
V/f>	Overexcitation
V012	Symmetrical Components: Supervision of the Positive Phase Sequence or Negative Phase Sequence
Vac / V ac	Volts alternating current
Vdc / V dc	Volts direct current
VDE	Verband Deutscher Elektrotechnik
VDEW	Verband der Elektrizitätswirtschaft
VE	Residual voltage
VG	Residual voltage-Stage
VINV	Very inverse tripping characteristic
VTS	Voltage transformer supervision
W	Watt(s)
WDC	Watch dog contact (supervision contact)
www	World wide web
XCT	4th current measuring input (ground or neutral current)
XInv	Inverse characteristic

List of ANSI Codes

ANSI	Functions
14	Underspeed
21	Distance Protection
21P	Phase Distance Protection
24	Overexcitation Protection (Volts per Hertz)
25	Synchronizing or Synchronism-check via 4th measuring channel of voltage measurement card
26	Temperature Protection
27	Undervoltage Protection
27(t)	Undervoltage (time dependent) Protection
27A	Undervoltage Protection (Auxiliar) via 4th measuring channel of voltage measurement card
27N	Neutral Undervoltage via 4th measuring channel of voltage measurement card
27TN	Third Harmonic Neutral Undervoltage via 4th measuring channel of voltage measurement card
32	Directional Power Protection
32F	Forward Power Protection
32R	Reverse Power Protection
37	Undercurrent / Under Power
38	Temperature Protection (optional via Interface/external Box)
40	Loss of Excitation / Loss of Field
46	Unbalanced Current Protection
46G	Unbalanced Generator Current Protection
47	Unbalanced Voltage Protection
48	Incomplete Sequence (Start-up time Supervison)
49	Thermal Protection
49M	Thermal Motor Protection
49R	Thermal Rotor Protection
49S	Thermal Stator Protection
50BF	Breaker Failure
50	Overcurrent (instantaneous)
50P	Phase Overcurrent (instantaneous)
50N	Neutral Overcurrent (instantaneous)
50Ns	Sensitive Neutral Overcurrent (instantaneous)
51	Overcurrent
51P	Phase Overcurrent
51N	Neutral Overcurrent
51Ns	Sensitive Neutral Overcurrent
51LR	Locked Rotor
51LRS	Locked Rotor Start (during start sequence)
51C	Voltage Controlled Overcurrent (via adaptive Parameters)
51Q	Negative Phase Sequence Overcurrent (multiple trip characteristics)
51V	Voltage Restrained Overcurrent
55	Power Factor Protection
56	Field Application Relay
59	Overvoltage Protection
59TN	Third Harmonic Neutral Overvoltage via 4th measuring channel of voltage measurement card
59A	Overvoltage Protection via 4th (Auxiliar) measuring channel of voltage measurement card
59N	Neutral Overvoltage Protection
60FL	Voltage Transformer Supervision
60L	Current Transformer Supervision
64R	Rotor Earth Fault Protection
64REF	Restricted Ground Fault Protection

ANSI	Functions
66	Starts per h (Start Inhibit)
67	Directional Overcurrent
67N	Directional Neutral Overcurrent
67Ns	Sensitive Directional Neutral Overcurrent
68	Power Swing Blocking
74TC	Trip Circuit Supervision
78	Out of Step Tripping
78V	Vector Surge Protection
79	Auto Reclosure
81	Frequency Protection
81U	Underfrequency Protection
81O	Overfrequency Protection
81R	ROCOF (df/dt)
86	Lock Out
87B	Busbar Differential Protection
87G	Generator Differential Protection
87GP	Generator Phase Differential Protection
87GN	Generator Ground Differential Protection
87L	Cable and Line Differential Protection
87M	Motor Differential Protection
87T	Transformer Differential Protection
87TP	Transformer Phase Differential Protection
87TN	Transformer Ground Differential Protection
87U	Unit Differential Protection (protected zone includes generator and step-up transformer)
87UP	Unit Phase Differential Protection (protected zone includes generator and step-up transformer)

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